

Model Checking Higher-Order Computation: I

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Model checking and computer-aided verification

Beginning in the 80s, computer-aided verification (notably model checking) of **finite-state systems** (e.g. hardware and communication protocols) has been a great success story in computer science.

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What is (software) model checking?

Problem: Given a system Sys (e.g. an OS), and given a desirable behavioural property $Spec$ (e.g. deadlock freedom), does Sys satisfy $Spec$?

The model checking approach:

- 1 Find an abstract model M of the system Sys .
- 2 Describe the property $Spec$ as a formula φ of a suitable logic.
- 3 Exhaustively check if φ is violated by M .

Huge strides made in **verification of 1st-order imperative programs**.

Many tools: SLAM, Blast, Terminator, SatAbs, etc.

Two key techniques: State-of-the-art tools use

- 1 abstraction techniques, as exemplified by CEGAR (Counter-Example Guided Abstraction Refinement)
- 2 acceleration methods such as SAT- and SMT-solvers.

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Verification of higher-order programs

Examples: OCaml, F#, Haskell, Lisp/Scheme, Ptalon, etc.

By comparison with 1st-order imperative program, the model checking of higher-order programs is in its **infancy**.

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Model-checking higher-order programs is hard:

- 1 Infinite-state and extremely complex: Even without recursion, higher-order programs over a finite base type are infinite-state. (Other sources of infinity: data structures and manipulation, control structures (with recursion), asynchronous communication, real-time and embedded systems, systems with parameters etc.)
- 2 Models of higher-order features as studied in semantics – are typically too “abstract” to support any algorithmic analysis. (A notable exception is game semantics.)

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Verifying higher-order programs: a worthwhile challenge

1. **Widely used in diverse domains.** Succinct, less error-prone, easy to write and hence good for prototyping; performance (of e.g. F#) approaching C++.

Traditional applications: theorem proving and reasoning assistance, computational linguistics, programming language processing.

More recently: databases, networking, internet search (Google's MapReduce), trading and investment banking.

See Wadler's page "Functional Programming in the Real World"¹

2. **Many hard theoretical problems:** E.g. termination analysis, higher-order matching, and (contextual) reachability analysis.

Our goal: To use semantic methods, in conjunction with algorithmic ideas and techniques from Verification, to formally analyze programming situations in which higher-order features are important.

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Aim

To introduce a systematic approach to the algorithmics of infinite structures generated by families of higher-order generators, suitable as a basis for model checking a wide range of behavioural properties of higher-order functional programs.

4 lectures.

Part 1: Background and Survey

- 1 Families of Generators of Higher-Order Infinite Structures
- 2 Survey of Algorithmic Model Theory

Part 2: Some Theory and Application

- 1 Type Theory and Modal μ -Calculus Model Checking
- 2 Application: Model Checking Functional Programs

1 Relating (Families of) Generators of Infinite Structures

- Higher-Order Pushdown Automata
- Higher-Order Recursion Schemes
- Relating the Generator Families: Word Languages

2 Recursion Schemes and their Algorithmic Model Theory

- Q1: Decidability of MSO / Modal Mu-Calculus Theories
- Q2: Machine Characterisation by Collapsible Pushdown Automata
- Q3: Expressivity: *The Safety Conjecture*
- Q4: Infinite Graphs Generated by Recursion Schemes / CPDA

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Higher-order pushdown automata (HOPDA) [Maslov 74]

Order-2 pushdown automata

A 1-stack is an ordinary stack. A 2-stack (resp. $n + 1$ -stack) is a stack of 1-stacks (resp. n -stack).

Operations on 2-stacks: s_j ranges over 1-stacks. Top of stack is at the righthand end.

$$\text{push}_2 : [s_1 \cdots s_{i-1} \underbrace{[a_1 \cdots a_n]}_{s_i}] \mapsto [s_1 \cdots s_{i-1} s_i s_i]$$

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Idea extends to all finite orders: an order- n PDA has an order- n stack, and has push_i and pop_i for each $1 \leq i \leq n$.

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HOPDA as recognizers of word languages

HOPDA can be used as recognizing/generating device for

- 1 finite-word languages (Maslov 74) (and ω -word languages)

$$\langle \Sigma, Q, q_0, \Gamma, \Delta \subseteq (\Sigma \cup \{\epsilon\}) \times Q \times \Gamma \times Op_n \times Q, F \rangle$$

- 2 possibly-infinite (ranked) trees (KNU01), and tree languages
- 3 possibly infinite graphs (Muller+Schupp 86, Courcelle 95, Cachat 03)

Some basic facts (Maslov 74, 76):

- 1 HOPDA define an infinite hierarchy of word languages.
- 2 Low orders are well-known: orders 0, 1 and 2 are the regular, context free, and indexed languages (Aho 68). Higher-order languages are poorly understood.
- 3 For each $n \geq 0$, the order- n languages form an abstract family of languages (closed under $+$, \cdot , $(-)^*$, intersection with regular languages, homomorphism and inverse homo.)
- 4 For each $n \geq 0$, the emptiness problem for order- n PDA is decidable.

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Pumping Lemma for Context-Free Languages

Theorem ($uvwx$)

Let L be an infinite CFL. Every word in L longer than p can be written as a concatenation of subwords, $u v w x y$, such that $|v w x| \leq p$, $|v x| \geq 1$, and for every $i \geq 0$, $u v^i w x^i y$ is in L .

A reminder: simple types

Types $A ::= o \mid (A \rightarrow B)$

Every type can be written uniquely as

$$A_1 \rightarrow (A_2 \cdots \rightarrow (A_n \rightarrow o) \cdots), \quad n \geq 0$$

often abbreviated to $A_1 \rightarrow A_2 \cdots \rightarrow A_n \rightarrow o$.

Order of a type: measures “nestedness” on LHS of \rightarrow .

$$\begin{aligned} \text{order}(o) &= 0 \\ \text{order}(A \rightarrow B) &= \max(\text{order}(A) + 1, \text{order}(B)) \end{aligned}$$

Examples. $\mathbb{N} \rightarrow \mathbb{N}$ and $\mathbb{N} \rightarrow (\mathbb{N} \rightarrow \mathbb{N})$ both have order 1;
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Higher-order recursion schemes [Par68, Niv72, NC78, Dam82,...]

An *order- n recursion scheme* = closed ground-type term definable in order- n fragment of simply-typed λ -calculus with recursion and uninterpreted order-1 constant symbols.

Example: An order-1 recursion scheme. Fix ranked alphabet $\Sigma = \{f : 2, g : 1, a : 0\}$.

$$G : \begin{cases} S = F a \\ F x = f x (F (g x)) \end{cases}$$

Unfolding from the start symbol S :

$$\begin{aligned} S &\rightarrow F a \\ &\rightarrow f a (F (g a)) \\ &\rightarrow f a (f (g a) (F (g (g a)))) \\ &\rightarrow \dots \end{aligned}$$

The (term-)tree thus generated, $\llbracket G \rrbracket$, is $f a (f (g a) (f (g (g a)) (\dots)))$.

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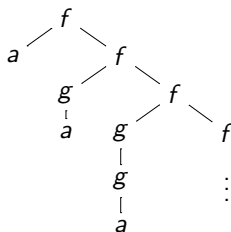
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Representing the term-tree $\llbracket G \rrbracket$ as a Σ -labelled tree

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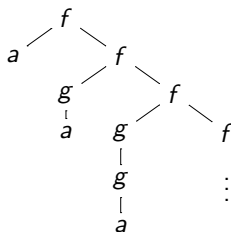


We view the infinite term $\llbracket G \rrbracket$ as a Σ -labelled tree, formally, a map $T \rightarrow \Sigma$, where T is a prefix-closed subset of Dir^* , with Dir a set of edge labels.

Formally term-trees such as $\llbracket G \rrbracket$ are ranked and ordered.

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Definition: Order- n (deterministic) recursion scheme $G = (\mathcal{N}, \Sigma, \mathcal{R}, S)$

Fix a set of typed variables (written as φ, x, y etc).

- \mathcal{N} : Typed **non-terminals** of order at most n (written as upper-case letters), including a distinguished **start symbol** $S : o$.
- Σ : **Ranked** alphabet of terminals: $f \in \Sigma$ has **arity** $\text{ar}(f) \geq 0$
- \mathcal{R} : An **equation** for each non-terminal $D : A_1 \rightarrow \dots \rightarrow A_m \rightarrow o$ of shape

$$D \varphi_1 \cdots \varphi_m = e$$

where the term $e : o$ is constructed from

- ▶ terminals f, g, a , etc. from Σ
- ▶ variables $\varphi_1 : A_1, \dots, \varphi_m : A_m$ from Var ,
- ▶ non-terminals D, F, G , etc. from \mathcal{N} .

using the **application rule**: If $s : A \rightarrow B$ and $t : A$ then $(s t) : B$.

The tree generated by a recursion scheme: value tree

Given a term t , define a (finite) tree t^\perp by

$$t^\perp := \begin{cases} f & \text{if } t \text{ is a terminal } f \\ t_1^\perp t_2^\perp & \text{if } t = t_1 t_2 \text{ and } t_1^\perp \neq \perp \\ \perp & \text{otherwise} \end{cases}$$

We extend the flat partial order on Σ (i.e. $\perp \leq a$ for all $a \in \Sigma$) to trees by:

$$s \leq t := \forall \alpha \in \text{dom}(s). \alpha \in \text{dom}(t) \wedge s(\alpha) \leq t(\alpha)$$

E.g. $\perp \leq f\perp\perp \leq f\perp b \leq fab$.

For a directed set T of trees, we write $\bigsqcup T$ for the lub of T w.r.t. \leq .

Let G be a recursion scheme. We define the **tree generated by G** by

$$\llbracket G \rrbracket := \bigsqcup \{ t^\perp \mid S \rightarrow^* t \}$$

Using recursion schemes as generators of word languages

Idea: A word is just a linear tree.

Represent a finite word “ $a b c$ ” (say) as the applicative term $a(b(c e))$, viewing a , b and c as symbols of arity 1, where e is the arity-0 end-of-word marker.

Fix an input alphabet Σ . We can use a (non-deterministic) recursion scheme to generate finite-word languages, with ranked alphabet $\overline{\Sigma} := \{a : 1 \mid a \in \Sigma\} \cup \{e : 0\}$.

Example. $\{a^n b^n \mid n \geq 0\}$ is generated by order-1 recursion scheme:

$$\begin{cases} S & \rightarrow F e \\ F x & \rightarrow a(F(bx)) \quad | \quad x \end{cases}$$

Exercises

- 1 Find an order-2 (word-language) recursion scheme that generates $L = \{a^i b^j c^i \mid i \geq 0\}$.
- 2 Prove that context-free languages are equivalent to languages generated by order-1 (word-language) recursion schemes.

Answer to 1.

$$\left\{ \begin{array}{l} S \rightarrow F I e \\ F \varphi x \rightarrow \varphi x \mid F (H \varphi) (c x) \\ H \varphi y \rightarrow a(\varphi(b y)) \\ I x \rightarrow x \end{array} \right.$$

Theorem (Equi-expressivity)

For each $n \geq 0$, the three formalisms

- 1 order- n pushdown automata (Maslov 76)
- 2 order- n **safe** recursion schemes (Damm 82, Damm + Goerdt 86)
- 3 order- n indexed grammars (Maslov 76)

generate the same class of word languages.

What is **safety**? (See later.)

Maslov Hierarchy: Many Open Problems

- 1 Pumping Lemma, Myhill-Nerode, and Parikh Theorems.
Weak “pumping lemmas” for levels 1 and 2 (Hayashi 73, Gilman 96).
Pace (Blumensath 04) for Maslov Hierarchy – but runs (*not* plays) are pumpable, conditions given as lengths of runs and configuration size.
- 2 Logical characterisations.
E.g. MSOL for regular languages (Büchi 60). Characterisation of CFL using quantification over matchings (LST 94).
- 3 Complexity-theoretic characterisations.
Pace (Engelfriet 83, 91): characterisations of languages accepted by alternating / two-way / multi-head / space-auxiliary order- n PDA as time-complexity classes (but no result for Maslov Hierarchy itself)
- 4 Relationship with Chomsky Hierachy. E.g. is level 3 context-sensitive?

Why study the two families of generators?

They are relevant to both **semantics** and **verification**:

- 1 Recursion schemes are an old and influential formalism for the **semantical analysis** of imperative and functional programs (Nivat 75, Damm 82). They are a compelling model of computation for higher-order functional programs.
- 2 Pushdown automata characterize the control flow of 1st-order (recursive) procedural programs. Pushdown checkers (e.g. MOPED) are essential back-end engines of state-of-the-art software model checkers (e.g. SLAM, Terminator).
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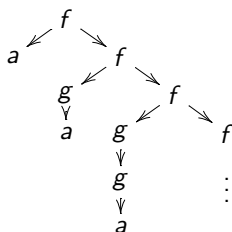
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A challenge problem in higher-order verification

Example: Consider $\llbracket G \rrbracket$ on the right

- $\varphi_1 =$ “Infinitely many f -nodes are reachable”.
- $\varphi_2 =$ “Only finitely many g -nodes are reachable”.



Every node on the tree satisfies $\varphi_1 \vee \varphi_2$.

Let $\mathbf{RecSchTree}_n$ be the class of Σ -labelled trees generated by order- n recursion schemes.

Is the “MSO Model-Checking Problem for $\mathbf{RecSchTree}_n$ ” decidable?

- INSTANCE: An order- n recursion scheme G , and an MSO formula φ
- QUESTION: Does the Σ -labelled tree $\llbracket G \rrbracket$ satisfy φ ?

Why study MSO logic?

Because it is the **gold standard** of logics for describing model-checking properties.

- **MSO is *very expressive*.** Over graphs, MSO is more expressive than the modal μ -calculus, into which all standard temporal logics (e.g. LTL, CTL, CTL*, etc.) can embed.
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Review: Representing trees as logical structures

Represent a Σ -labelled tree $t : \text{dom}(t) \rightarrow \Sigma$ as a logical structure

$$\langle \text{dom}(t), \langle \mathbf{d}_i : 1 \leq i \leq m \rangle, \langle \mathbf{p}_f : f \in \Sigma \rangle \rangle$$

- Parent-child relationship between nodes: $\mathbf{d}_i(x, y) \equiv$ “ y is i -child of x ”
- Node labelling: $\mathbf{p}_f(x) \equiv$ “ x has label f ” where f is a Σ -symbol

Monadic Second-Order Logic (for Σ -labelled trees)

First-order variables: x, y, z , etc. (ranging over **nodes**)

Second-order variables: X, Y, Z , etc. (ranging over **sets** of nodes
i.e. **monadic** relations)

MSO formulas are built up from **atomic formulas**:

- Parent-child relationship between nodes: $\mathbf{d}_i(x, y)$
- Node labelling: $\mathbf{p}_f(x)$
- Set-membership: $x \in X$

and closed under boolean connectives, first-order quantification ($\forall x. -, \exists x. -$) and second-order quantifications: ($\forall X. -, \exists X. -$).

Examples of MSO-definable properties

Several useful relations are definable:

- 1 Set inclusion (and hence equality): $X \subseteq Y \equiv \forall x. x \in X \rightarrow x \in Y$.
- 2 “Is-an-ancestor-of” or prefix ordering $x \leq y$ (and hence $x = y$):

$$\begin{aligned}\text{PrefCl}(X) &\equiv \forall x, y. y \in X \wedge \bigvee_{i=1}^m \mathbf{d}_i(x, y) \rightarrow x \in X \\ x \leq y &\equiv \forall X. \text{PrefCl}(X) \wedge y \in X \rightarrow x \in X\end{aligned}$$

Reachability property: “X is a path”

$$\begin{aligned}\text{Path}(X) &\equiv \forall x, y \in X. x \leq y \vee y \leq x \\ &\wedge \forall x, y, z. x \in X \wedge z \in X \wedge x \leq y \leq z \rightarrow y \in X\end{aligned}$$

$$\text{MaxPath}(X) \equiv \text{Path}(X) \wedge \forall Y. \text{Path}(Y) \wedge X \subseteq Y \rightarrow Y \subseteq X.$$

E.g. MSO can express “ \exists infinitely many f -labelled nodes”

A set of nodes is a **cut** if no two nodes in it are \leq -compatible, and it has a non-empty intersection with every maximal path.

$$\begin{aligned}\text{Cut}(X) &\equiv \forall x, y \in X . \neg(x \leq y \vee y \leq x) \\ &\wedge \forall Z . \text{MaxPath}(Z) \rightarrow \exists z \in Z . z \in X\end{aligned}$$

Lemma

A set X of nodes in a finitely-branching tree is finite iff there is a cut C such that every X -node is a prefix of some C -node.

$$\text{Finite}(X) \equiv \exists Y . \text{Cut}(Y) \wedge \forall x \in X . \exists y \in Y . x \leq y$$

Hence “there are finitely many nodes labelled by f ” is expressible in MSO by $\exists X . \text{Finite}(X) \wedge \forall x . \mathbf{p}_f(x) \rightarrow x \in X$.

But “MSO cannot count”: E.g. “ X has twice as many elements as Y ”.

A (selective) survey of MSO-decidable structures: up to 2002

- Rabin 1969: Regular trees. “Mother of all decidability results in Verification.”
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- Caucal 1996 Prefix-recognizable graphs (ϵ -closures of configuration graphs of pushdown automata, Stirling 2000).
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PushdownTree $_n\Sigma$ = Trees generated by order- n pushdown automata.
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Safety is a set of constraints on where variables may occur in a term.

Definition (Damm TCS 82, KNU FoSSaCS'02)

An order-2 equation is **unsafe** if the RHS has a subterm P s.t.

- 1 P is order 1
- 2 P occurs in an **operand** position (i.e. as 2nd argument of application)
- 3 P contains an order-0 parameter.

Consequence: An order- i subterm of a safe term can only have free variables of order at least i .

Example (unsafe eqn): $F : (o \rightarrow o) \rightarrow o \rightarrow o \rightarrow o$, $f : o^2 \rightarrow o$, $x, y : o$.

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What is the point of safety?

Safety does have an important algorithmic advantage!

Theorem (Blum + O. TLCA 07, LMCS 09)

Substitution (hence β -red.) in safe λ -calculus can be safely implemented without renaming bound variables! Hence no fresh names needed.

Theorem

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(See (Blum + O. LMCS 09) for a study on the safe lambda calculus.)

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Infinite structures generated by recursion schemes: key questions

- 1 **MSO decidability:** Is safety a genuine constraint for decidability?
I.e. do trees generated by (arbitrary) recursion schemes have decidable MSO theories?
- 2 **Machine characterisation:** Find a hierarchy of automata that characterise the expressive power of recursion schemes.
I.e. how should the power of higher-order pushdown automata be augmented to achieve equi-expressivity with (arbitrary) recursion schemes?
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4 Graph families:

- ① **Definition:** What is a good definition of “graphs generated by recursion schemes”?
- ② **Model-checking properties:** What are the **decidable** (modal-) logical theories of the graph families?

Q1. Do trees in $\text{RecSchTree}_n\Sigma$ have decidable MSO theories?

Recent Progress:

Theorem (Aehlig, de Miranda + O. TLCA 2005)

Σ -labelled trees generated by order-2 recursion schemes (*whether safe or not*) have decidable MSO theories.

Theorem (Knapik, Niwinski, Urczyzn + Walukiewicz, ICALP 2005)

Modal μ -calculus model checking problem for homogenously-typed order-2 schemes (*whether safe or not*) is 2-EXPTIME complete.

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Yes: MSO decidability extends to all orders (O. LICS06).

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[This is the largest generically-defined MSO-decidable class of ranked trees (cf. Montanari + Puppis, LICS 2007).]

Two key ingredients:

- $\llbracket G \rrbracket$ satisfies modal mu-calculus formula φ
- \iff { Emerson + Jutla 1991 }
- APT \mathcal{B}_φ has accepting run-tree over generated tree $\llbracket G \rrbracket$
- \iff { **I. Transference Principle: Traversal-Path Correspondence** }
- APT \mathcal{B}_φ has accepting traversal-tree over computation tree $\lambda(G)$
- \iff { **II. Simulation of traversals by paths** }
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which is decidable.

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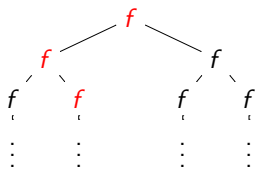
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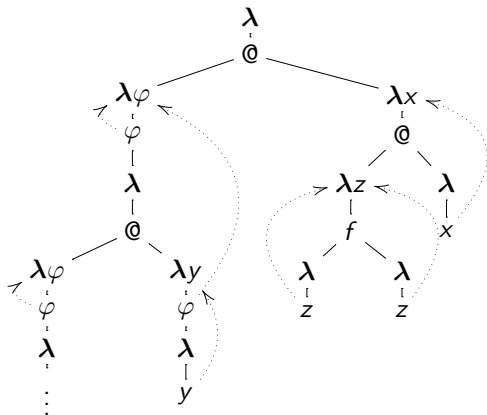
Transference principle, based on a theory of **traversals**

$$G : \begin{cases} S & = & FH \\ F\varphi & = & \varphi(F\varphi) \\ Hz & = & fzz \end{cases} \quad \mapsto \quad \overline{G} : \begin{cases} S & = & \lambda.\@F(\lambda x.\@H\lambda.x) \\ F & = & \lambda\varphi.\varphi(\lambda.\@F(\lambda y.\varphi(\lambda.y))) \\ H & = & \lambda z.f(\lambda.z)(\lambda.z) \end{cases}$$

$\llbracket G \rrbracket$



$\lambda(G)$



Idea: β -reduction is **global** (i.e. substitution changes the term being evaluated); game semantics gives an equivalent but **local** view.

A **traversal** (over the computation tree $\lambda(G)$) is a trace of the local computation that produces a path (over $\llbracket G \rrbracket$).

Theorem (Path-traversal correspondence)

Let G be an order- n recursion scheme.

- (i) There is a 1-1 correspondence between maximal paths p in (Σ -labelled) generated tree $\llbracket G \rrbracket$ and maximal traversals t_p over computation tree $\lambda(G)$.
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Proof is by game semantics.

Explanation (for game semanticists):

- Term-tree $\llbracket G \rrbracket$ is (a representation of) the game semantics of G .
- Paths in $\llbracket G \rrbracket$ correspond to **plays** in the strategy-denotation.
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Order-2 **collapsible** pushdown automata [HOMS, LiCS 08a] are essentially the same as **2PDA with links** [AdMO 05], and **panic automata** [KNUW 05].

Idea: Each stack symbol in 2-stack “remembers” the stack content at the point it was first created (i.e. $push_1$ ed onto the stack), by way of a pointer to some 1-stack underneath it (if there is one such).

Two new stack operations: $a \in \Gamma$ (stack alphabet)

- $push_1 a$: pushes a onto the top of the top 1-stack, together with a pointer to the 1-stack immediately below the top 1-stack.
- $collapse$ (= panic) collapses the 2-stack down to the prefix pointed to by the top_1 -element of the 2-stack.

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An example

Order-2 Collapsible Pushdown Automata (for word languages):

$$\langle \Sigma, Q, q_0, \Gamma, \Delta \subseteq (\Sigma \cup \{\epsilon\}) \times Q \times \Gamma \times Q \times Op_2, F \rangle$$

where $Op_2 := \{ \text{push}_2, \text{pop}_2, \text{pop}_1, \text{collapse} \} \cup \{ \text{push}_1 a \mid a \in \Gamma \}$.

Example. Starting from the empty 2-stack $[[[]]]$, what is the top-of-stack symbol after the following sequence of actions?

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2. $\text{push}_1 a$
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Collapsible pushdown automata: extending to all finite orders

In **order- n CPDA**, there are $n - 1$ versions of $push_1$, namely, $push_1^j a$, with $1 \leq j \leq n - 1$:

$push_1^j a$: pushes a onto the top of the top 1-stack, together with a pointer to the j -stack immediately below the top j -stack.

Example: Urzyczyn's Language U over alphabet $\{(,), *\}$

Definition (Aehlig, de Miranda + O. FoSSaCS 05) A U -word has 3 segments:

$$\underbrace{(\dots(\dots((\dots) \dots (\dots)) \dots (\dots)) \dots (\dots))}_{A} \underbrace{(\dots(\dots((\dots) \dots (\dots)) \dots (\dots))}_{B} \underbrace{*\dots*}_{C}$$

- Segment A is a prefix of a well-bracketed word that ends in $($, and the opening $($ is **not** matched in the entire word.
- Segment B is a well-bracketed word.
- Segment C has length equal to the number of $($ in segment A .

Examples

- 1 $((()((()((()*)***) \in U$
- 2 For each $n \geq 0$, we have $((^{(n)})^n (*^n ** \in U$. (Hence by “ $uvwxy$ Lemma”, U is not context-free.)

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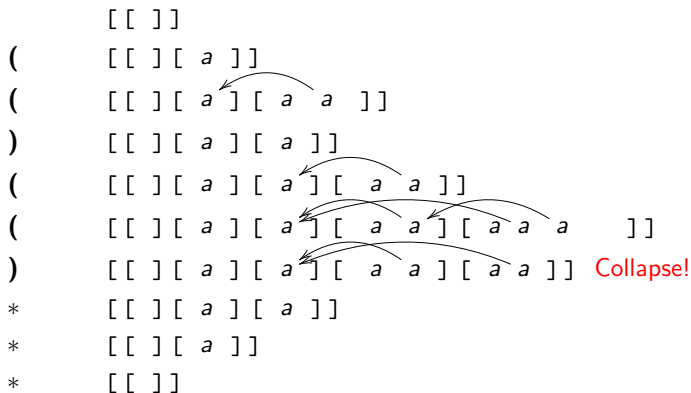
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Recognising U by a (det.) 2CPDA. E.g. $((()) (**))^{***} \in U$
 (Ignoring control states for simplicity)

Upon reading	Do
{	$push_2 ; push_1 a$
}	pop_1
first *	$collapse$
subsequent *	pop_2



What does the depth of the top 1-stack mean?

E.g. Urzyczyn's Language U (cont'd)

Observation

- 1 U is recognisable by a **deterministic order-2 CPDA**.
- 2 Equivalently (thanks to [AdMO 05]) U is recognisable by a **non-deterministic order-2 PDA** — because of the need to guess the transition from segment A to segment B.

Conjecture

U is not recognisable by a deterministic order-2 PDA.

(Related to the Safety Conjecture - more anon.)

Exercise (moderately hard). Give an order-2 recursion scheme that generates U .

Q2: Recursion schemes are equi-expressive with CPDA

Theorem (Equi-Expressivity, Hague, Murawski, O. + Serre LICS'08)

For each $n \geq 0$, order- n recursion schemes and order- n collapsible PDA are equi-expressive for Σ -labelled trees. I.e. $\mathbf{RecSchTree}_n\Sigma = \mathbf{CPDATree}_n\Sigma$

(Proof uses theory of **traversals**, based on game semantics.)

Consequences:

- 1 **Kleene's Problem:** What computing power is required to compute order- n lambda-definable functionals?
The Theorem gives a syntax-independent characterisation of pure simply-typed lambda-calculus with recursion.
- 2 A **new proof** of the MSO decidability of trees generated by order- n recursion schemes.

Open Problem. Find a new proof of “RS \rightarrow CPDA” without using game semantics.

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Q3: Does safety constrain expressivity?

Case 1: Word languages. Conjecture: Yes; but note

Theorem (Aehlig, de Miranda + O., FoSSaCS 2005)

At order 2, there are no inherently unsafe word languages. I.e. for every unsafe order-2 recursion scheme, there is a safe (non-deterministic) order-2 recursion scheme that generates the same language.

Case 2: Trees. Conjecture: Yes.

The Safety Conjecture

For each $n \geq 2$, there is a tree generated by an unsafe order- n recursion scheme but not by any safe order- n recursion scheme.

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Q3: Does safety constrain expressivity?

Case 3: Graphs. Yes.

Theorem (Hague, Murawski, O. + Serre LICS 2008a)

There is an order-2 CPDA graph that is not generated by any order-2 PDA.

(See example graph later.)

A survey of graph families with model-checking properties

Causal Graph Hierarchy

Ground-term tree rewriting (Löding 02)

Automatic graphs (Hodgson 76, KN 94)

Rational graphs

Decidable?			
MSO	μ	FO(R)	FO
yes	yes	yes	yes
no	no	yes	yes
no	no	no	yes
no	no	no	no

A survey of graph families with model-checking properties

Caucal's Graph Hierarchy

C

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Decidable?			
MSO	μ	FO(R)	FO
yes	yes	yes	yes
no	yes	?	?
no	no	yes	yes
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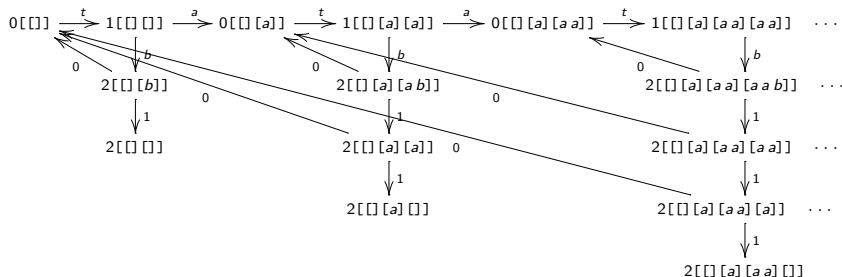
Question

Is there a generically-defined family **C** of graphs that have decidable modal- μ calculus theories but undecidable MSO theories?

Yes. See construction on next slide (HMOS, LiCS 08a).

Configuration graphs of (order-2) CPDA is not MSO-decidable

An order-2 CPDA graph: MSO-interpretable into the infinite half-grid.



To our knowledge CPDA graphs are the first “natural” generically-defined graph families that have decidable modal mu-calculus theories but undecidable MSO theories.

Q4: Model-checking properties of CPDA graphs

Theorem (Hague, Murawski, O and Serre, LiCS 2008a)

- 1 For each $n \geq 0$, the decidability of modal μ -calculus model-checking problem for configuration graphs of order- n CPDA is n -EXPTIME complete.
- 2 Equivalently solvability of parity games over order- n CPDA graphs is n -EXPTIME complete.