

What is a Resource?

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Complexity Resources in Physical Computation
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So, why not try other models of computation, such as *analogue computers*?

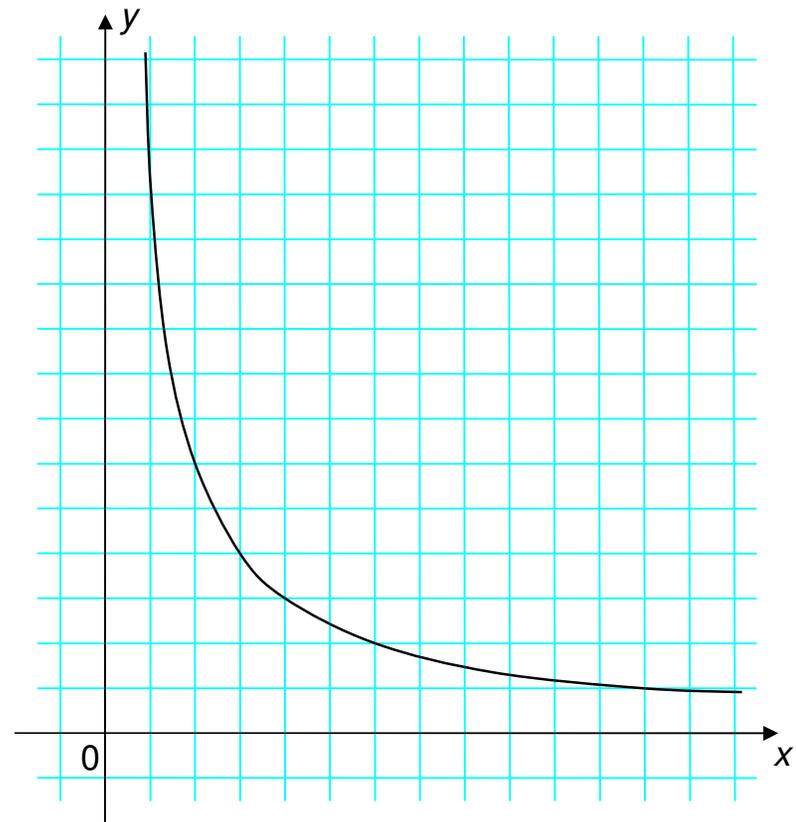
Geometric formulation.

Descartes tells us that *numerical* problems can often be recast *geometrically*.

So, don't think about finding **numbers** x and y such that $xy = n$ (i.e. $y = n/x$); think about the **graph** $y = n/x$.

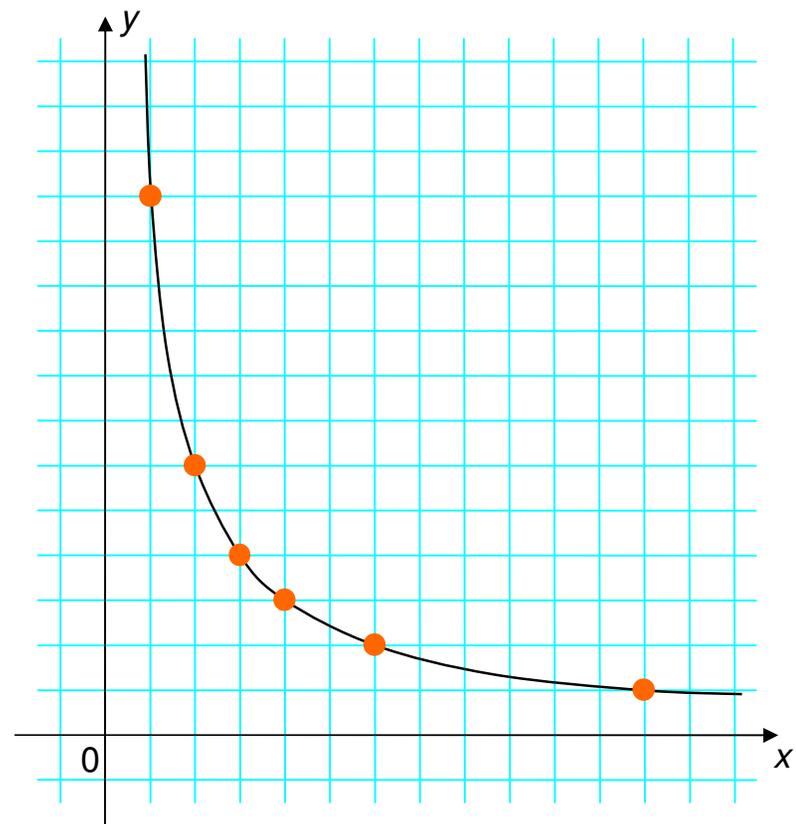
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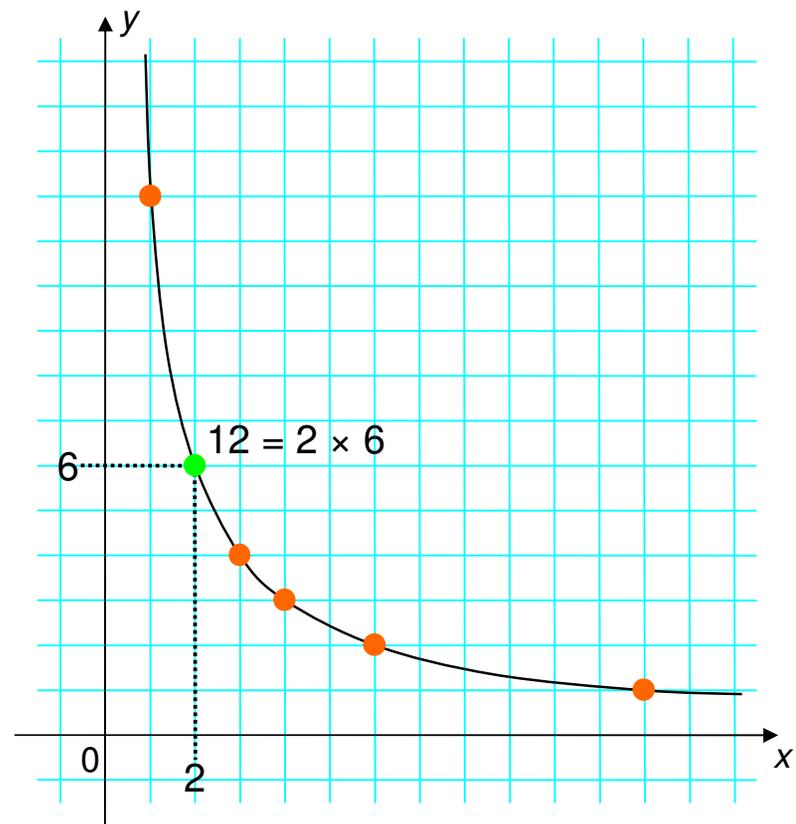
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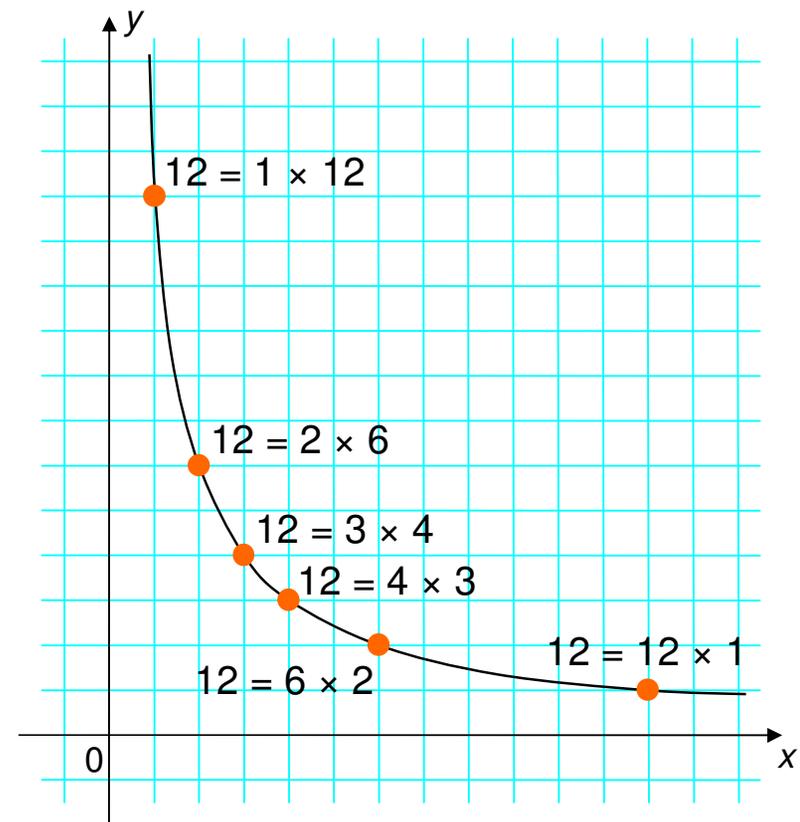
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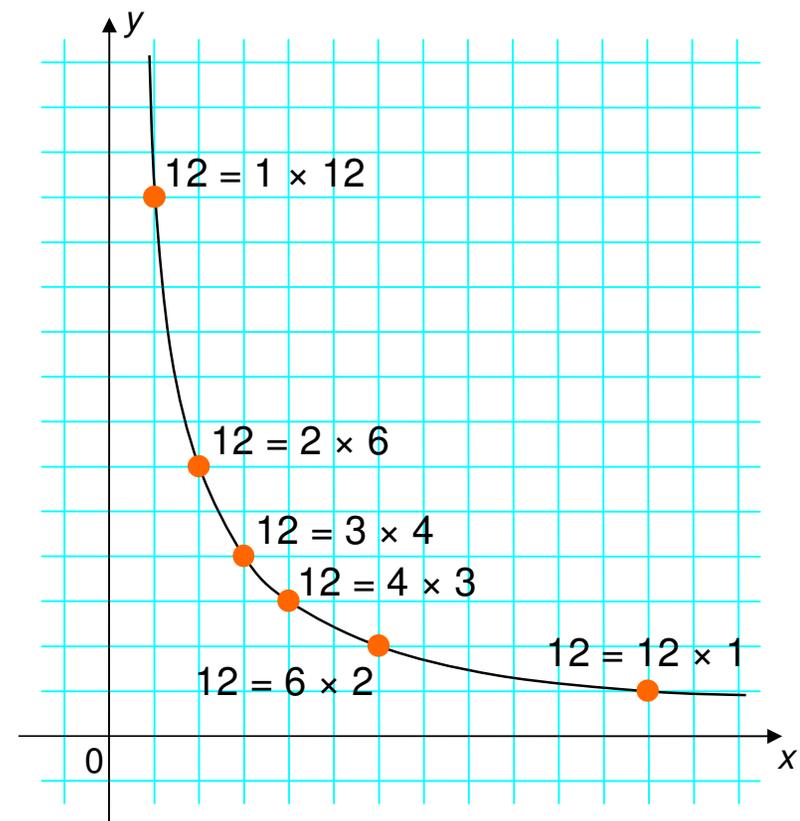
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The curve is a hyperbola, and, hence, a *conic section*.

So, **we seek points that are both**

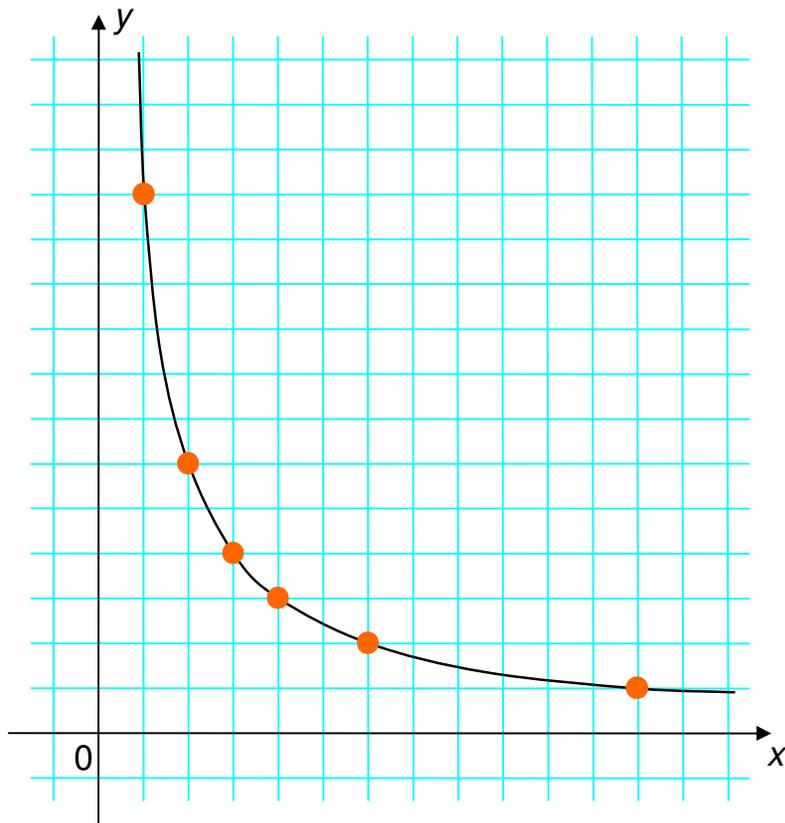
- **on a cone and**
- **on the integer grid.**

We implement this cone and grid.



Implementing the grid.

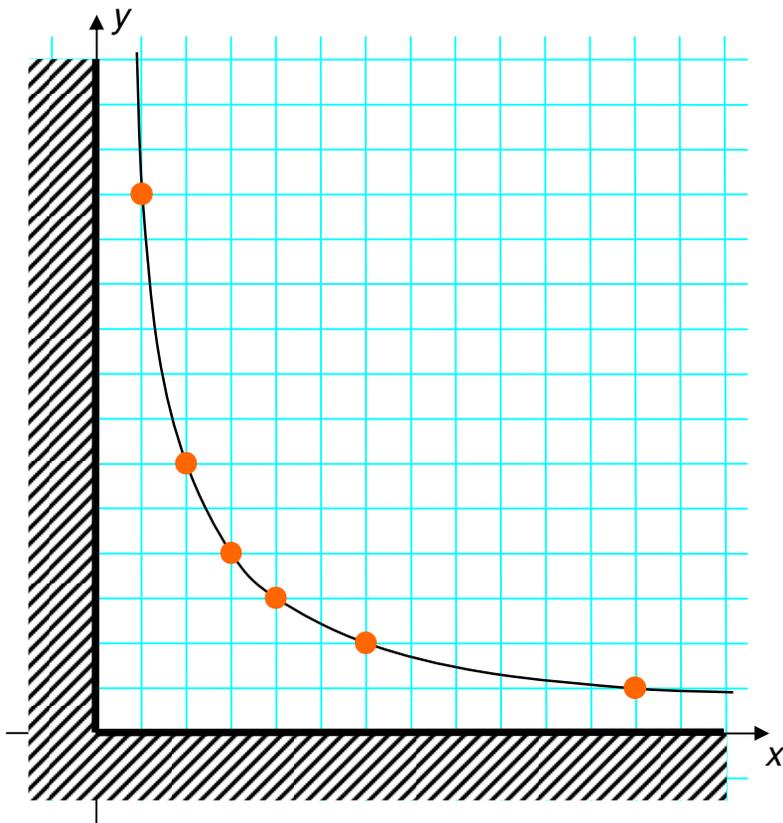
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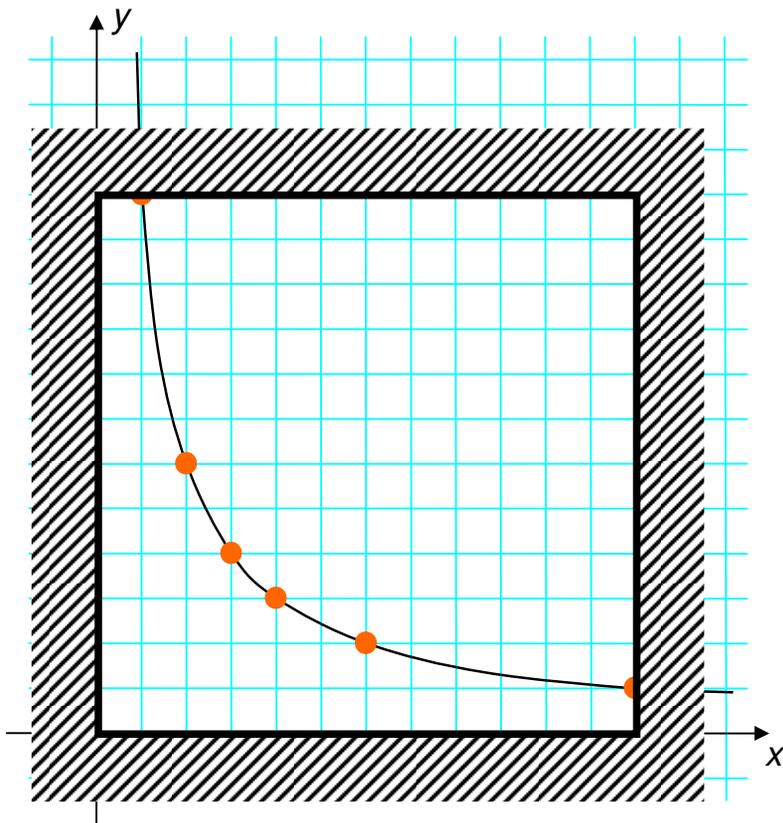
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- Factors are ≥ 0 (in fact, ≥ 1), so $x, y \geq 0$.



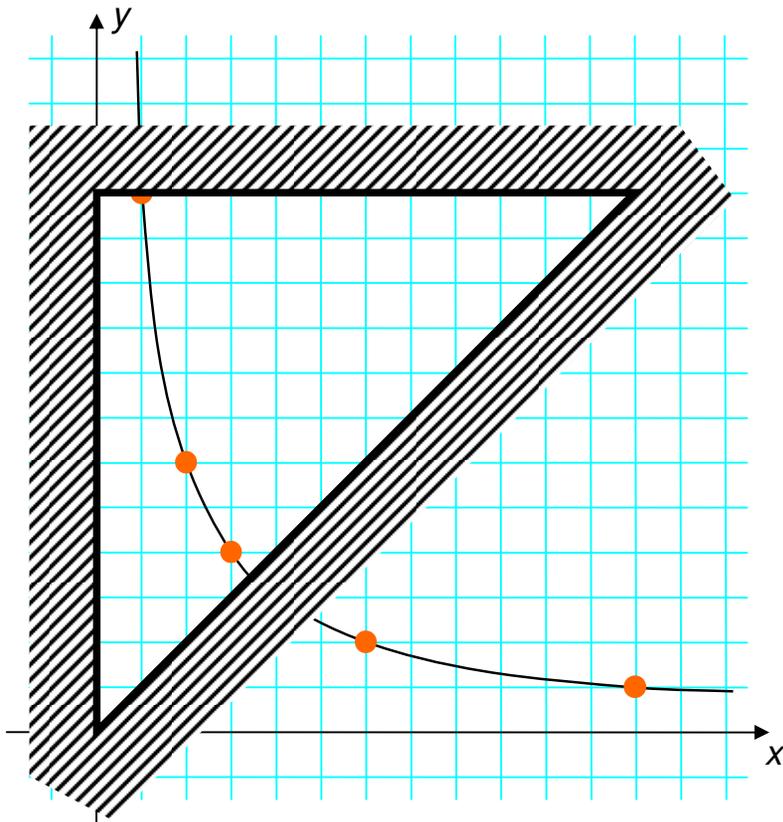
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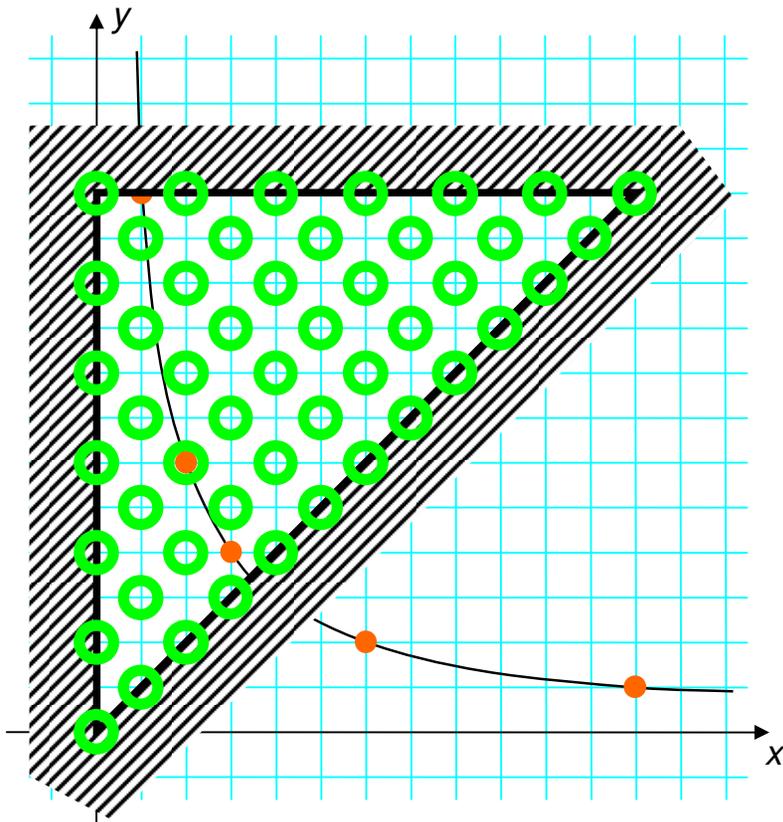
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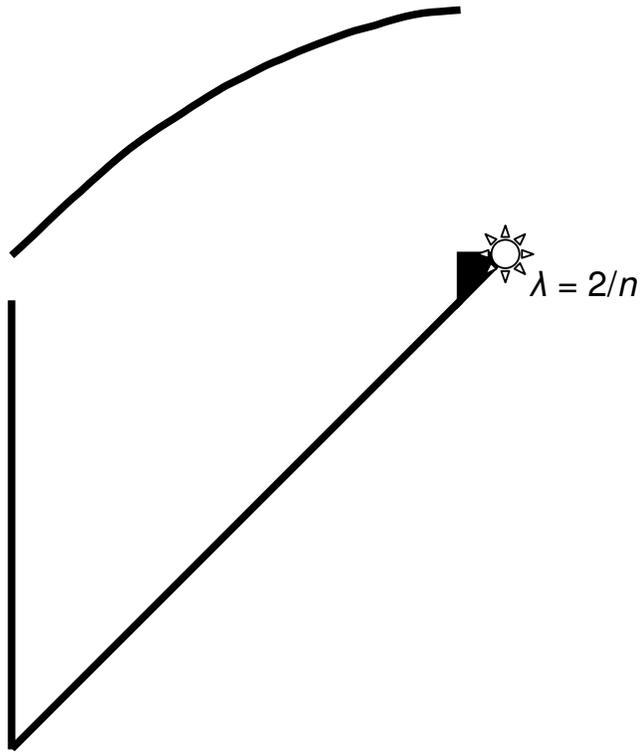
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- (x, y) gives the same factors as (y, x) , so we suppose that $\mathbf{x \leq y}$.
- We assume that n is odd, and so need only consider points where x and y are odd; we implement points where \mathbf{x} and \mathbf{y} have the same parity.

This is the part of the integer grid that we implement.

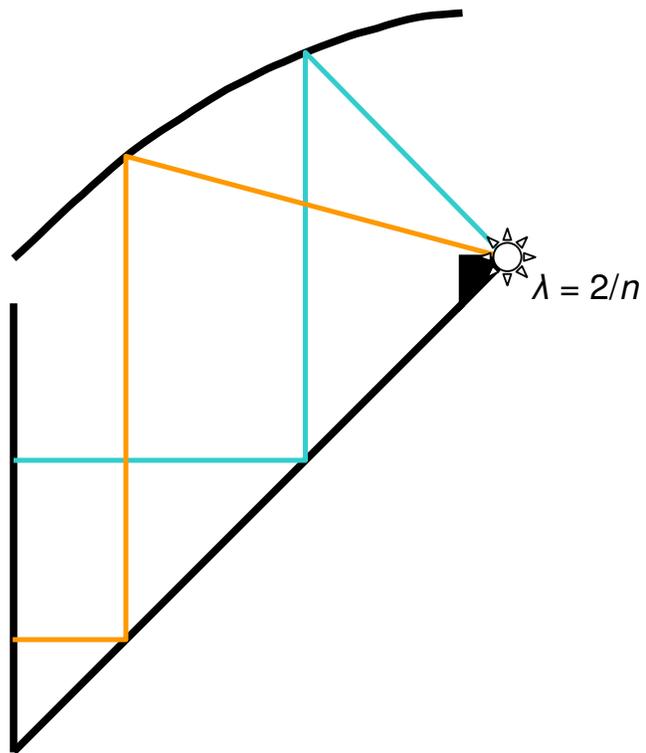
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- a *source of waves* of wavelength $\lambda = 2/n$, and
- three *mirrors* (one parabolic, two plane).



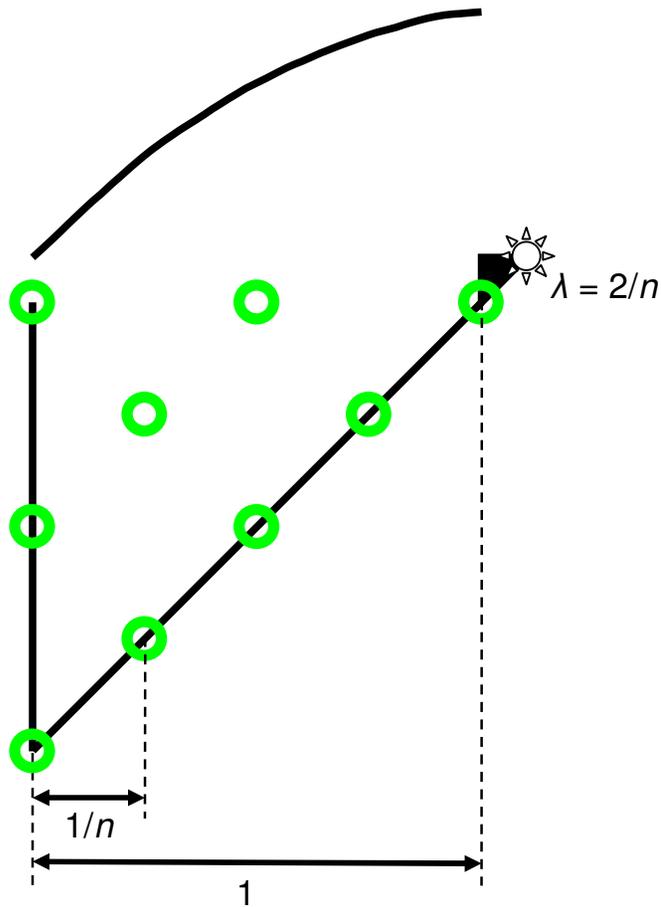
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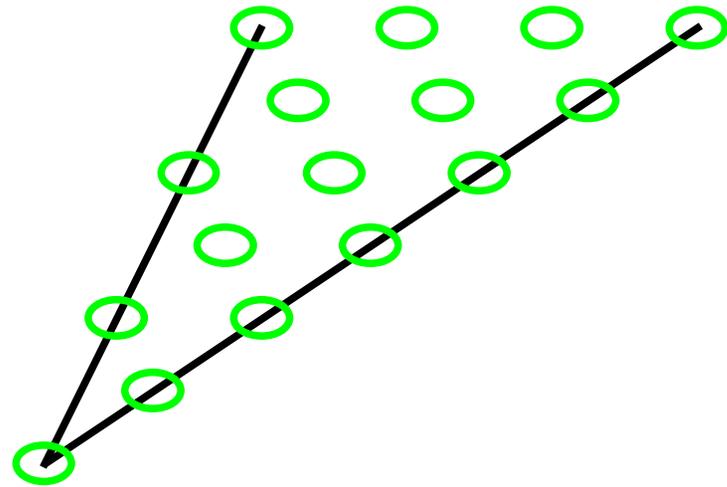
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The points of maximal wave activity in the resultant interference pattern model the grid points.

Since λ depends on the input value n , setting the wavelength forms part of the system's input process.

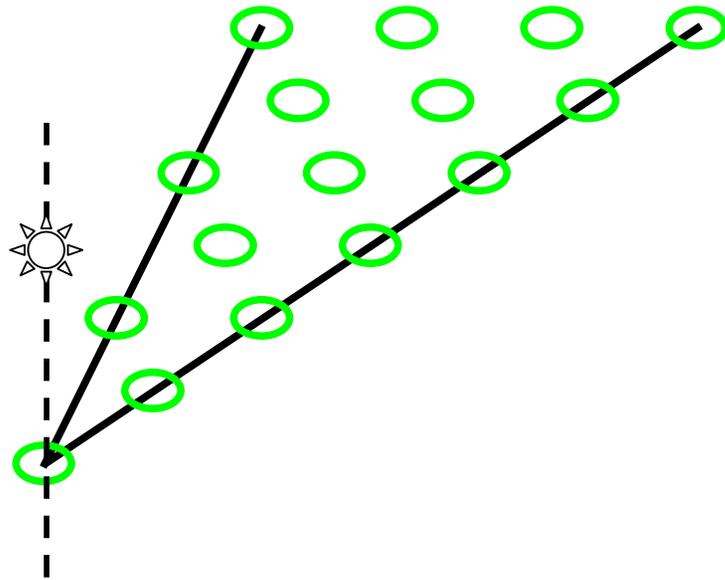
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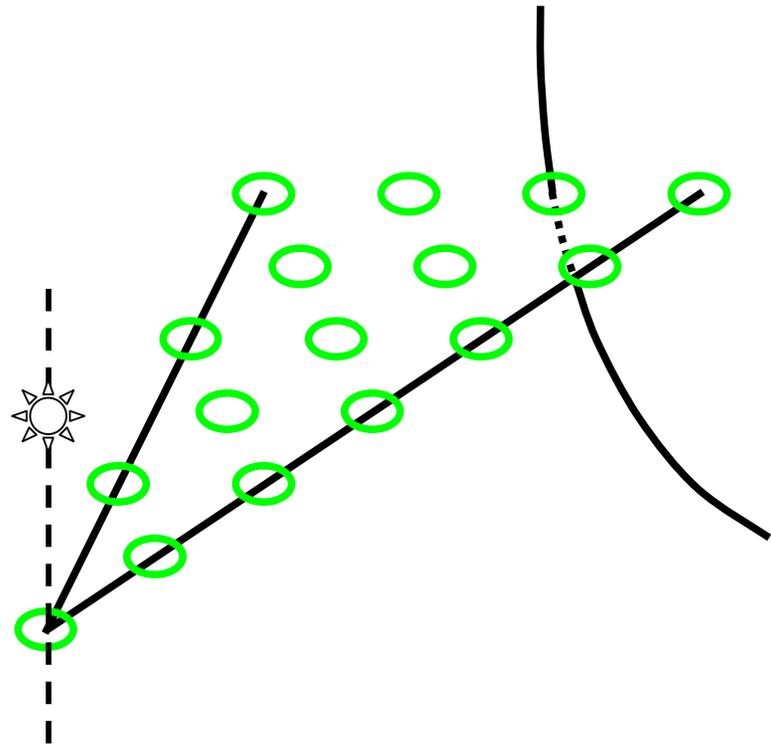
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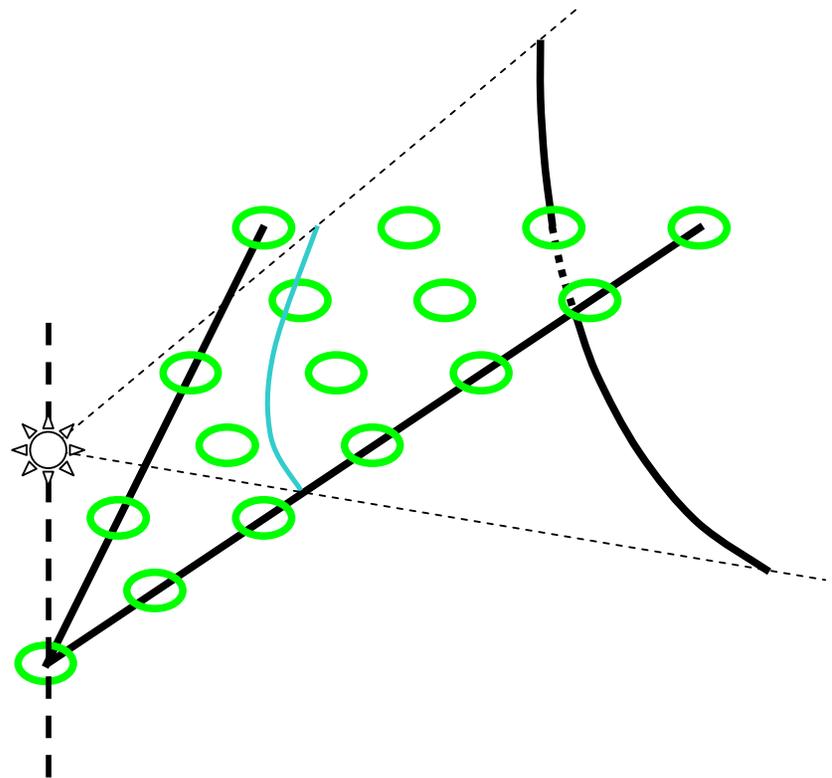


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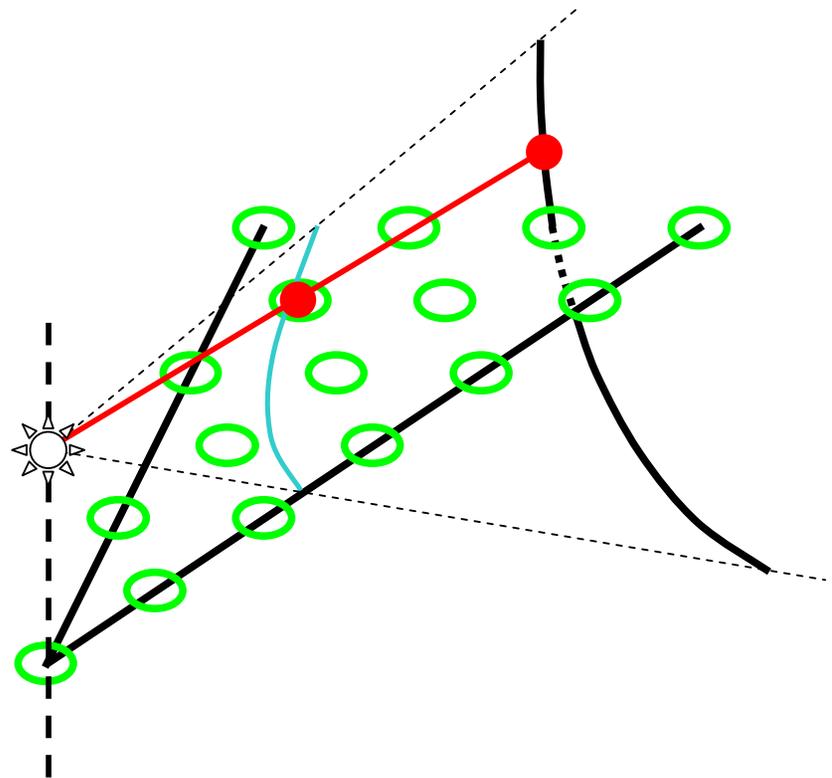
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If this point is also an [integer point](#), then the radiation will appear diminished at the sensor.



Finding factors.

- **Input.** Set parameters that depend on n : wavelength of first source, height of second source, height of sensor.
- **Processing.** Waves propagate and produce interference pattern (esp. on sensor).
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Time/space complexity.

- **Input.** Given n , calculate values (e.g. $\lambda = 2/n$) of input parameters.
- **Output.** Convert coordinates of dark spots, which encode factors of n , into factors.

These steps take *polynomial* time and space (via Turing machine).

Everything else is constant time/space!

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Precision.

Precision complexity captures robustness against I/O imprecision. Our system's precision complexity is *exponential*.

That is, as n increases, the precision with which parameters must be manipulated and measured increases *exponentially*.

How should we measure non-Turing computers' complexity?

Simply by considering all relevant resources (not just the Turing-type ones).

Given a computer, the key question is:

what resources does the computation consume,
and in ***what quantities***?

Obviously still consider *algorithmic* measures (time, space, etc.) but,

especially if these seem too good to be true,

consider whether anything else *non-algorithmic* (precision, energy, etc.) is being consumed.

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- **Precision** (e.g. in analogue, quantum, chemical and optical computers).
- **Thermodynamic cost** (in irreversible computations, where entropy increases).
- **Energy** (e.g. in mechanical/analogue and quantum-adiabatic computers).
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We can then define the *complexity function* corresponding to a given resource:

$$TC_\phi(n) := \sup \{ T_\phi(x) : |x| = n \} .$$

Blum's axioms.

These are conditions that a resource may or may not satisfy.

The axioms ensure:

1. that a resource is **defined** precisely at inputs at which the computation being measured is defined, and
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In my work (where the resources are deterministic, even if the computers being measured aren't), the axioms should hold.

But they alone aren't enough...

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Motivation:

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We'd like to be able to say that resource X is '**relevant**' for the optical computer, and that Y is for the chemical computer; then we can \mathcal{O} -compare X and Y .

Dominance formalizes this idea of 'relevance'.

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Resource A is *dominant* if, for all B ,
 $AC_\phi \in \mathcal{O}(BC_\phi) \Rightarrow BC_\phi \in \mathcal{O}(AC_\phi)$.

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We define *dominance* relative to a set of resources .

- \mathcal{R} is a set of *resources*.

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That is,

\mathcal{R} -dominant resources are those that \mathcal{O} -exceed all resources with which they are \mathcal{O} -comparable.

\mathcal{R} -complexity.

(As before, \mathcal{R} is a set of *resources* and ϕ is a *computer*.)

The \mathcal{R} -complexity of ϕ , denoted $\mathcal{B}_{\mathcal{R}, \phi}$, is the complexity function given by:

$$\mathcal{B}_{\mathcal{R}, \phi}(n) := \sum_{A \text{ is } \mathcal{R}\text{-dominant}} AC_{\phi}(n) .$$

We sum ‘relevant’ resources (and no others).

This captures ‘overall complexity’.

Why Blum's axioms aren't enough.

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- Each is an **internally consistent** measure of space usage.
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But then there's dominance...

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- **S' dominates T** (i.e. S' is $\{S', T\}$ -dominant but T is not), but
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We can engineer which resource appears more important. By applying to the more slowly growing, non-dominant resource a sufficiently fast-growing, monotonic function (e.g. $n \mapsto 2^n$), this resource becomes dominant. **We don't want this!**

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So, let's restrict resources (so that, e.g., S is valid but S' is not) to stop this sort of thing. We do this with ***normalization***.

Normalization—motivation.

Recall resources S (the number of tape-cells) and $S' (= 2^S)$.

What values can these resources take?

- We can write to any number of cells, then halt. So S maps surjectively to \mathbb{N} .
- Hence, S' maps surjectively to $\{1, 2, 4, 8, \dots\}$.

The former property—mapping onto \mathbb{N} —seems the more natural (quite literally!), and we use it as our blueprint for normalization.

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- Let A be a resource that can take as its subscript any computing system $\phi \in \mathcal{C}$ ($A_\phi: X_\phi \rightarrow \mathbb{N}$). Define the \mathcal{C} -normalized form of A to be the resource A^e given by $A^e_\phi: X_\phi \rightarrow \mathbb{N}$,

$$A^e_\phi(x) := |\{ A_\psi(y) : \psi \in \mathcal{C} \text{ and } y \in X_\psi \text{ and } A_\psi(y) < A_\phi(x) \}| .$$

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In words, $A^e_\phi(x)$ is the number of distinct values less than $A_\phi(x)$ taken by A (as it ranges over all computers in \mathcal{C} and all input values).

This is a measure of ‘how much use A makes’ of the natural numbers less than $A_\phi(x)$.

Normalization—example.

Revisiting our example of S (the number of tape-cells) and $S' (= 2^S)$, we have that

$$S^{\mathcal{T}} = S^{\mathcal{J}} = S$$

(and that $T^{\mathcal{T}} = T$),

where \mathcal{J} is the class of Turing machines.

So, if we use only *normal* resources, we may validly compare S and T , but not S' and T .

Normalization—properties.

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$$A_{\phi}(x) < A_{\psi}(y) \text{ if and only if } A^e_{\phi}(x) < A^e_{\psi}(y) .$$

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- **Characterization** of normal resources:

Resource A is normal if and only if its image set (over all **computers** and **input values**) $\{A_\psi(y) : \psi \in \mathcal{C} \text{ and } y \in X_\psi\}$ is an ‘initial segment’ $\{i \in \mathbb{N} : i < n\}$ for some $n \in \mathbb{N} \cup \{\infty\}$.

Normalization—intuition.

Non-normalized: cardinal.
Normalized: ordinal.

If we let resources be *any* functions that satisfy Blum's axioms and have codomain \mathbb{N} , then we are effectively dealing with ***cardinals***: we are *counting* time steps, units of energy or similar—we have an intrinsic *unit of measurement*.

This is resource-dependent and not conducive to resource-heterogeneous comparison (e.g., how many time steps should we deem of equivalent cost/value to one tape cell?).

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But if we allow only *c-normal* resources, then we have ***ordinals***: 0 represents the *least* resource consumption, 1 the *second-least*, 2 the *third-least*, and so on; this is independent of resources and units. Comparison then seems fair and equal-footed.

Concluding comments.

- With *Turing machines*, we know what resources to consider.
- With *unconventional computers*, it's not so obvious.
- And even when we've identified our unconventional resources, there are comparison difficulties. Hence ***dominance***.
- But to make dominance work, we need to restrict our notion of resource (more than Blum's axioms do). Hence ***normalization***.
- This restriction stops certain 'deceptive' complexity behaviour, e.g. 'dominance engineering' via application of quickly growing, isotone functions.
- The restriction also renders resources 'ordinal', not 'cardinal', allowing seemingly fairer comparison.

Questions?

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A paper, ***Beyond Blum: What is a Resource?***, related to parts of this talk is to appear in the *International Journal of Unconventional Computation*.

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Complexity and Decidability in Unconventional Computational Models.