# Semantics of Higher-Order Probabilistic Programs with Continuous Distributions

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Based on work with or by Chris Heunen, Ohad Kammar, Sam Staton, and Frank Wood

#### Learning outcome

- Can explain what one can do with higherorder probabilistic programming language.
- Can use measure theory to interpret prob. prog. with continuous distributions.
- Can use quasi-Borel space to interpret higher-order prob. prog. with conditioning.

#### References

- A convenient category for higher-order probability theory. Heunen et a. LICS'17.
- 2. Commutative semantics for probabilistic programs. Staton. ESOP'17.

# What is probabilistic programming?

# (Bayesian) probabilistic modelling of data

- I. Develop a new probabilistic (generative) model.
- 2. Design an inference algorithm for the model.
- 3. Using the algo., fit the model to the data.

# (Bayesian) probabilistic modelling of data in a prob. prog. language

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# (Bayesian) probabilistic modelling of data in a prob. prog. language

as a program

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# (Bayesian) probabilistic modelling of data in a prob. prog. language

as a program

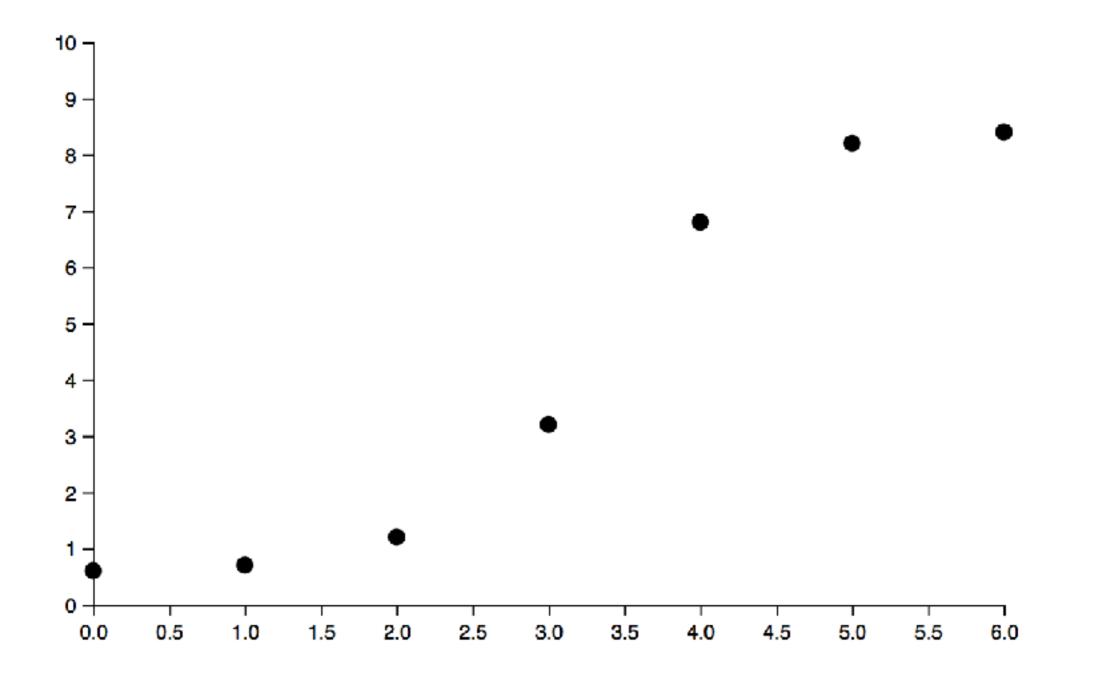
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2. Design an inference algorithm for the model.

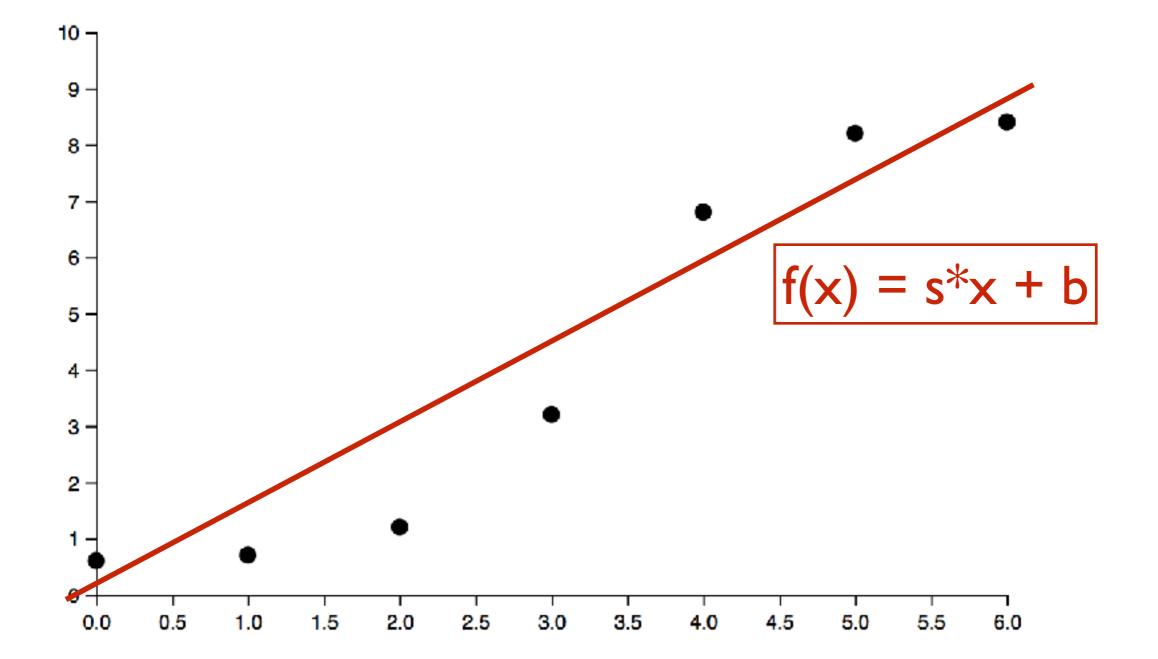
3. Using the algo, fit the model to the data.

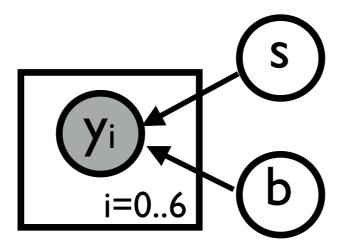
a generic inference algo. of the language

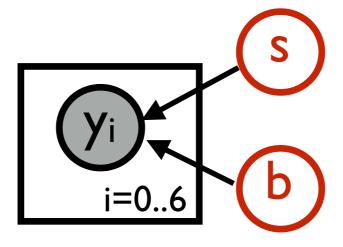
#### Line fitting



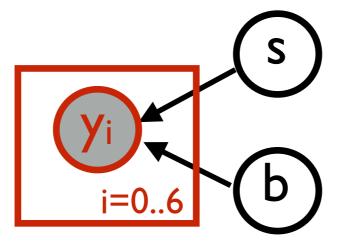


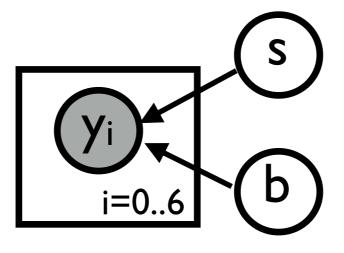






s b





Q: posterior of (s,b) given  $y_0=0.6$ , ...,  $y_6=8.4$ ?

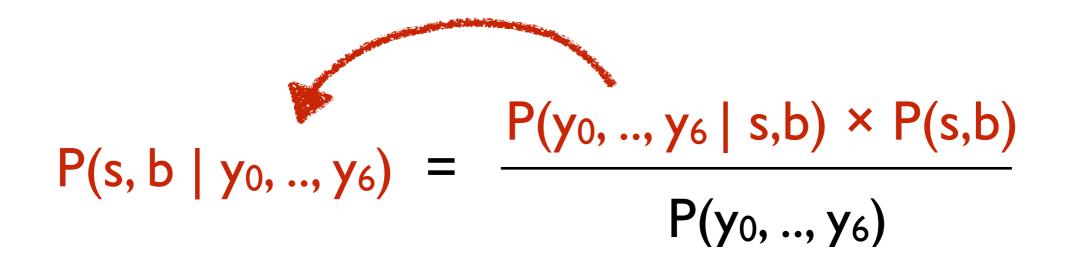
$$P(s, b | y_0, ..., y_6) = \frac{P(y_0, ..., y_6 | s, b) \times P(s, b)}{P(y_0, ..., y_6)}$$

$$\frac{P(s, b \mid y_0, ..., y_6)}{P(y_0, ..., y_6 \mid s, b)} \times \frac{P(s, b)}{P(y_0, ..., y_6)}$$

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## (almost) Anglican program

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> (observe (normal (f 0) .5) .6) (observe (normal (f 1) .5) .7) (observe (normal (f 2) .5) 1.2) (observe (normal (f 3) .5) 3.2) (observe (normal (f 4) .5) 6.8) (observe (normal (f 5) .5) 8.2) (observe (normal (f 6) .5) 8.4)

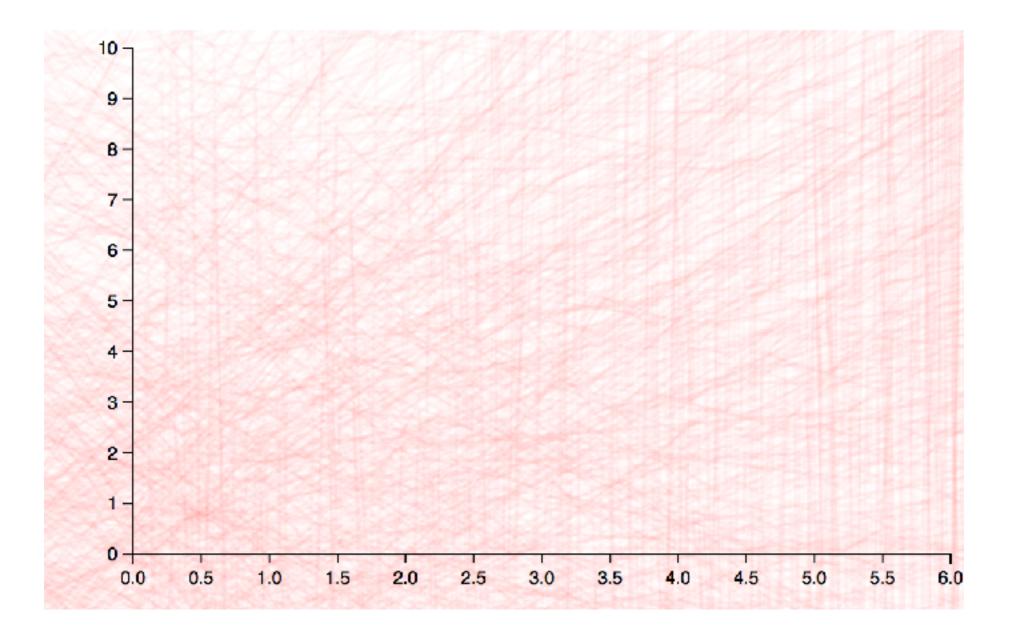
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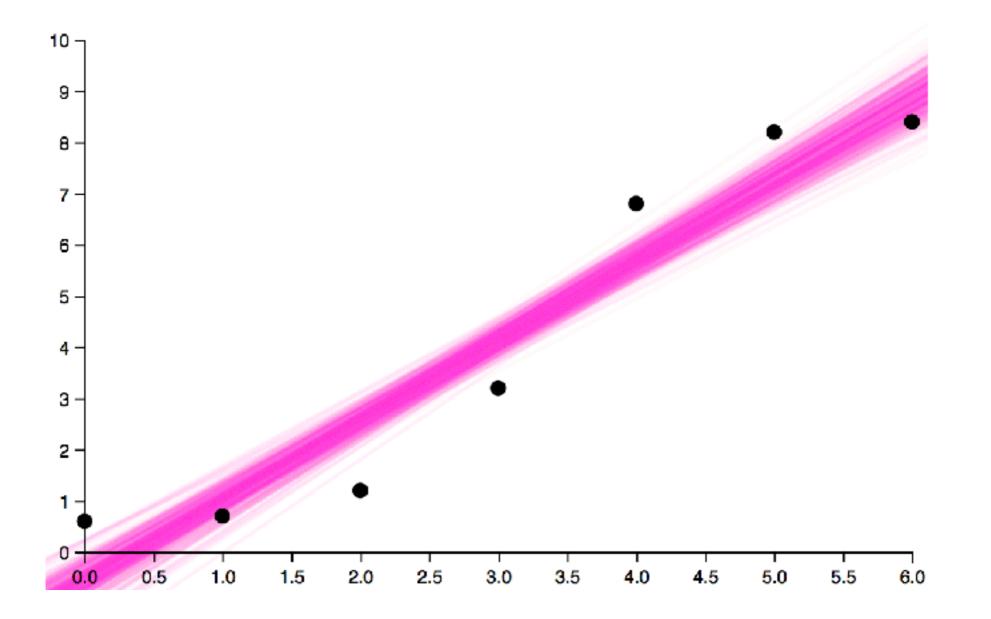
[s b])

NB: (predict :sb [s b]) should be used instead of [s b] in Anglican

#### Samples from prior



#### Samples from posterior



# Semantic challenges

> (observe (normal (f 0) .5) .6) (observe (normal (f 1) .5) .7) (observe (normal (f 2) .5) 1.2) (observe (normal (f 3) .5) 3.2) (observe (normal (f 4) .5) 6.8) (observe (normal (f 5) .5) 8.2) (observe (normal (f 6) .5) 8.4)

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[s b]) I. Continuous distributions.

# Challenge I: Continuous distributions

- Need care for handling continuous distributions on  $\mathbb{R}$ , to avoid paradoxes.
- Something like measure theory needed.
- Complex math.

> (observe (normal (f 0) .5) .6) (observe (normal (f 1) .5) .7) (observe (normal (f 2) .5) 1.2) (observe (normal (f 3) .5) 3.2) (observe (normal (f 4) .5) 6.8) (observe (normal (f 5) .5) 8.2) (observe (normal (f 6) .5) 8.4)

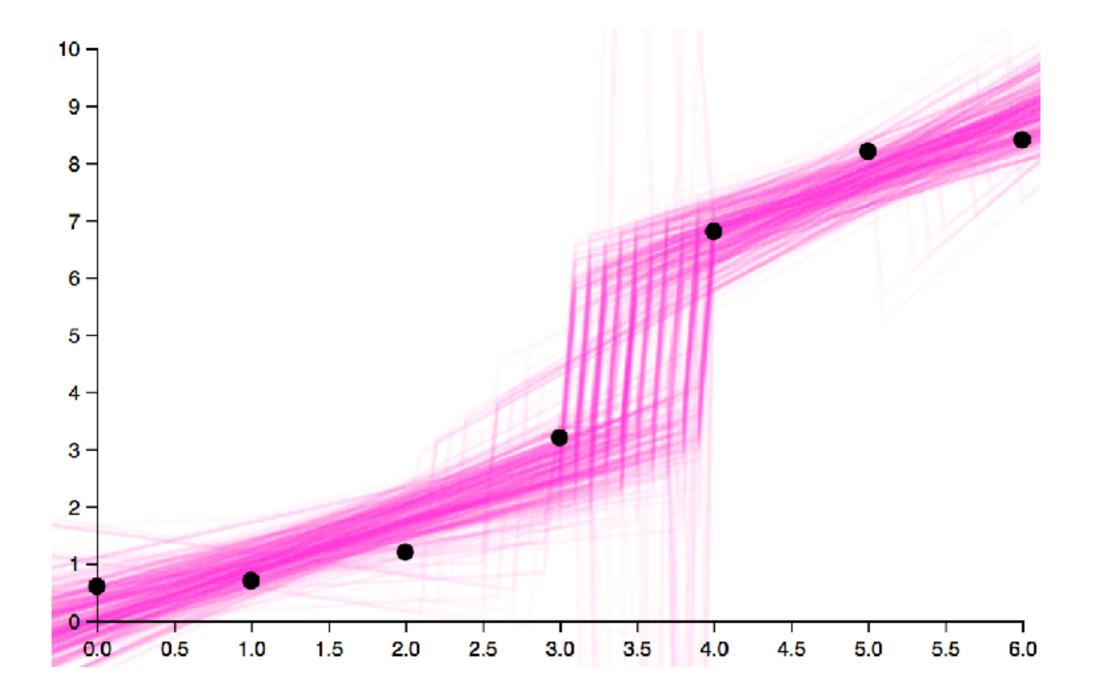
[s b]) I. Continuous distributions. 2. Higher-order functions. 
> (observe (normal (f 0) .5) .6) (observe (normal (f 1) .5) .7) (observe (normal (f 2) .5) 1.2) (observe (normal (f 3) .5) 3.2) (observe (normal (f 4) .5) 6.8) (observe (normal (f 5) .5) 8.2) (observe (normal (f 6) .5) 8.4)



```
(let [F (fn []
          (let [s (sample (normal 0 2))
                b (sample (normal 0 6))]
            (fn [x] (+ (* s x) b)))
      f (F)]
    (observe (normal (f 0) .5) .6)
    (observe (normal (f 1) .5) .7)
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```

#### (let [F (fn [] (let [s (sample (normal 0 2)) b (sample (normal 0 6))] (fn [x] (+ (\* s x) b))) f (add-change-points F 0 6)] (observe (normal (f 0) .5) .6)(observe (normal (f 1) .5) .7)(observe (normal (f 2) .5) 1.2)(observe (normal (f 3) .5) 3.2) (observe (normal (f 4) .5) 6.8) (observe (normal (f 5) .5) 8.2) (observe (normal (f 6) .5) 8.4)

#### Samples from posterior



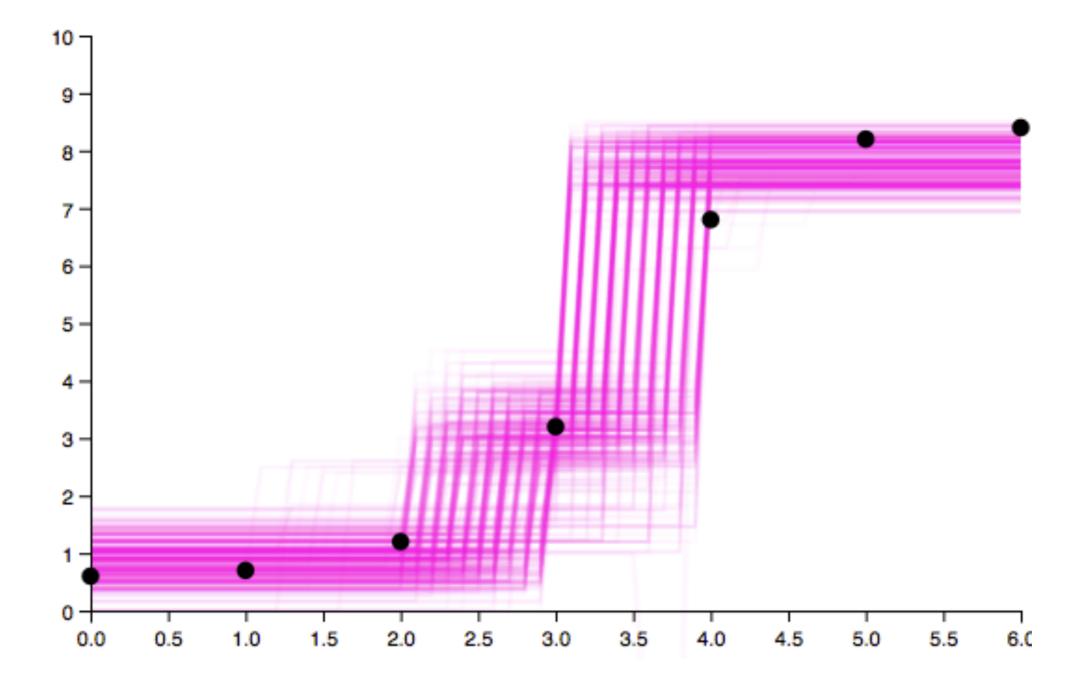
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**ESH]**)

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f)

#### Samples from posterior



### Challenge 2: Higher-order functions

Measure theory doesn't support HO fns well.

 $ev: (\mathbb{R} \rightarrow_m \mathbb{R}) \times \mathbb{R} \rightarrow \mathbb{R}, \quad ev(f,x) = f(x).$ 

[Aumann 61] ev is not measurable no matter which  $\sigma$ -algebra is used for  $\mathbb{R} \rightarrow_m \mathbb{R}$ .

[Cor] The category of measurable spaces is not cartesian closed.

#### (let [F (fn [] (let [s (sample (normal 0 2)) b (sample (normal 0 6))] (fn [x] (+ (\* s x) b))) f (add-change-points F 0 6)] (observe (normal (f 0) .5) .6)(observe (normal (f 1) .5) .7)(observe (normal (f 2) .5) 1.2)(observe (normal (f 3) .5) 3.2) (observe (normal (f 4) .5) 6.8) (observe (normal (f 5) .5) 8.2) (observe (normal (f 6) .5) 8.4)

Estado f) Continuous distributions.
 Higher-order functions.

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**ESHJ)** 

Continuous distributions.
 Higher-order functions.
 Conditioning and prog. eqs.

# Challenge 3: Conditioning and prog. eqs [[e:rea1]] ∈ M(ℝ)

- M should model prob. computations.
- M should validate equations from statistics.
- M should be commutative.
- Difficult to find such M due to conditioning.

# Challenge 3: Conditioning and prog. eqs $[e:rea] \in M(\mathbb{R})$ nonfinite measures

- M should model prob. computations.
- M should validate equations from statistics
- M should be commutative.
- Difficult to find such M due to conditioning.

#### Challenge 3: Conditioning and prog. eqs nearly-finite measures $[e:real] \in M(\mathbb{R})$ nonfinite measures

- M should model prob. computations.
- M should validate equations from statistics
- M should be commutative.
- Difficult to find such M due to conditioning.

#### (let [F (fn [] (let [s (sample (normal 0 2)) b (sample (normal 0 6))] (fn [x] (+ (\* s x) b))) f (add-change-points F 0 6)] (observe (normal (f 0) .5) .6)(observe (normal (f 1) .5) .7)(observe (normal (f 2) .5) 1.2) (observe (normal (f 3) .5) 3.2) (observe (normal (f 4) .5) 6.8) (observe (normal (f 5) .5) 8.2) (observe (normal (f 6) .5) 8.4)

Continuous distributions.
 Higher-order functions.
 Conditioning and prog. eqs.

#### (let [F (fn [] (let [s (sample (normal 0 2)) b (sample (normal 0 6))] (fn [x] (+ (\* s x) b))) f (add-change-points F 0 6)] (observe (normal (f 0) .5) .6)(observe (normal (f 1) .5) .7)(observe (normal (f 2) .5) 1.2) (observe (normal (f 3) .5) 3.2)(observe (normal (f 4) .5) 6.8)(observe (normal (f 5) .5) 8.2) (observe (normal (f 6) .5) 8.4)I. Continuous distributions. Quasi-Borel space 2. Higher-order functions. 3. Conditioning and prog. eqs.

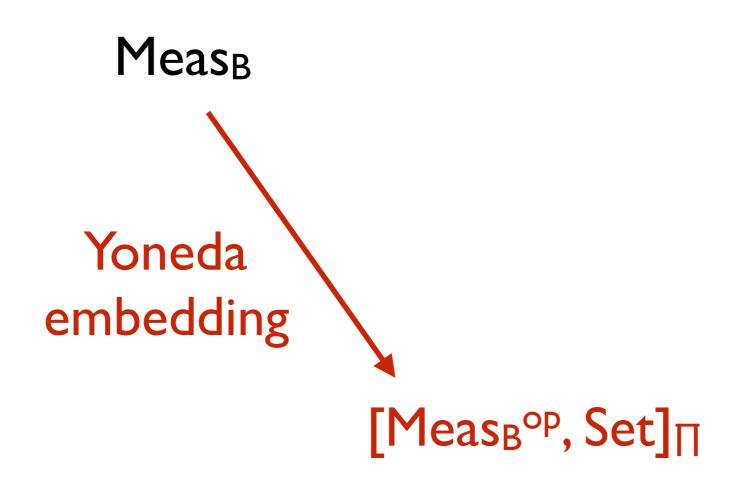
# Big picture 1: Extend measure theory using category theory.

Continuous distr.
 Higher-order fns.
 Conditioning, prog. eqs.

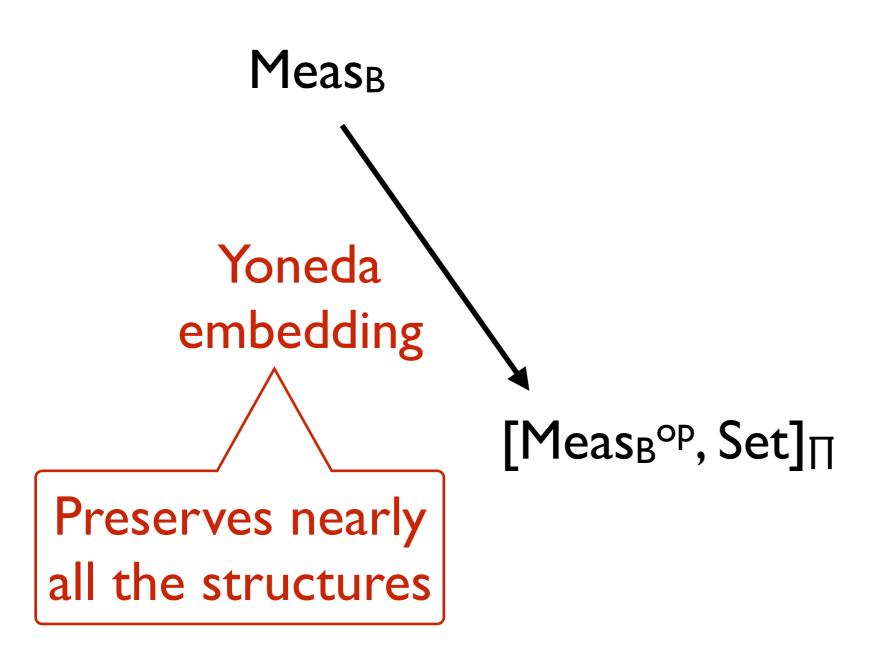
I. Continuous distr.
2. Higher-order fns.
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#### Meas<sub>B</sub>

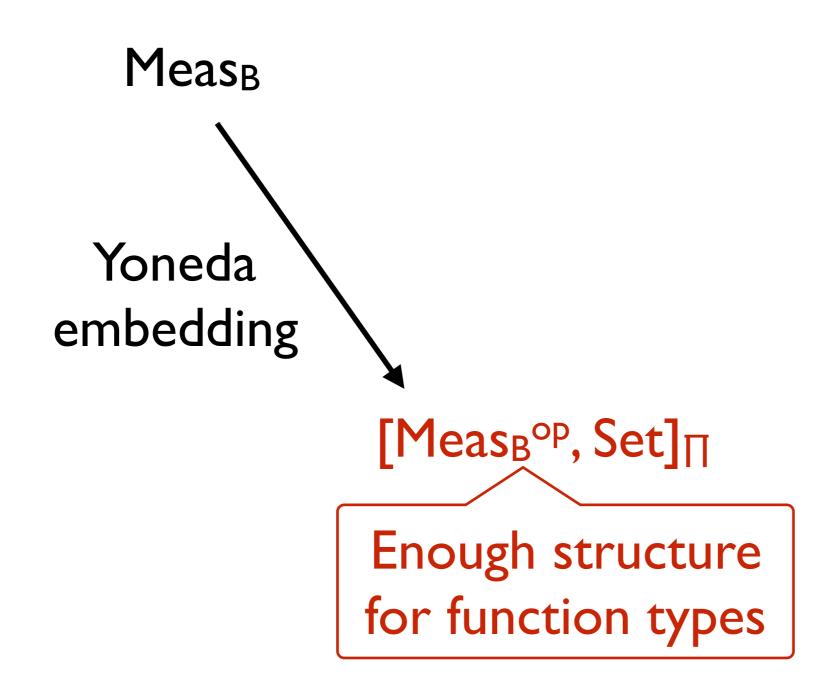




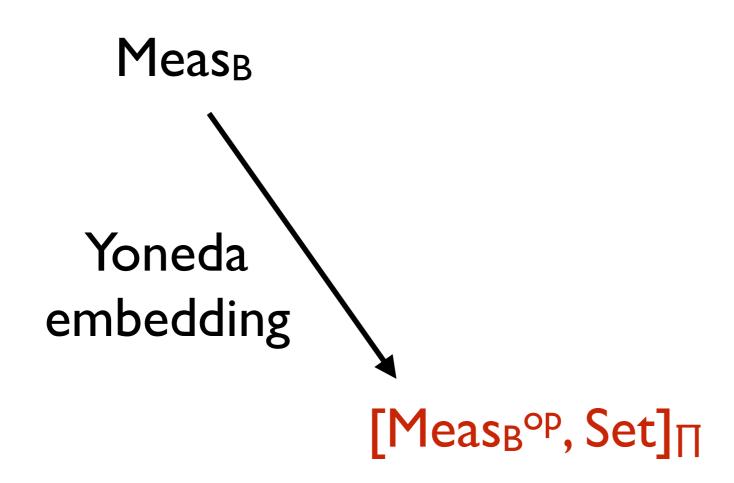




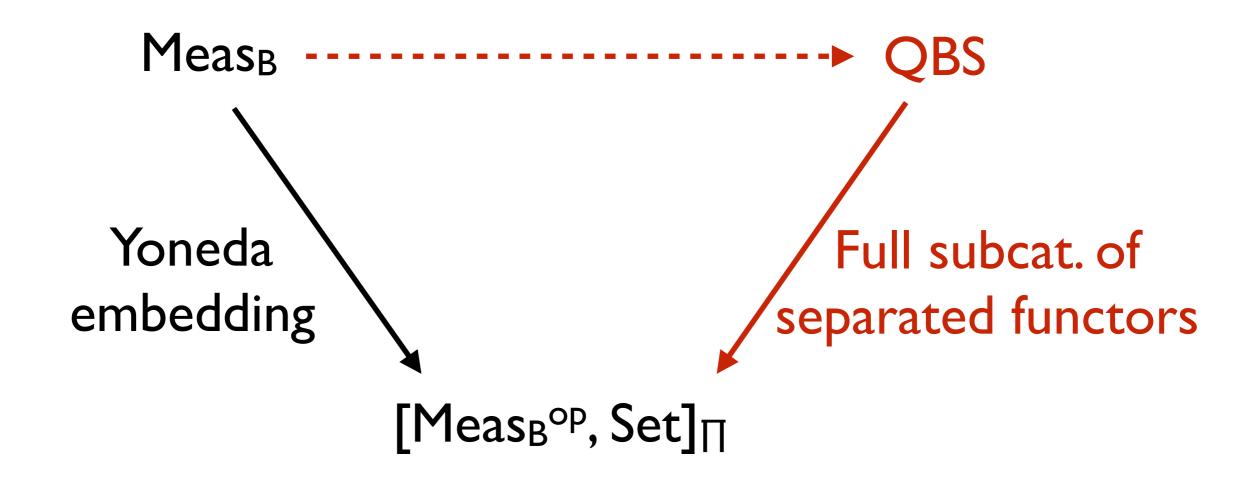


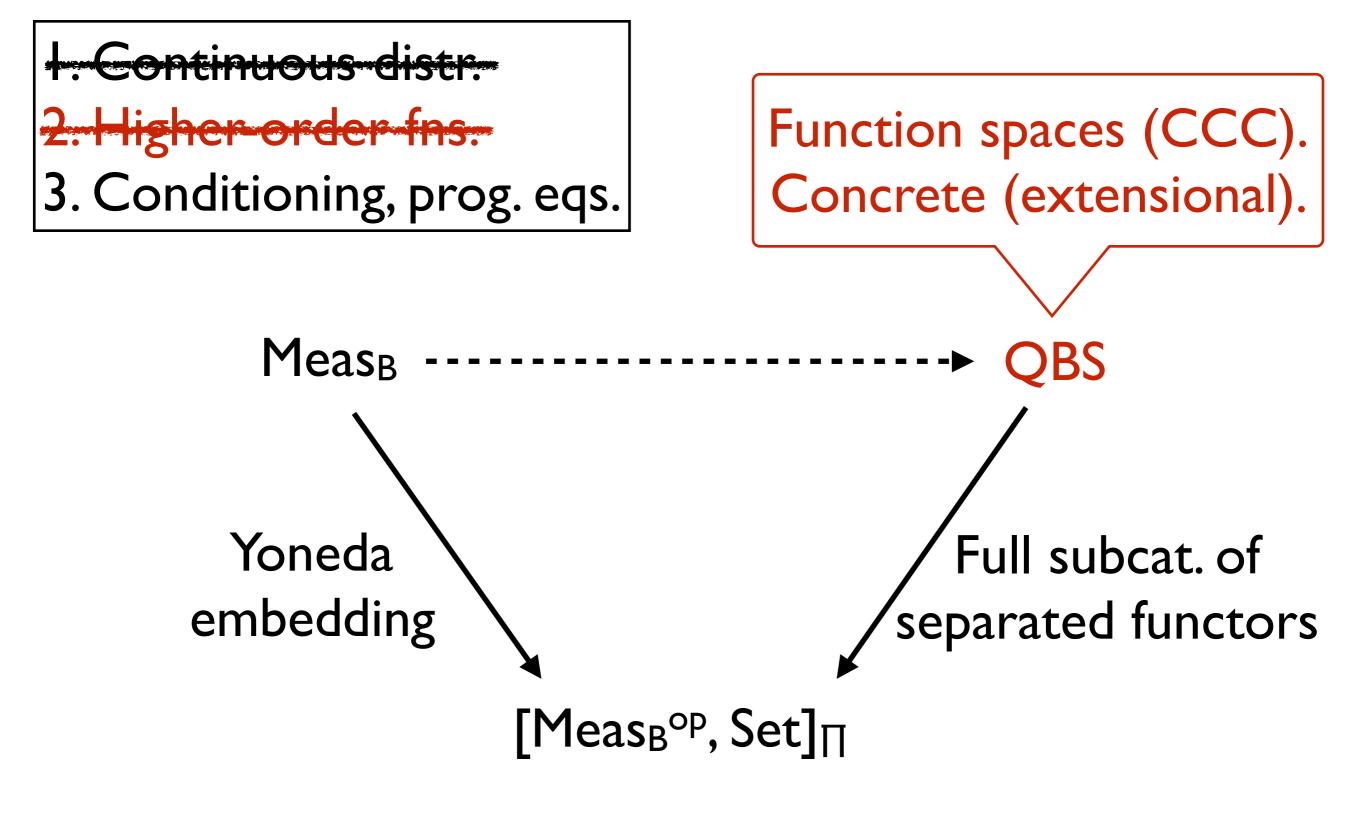


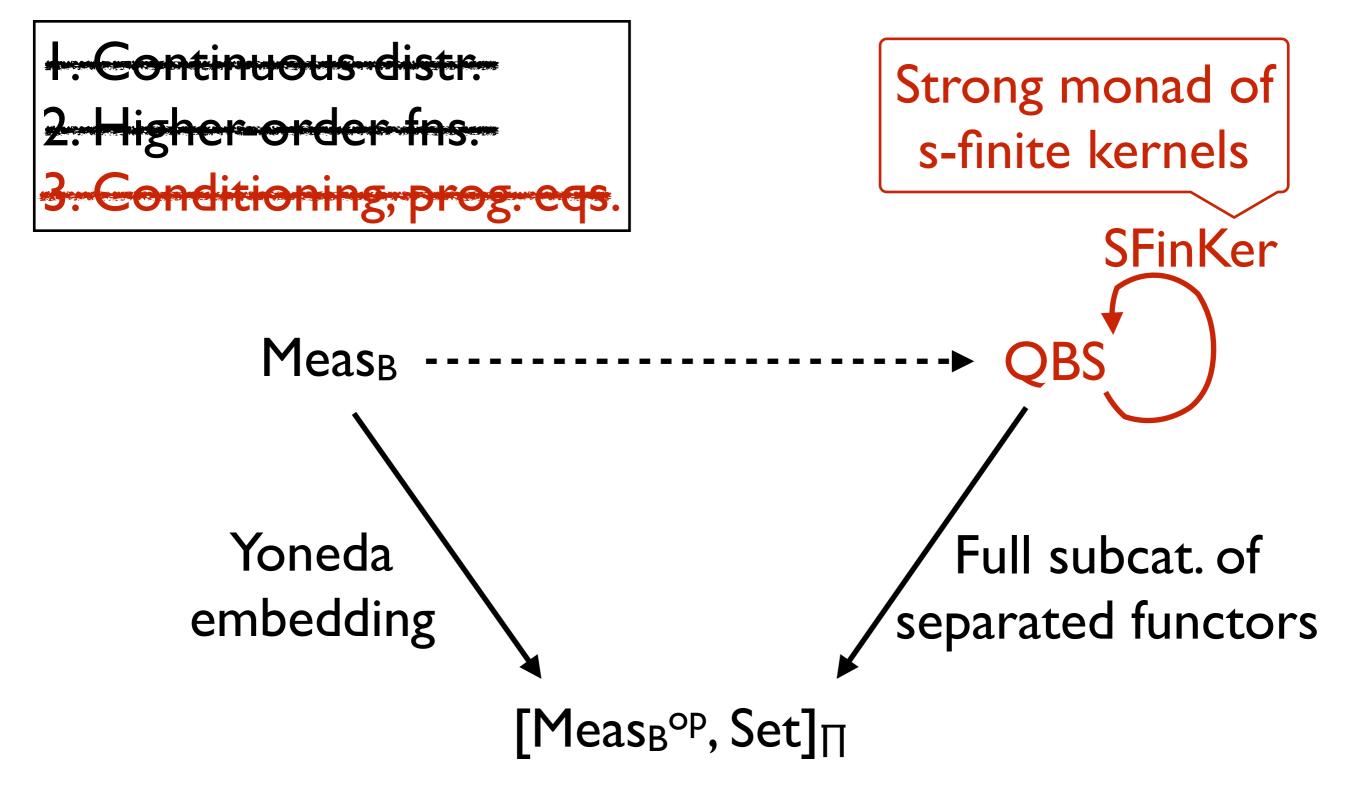


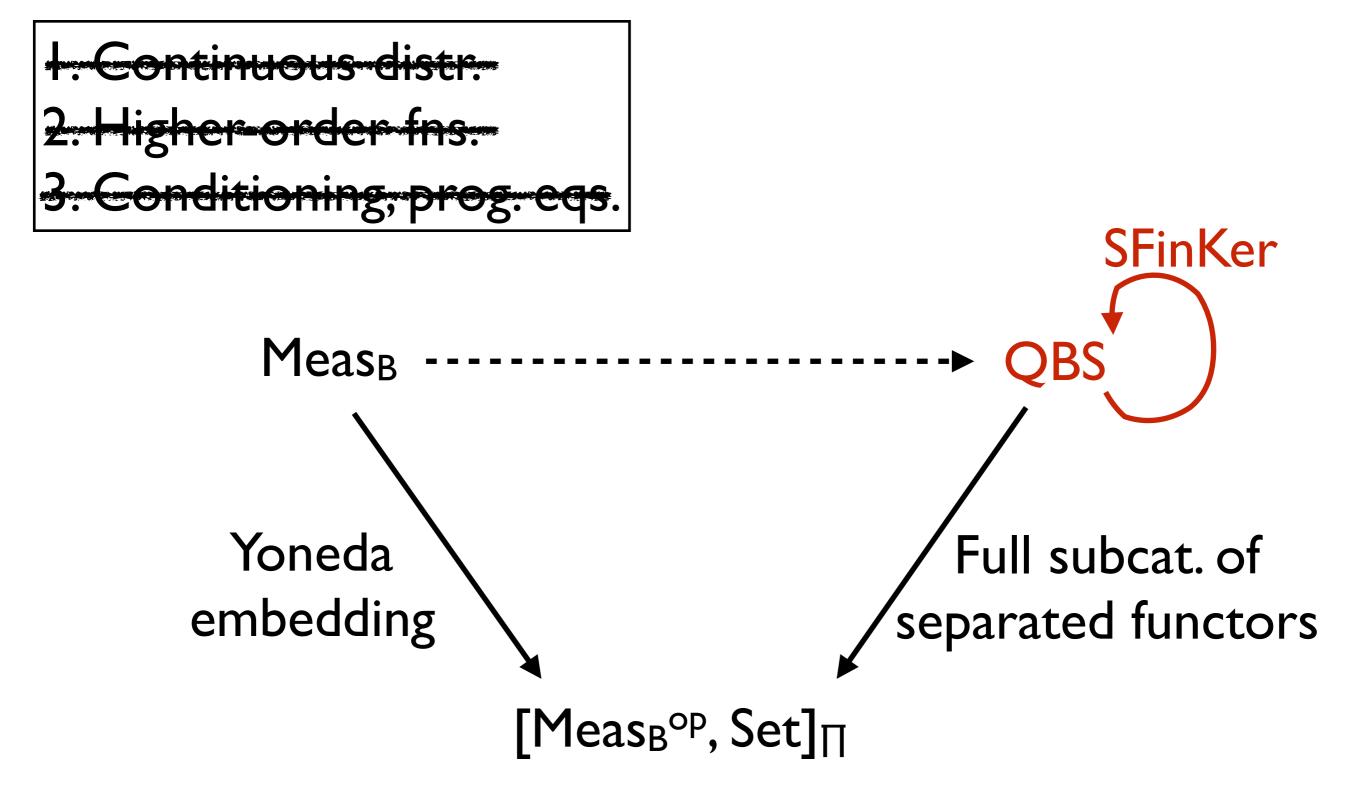












## Big picture 2: Random element first.

#### Random element $\alpha$ in X

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- X set of values.
- $\Omega$  set of random seeds.
- Random seed generator.

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 $\alpha:\Omega\to X$ 

- X set of values.
- $\Omega$  set of random seeds.
- Random seed generator.

I. Σ⊆2<sup>Ω</sup>, Θ⊆2<sup>X</sup> 2. μ : Σ→[0, I]

 $\alpha : \Omega \rightarrow X$  is a random element if  $\alpha^{-1}(A) \in \Sigma$  for all  $A \in \Theta$ 

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#### Random element $\alpha$ in X

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 $\alpha:\mathbb{R}\to X$ 

- X set of values.
- R set of random seeds.
- Random seed generator.

I.  $\mathbb{R}$  as random source 2. Borel subsets  $\mathfrak{B} \subseteq 2^{\mathbb{R}}$ 

 $\alpha: \mathbb{R} \to X$ 

- X set of values.
- $\mathbb{R}$  set of random seeds.
- Random seed generator.

 $I \,.\, \mathbb{R}$  as random source

2. Borel subsets  $\mathfrak{B} \subseteq 2^{\mathbb{R}}$ 

 $\alpha: \mathbb{R} \to X$ 

- X set of values.
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I.  $\mathbb{R}$  as random source 2. Borel subsets  $\mathfrak{B} \subseteq 2^{\mathbb{R}}$ 3.  $\mathbb{M} \subseteq [\mathbb{R} \rightarrow X]$ 

 $\alpha : \mathbb{R} \to X \text{ is a random variable}$ if  $\alpha \in M$ 

- X set of values.
- $\mathbb{R}$  set of random seeds.
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I.  $\mathbb{R}$  as random source 2. Borel subsets  $\mathfrak{B} \subseteq 2^{\mathbb{R}}$ 3.  $\mathbb{M} \subseteq [\mathbb{R} \rightarrow \mathbb{X}]$ 

- Measure theory:
  - Measurable space (X,  $\Theta \subseteq 2^X$ ).
  - Random element is an induced concept.
- QBS:
  - Quasi-Borel space (X,  $M \subseteq [\mathbb{R} \rightarrow X]$ ).
  - M is the set of random elements.

#### Rest of this tutorial

- I. Baby measure theory.PL with cont. distribution.
- Quasi-Borel space (QBS).
   PL with cont. distr. & HO fns.
- SFinKer monad on QBS.
   PL with cont. distr., HO fns & conditioning.

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#### Programming language

- Will be sloppy about its syntax.
- Higher-order call-by-value probabilistic PL.
  - t ::= bool | real |  $t \times t$  |  $t \rightarrow t$

e ::= ...

## Baby measure theory

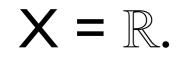
X = {0, 1, 2}. Define  $\mu$  : X → [0,1]. E.g.,  $\mu$  = [0.4, 0.4, 0.2]. Lifted  $\mu$  : 2<sup>X</sup> → [0,1] by  $\mu$ (A) =  $\sum_{x \in A} \mu$ (x).

 $X = \mathbb{R}$ .

#### Define $\mu : X \rightarrow [0, I]$ . Lifted $\mu : 2^{X} \rightarrow [0, I]$ by $\mu(A) = \sum_{x \in A} \mu(x)$ .

X = R. Define  $\mu$  : X→[0,1]. Lifted  $\mu$  : 2<sup>X</sup>→[0,1] by  $\mu(A) = \sum_{x \in A} \mu(x)$ . Uncountable sum. Typically ∞.

X = R. Define  $\mu : X \rightarrow [0,1]$ Lifted  $\mu : 2^{X} \rightarrow [0,1]$  by  $\mu(A) = \sum_{x \in A} \mu(x)$ . Define



Define IIX - [0,1]

/Lifted  $\mu: 2^{\times} \rightarrow [0, 1]$  by  $\mu(A) = \sum_{x \in A} \mu(x)$ . Define

Pick a good collection  $\sum \subseteq 2^{\times}$ . Define  $\mu : \sum \rightarrow [0, 1]$  with some care.

 $X = \mathbb{R}$ . Define  $\sigma$ -algebra Pick a good collection  $\sum \subseteq 2^{\times}$ . Define  $\mu : \Sigma \rightarrow [0, 1]$  with some care. probability measure

Let  $\Sigma \subseteq 2^{\times}$ .

 $\Sigma$  is a <u> $\sigma$ -algebra</u> if it contains X, and is closed under countable union and set subtraction.

 $(X, \Sigma)$  is a <u>measurable space</u> if  $\Sigma$  is a  $\sigma$ -algebra.

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 $\mu : \Sigma \rightarrow [0, I]$  is a <u>probability measure</u> if  $\mu(X) = I$ and  $\mu(\bigcup_{n \in \mathbb{N}} A_n) = \sum_{n \in \mathbb{N}} \mu(A_n)$  for all disjoint  $A_n$ 's.

 $(X, \Sigma, \mu)$  is a <u>probability space</u> if ...

# [Q] What are not measurable spaces?

- I.  $(\mathbb{B}, 2^{\mathbb{B}}).$
- 2. ( $\mathbb{B}x\mathbb{B}$ , {AxB |  $A \in 2^{\mathbb{B}}$  and  $B \in 2^{\mathbb{B}}$  }).
- 3. ( $\mathbb{R}$ , {A  $\subseteq \mathbb{R}$  | A or ( $\mathbb{R}$ -A) countable }).
- **4**. (ℝ, { (r,s] | r<s }).

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# [Q] Convert them to measurable spaces.

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#### [Q] Convert them to measurable spaces.

- 1.  $(\mathbb{B}, 2^{\mathbb{B}})$ . 2.  $(\mathbb{B} \times \mathbb{B}, \{A \times B \mid A \in 2^{\mathbb{B}} \text{ and } B \in 2^{\mathbb{B}}\})$ .
- 3. ( $\mathbb{R}$ , {A  $\subseteq \mathbb{R}$  | A or ( $\mathbb{R}$ -A) countable }).
- 4. (R, {(r,s] | r<s }).

Closure exists.  $(\Pi)$  smallest  $\sigma$ -algebra containing  $\Pi$ .

$$(X, \Sigma), (Y, \Theta)$$
 - mBle spaces.

Product  $\sigma$ -algebra:  $\Sigma \otimes \Theta = \sigma \{AxB \mid A \in \Sigma, B \in \Theta\}$ . Product space:  $(X, \Sigma)_{X_m}(Y, \Theta) = (XxY, \Sigma \otimes \Theta)$ .

Borel  $\sigma$ -algebra on  $\mathbb{R}$ :  $\mathfrak{B} = \sigma\{(r,s] \mid r < s\}$ . Borel space: ( $\mathbb{R}$ ,  $\mathfrak{B}$ ).

#### Types mean mBle spaces

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 $\llbracket bool \rrbracket = (\mathbb{B}, 2^{\mathbb{B}})$ 

 $\llbracket real \rrbracket = (\mathbb{R}, \mathfrak{B})$ 

#### Types mean mBle spaces

 $[boo1] = (\mathbb{B}, 2^{\mathbb{B}})$  $[rea1] = (\mathbb{R}, \mathfrak{B})$  $[t \times t'] = [t] \times_m [t']$  $[x_1:t_1, \dots, x_n:t_n] = [t_1] \times_m \dots \times_m [t_n]$ 

 $(X, \Sigma), (Y, \Theta)$  - mBle spaces.

f:X $\rightarrow$ Y is <u>measurable</u> (denoted f:X $\rightarrow$ <sub>m</sub>Y) if f<sup>-1</sup>(A) $\in$ \Sigma for all A $\in$  $\Theta$ .

 $(X, \Sigma), (Y, \Theta)$  - mBle spaces.

f:X $\rightarrow$ Y is <u>measurable</u> (denoted f:X $\rightarrow_m$ Y) if  $f^{-1}(A) \in \Sigma$  for all  $A \in \Theta$ .

k:Xx $\Theta$ →[0,1] is a prob. kernel if k(x,-) is a prob. measure and k(-,A) is measurable for all x,A.

 $\llbracket \Gamma \vdash e:t \rrbracket$  is a prob. kernel from  $\llbracket \Gamma \rrbracket$  to  $\llbracket t \rrbracket$ .

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 $[y:rea] \vdash y + sample(norm(0,1)):real]$ 

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- $[[y:rea] \vdash y + sample(norm(0,1)):real](r,A)$
- =  $\int_A \text{density-norm}(s | r, I) \, ds.$

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## Quasi-Borel space

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#### Quasi-Borel space - set with random elements. (X, M $\subseteq$ [ $\mathbb{R} \rightarrow$ X])

## Quasi-Borel space - set with random elements. $(X, M \subseteq [\mathbb{R} \rightarrow X])$

such that M has enough random elements.

I. M contains all constant functions.

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- 2.  $(\alpha \circ \beta) \in M$  for all  $\alpha \in M$  and mBle  $\beta: \mathbb{R} \rightarrow \mathbb{R}$ .

## Quasi-Borel space - set with random elements. $(X, M \subseteq [\mathbb{R} \rightarrow X])$

such that M has enough random elements.

- I. M contains all constant functions.
- 2.  $(\alpha \circ \beta) \in M$  for all  $\alpha \in M$  and mBle  $\beta: \mathbb{R} \rightarrow \mathbb{R}$ .
- 3. If  $\mathbb{R}= \bigcup_{i \in \mathbb{N}} R_i$  with  $R_i \in \mathfrak{B}$  and  $\alpha_1, \alpha_2, \ldots \in M$ , then  $(\alpha_i \text{ when } R_i)_{i \in \mathbb{N}} \in M$ .

Here  $(\alpha_i \text{ when } R_i)_{i \in \mathbb{N}}(r) = \alpha_i(r)$  for all  $r \in R_i$ .

## [Q] Pick a non-QBS.

- 1. ( $\mathbb{R}$ , { $\alpha:\mathbb{R}\to\mathbb{R} \mid \alpha$  is a constant function}).
- **2.** (ℝ, [ℝ→ℝ]).
- 3. ( $\mathbb{R}$ , { $\alpha:\mathbb{R}\to\mathbb{R} \mid \alpha \text{ measurable wrt. } \mathfrak{B}$ }).

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 $\{ (\alpha_i \text{ when } R_i)_{i \in \mathbb{N}} \mid \alpha_i \text{ constant fn and } R_i \in \mathfrak{B} \}$   $I. (\mathbb{R}, \{ \alpha: \mathbb{R} \to \mathbb{R} \mid \alpha \text{ is a constant function} \} ).$ 

- 2. ( $\mathbb{R}$ , [ $\mathbb{R} \rightarrow \mathbb{R}$ ]).
- 3. ( $\mathbb{R}$ , { $\alpha:\mathbb{R}\to\mathbb{R} \mid \alpha \text{ measurable wrt. } \mathfrak{B}$ }).

### [Q] Turn it to a QBS.

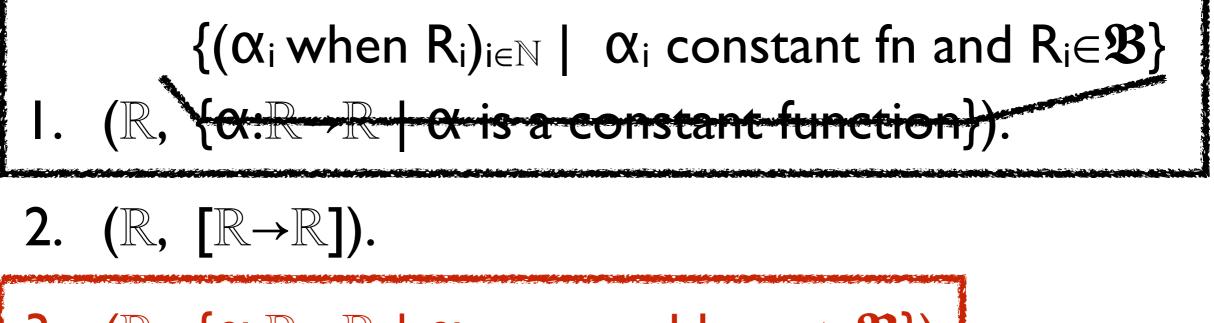
Standard way of converting a set to a QBS.

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- 2. ( $\mathbb{R}$ , [ $\mathbb{R} \rightarrow \mathbb{R}$ ]).
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### [Q] Turn it to a QBS.

Standard way of converting a set to a QBS.



3. ( $\mathbb{R}$ , { $\alpha:\mathbb{R}\to\mathbb{R} \mid \alpha$  measurable wrt. **B**}).

Standard way of converting a mBle space to a QBS.

### (QBS) morphism

(X,M), (Y,N) - QBSes.

f : X→Y is a morphism if (foα)∈N for all α∈M. Maps random elements to random elements.

We will write  $f: X \rightarrow_q Y$ .

[Th] QBSes form a cartesian closed category. So, they provide good product and function spaces.

#### [Q] What are the sets of random elements? I. Product: $(X,M) \times_q (Y,N) = (Z,O)$ .

• 
$$Z = X \times Y$$
,  $\pi_1(x,y) = x$ ,  $\pi_2(x,y) = y$ .

• O = ???

2. Fn space:  $[(X,M) \rightarrow_q(Y,N)] = (Z,O)$ 

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$$Z = \{ f | f : X \rightarrow_q Y \}, ev(f,x) = f(x)$$

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#### [Q] What are the sets of random elements?

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  - $Z = X \times Y$ ,  $\pi_1(x,y) = x$ ,  $\pi_2(x,y) = y$ .
  - **O** = { < $\alpha,\beta$ > |  $\alpha \in M$  and  $\beta \in N$  }.
- 2. Fn space:  $[(X,M) \rightarrow_q(Y,N)] = (Z,O)$ 
  - $Z = \{ f | f : X \rightarrow_q Y \}, ev(f,x) = f(x)$
  - $O = \{ curry(g) \mid g : \mathbb{R} \times_q X \rightarrow_q Y \}.$

#### Why works?

#### [NO] ev : ( $\mathbb{R} \rightarrow_m \mathbb{R}$ ) $\mathbf{x}_m \mathbb{R} \rightarrow_m \mathbb{R}$

#### VS

 $[YES] ev : (\mathbb{R} \rightarrow_q \mathbb{R}) \times_q \mathbb{R} \rightarrow_q \mathbb{R}$ 

#### Why works?

#### $[NO] ev : (\mathbb{R} \rightarrow_m \mathbb{R}) \times_m \mathbb{R} \rightarrow_m \mathbb{R}$

VS

$$[YES] ev : (\mathbb{R} \rightarrow_q \mathbb{R}) \times_q \mathbb{R} \rightarrow_q \mathbb{R}$$

Because the QBS product is more permissive.

#### Types mean QBSes

 $\llbracket bool \rrbracket = MStoQBS(\mathbb{B}, 2^{\mathbb{B}})$ 

 $\llbracket real \rrbracket = MStoQBS(\mathbb{R}, \mathfrak{B})$ 

#### Types mean QBSes

[[boo1]] = MStoQBS(B, 2<sup>B</sup>)
[[rea1]] = MStoQBS(R, B)
[[t x t']] = [[t]] ×q [[t']]

 $\llbracket x_{l}:t_{l}, \ldots, x_{n}:t_{n} \rrbracket = \llbracket t_{l} \rrbracket x_{q} \ldots x_{q} \llbracket t_{n} \rrbracket$ 

#### Types mean QBSes

 $\begin{bmatrix}bool\end{bmatrix} = MStoQBS(\mathbb{B}, 2^{\mathbb{B}})$  $\begin{bmatrix}real\end{bmatrix} = MStoQBS(\mathbb{R}, \mathfrak{B})$  $\begin{bmatrix}t \times t'\end{bmatrix} = [t] \times_q [t']$  $\begin{bmatrix}t \to t'\end{bmatrix} = [t] \rightarrow_q Monad([t'])]$  $[x_1:t_1, \dots, x_n:t_n] = [t_1] \times_q \dots \times_q [t_n]$ 

#### Terms mean morphisms almost

 $\llbracket \Gamma \vdash e:t \rrbracket$  is a morphism  $\llbracket \Gamma \rrbracket \rightarrow_q Monad \llbracket t \rrbracket$ .

## Probability measure on Quasi-Borel space

E.g.

$$(X,M) = MStoQBS(\mathbb{B}, 2^{\mathbb{B}})$$
  
 $\mu = uniform(0,I], \quad \alpha(r) = if (r < 0.5) true false$ 

E.g.

$$(X,M) = MStoQBS(\mathbb{B}, 2^{\mathbb{B}})$$
  

$$\mu = uniform(0,1], \quad \alpha(r) = if (r < 0.5) true false$$
  

$$\mu' = uniform(0,2]/2, \quad \alpha'(r) = if (r < 1) true false$$

<u>Quotient</u> prob. measures by the smallest  $\sim$  s.t.

$$(\alpha,\mu) \sim (\beta,\nu)$$

if  $\alpha$  of =  $\beta$  and  $\nu$  of f<sup>-1</sup> =  $\mu$  for some f: $\mathbb{R} \rightarrow_m \mathbb{R}$ .

 $[\alpha, \mu]$  - equivalence class.

#### QBS of prob. measures

Prob(X,M) = (Y,N)

 $Y = \{ [\alpha, \mu] | (\alpha, \mu) \text{ is a prob. meas. on } (X, M) \}.$ 

N = {  $\lambda r.[\alpha, k(r)] \mid \alpha \in M \text{ and } k : \mathbb{R} \times \mathfrak{B} \rightarrow [0, 1] \text{ is a prob. kernel }.$ 

[Lem] Prob is a strong monad.

### Completing the definitions

 $\llbracket t \rightarrow t' \rrbracket = \llbracket t \rrbracket \rightarrow_q \operatorname{Prob}(\llbracket t' \rrbracket) \rrbracket$  $\llbracket \Gamma \vdash e:t \rrbracket \text{ is a morphism } \llbracket \Gamma \rrbracket \rightarrow_q \operatorname{Prob}[\llbracket t \rrbracket]$ 

#### Rest of this tutorial

- I. Baby measure theory.PL with cont. distribution.
- Quasi-Borel space (QBS).
   PL with cont. distr. & HO fns.
- SFinKer monad on QBS.
   PL with cont. distr., HO fns & conditioning.

### Conditioning and SFinKer monad on QBS

#### **[Γ** ⊦ e : t]] is a morphism **[Γ**] →<sub>q</sub> Monad[[t]]

#### **[Γ** ⊦ e : t]] is a morphism **[Γ**]]→<sub>q</sub> Monad[[t]]

Bayes's rule:

#### $p(o | h) \times p(h) = p(h | o) \times p(o)$

# [[Γ ⊦ e : t]] is a morphism [[Γ]]→<sub>q</sub> Monad[[t]] Bayes's rule:

$$p(o | h) \times p(h) = p(h | o) \times p(o)$$

I. Monad() = Prob().

#### $\llbracket \Gamma \vdash e : t \rrbracket$ is a morphism $\llbracket \Gamma \rrbracket \rightarrow_q Monad \llbracket t \rrbracket$ Bayes's rule:

$$p(o \mid h) \times p(h) = p(h \mid o) \times p(o)$$

I. Monad(\_) = Prob(\_). Sometimes undefined.

 $\llbracket \Gamma \vdash e:t \rrbracket$  is a morphism  $\llbracket \Gamma \rrbracket \rightarrow_q Monad \llbracket t \rrbracket$ Bayes's rule:

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I. Monad(\_) = Prob(\_). Sometimes undefined.

2. Monad(\_) = Prob([0, $\infty$ ) x<sub>q</sub>\_).

 $\llbracket \Gamma \vdash e:t \rrbracket$  is a morphism  $\llbracket \Gamma \rrbracket \rightarrow_q Monad \llbracket t \rrbracket$ Bayes's rule:

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I. Monad(\_) = Prob(\_). Sometimes undefined.

2. Monad(\_) = Prob([0, $\infty$ ) x<sub>q</sub>\_). Failed eqs.

### Failed conjugate-prior equation from statistics

let x=sample(beta(1,1)) in
observe(flip(x),true);

observe(flip(0.5),true);
sample(beta(2,1))

 $\llbracket \Gamma \vdash e:t \rrbracket$  is a morphism  $\llbracket \Gamma \rrbracket \rightarrow_q Monad \llbracket t \rrbracket$ Bayes's rule:

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- 3. Monad(\_) = Meas(\_).

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- 3. Monad(\_) = Meas(\_). No commutativity.

### Failed commutativity

$$\llbracket \begin{bmatrix} let & x=e & in \\ let & y=e' & in \\ e'' & & \end{bmatrix} \not= \llbracket \begin{bmatrix} let & y=e' & in \\ let & x=e & in \\ e'' & & & e'' \end{bmatrix}$$

if x doesn't occur in e' and y doesn't occur in e

 $\llbracket \Gamma \vdash e : t \rrbracket$  is a morphism  $\llbracket \Gamma \rrbracket \rightarrow_q Monad \llbracket t \rrbracket$ Bayes's rule:

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- 4. Monad(\_) = SFinKer(\_).

# QBS of prob. measures

Prob(X,M) = (Y,N)

 $Y = \{ [\alpha, \mu] \mid \alpha \in M, \mu \text{ prob. meas. on } (\mathbb{R}, \mathfrak{B}) \}.$  $N = \{ \lambda r. [\alpha, k(r)] \mid \alpha \in M, k : \mathbb{R} \times \mathfrak{B} \rightarrow [0, 1] \text{ prob. kernel } \}.$ 

## QBS of prob. measures s-finite kernels

# $\frac{\text{SFinKer}(X,M)}{\text{Prob}(X,M)} = (Y,N)$

 $Y = \{ [\alpha, \mu] \mid \alpha \in M, \mu \text{ prob. meas. on } (\mathbb{R}, \mathfrak{B}) \}.$  $N = \{ \lambda r. [\alpha, k(r)] \mid \alpha \in M, k : \mathbb{R} \times \mathfrak{B} \rightarrow [0, 1] \text{ prob. kernel } \}.$ 

# QBS of prob. measures s-finite kernels

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 $\mu$  <u>finite</u> if like prob. measure but just  $\mu(\mathbb{R}) < \infty$ .  $\mu$  <u>s-finite</u> if countable sum of finite measures. k finite if like prob. kernel but  $\sup_r k(r,\mathbb{R}) < \infty$ . k s-finite if countable sum of finite kernels.

SFinKer(X,M)  
$$Prob(X,M) = (Y,N)$$

 $Y = \{ [\alpha, \mu] \mid \alpha \in M, \quad \mu \text{ prob. meas. on } (\mathbb{R}, \mathfrak{B}) \}.$ s-finite measure  $N = \{ \lambda r. [\alpha, k(r)] \mid$ 

$$\alpha \in M$$
,  $k : \mathbb{R} \times \mathfrak{B} \to [0,1]$  prob. kernel },  
k :  $\mathbb{R} \times \mathfrak{B} \to [0,\infty]$  s-finite kernel

 $\mu$  <u>finite</u> if like prob. measure but just  $\mu(\mathbb{R}) < \infty$ .  $\mu$  <u>s-finite</u> if countable sum of finite measures. [Th] SFinKer can be used to define the semantics of prob. PL with conditioning. (i.e., strong monad.)

[Th] It validates commutativity of programs and prog. eqs from statistics.

 $\llbracket boo1 \rrbracket = MStoQBS(\mathbb{B}, 2^{\mathbb{B}})$  $\llbracket real \rrbracket = MStoQBS(\mathbb{R}, \mathfrak{B})$  $[[t \times t']] = [[t]] \times_q [[t']]$  $[t \rightarrow t'] = [[t]] \rightarrow_q SFinKer([t'])]$  $[x_1:t_1, ..., x_n:t_n] = [t_1] x_q ... x_q [t_n]$  $\llbracket \Gamma \vdash e:t \rrbracket$  is a morphism  $\llbracket \Gamma \rrbracket \rightarrow_q SFinKer \llbracket t \rrbracket$ 

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### References

- A convenient category for higher-order probability theory. Heunen et a. LICS'17.
- 2. Commutative semantics for probabilistic programs. Staton. ESOP'17.

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