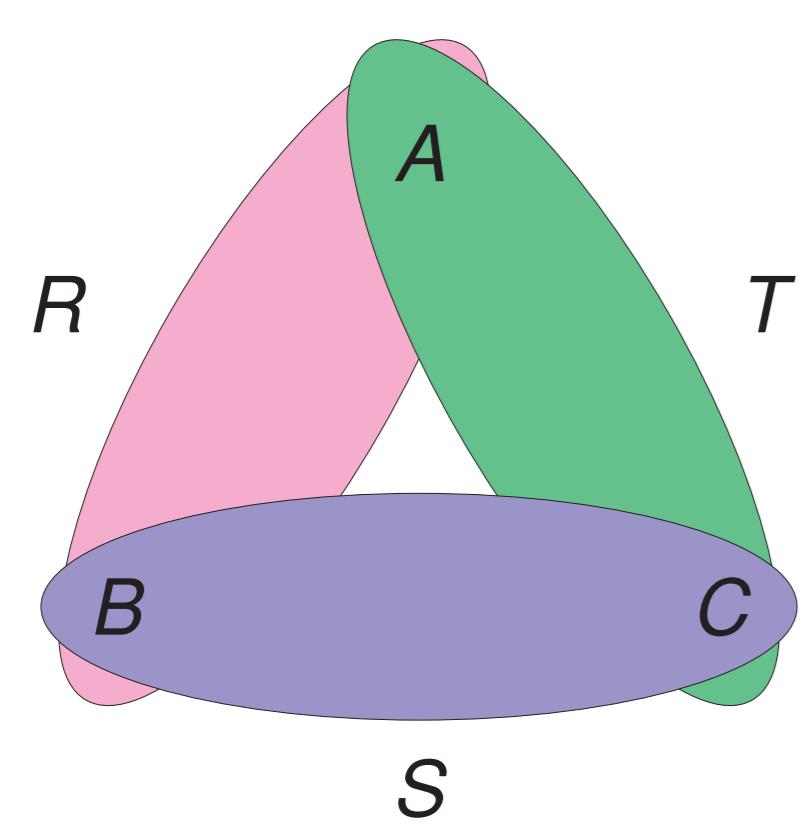


Problem Setting

Maintain the triangle count Q under single-tuple updates to R , S , and T !



Q counts the number of tuples in the join of R , S , and T .

$$Q = \sum_{a,b,c} R(a,b) \cdot S(b,c) \cdot T(c,a)$$

*We write a instead of $a \in \text{dom}(A)$.

Relations and Single-Tuple Updates

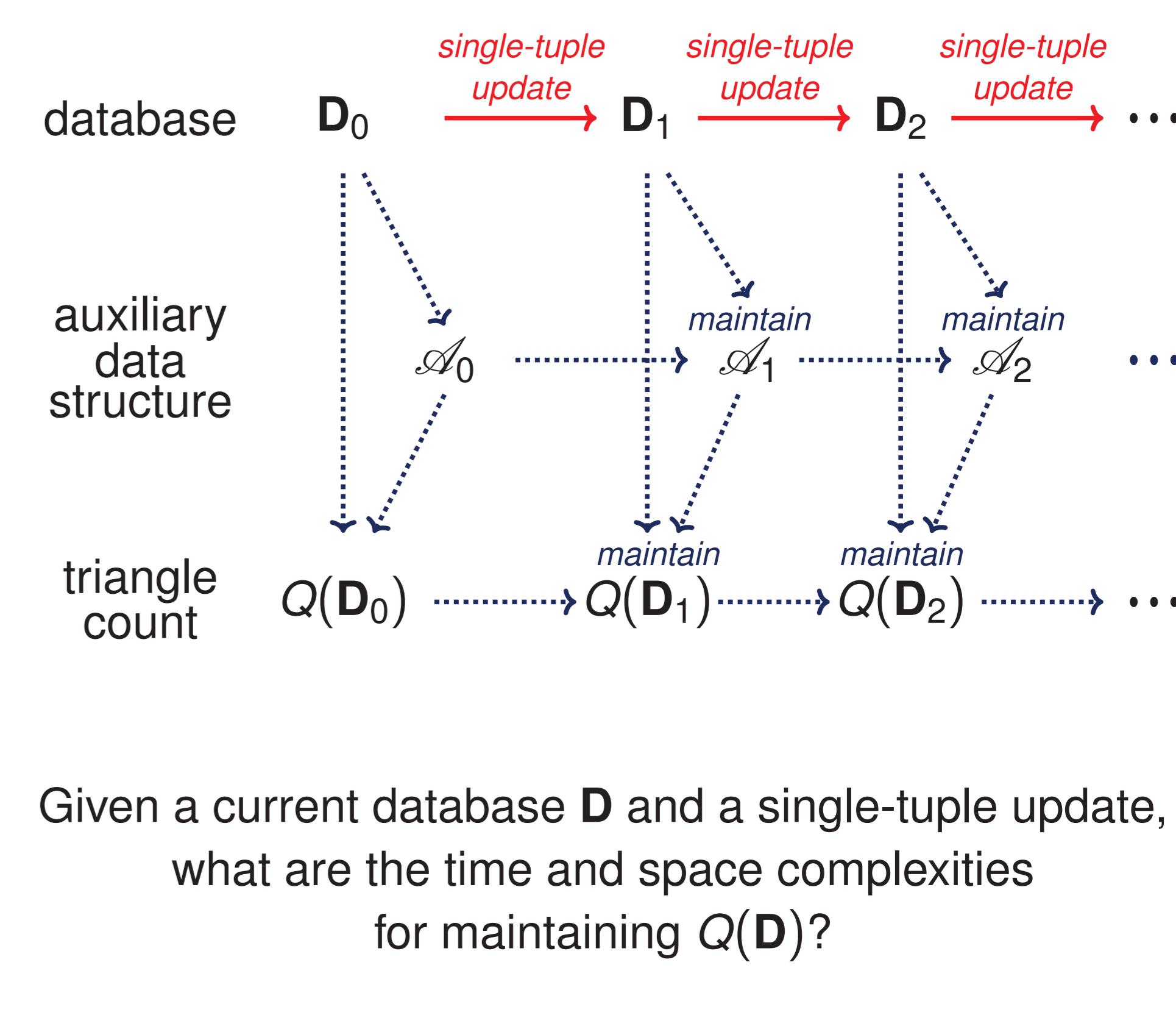
- Relations are functions mapping tuples to multiplicities.
- A single-tuple update maps a tuple to a non-zero value (positive for insertions negative for deletions).

database \mathbf{D}		
R	S	T
$\begin{array}{ c c }\hline A & B \\ \hline a_1 & b_1 \\ \hline \end{array}$	$\begin{array}{ c c }\hline B & C \\ \hline b_1 & c_1 \\ \hline \end{array}$	$\begin{array}{ c c }\hline C & A \\ \hline c_1 & a_1 \\ \hline c_2 & a_1 \\ \hline c_2 & a_2 \\ \hline \end{array}$
$a_1 b_1 2$	$b_1 c_1 2$	$c_1 a_1 1$
$a_2 b_T 3$	$b_1 c_2 1$	$c_2 a_1 3$
$a_2 b_1 1$	$b_1 c_2 1$	$c_2 a_2 3$

$R \cdot S \cdot T$
$a_1 b_1 c_1 2 \cdot 2 \cdot 1 = 4$
$a_1 b_1 c_2 2 \cdot 1 \cdot 3 = 6$
$a_2 b_T c_2 3 - 1 - 3 = 9$
$a_2 b_1 c_2 1 \cdot 1 \cdot 3 = 3$

$\delta R(a_2, b_1)$	$A \cdot B$	$Q(\mathbf{D})$
$a_2 b_1 1$	$\begin{array}{ c c }\hline A & B \\ \hline a_2 & b_1 \\ \hline \end{array}$	\emptyset
-2	$\begin{array}{ c c }\hline A & B \\ \hline a_2 & b_1 \\ \hline -2 \\ \hline \end{array}$	$\begin{array}{ c c }\hline \emptyset \\ \hline () \\ \hline 4+6+9=19 \\ \hline () \\ \hline 4+6+3=13 \\ \hline \end{array}$

The Maintenance Problem



Given a current database \mathbf{D} and a single-tuple update, what are the time and space complexities for maintaining $Q(\mathbf{D})$?

Naïve Maintenance

"Compute from scratch!"

$$\sum_{a,b,c} [R(a,b) + \delta R(a',b')] \cdot S(b,c) \cdot T(c,a) = \sum_{a,b,c} \text{newR}(a,b) \cdot S(b,c) \cdot T(c,a)$$

Maintenance complexity:

- Time: $O(|\mathbf{D}|^{1.5})$ by worst-case optimal join algorithms
- Space: $O(|\mathbf{D}|)$ to store the relations

IVM $^\varepsilon$ Closes the Maintenance Complexity Gap

Complexity bounds for maintaining the triangle count

Known upper bound
Time $O(|\mathbf{D}|)$, Space $O(|\mathbf{D}|)$

Known lower bound

Amortized time not $O(|\mathbf{D}|^{0.5-\gamma})$ for any $\gamma > 0$
(under reasonable complexity theoretic assumptions)

Can the triangle count be maintained in sublinear time?

Yes! We propose IVM $^\varepsilon$!

It maintains the triangle count in $O(|\mathbf{D}|^{0.5})$ amortized time.
This is **worst-case optimal!**

Classical Incremental View Maintenance (IVM)

"Compute the difference!"

$$\begin{aligned} \sum_{a,b,c} [R(a,b) + \delta R(a',b')] \cdot S(b,c) \cdot T(c,a) &= \\ \sum_{a,b,c} R(a,b) \cdot S(b,c) \cdot T(c,a) &+ \\ \sum_c \delta R(a',b') \cdot S(b',c) \cdot T(c,a') \end{aligned}$$

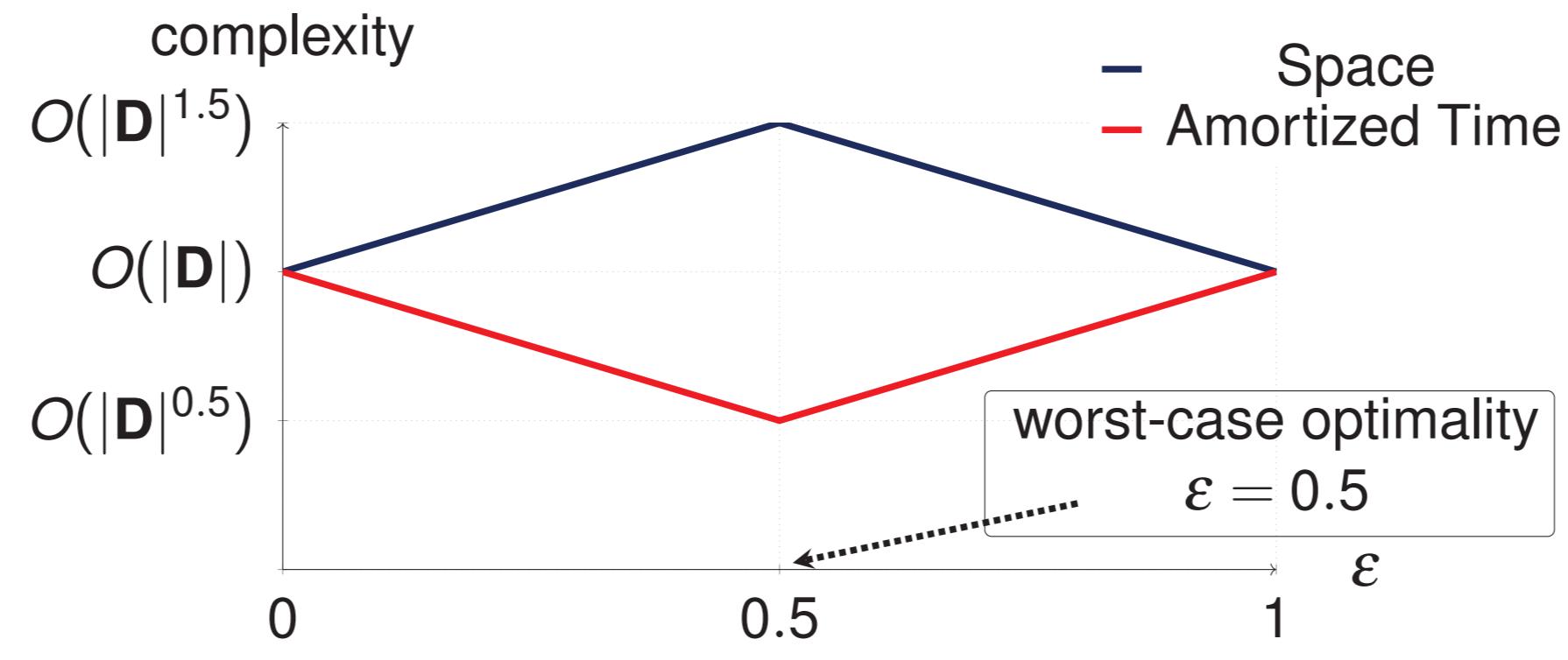
Maintenance complexity:

- Time: $O(|\mathbf{D}|)$ to intersect C -values from S and T
- Space: $O(|\mathbf{D}|)$ to store the relations

IVM $^\varepsilon$ Exhibits a Time-Space Tradeoff

Given $\varepsilon \in [0, 1]$, IVM $^\varepsilon$ maintains the triangle count with

- $O(|\mathbf{D}|^{\max\{\varepsilon, 1-\varepsilon\}})$ amortized time and
- $O(|\mathbf{D}|^{1+\min\{\varepsilon, 1-\varepsilon\}})$ space.



- IVM $^\varepsilon$ recovers known maintenance approaches.

Factorized Incremental View Maintenance (F-IVM)

"Compute the difference by using pre-materialized views!"

$$\begin{aligned} \text{Pre-materialize } V_{ST}(b,a) &= \sum_c S(b,c) \cdot T(c,a) \\ \sum_{a,b,c} [R(a,b) + \delta R(a',b')] \cdot S(b,c) \cdot T(c,a) &= \\ \sum_{a,b,c} R(a,b) \cdot S(b,c) \cdot T(c,a) &+ \\ \delta R(a',b') \cdot V_{ST}(b',a') \end{aligned}$$

Maintenance complexity:

- Time for updates to R : $O(1)$ to look up in V_{ST}
- Time for updates to S and T : $O(|\mathbf{D}|)$ to maintain V_{ST}
- Space: $O(|\mathbf{D}|^2)$ to store the relations and V_{ST}

Summary and Future Work

Main ideas in IVM $^\varepsilon$

- Compute the difference like in Classical IVM!
- Materialize views like in F-IVM!
- New: Use adaptive processing based on data skew!

Generalization of IVM $^\varepsilon$

- IVM $^\varepsilon$ variants achieve amortized sublinear maintenance time for counting versions of Loomis-Whitney, 4-cycle, and 4-path.

Ongoing Work

- Using IVM $^\varepsilon$ to characterize the class of conjunctive count queries admitting sublinear maintenance time!
- Implementing IVM $^\varepsilon$ on top of DB-Toaster

Quick Look inside IVM $^\varepsilon$

Heavy-Light Partitioning

IVM $^\varepsilon$ partitions R into a light part R_L and a heavy part R_H based on the degrees of A -values:

- $R_L = \{t \in R \mid |\sigma_{A=t} R| < |\mathbf{D}|^\varepsilon\}$
- $R_H = R \setminus R_L$

Derived bounds on the two parts of R :

- for all A -values a : $|\sigma_{A=a} R_L| < |\mathbf{D}|^\varepsilon$
- $|\pi_A R_H| \leq |\mathbf{D}|^{1-\varepsilon}$

Analogous partitioning of S and T :

- $S = S_L \cup S_H$ (based on degrees of B -values)
- $T = T_L \cup T_H$ (based on degrees of C -values)

Adaptive Maintenance Strategy

- IVM $^\varepsilon$ rewrites the triangle count into a sum $\sum_{U,V,W \in \{L,H\}} Q_{UVW}$ of skew-aware views $Q_{UVW} = \sum_{a,b,c} R_U(a,b) \cdot S_V(b,c) \cdot T_W(c,a)$.
- It uses adaptive strategies for the maintenance of these skew-aware views.

Pre-materialized views maintained by IVM $^\varepsilon$

Pre-materialized view	Space
Q_{UVW} with $U, V, W \in \{L, H\}$	$O(1)$
$V_{RS}(a,c) = \sum_b R_H(a,b) \cdot S_L(b,c)$	$O(\mathbf{D} ^{1+\min\{\varepsilon, 1-\varepsilon\}})$
$V_{ST}(b,a) = \sum_c S_H(b,c) \cdot T_L(c,a)$	$O(\mathbf{D} ^{1+\min\{\varepsilon, 1-\varepsilon\}})$
$V_{TR}(c,b) = \sum_a T_H(c,a) \cdot R_L(a,b)$	$O(\mathbf{D} ^{1+\min\{\varepsilon, 1-\varepsilon\}})$

Delta computation strategy from left to right

$\delta Q_{HH} = \delta R_*(a',b') \cdot \sum_c T_H(c,a') \cdot S_H(b',c)$	$O(\mathbf{D} ^{1-\varepsilon})$
$\delta Q_{HL} = \delta R_*(a',b') \cdot V_{ST}(b',a')$	$O(1)$
$\delta Q_{LH} = \delta R_*(a',b') \cdot \sum_c T_H(c,a') \cdot S_L(b',c)$ or $= \delta R_*(a',b') \cdot \sum_c S_L(b',c) \cdot T_H(c,a')$	$O(\mathbf{D} ^{\min\{\varepsilon, 1-\varepsilon\}})$
$\delta Q_{LL} = \delta R_*(a',b') \cdot \sum_c S_L(b',c) \cdot T_L(c,a')$	$O(\mathbf{D} ^\varepsilon)$
$\delta V_{RS}(a',c) = \delta R_H(a',b') \cdot S_L(b',c)$	$O(\mathbf{D} ^\varepsilon)$
$\delta V_{ST}(b,a) = \emptyset$	-
$\delta V_{TR}(c,b') = \delta R_L(a',b') \cdot T_H(c,a')$	$O(\mathbf{D} ^{1-\varepsilon})$

Reference