

Rethinking Optimal Embedding

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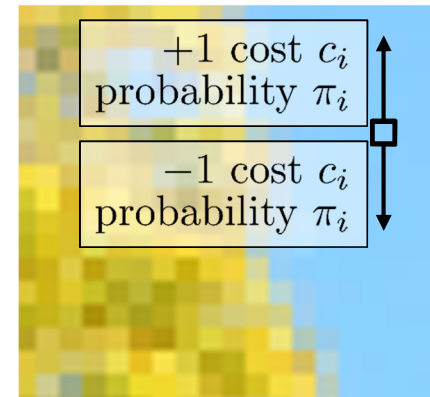


4th ACM Workshop on Information Hiding & Multimedia Security

Adaptive steganography

Some embedding changes are more detectable than others.

- Assign each possible change a cost c_i .



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- Assign each possible change a cost c_i .
- Use coding (STCs) to minimize average cost $\sum_i \pi_i c_i$.



e.g. HUGO [2010], WOW [2012], UNIWARD [2013-4], HILL [2014], ...

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What if the enemy is aware of your adaptivity?

e.g. ‘tSRM’ attack on WOW [Tang et al., 2014]

‘CSR’ on 1st version of UNIWARD [Denemark et al., 2014]

‘maxSRM’ on 2nd version of UNIWARD [Denemark et al., 2014]

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What if the enemy is aware of your adaptivity?

- Use coding (STCs) to minimize $\sum_i \pi_i^2 c_i$.

Two-player, zero-sum game

Embedder

chooses probability of changing each location π_i ('p-map').

Detector

chooses weights for each observation ω_i .

Embedder's payoff = $-$ (Detector's payoff) = FP-50:
false positive rate @ 50% true positives

- Used in game theory of embedding since at least 2007.
- Slightly simplifies the analysis.

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If based on some detection value ℓ , inverse in the *deflection*:

$$\delta = \frac{E_{Stego}[\ell] - E_{Cover}[\ell]}{\sqrt{\text{Var}_{Cover}[\ell]}}.$$

(assuming ℓ asymptotically Gaussian).

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- Also used in game theory of embedding since at least 2007, and recently.
- Monotone relationship with other popular metrics.

Binary covers

Independent pixels taking binary values (X_1, \dots, X_n) .

Embedder flips pixels.

In cover:

$$P[X_i = 1] = p_i$$

In stego:

$$P[X_i = 1] = p_i + \pi_i(1 - 2p_i)$$

 Embedder's strategy (change probabilities)

Binary covers

We may assume the detector is based on log likelihood ratio:

$$\ell = \sum_i X_i \omega_i$$


Detector's strategy (weights)

In cover:

$$P[X_i = 1] = p_i$$

In stego:

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Binary covers

We may assume the detector is based on log likelihood ratio:

$$\ell = \sum_i X_i \omega_i$$

In cover:

$$P[X_i = 1] = p_i \quad E[\ell] = \sum_i p_i \omega_i \quad \text{Var}[\ell] = \sum_i \overbrace{p_i(1-p_i)}^{e_i} \omega_i^2$$

In stego:

$$P[X_i = 1] = p_i + \pi_i(1-2p_i) \quad E[\ell] = \sum_i p_i \omega_i + \sum_i \overbrace{\pi_i(1-2p_i)}^{d_i} \omega_i$$

$$\left. \begin{array}{l} \text{Embedder wants to minimize} \\ \text{Detector wants to maximize} \end{array} \right\} \text{Deflection: } \delta = \frac{\sum_i \pi_i d_i \omega_i}{\sqrt{\sum_i e_i \omega_i^2}}$$

Binary covers

Detector maximizes δ

Embedder minimizes δ

$$\delta = \frac{\sum_i \pi_i d_i \omega_i}{\sqrt{\sum_i e_i \omega_i^2}}$$

arg max $\delta \propto \pi_i \frac{d_i}{e_i}$
knowing

arg max $\delta \propto \frac{d_i}{e_i}$
ignorant

$\delta = \frac{\sum_i \pi_i^2 d_i^2 / e_i}{\sqrt{\sum_i \pi_i^2 d_i^2 / e_i}}$ i.e. $\min_{\pi_i} \sum_i \pi_i^2 c_i$

$\delta = \frac{\sum_i \pi_i d_i^2 / e_i}{\sqrt{\sum_i d_i^2 / e_i}}$ i.e. $\min_{\pi_i} \sum_i \pi_i c_i$

Minimax in two-player, zero-sum game, hence equilibrium.

Binary covers

Detector's optimal behaviour is to weight each pixel according to its 'p-map'.

embedder minimizes δ

$$\delta = \frac{\sum_i \pi_i d_i \omega_i}{\sqrt{\sum_i e_i \omega_i^2}}$$

$\arg \max_{\omega_i} \delta \propto \pi_i \frac{d_i}{e_i}$
knowing

$$\delta = \frac{\sum_i \pi_i^2 d_i^2 / e_i}{\sqrt{\sum_i \pi_i^2 d_i^2 / e_i}} \quad \text{i.e.} \quad \min_{\pi_i} \sum_i \pi_i^2 c_i$$

Minimax in two-player, zero-sum game, hence equilibrium.

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Arbitrary covers

Independent pixels taking k -ary values, with a different distribution at each pixel.

- Fixed embedding operation, at pixel i with probability π_i ,

vs. ignorant: $\min_{\pi_i} \sum_i \pi_i c_i$

vs. knowing: $\min_{\pi_i} \sum_i \pi_i^2 c_i$

- Arbitrarily changing embedding operations,

vs. ignorant: $\min_{\pi_i} \sum_i \pi_i^T e_i$

vs. knowing: $\min_{\pi_i} \sum_i \pi_i^T E_i^{-1} \pi_i$

Connections with other work

- Optimal detectors weight the evidence.

e.g. maxSRM [Denemark et al., 2014] and tSRM [Tang et al., 2014].

- Squared probabilities.

Intuitive. Appear as far back as [Ker, 2007].

- Generalizes recent work of Sedighi, Cogranne & Fridrich:
 - independent discretized Gaussian pixels, varying variance,
 - symmetric ternary coding: $\min \sum_i \pi_i^2 / \sigma_i^4$
 - pentary coding: $\min \sum_i \pi_i^T E_i^{-1} \pi_i$

Payload constraint

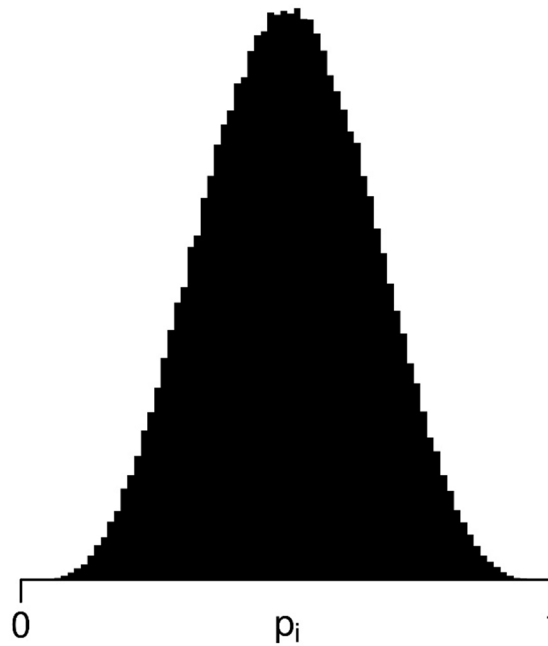
subject to $\sum_i H(\pi_i) \geq \text{payload length},$

- **Naive:** $\min_{\pi_i} \sum_i \pi_i c_i \longrightarrow H'(\pi_i) = \lambda c_i$
- **Equilibrium:** $\min_{\pi_i} \sum_i \pi_i^2 c_i \longrightarrow H'(\pi_i)/\pi_i = \lambda c_i$
- **Equilibrium:** $\min_{\pi_i} \sum_i \pi_i^T E_i^{-1} \pi_i \longrightarrow \text{convex set of equations}$
(arbitrary embedding)

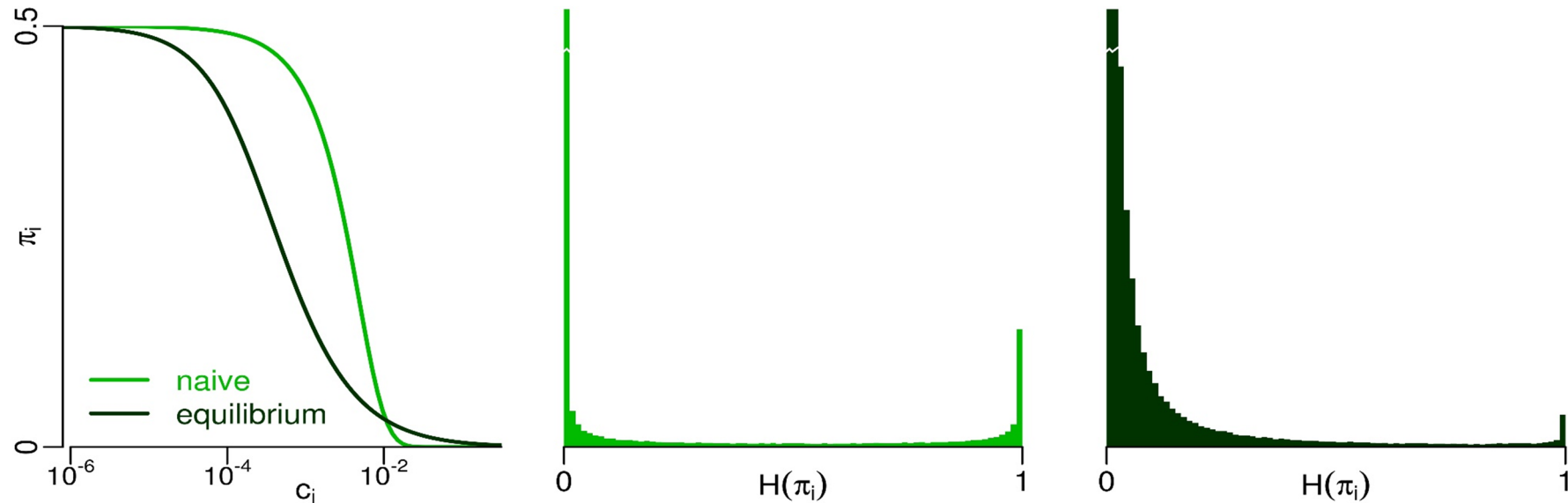
Experiments on binary covers

We generated artificial binary covers:

- $n = 2^{18}$ pixels (à la BOSSBase),
- p_i drawn from $\text{Beta}(5, 5)$,



Experiments on binary covers



- simulated payload of 0.1 bits per pixel with optimal coding:
 - constant π_i ,
 - naive adaptivity: $\min_{\pi_i} \sum_i \pi_i c_i$,
 - equilibrium adaptivity: $\min_{\pi_i} \sum_i \pi_i^2 c_i$.
- Used likelihood ratio tests on 10 000 covers & stego objects.

Experiments on binary covers

LRT detector for...	Embedding probabilities		
	Constant π_i	Naive π_i	Equilibrium π_i
Constant π_i	0.000	0.492	0.335
Naive π_i	0.443	0.023	0.225
Equilibrium π_i	0.038	0.081	0.145 (equilibrium)


FP-50 (false positive rate at 50% true positive)

- simulated payload of 0.1 bits per pixel with optimal coding:
 - constant π_i ,
 - naive adaptivity: $\min_{\pi_i} \sum_i \pi_i c_i$,
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Experiments on S-UNIWARD

Computes cost in a wavelet domain: [Holub et al., 2014]

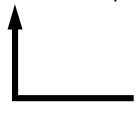
$$c_i = \sum_j \frac{|W_j(\text{Cover}) - W_j(\text{Cover} + \text{change } i)|}{\sigma + |W_j(\text{Cover})|}$$

 wavelet coefficient

Experiments on S-UNIWARD

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 stabilization value

In the original definition, $\sigma = 10^{-15}$

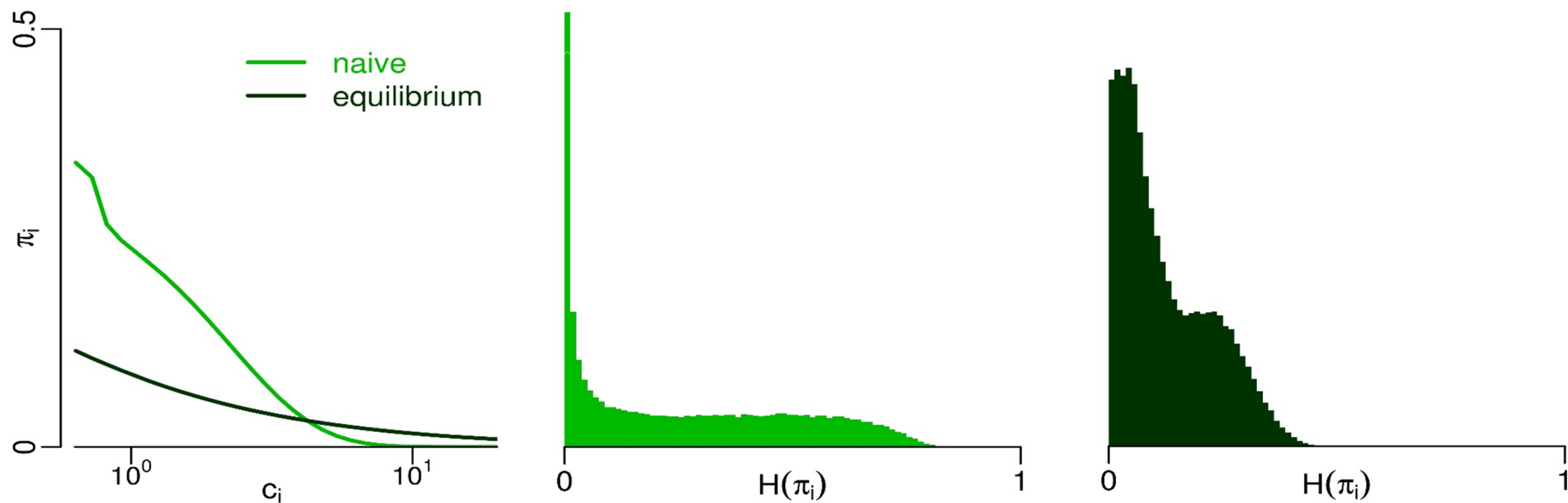
... exploited by ‘CSR features’ [Denemark et al., 2014]

Experiments on S-UNIWARD

Computes cost in a wavelet domain: [Holub et al., 2014]

$$c_i = \sum_j \frac{|W_j(\text{Cover}) - W_j(\text{Cover} + \text{change } i)|}{\sigma + |W_j(\text{Cover})|}$$

↑
stabilization value



Experiments on S-UNIWARD

Detector trained on ...	Embedding probabilities	
	Naive π_i	Equilibrium π_i
Naive π_i	0.007	0.500
Equilibrium π_i	0.502	0.130 (NOT equilibrium)

$P_{\text{err}} = 0.5(P_{\text{fp}} + P_{\text{fn}})$

- BOSSBase images (8000 training, 2000 testing, 10 iterations),
- simulated payload of 0.3 bits per pixel,
- CSR features, ensemble of FLDs detector.

Conclusions

- $\min_{\pi_i} \sum_i \pi_i c_i \rightarrow \min_{\pi_i} \sum_i \pi_i^2 c_i$ is not a panacea!
 - *Need to start with statistically correct costs.*
- Very general, but completely theoretical, results.
 - *Assumes both players know cover source exactly.*
 - *Unlike MiPOD, does not give a new embedding method.*
- (Recent work) the square root law still holds...
 - *with some interesting wrinkles.*
- (Further work) for non-independent pixels/changes/costs?