

# **A Prototype Embedding of Bluespec SystemVerilog in the SAL Model Checker**

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# Introduction

- Bluespec SystemVerilog (BSV) is a language for high level hardware design
- Developed from Term Rewriting Systems (TRS)
  - A language for designing and formally verifying hardware
- Elegant semantics  $\Rightarrow$  well suited for formal verification
- To date, a number of BSV designs have been verified with hand proof, but little work conducted on the application of automated reasoning.
- We have investigated automated reasoning for BSV, in the SAL model checker, and also the PVS theorem prover

# Why Use Automated Reasoning?

- Hand proofs are convenient, but:
  - Can contain errors (analogy - doing arithmetic by hand v.s. on a calculator)
  - Proofs for large systems can be time consuming and tedious
- Automated reasoning has the potential to provide rigorous and efficient verification for some classes of systems...
  - ... and these classes are ever expanding

# Automated Reasoning for BSV

- Two approaches:
  - Verifying BSV designs with a model checker:
    - Presented today
  - Verifying BSV designs with a theorem prover:
    - ***A Prototype Embedding of Bluespec SystemVerilog in the PVS Theorem Prover***, Second NASA Formal Methods Symposium, Washington D.C. April 13 – 15, 2010
- Currently compile by hand

# In This Presentation...

- Introduce BSV
- Introduce the SAL language
- Outline key challenges of embedding BSV in SAL
- Outline of our approach
- Experimental results: verifying a BSV implementation of Peterson's Protocol

# Take Home Information

- Basic understanding of BSV SAL languages
- How to embed BSV in SAL
  - Surprisingly simple
- Understanding of advantages of verifying the embedding
  - Makes proof more rigorous
- Motivation to look at the paper for a strategy for verifying the translation

# Bluespec SystemVerilog

- A Hardware Description Language based on the guarded action model of concurrency
- Hardware specified with modules, which associate elements of state with:
  - **Rules:** guarded actions that spontaneously change the state
  - **Methods:** functions that return values from the state and/or transform it
    - Methods from one module can be used to compose the rules and methods of other modules

# Rules in BSV

```
rule my_rule (rl_guard);
```

```
  statement_1;
```

```
  statement_2;
```

```
  ...
```

```
endrule
```



# The Semantics of a BSV Module

- Behaviour of a module can be understood with a simple semantics called Term Rewriting System (TRS) semantics
  - Also called one-rule-at-a-time semantics
- In a given state, a module chooses *one* rule for which the guard evaluates to `true' and applies the associated action
- If more than one guard is true, a non-deterministic choice is made

# Bluespec SystemVerilog

- Reg module:
  - A register with 1 element of state and 2 methods: `_read` and `_write`
- Other modules can create instances of Reg, and use `_read` and `_write` in their rules and methods. Eg:

```
rule request_rl (!request._read && !acknowledge._read));  
    request._write(True);  
endrule
```

# The SAL Language

- Also a guarded action language, but simpler
- Guarded action systems defined in contexts that define:
  - Type of state
  - An initial state
  - A transition relation

# The SAL Language

TRANSITION

```
[  
  guarded_action_1 : guard_1 --> action_1  
  []  
  guarded_action_2 : guard_2 --> action_2  
  []  
  ...  
]
```

# The Challenges of Embedding BSV in the SAL Language

- BSV is a guarded action language
- Similar to specification languages of several proof tools:
  - Model checkers: SAL, SPIN etc.
  - Model checkable subset of the PVS theorem prover
- However, BSV is a more complex language in some respects...

# The Challenges of Embedding BSV in a Automated Proof Tools

- Complex language constructs:
  - Modules and methods
- Widespread presence of data paths:
  - Can't always directly apply model checking to designs with data paths due to state space explosion
  - In SAL etc., we can build a specification that excludes data paths...
  - ... but with BSV, the design *is* the specification

# The Challenges of Embedding BSV in a Guarded Action Language

- Bridge the semantic gap
  - Express the constructs of BSV with the more limited constructs of the target language
- Bridge the abstraction gap
  - Abstract away from data path complexity to give abstract specifications that can be efficiently verified
- Our work concentrates on bridging the semantic gap

# Bridging the Semantic Gap

- Translate BSV to SAL specifications that can be efficiently model checked, but bear little resemblance to the original BSV
  - Problematic, because difficult to rule out false positives and false negatives
- Verify the BSV-to-SAL translation with deductive proof
  - Currently performed in the PVS theorem prover
  - Simple proof, could possibly be done with an SMT solver



# An Example Rule

```
rule p_critical (pcp._read == Critical && fifo.notFull);  
    fifo.enq (True);  
    pcp._write (Sleeping);  
    turn._write (False);  
endrule
```

# A Primitive Embedding in SAL

```
Reg {T : type} : CONTEXT = BEGIN
```

```
  State : type = [# data : T #];
```

```
END
```

```
FIFO1 {T : type} : CONTEXT = BEGIN
```

```
  State : type = [# notFull : bool, notEmpty : bool, data : T #];
```

```
END
```

# A Primitive Embedding in SAL

PC: TYPE = {Sleeping, Trying, Critical};

...

pcp : Reg{PC}!State,

pcq : Reg{PC}!State,

turn : Reg{bool}!State,

fifo : FIFO1{bool}!State

# Rules in BSV

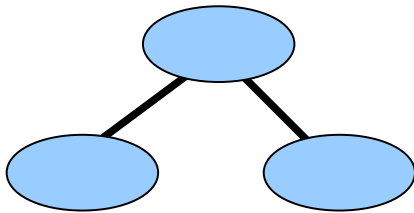
```
p_critical : pcp.data = Critical and fifo.notFull
--> fifo' = (# data := true,
            notFull := false,
            notEmpty := true #);
pcp' = (# data := Sleeping #);
turn' = (# data := false #)
```

# BSV-to-SAL Translation

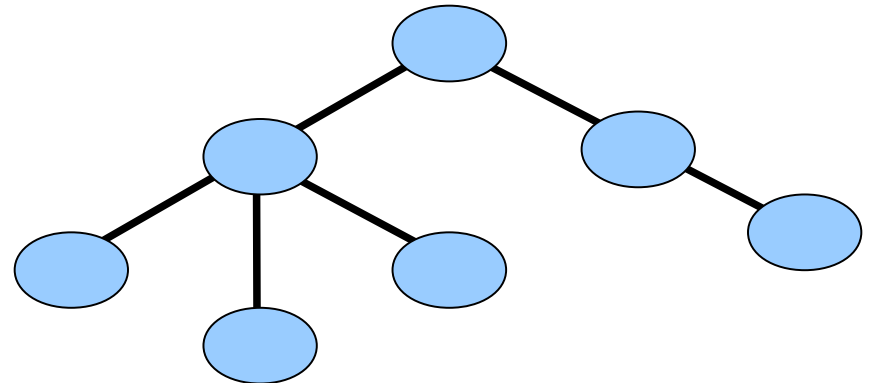
```
rule p_critical (pcp._read == Critical && fifo.notFull);
  fifo.enq (True);
  pcp._write (Sleeping);
  turn._write (False);
endrule
```

```
p_critical : pcp.data = Critical and fifo.notFull
--> fifo' = (# data := true,
             notFull := false,
             notEmpty := true #);
pcp' = (# data := Sleeping #);
turn' = (# data := false #)
```

AST



Expanded AST



# BSV-to-SAL Translation

BSV Code

Primitive SAL Embedding

AST

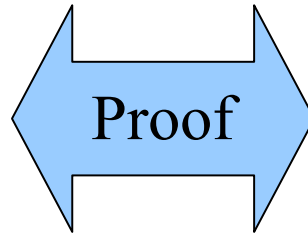
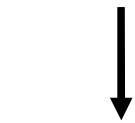
Expanded AST

Monadic PVS Embedding

Proof

Primitive PVS Embedding

Currently in PVS, but might be possible in SMT Solver



# A Module's State in PVS

```
Peterson : type = [# pcp : Reg [PC],  
                  pcq : Reg [PC],  
                  turn : Reg [bool],  
                  fifo : FIFO1 [bool]  
                  #]
```

# Primitive Embedding in PVS

```

p_critical_primitive (pre, post : Peterson) : bool
= pre'pcp'data = Critical  $\wedge$  pre'fifo'notFull
 $\wedge$  post = pre with [(fifo) := (# data := true,
                                notFull := false,
                                notEmpty := true #),
                    (pcp) := (# data := Sleeping #),
                    (turn) := (# data := false #)]

```



# A Monadic Embedding in PVS

```
p_critical = rule (pcp'read = Critical  $\wedge$  fifo'notFull)
                (fifo'enq (true)  $\gg$ 
                 pcp'write (Sleeping)  $\gg$ 
                 turn'write (false))
```

# Rules in BSV

```
rule p_critical (pcp._read == Critical && fifo.notFull);  
  fifo.enq (True);  
  pcp._write (Sleeping);  
  turn._write (False); endrule
```

```
p_critical = rule (pcp'read = Critical  $\wedge$  fifo'notFull)  
  (fifo'enq (true)  $\gg$   
  pcp'write (Sleeping)  $\gg$   
  turn'write (false))
```

# Experimental Results: Peterson's Protocol

- Verified a BSV implementation of 2 process Peterson's Protocol
- 50 lines of BSV code (extracts provided in paper)
- Hand embedded BSV code in SAL
- Verified the BSV translation in PVS
- All code will shortly be on sourceforge
  - Search on sourceforge for “Bluespec”

# Example: Peterson's Protocol

mutex: THEOREM

System  $\models G(\text{NOT}(\text{pcp.data} = \text{Critical AND pcq.data} = \text{Critical}))$

“The two processes will never be in critical mode at the same time”

liveness: THEOREM

System  $\models (G(\text{F}(\text{pcp.data} = \text{Trying})) \Rightarrow G(\text{F}(\text{pcp.data} = \text{Critical})))$   
and  $(G(\text{F}(\text{pcq.data} = \text{Trying})) \Rightarrow G(\text{F}(\text{pcq.data} = \text{Critical})))$

“A Trying process will always (eventually) gain access to the Critical mode”

# Conclusion

- BSV is a semantically elegant HDL
  - Well suited for formal reasoning
  - But little work carried out on application of automated reasoning
- We have carried out investigations into the application of model checking and theorem proving for verifying BSV designs
- Today, I presented a strategy for embedding a subset of BSV in SAL model checker, where BSV-to-SAL translation is verified in PVS