Verifying Finitely-Presentable Infinite Structures:

A Game-Semantic Approach

(Lecture 2)

Luke Ong

University of Oxford

29 May - 2 June 2006

Review

- Background
- Two questions about safety
- Safety is not necessary for MSO decidability
- Key Steps of the Decidability Proof
- Outline
- Alternating Parity Tree Automata (APT) and the Modal Mu-Calculus
- Decidability Argument 1: Transference Principle
- Decidability Argument 2: Simulating Traversals
- Complexity Analysis

Characterising recursion schemes by collapsible PDA (with A. Murawski)

Parity games over collapsible *n*-pushdown graphs

Review

Background

Theorem (Knapik, Niwiński + Urzyczyn FOSSACS02). The MSO model checking problem for trees generated by order-n safe recursion schemes is decidable, for each $n \ge 0$.

Recall: Homogeneous types

- *o* is homogeneous
- $(A_1 \to \cdots \to A_n \to o)$ is homogeneous just if $order(A_1) \ge order(A_2) \ge \cdots \ge order(A_n)$, and each A_i is homogeneous.

Safety (which presupposes that all types are homogeneous) is a rather awkward syntactic constraint; but

- It has a clear algorithmic virtue: Safe lambda calculus is an " α -conversion free lambda calculus".
- It has an elegant automata-theoretic characterization: Order-n safe recursion schemes = order-n pushdown automata.

Is safety a genuine or spurious constraint for:

Expressiveness. Are there *inherently* unsafe Σ-labelled trees?
 I.e. Is there an unsafe recursion scheme whose value tree is not the value tree of any safe recursion scheme? If so, at what order?
 Conjecture. Yes, at order 2. But note:

Theorem. (A+deM+O FOSSACS 2005) There is no inherently unsafe word language at order 2.

2. **Decidability**. Is safety necessary for decidabiliy? Two partial results:

Theorem. (A+deM+O 05) Σ -labelled trees generated by order-2 recursion schemes (whether safe or not) have decidable MSO theories. **Theorem**. (KNUW 05) Modal mu-calculus model checking problem for homogeneously-typed order-2 schemes (whether safe or not) is 2-EXPTIME complete.

Question. What about higher orders?

Yes: Decidability result extends to all orders – main topic of this lecture.

Verifying Finitely-Presentable Infinite Structures Games in Semantics and Verification, 29 May - 2 June 06 – 4 / 47

Safety is not necessary for MSO decidability

Theorem. (LICS 06) The modal mu-calculus model checking problem for trees generated by arbitrary order-n recursion schemes is n-EXPTIME complete, for each $n \ge 0$.

We first consider the decidability argument and then discuss the complexity analysis.

Key Steps of the Decidability Proof

Let *G* be any order-*n* recursion scheme, and φ a modal mu-calculus formula. The question of whether:



which is decidable, since the computation tree $\lambda(G)$ is regular, and the APT acceptance problem of regular trees is decidable (Rabin, Emerson, Jutla, etc.).

Outline

Review

Alternating Parity Tree Automata (APT) and the Modal Mu-Calculus Decidability Argument 1: Transference Principle Decidability Argument 2: Simulating Traversals Complexity Analysis Characterising recursion schemes by collapsible PDA (with A. Murawski) Parity games over collapsible *n*-pushdown graphs

Review

Alternating Parity Tree Automata (APT) and the Modal Mu-Calculus

Mu-calculus and APT

• APT

Decidability Argument 1: Transference Principle

Decidability Argument 2: Simulating Traversals

Complexity Analysis

Characterising recursion schemes by collapsible PDA (with A. Murawski)

Parity games over collapsible *n*-pushdown graphs

Alternating Parity Tree Automata (APT) and the Modal Mu-Calculus

Modal mu-calculus and alternating parity tree automata (APT) are equivalent

Theorem [EM91]. There is a transformation from mu-calulus formulas to APT, $\varphi \mapsto \mathcal{B}_{\varphi}$, such that for any Σ -labelled tree $t, t \vDash \varphi$ iff the APT \mathcal{B}_{φ} accepts t.

Positive boolean formulas over a set P: p ranges over P

$$\mathsf{B}^+(P) \ni \theta ::= \mathsf{true} \mid \mathsf{false} \mid p \mid \theta \land \theta \mid \theta \lor \theta$$

For $S \subseteq P$ and $\theta \in B^+(P)$, we say S satisfies θ if assigning true to elements in S and false to elements in $P \setminus S$ makes θ true.

Alternating Parity Tree Automaton (APT)

$$\mathcal{B} = \langle \Sigma, Q, \delta, q_0 \in Q, \Omega : Q \longrightarrow \mathbb{N} \rangle$$

where

 $\delta: Q \times \Sigma \longrightarrow \mathsf{B}^+([ar(\Sigma)] \times Q) \text{ is the transition function where, for each } f \in \Sigma \text{ and } q \in Q, \text{ we have } \delta(q, f) \in \mathsf{B}^+([ar(f)] \times Q) \text{ Notation: } [m] = \{1, \cdots, m\}; ar(\Sigma) = \max\{ar(f) : f \in \Sigma\}.$

Acceptance of Σ -labelled tree $t : \operatorname{dom}(t) \longrightarrow \Sigma$ by an APT \mathcal{B}

An APT \mathcal{B} accepts a Σ -labelled tree t just if it has an accepting run-tree over t. I.e. "there is a certain set of state-annotated paths in t that is

- 1. ' $\delta_{\mathcal{B}}$ -respecting', and
- 2. such that the infinite paths among them satisfy the parity condition."

Think of these (state-annotated) paths as footprints of automata descending the tree.

Acceptance of Σ -labelled tree $t : \operatorname{dom}(t) \longrightarrow \Sigma$ by an APT \mathcal{B}

An APT \mathcal{B} accepts a Σ -labelled tree t just if it has an accepting run-tree over t. I.e. "there is a certain set of state-annotated paths in t that is

- 1. ' $\delta_{\mathcal{B}}$ -respecting', and
- 2. such that the infinite paths among them satisfy the parity condition."

Think of these (state-annotated) paths as footprints of automata descending the tree.

$\delta_{\mathcal{B}}$ -respecting:

Automaton reads root ϵ with initial state q_0 .

Suppose automaton reads node α of dom(t) with state q.

- Recall: $\delta_{\mathcal{B}} : Q \times \Sigma \longrightarrow \mathsf{B}^+([ar(\Sigma)] \times Q)$. Guess a set $S \subseteq [ar(t(\alpha))] \times Q$ that satisfies the positive boolean formula $\delta_{\mathcal{B}}(q, t(\alpha))$.
- For each $(i, q') \in S$, spawn automaton to read *i*-child of α with state q'.

Acceptance of Σ -labelled tree $t : \operatorname{dom}(t) \longrightarrow \Sigma$ by an APT \mathcal{B}

An APT \mathcal{B} accepts a Σ -labelled tree t just if it has an accepting run-tree over t. I.e. "there is a certain set of state-annotated paths in t that is

- 1. ' $\delta_{\mathcal{B}}$ -respecting', and
- 2. such that the infinite paths among them satisfy the parity condition."

Think of these (state-annotated) paths as footprints of automata descending the tree.

$\delta_{\mathcal{B}}$ -respecting:

Automaton reads root ϵ with initial state q_0 .

Suppose automaton reads node α of dom(t) with state q.

- Recall: $\delta_{\mathcal{B}} : Q \times \Sigma \longrightarrow \mathsf{B}^+([ar(\Sigma)] \times Q)$. Guess a set $S \subseteq [ar(t(\alpha))] \times Q$ that satisfies the positive boolean formula $\delta_{\mathcal{B}}(q, t(\alpha))$.
- For each $(i, q') \in S$, spawn automaton to read *i*-child of α with state q'.

Parity condition: largest priority that occurs infinitely often is even.

Review

Alternating Parity Tree Automata (APT) and the Modal Mu-Calculus

Decidability Argument

1: Transference

Principle

- Transference principle
- Long transform
- Traversals
- Path-Traversal
- Correspondence
- Composition
- Traversal tree
- Example
- Example

Decidability Argument 2: Simulating Traversals

Complexity Analysis

Characterising recursion schemes by collapsible PDA (with A. Murawski)

Parity games over collapsible *n*-pushdown graphs

Decidability Argument 1: Transference Principle

Transference Principle: from value tree to computation tree

Direct algorithmic analysis of value tree $\llbracket G \rrbracket$ is futile:

Value tree has no useful structure for our purpose: It is the "extensional" outcome of a (potentially infinite) computational process comprising two kinds of intertwined basic actions

- 1. unfolding
- 2. β -reduction

It is the algorithmics of this process that we *should* analyse. [KNU2002 did, hence their restriction to the safe case!]

Transference Principle: from value tree to computation tree

Direct algorithmic analysis of value tree $\llbracket G \rrbracket$ is futile:

Value tree has no useful structure for our purpose: It is the "extensional" outcome of a (potentially infinite) computational process comprising two kinds of intertwined basic actions

- 1. unfolding
- 2. β -reduction

It is the algorithmics of this process that we *should* analyse. [KNU2002 did, hence their restriction to the safe case!]

Our approach: By considering rewrite-rule in **long form** (= curried, eta-long form), unfolding and β -reduction can be analysed separately (Aehlig).

- Build an auxiliary computation tree $\lambda(G)$ which is the outcome of performing all of the unfolding, but none of the β -reduction (thus no substitution and hence no renaming needed!).
- Analyse the β -reduction locally (i.e. without the global operation of substitution) using game semantics **traverals**.

The Long Transform: from (order-n) G to (order-0) G

 \overline{G} -rules are obtained by: For each G-rule

- 1. Expand RHS to its η -long form, including ground-type subterm in *operand* position. Thus $e : o \eta$ -expands to $\lambda . e$ ("dummy lambdas").
- 2. Insert long-apply symbol @: Replace every ground-type subterm $D e_1 \cdots e_n$ by @ $D e_1 \cdots e_n$, where D ranges over non-terminals.
- 3. Curry each equation.
- 4. Rename (bound) variables afresh. Only finitely many new names.

Note: This transform is canonical for innocent game semantics.

Example.

$$G: \begin{cases} S = FH \\ F\varphi = \varphi(F\varphi) \\ Hz = fzz \end{cases} \mapsto \overline{G}: \begin{cases} S = \lambda . @F(\lambda x. @H\lambda. x) \\ F = \lambda \varphi. \varphi(\lambda . @F(\lambda y. \varphi(\lambda . y)))) \\ H = \lambda z. f(\lambda . z)(\lambda . z) \end{cases}$$

Computation tree $\lambda(G)$ is obtained by infinitely unfolding G:



Traversals

Definition. *Traversals* over $\lambda(G)$ are justified sequences defined by induction: (Root) The singleton sequence (comprising ϵ) is a traversal. (App) If t @ is a traversal, so is t @ $\lambda \overline{\xi}$. (Sig) If t f is a traversal, so is t f λ where $1 \le i \le \operatorname{arity}(f)$. (Var) If $t n \lambda \overline{\xi}$ \cdots ξ is a traversal, so is $t n \lambda \overline{\xi}$ \cdots $\xi \lambda \overline{\eta}$. (Lam) If $t \lambda \overline{\xi}$ is a traversal, so is $t \lambda \overline{\xi} n$, such that $\lceil t \lambda \overline{\xi} n \rceil$ is a path in $\lambda(G)$.

Key lemma:

- (i) Traversals are justified sequences that satisfy Visibility.
- (ii) P-views of traversals are paths in the computation tree.

Path-Traversal Correspondence

Theorem. (Correspondence) Let G be an order-n recursion scheme.

(i) There is a 1-1 correspondence between maximal paths *p* in (Σ-labelled) value tree [[*G*]] and maximal traversals *t_p* over computation tree λ(*G*).
(ii) Further for each *p*, we have *p* ↾ Σ = *t_p* ↾ Σ.

Proof is by game semantics.

Idea:

- Value tree [[G]] is a representation of the strategy-denotation of G (in game semantics).
- Paths in $\llbracket G \rrbracket$ correspond to plays in the strategy-denotation.
- Nodes of the computation trees are representations of move-occurrences of the constituent arenas.
- Traversals t_p over computation tree $\lambda(G)$ are just (representations of) the uncoverings of the plays (= path) p in the strategy-denotation of G.

Composition

Strategy composition is "parallel composition of two processes $\sigma : A \Rightarrow B$ and $\tau : B \Rightarrow C$ synchronizing on B, followed by hiding of B-moves."



Verifying Einitely-Presentable Infinite Structures Games in Semantics and Verification, 29 May - 2 June 06 – 17 / 47 play in O, 7 thus constructed is $c_1 a_1 a_2 c_2 c_3 a_3$.

From run-tree over $\llbracket G \rrbracket$ to traversal-tree over $\lambda(G)$

Thus:Property APT \mathcal{B} has an accepting run-tree over $\llbracket G \rrbracket$ by def. \exists certain set of $\delta_{\mathcal{B}}$ -respecting, state-annotated
paths in $\llbracket G \rrbracket$ satisfying parity conditionThm (Corr) \exists certain set of $\delta_{\mathcal{B}}$ -respecting, state-annotated
traversals over $\lambda(G)$ satisfying parity conditionnew def.Property APT \mathcal{B} has an accepting traversal-tree over $\lambda(G)$.

Higher-order traversals can be very complex - they jump all over the tree, and can visit certain nodes infinitely often. See order-3 example!

Problem: Find a device to recognise an accepting traversal-tree.

Example



Verifying Finitely-Presentable Infinite Structures Games in Semantics and Verification, 29 May - 2 June 06 – 19 / 47



Review

Alternating Parity Tree Automata (APT) and the Modal Mu-Calculus

Decidability Argument 1: Transference Principle

Decidability Argument 2: Simulating Traversals

- Simulation
- Variable profiles
- Traversal-simulating APT
- Main Technical
- Lemma
- Key Steps of the Decidability Proof

Complexity Analysis

Characterising recursion schemes by collapsible PDA (with A. Murawski)

Parity games over collapsible *n*-pushdown graphs

Decidability Argument 2: Simulating Traversals

Simulate traversals by *paths* – an order-2 illustration

Idea. Simulate an annotated traversal by the respective P-views of all its prefixes, which are a set of annotated paths in the computation tree.



Simulate the traversal above (indicated by arrows) by paths:

- At φ with q_1 , guess that the detour will return at first λ -child with state q_2
- Spawn an automaton at $\lambda y_1 y_2$ to verify the guess.

Formalising the guesses as Variable Profiles $VP_G^{\mathcal{B}}(A)$

Fix a recursion scheme G, and a property APT $\mathcal{B} = \langle \Sigma, Q, \delta, q_0, \Omega \rangle$ with p priorities. Write $[p] = \{1, \dots, p\}$.

$$\mathbf{VP}_{G}^{\mathcal{B}}(o) = Var_{G}^{o} \times Q \times [p] \times 2^{\varnothing}$$
$$\mathbf{VP}_{G}^{\mathcal{B}}(A_{1} \to \dots \to A_{n} \to o) = Var_{G}^{A} \times Q \times [p] \times 2^{(\bigcup_{i=1}^{n} \mathbf{VP}_{G}^{\mathcal{B}}(A_{i}))}$$

Asserting $(\varphi, q, m, c) \in \mathbf{VP}_G^{\mathcal{B}}(A)$ at node α of computation tree means: the traversal being simulated will reach some descendant-node that is labelled φ

- 1. with state q, such that
- 2. m is the highest priority that will have been encountered up to that point
- 3. further, the traversal (which will then jump to the root of a subtree that denotes the *actual* argument of φ) will eventually return to the children of the node labelled φ "in accord with c".

Note: $|\mathbf{VP}_{G}^{\mathcal{B}}(i)| = \exp_{i}O(|G| \cdot |Q| \cdot p).$

Traversal-simulating APT

Aim: Simulate \mathcal{B} -states + verify guesses (= variable profiles).

C-states: $q \rho$ where q is \mathcal{B} -state being simulated, and environment ρ is the set of profiles of variable (within current scope) to be verified.

Suppose automaton with state $q \rho$ reading node with label l: Some cases (verification of priorities omitted)

•
$$l$$
 is a Σ -symbol $f: o^k \to o$.

Guess a set { $(i_1, q_1), \dots, (i_l, q_l)$ } satisfying $\delta_{\mathcal{B}}(q, f)$ (abort, if impossible), and guess environments ρ_1, \dots, ρ_l such that $\bigcup_{j=1}^l \rho_j = \rho$. For each j, spawn automata with state $q_j \rho_j$ in direction i_j .

• l is an @ with children labelled by $\lambda \overline{\varphi}$ and $\lambda \overline{\eta_1}, \dots, \lambda \overline{\eta_k}$. Guess $\rho' = \{ (\varphi_{i_j}, q_j, m_j, c_j) : 1 \le j \le l \}$, and spawn automaton with state $q \rho'$ in direction 0. Guess ρ_1, \dots, ρ_l with $\bigcup_{j=1}^l \rho_j = \rho$. For each j, spawn automaton with state $q_j (\rho_j \cup c_j)$ in direction i_j .

Main Technical Lemma

Theorem (Simulation). The following are equivalent:

- (i) Property APT \mathcal{B} has an accepting traversal-tree over the computation tree $\lambda(G)$.
- (ii) Traversal-simulating APT \mathcal{C} has an accepting run-tree over the computation tree $\lambda(G)$.

" $(i) \Rightarrow (ii)$ ": From the traversal-tree annotated only by \mathcal{B} -states, we perform a succession of annotation operations, transforming it to a traversal-tree annotated by \mathcal{C} -states.

The set of P-views of all such C-state-annotated traversals *is* precisely an accepting run-tree of C.

" $(ii) \Rightarrow (i)$ ": Reconstruct each traversal (of the putative traversal-tree) as a sequence of segments of paths (=P-views) in the accepting run-tree, thus inheriting an accepting state-annotation.

Satisfaction of parity condition tricky to show!

Key Steps of the Decidability Proof

Let *G* be any order-*n* recursion scheme, and φ a modal mu-calculus formula. The question of whether:

```
Value tree [\![\,G\,]\!] satisifes \varphi
```

 \iff { Emerson + Jutla 1991}

Property APT \mathcal{B} has accepting run-tree over $\llbracket G \rrbracket$

 \iff { Correspondence Theorem }

 ${\mathcal B}$ has an accepting traversal-tree over computation tree $\lambda(G)$

 \iff {Simulation Theorem }

Traversal-simulating APT C has an accepting run-tree over $\lambda(G)$

which is decidable, since the computation tree $\lambda(G)$ is regular, and the APT acceptance problem of regular trees is decidable.

Review

Alternating Parity Tree Automata (APT) and the Modal Mu-Calculus

Decidability Argument 1: Transference Principle

Decidability Argument 2: Simulating Traversals

Complexity Analysis

- Equivalence of decision problems
- Complexity of Modal Mu-Calculus Model Checking
- Complexity

Characterising recursion schemes by collapsible PDA (with A. Murawski)

Parity games over collapsible *n*-pushdown graphs

Complexity Analysis

Equivalence of decision problems

Let *G* be any order-*n* recursion scheme, and φ a modal mu-calculus formula. The question of whether

- Value tree $[\![\,G\,]\!]$ satisifes φ
- \iff { Emerson + Jutla 1991}
 - **Property APT** \mathcal{B} has accepting run-tree over $\llbracket G \rrbracket$
- \iff { Correspondence Theorem }

 $\mathcal B$ has an accepting traversal-tree over computation tree $\lambda(G)$

 \iff {Simulation Theorem }

Traversal-simulating APT C has an accepting run-tree over $\lambda(G)$

 \iff { Emerson + Jutla, Stirling, etc. }

Eloise has winning strategy in acceptance parity game G(Gr(G), C)

(from root) for finite graph $\operatorname{Gr}(G)$ which unravels to $\lambda(G)$

Complexity of Modal Mu-Calculus Model Checking

Model-checking safe trees is already *n*-EXPTIME hard. (Cachat ICALP'04 + Walukiewicz)

Use parity game to show problem is decidable in n-EXPTIME.

Theorem. (Jurdzinski 2000) Eloise's winning regions and strategy in a parity game over (V, E) with $p \ (\geq 2)$ priorities is computable in time

$$O\left(p \cdot |E| \cdot \left(\frac{|V|}{\lfloor p/2 \rfloor}\right)^{\lfloor p/2 \rfloor}\right)$$

Note: Actually a coarse bound $|V|^{O(|p|)}$ suffices (Emerson + Lei 86).

Fix an order-n G, a property APT \mathcal{B} with traversal-simulating APT \mathcal{C} . Construct **acceptance parity game** $\mathbf{G}(\operatorname{Gr}(G), \mathcal{C})$ such that the finite deterministic Λ_G -labelled graph $\operatorname{Gr}(G)$ unfolds to $\lambda(G)$.

Fact. Eloise has a winning strategy in G(Gr(G), C) iff the APT C accepts $\lambda(G)$ (iff \mathcal{B} accepts $\llbracket G \rrbracket$).

Complexity

Recall $\mathsf{VP}_G^{\mathcal{B}}(A_1 \to \cdots \to A_n \to o) = Var_G^A \times Q \times [p] \times 2^{(\bigcup_{i=1}^n \mathsf{VP}_G^{\mathcal{B}}(A_i))}$ Write $\mathsf{VP}_G^{\mathcal{B}}(i)$ for the set of profiles of variables of order at most i. We have

$$|\mathbf{VP}_G^{\mathcal{B}}(i)| = \exp_i O(|G| \cdot |Q| \cdot p).$$

Theorem. (Succinctness). If the traversal-simulating APT C has an accepting run-tree, it has one with a small branching factor.

As a corollary, $|V| = \exp_n O(|G| \cdot |Q| \cdot p).$ Since |E| is at most $|V|^2$, time complexity is

$$O\left(p \cdot (|V|)^{\lfloor p/2 \rfloor + 2}\right) = \exp_n O(|G| \cdot |Q| \cdot p)$$

Theorem. The modal mu-calculus model checking problem for trees generated by order-n recursion schemes is n-EXPTIME complete.

Verifying Finitely-Presentable Infinite Structures Games in Semantics and Verification, 29 May - 2 June 06 – 30 / 47

Review

Alternating Parity Tree Automata (APT) and the Modal Mu-Calculus

Decidability Argument 1: Transference Principle

Decidability Argument 2: Simulating Traversals

Complexity Analysis

Characterising recursion schemes by collapsible PDA (with A. Murawski)

• Order-2 PDA

- Collapsible PDA
- Schemes and

Automata

Parity games over collapsible *n*-pushdown graphs

Characterising recursion schemes by collapsible PDA (with A. Murawski)

Order-2 pushdown automata (Maslov 74)

A 1-stack is just an ordinary stack.

A 2-stack (resp. n + 1-stack) is a stack of 1-stacks (resp. n-stack).

Operations on 2-stacks: s_i ranges over 1-stacks

$$push_{2} : s_{1} \cdots s_{i-1} \underbrace{[a_{1} \cdots a_{n}]}_{S_{i}} \mapsto s_{1} \cdots s_{i-1} s_{i} s_{i}$$

$$pop_{2} : s_{1} \cdots s_{i-1} \underbrace{[a_{1} \cdots a_{n}]}_{S_{i}} \mapsto s_{1} \cdots s_{i-1}$$

$$push_{1} a : s_{1} \cdots s_{i-1} \underbrace{[a_{1} \cdots a_{n}]}_{S_{i}} \mapsto s_{1} \cdots s_{i-1} \underbrace{[a_{1} \cdots a_{n} a]}_{S_{i}}$$

$$pop_{1} : s_{1} \cdots s_{i-1} \underbrace{[a_{1} \cdots a_{n}]}_{S_{i}} \mapsto s_{1} \cdots s_{i-1} \underbrace{[a_{1} \cdots a_{n-1}]}_{S_{i}}$$

Order-n collapsible pushdown automata (CPDA)

Order-2 CPDA:

[KNUW ICALP05] "panic automata"; [AdMO FOSSACS05] "2PDA with links"

Each stack symbol in 2-stack "remembers" the stack content at the point it was first created (i.e. $push_1$ -ed), by way of a pointer to some 1-stack buried underneath it (if there is one such).

Two new operations:

- push₁ *a*: Whenever a symbol is pushed onto the top of stack, it has a pointer to the 1-stack immediately below the top 1-stack.
- "collapse" (= panic) collapses the 2-stack up to the point as remembered by (i.e. pointed to) by the top element of the 2-stack.

In order-*n* CPDA, there are n - 1 versions of push₁, namely, push₁^J a, with $1 \le j \le n - 1$: push₁^j a: Whenever a symbol is pushed onto the top of stack, it has a pointer to the *j*-stack immediately below the top *j*-stack.

Example: Urzyczyn's Language U over alphabet $\{(,),*\}$

U-words are uniquely composed of 3 segments:



- Segment A is a prefix of a well-bracketed word that ends in (, such that none of its prefixes is a well-bracketed word.
- Segment B is a well-bracketed word.
- Segment C has length equal to the number of (in A.

```
E.g. (()(()()) * * * \in U.
```

Recognising U by a 2CPDA. E.g. (() (() $\ast \ \ast \ast \in \ U$

- push_2 ; push_1a upon reading (
- pop₁ upon reading)
- collapse upon reading first *, thereafter pop₂ for each subsequent *.



Recognising U by a 2CPDA. E.g. (() (() $\ast \ \ast \ast \in \ U$

- push_2 ; push_1a upon reading (
- pop₁ upon reading)
- collapse upon reading first *, thereafter pop₂ for each subsequent *.

$$([[a]] \\ ([[a]] [a a]]$$

Recognising U by a 2CPDA. E.g. (() (() $* \ * \ * \ \in \ U$

- push_2 ; push_1a upon reading (
- pop₁ upon reading)
- collapse upon reading first *, thereafter pop₂ for each subsequent *.

Recognising U by a 2CPDA. E.g. (() (() $\ast \ \ast \ast \in \ U$

- push_2 ; push_1a upon reading (
- pop₁ upon reading)
- collapse upon reading first *, thereafter pop₂ for each subsequent *.



Recognising U by a 2CPDA. E.g. (() (() $* \ * \ * \ \in \ U$

- push_2 ; push_1a upon reading (
- pop_1 upon reading)
- collapse upon reading first *, thereafter pop₂ for each subsequent *.



Recognising U by a 2CPDA. E.g. (() (() $\ast \ \ast \ast \in \ U$

- push_2 ; $\mathsf{push}_1 a$ upon reading (
- pop_1 upon reading)
- collapse upon reading first *, thereafter pop₂ for each subsequent *.



Recognising U by a 2CPDA. E.g. (() (() $\ast \ \ast \ast \in \ U$

- push_2 ; push_1a upon reading (
- pop_1 upon reading)
- collapse upon reading first *, thereafter pop₂ for each subsequent *.



Recognising U by a 2CPDA. E.g. (() (() $* \ * \ * \ \in \ U$

- push_2 ; $\mathsf{push}_1 a$ upon reading (
- pop_1 upon reading)
- collapse upon reading first *, thereafter pop₂ for each subsequent *.



Recognising U by a 2CPDA. E.g. (() (() $\ast \ \ast \ast \in \ U$

- push_2 ; push_1a upon reading (
- pop_1 upon reading)
- collapse upon reading first *, thereafter pop₂ for each subsequent *.



Order-n recursion schemes = order-n CPDA

U is recognised by a deterministic 2CPDA and a non-deterministic 2PDA.

Conjecture. U is not recognisable by a deterministic 2PDA.

As a corollary, there is an associated tree that is generated by an order-2 recursion scheme, but not by any order-2 safe scheme.

Theorem. For each $n \ge 0$, order-*n* collapsible PDA and order-*n* recursion schemes are equi-expressive for Σ -labelled trees.

Proof idea

- From recursion scheme G to CPDA A_G: Use game semantics.
 Code traversals as n-stacks.
 Invariant: The top 1-stack is the P-view of the encoded traversal.
- From CPDA \mathcal{A} to recursion scheme $G_{\mathcal{A}}$: Code configurations c as Σ -term M_c , so that $c \to c'$ implies M_c rewrites (in 1-step) to $M_{c'}$.

Review

Alternating Parity Tree Automata (APT) and the Modal Mu-Calculus

Decidability Argument 1: Transference Principle

Decidability Argument 2: Simulating Traversals

Complexity Analysis

Characterising recursion schemes by collapsible PDA (with A. Murawski)

Parity games over collapsible n-pushdown graphs

- CPDA graphs
- Many Further Directions

Parity games over collapsible *n*-pushdown graphs

Parity games over collapsible *n*-pushdown graphs

The same approach applies to solving parity games over graphs.

There is a **transformation** from *n*-collapsible pushdown systems (CPDS) A to an equivalent order-*n* (non-deterministic) recursion schemes G_A .

Transference Principle: Paths in the configuration graph of the CPDS A, CG_A , correspond exactly to traversals over the computation tree $\lambda(G_A)$ (or equivalently over the finite computation graph Gr(A) that unfolds to $\lambda(G_A)$).

Simulating Traversals: For any parity game over CG_A , accepting traversal-trees over Gr(A) can be recognised by a traversal-simulating APT C.

Thus, for any parity game over a collapsible *n*-pushdown graph CG_A , there is an equivalent finite acceptance parity game, which is an appropriate product of Gr(A) and C.

Hence parity games over collapsible *n*-pushdown graphs are solvable.

Many open problems. E.g. Is winning region of 2-collapsible pushdown game regular? What about higher-order games?

Many Further Directions

1. Is safety a genuine constraint on expressiveness? Equivalently, are order-n collapsible PDA more expressive than order-n PDA?

Conjecture. SafeRecSch₂ $\Sigma \subset RecSchTree_2\Sigma$ I.e. There are *inherently* unsafe trees (at order 2).

Candidate: Urzyczyn's tree.

2. Define graphs generated by order-n recursion schemes to be ϵ -closures of configuration graphs of order-n collapsible PDA? Are their MSO theories decidable?

Matthew Hague's work.

Notions of graphs definable by order-n recursion schemes.

3. "Mixing semantic and verification games": Denotational semantics of λ -calculus "relative to an alternating parity tree automaton (APT)". **Problem.** Construct a cartesian closed category (= model of the lambda calculus), parameterized by an APT, whose maps are witnessed by profiles ("guesses").