

Higher-Order Procedural Languages. E.g. ML, C, Reynold's Idealized Algol (IA).

Recent results obtained using fully abstract game semantics:

Fragments of finitary IA	Is observational equivalence decidable?
2nd-order	Yes. (Ghica+McCusker 00)
2nd-order + iteration 2nd-order + recursion	Yes (GM 00); PSPACE-complete (Murawski 03) No. (Ong LICS 02)
3rd-order 4th-order or higher	Yes: reduction to DPDA Equivalence. (Ong 02) No. (Murawski LICS 03)
3rd-order + iteration	Yes. Rationally innocent strategies.

Computaton: E.g. Hierarchy of purely functional programs defined by recursion (i.e. essentially type-levels of PCF)?

Properties: Other (or weaker) than observational equivalence? E.g. decidable fragments of MSO logic.

Pushdown Hierarchies and the Safe Lambda-Calculus

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Four Hierarchies of Finitely-Presentable Structures

Class of Structures	Hierarchy
string languages	Chomsky (1960's)
string languages	Maslov (1974) and others
(term) trees	Knapik-Niwinski-Urzyczyn (2002)
labelled graphs	Caucal (2002)

Review: Chomsky Hierarchy

A hierarchy of (string) languages. Four classes:

Type	Language Classes	Models of Computation
Type-0	Regular	Finite automaton
Type-1	Context-free	Pushdown automaton
Type-2	Context-sensitive	Linearly bounded automaton
Type-3	R. e.	Turing machines

0. Background

I. Maslov Hierarchy: Higher-Order Pushdown Automata

II. OI Hierarchy: Safe Lambda Calculus and Higher-Order Grammars

III. Knapik-Niwinski-Urzyczyn Hierarchy of Pushdown Trees

IV. Problems, a Result and an Example

V. Explanation and Proof Idea

VI. Further Directions

Level- n Stores

Fix a stack alphabet Γ with distinguished \perp . Define $\perp_1 = [\perp]$, $\perp_{k+1} = [\perp_k]$.

A **1-store** is a non-empty sequence $[a_1, \dots, a_l]$ of elements of Γ .

An **$(n + 1)$ -store** is a non-empty sequence $[s_1, \dots, s_l]$ of n -stores.

For $n \geq 2$, **level- n operations**, Op_n : defined over n -stores

$$\left\{ \begin{array}{l} \text{push}_n [s_1, \dots, s_l] = [s_1, s_1, \dots, s_l] \\ \text{push}_k [s_1, \dots, s_l] = [\text{push}_k s_1, s_2, \dots, s_l], \quad 2 \leq k < n \\ \text{push}_1^a [s_1, \dots, s_l] = [\text{push}_1^a s_1, s_2, \dots, s_l] \\ \text{pop}_n [s_1, \dots, s_l] = [s_2, \dots, s_l] \\ \text{pop}_k [s_1, \dots, s_l] = [\text{pop}_k s_1, s_2, \dots, s_l], \quad 1 \leq k < n \\ \text{id} [s_1, \dots, s_l] = [s_1, \dots, s_l] \end{array} \right.$$

$$\begin{array}{l} \text{top}_n [s_1, \dots, s_l] = s_1 \\ \text{top}_k [s_1, \dots, s_l] = \text{top}_k s_1, \quad 1 \leq k < n \end{array}$$

($\text{push}_k s$ undefined if $\text{top}_k s$ has only 1 element.)

An infinite hierarchy of (string) languages, arguably “more natural” (systematic, “unifying”) than Chomsky’s.

Levels	Language Classes
0	Regular
1	Context-free
2	Indexed languages [Aho68]
...	...

Three equivalent devices for defining the level- $(n + 1)$ languages inductively:

- (1) Level- n **generalized indexed languages** (Maslov '74, '76)
Raising a language to a power (given by a language).
- (2) Level- n **pushdown automata** (Maslov '74, '76, Fisher '68, Greibach '70)
Level- $(n + 1)$ store is a stack of level- n stores.
- (3) Level- n grammars definable in a system of **derived types** (Damm '82, Damm-Goerdt '86)

n PDA: Level- n Pushdown Automaton $A = \langle Q, \Sigma, \Gamma, q_0, \Delta \rangle$

Maslov 76 (Greibach 70). We follow definition in [KNU02].

By definition, OPDAs are DFAs, and 1PDAs are PDAs. For $n \geq 2$, we have:

- Input alphabet Σ , Stack alphabet Γ .
- Control states Q , initial state q_0
- Transition relation: $\Delta \subseteq Q \times (\Sigma \cup \{\epsilon\}) \times (\Gamma \cup \{\perp\}) \times Q \times Op_n$

Configuration: (q, s) where s is an n -store. Initial configuration: (q_0, \perp_n) .

Define: $(q, s) \xrightarrow{a} (q', s')$ just if $(q, a, \text{top}_1(s), q', \theta) \in \Delta$ where $\theta s = s'$.

Inductively $(q, s) \xrightarrow{wa} (q', s')$ just if $(q, s) \xrightarrow{w} (q'', s'')$ and $(q'', s'') \xrightarrow{a} (q', s')$, for some q'', s'' .

A **accepts** $w \in \Sigma^*$ just if $(q_0, \perp_n) \xrightarrow{w} (q, \perp_n)$, some q .

$\{a^n b^n c^n : n \geq 1\}$ (not context-free)

Idea: Check $a^n b^n$ using the top 1-store, then check c^n against length of 2-store.

$$\begin{aligned}
& q_0, [[\perp]] \\
\frac{a}{\rightarrow} & q_0, [[Z, \perp], [\perp]] \\
\frac{a}{\rightarrow} & q_0, [[Z, Z, \perp], [Z, \perp], [\perp]] \\
\frac{a}{\rightarrow} & q_0, [[Z, Z, Z, \perp], [Z, Z, \perp], [Z, \perp], [\perp]] \\
\frac{b}{\rightarrow} & q_1, [[Z, Z, \perp], [Z, Z, \perp], [Z, \perp], [\perp]] \\
\frac{b}{\rightarrow} & q_1, [[Z, \perp], [Z, Z, \perp], [Z, \perp], [\perp]] \\
\frac{b}{\rightarrow} & q_1, [[\perp], [Z, Z, \perp], [Z, \perp], [\perp]] \\
\frac{c}{\rightarrow} & q_2, [[Z, Z, \perp], [Z, \perp], [\perp]] \\
\frac{c}{\rightarrow} & q_2, [[Z, \perp], [\perp]] \\
\frac{c}{\rightarrow} & q_2, [[\perp]]
\end{aligned}$$

OI Hierarchy: Safe Types

Derived types: Damm '82; equivalently **Safety** (syntactic constraint): Knapik *et al.*

Let A range over simple types i.e. $A ::= o \mid A \rightarrow A$. Each A can be uniquely written (A_1, \dots, A_n, o) , meaning $A_1 \rightarrow \dots \rightarrow A_n \rightarrow o$.

Define: $\text{order}(o) = 0$; $\text{order}(A \rightarrow B) = \max(\text{order}(A) + 1, \text{order}(B))$.

Definition o is **safe**. For $n \geq 1$, $A = (A_1, \dots, A_n, o)$ is **safe** just if $\text{order}(A_1) \geq \text{order}(A_2) \geq \dots \geq \text{order}(A_n)$, and each A_i is safe.

Assume $A = (\underbrace{A_{11}, \dots, A_{1l_1}}_{\overline{A_1}}, \dots, \underbrace{A_{r1}, \dots, A_{rl_r}}_{\overline{A_r}}, o)$ is safe; write

$$A = (\overline{A_1} \mid \dots \mid \overline{A_r} \mid o)$$

to mean: all types in each sequence $\overline{A_i} = A_{i1}, \dots, A_{il_i}$ have the same order n_i (say), and $i > j \iff n_i > n_j$, making explicit the **type partitions**.

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Safe λ -Calculus: System \mathcal{S} Typing Rules

$$\frac{(\overline{A_1} \mid \dots \mid \overline{A_n} \mid B) \text{ safe} \quad b \text{ is a type-}B \text{ constant}}{\overline{x_1} : \overline{A_1} \mid \dots \mid \overline{x_n} : \overline{A_n} \vdash b : B}$$

$$\frac{(\overline{A_1} \mid \dots \mid \overline{A_n} \mid A_{ni}) \text{ safe}}{\overline{x_1} : \overline{A_1} \mid \dots \mid \overline{x_n} : \overline{A_n} \vdash x_{ni} : A_{ni}}$$

$$\frac{\overline{x_1} : \overline{A_1} \mid \dots \mid \overline{x_{n+1}} : \overline{A_{n+1}} \vdash M : B}{\overline{x_1} : \overline{A_1} \mid \dots \mid \overline{x_n} : \overline{A_n} \vdash \lambda \overline{x_{n+1}}. M : (\overline{A_{n+1}} \mid B)}$$

$$\frac{\Gamma \vdash M : (\overline{B_1} \mid \dots \mid \overline{B_m} \mid o) \quad \Gamma \vdash N_1 : B_{11} \dots \Gamma \vdash N_{l_1} : B_{1l_1}}{\Gamma \vdash MN_1 \dots N_{l_1} : (\overline{B_2} \mid \dots \mid \overline{B_m} \mid o)}$$

When forming abstraction, **all variables** of the (right-most) type-partition must be abstracted. When forming application, the operator-term must be applied to **all operand-terms** (one for each type) of the left-most type-partition.

Observations. Suppose $\overline{x_1} : \overline{A_1} \mid \cdots \mid \overline{x_n} : \overline{A_n} \vdash M : B$ is \mathcal{S} -valid, where $B = (\overline{B_1} \mid \cdots \mid \overline{B_m} \mid o)$. Then

- (i) $(\overline{A_1} \mid \cdots \mid \overline{A_n} \mid \overline{B_1} \mid \cdots \mid \overline{B_m} \mid o)$ is safe.
- (ii) Any free variable of M has order $\geq \text{order}(M)$.
- (iii) For any subterm $\lambda\phi.N$ of M , if variable x occurs in N and $\text{order}(x) < \text{order}(\phi)$ then x is bound in N .

Examples

1. $F : ((o, o), o, o, o), \phi : (o, o), x : o, y : o \vdash F(F\phi x)xy : o$ is not safe:
Reason: $F : ((o, o), o, o, o), \phi : (o, o), x : o \vdash F\phi x : (o, o)$ is not safe.
2. But $F : ((o, o), o, o, o), \phi : (o, o) \vdash F\phi a : (o, o)$ is safe for constant a .
3. $F : ((o, o), o, o, o), \phi : (o, o), x : o, y : o \vdash F\phi xy : o$ is safe.

Lemma. "In safe λ -calculus, it is safe not to rename bound variables afresh when performing substitution."

Proof idea. Take $\text{order}(\Phi) = 2, \text{order}(\phi) = \text{order}(\psi) = 1, \text{order}(x) = 0$. Suppose we do not rename bound variables in:

$$\underbrace{(\cdots \lambda\Phi.(\cdots \lambda x. \cdots \phi \cdots) \cdots \lambda\psi.(\cdots \phi \cdots) \cdots)}_M [G\Phi\psi x/\phi]$$

Three types of variable capture may occur.

Type-1 capture: variable bound has order $> \text{order}(\phi)$

$$(\cdots \lambda\Phi. \underbrace{(\cdots \phi \cdots)}_L \cdots) [G\Phi\psi x/\phi] \text{ becomes } \cdots \lambda\Phi. (\cdots (G\Phi\psi x) \cdots) \cdots.$$

Impossible because $\lambda\Phi.L$ safe implies L has no free variables of order $< \text{order}(\Phi)$.

Capture-avoiding substitution is commonly achieved using "Barendregt's Variable Convention".

The key clause in definition of **capture-avoiding** substitution:

$$(\lambda x.M)[N/y] \stackrel{\text{def}}{=} \lambda z.((M[z/x])[N/y]) \text{ where "z is fresh"}$$

Suppose one is restricted to only n fresh names, for fixed n . There exists a λ -term such that variable-capture occurs in some reduction sequence from it.

Happily in **safe λ -calculus**, it is safe to use **capture-permitting** substitution when contracting β -redexes.

Proviso: We only perform $M[N_1/x_1, \cdots, N_n/x_n]$ provided:

- (i) x_1, \cdots, x_n are **all** the free variables of same order in M , and
- (ii) The n replacement actions take place **simultaneously**.

Type-2 capture: variable bound has order $< \text{order}(\phi)$

$$(\cdots \lambda x. (\cdots \phi \cdots) \cdots) [G\Phi\psi x/\phi] \text{ becomes } \cdots \lambda x. (\cdots (G\Phi\psi x) \cdots) \cdots.$$

Impossible because $\underbrace{G\Phi\psi x}_N$ (of order 1) safe implies N has no free variables of order < 1 .

Type-3 capture: variable bound has order $= \text{order}(\phi)$

$$\underbrace{(\cdots \lambda\psi. (\cdots \phi \cdots) \cdots)}_M [G\Phi\psi x/\phi] \text{ becomes } (\cdots \lambda\psi. (\cdots (G\Phi\psi x) \cdots) \cdots).$$

Impossible because abstraction formation rule would force M to be $(\cdots \lambda\psi\phi. (\cdots \phi \cdots) \cdots)$, making ϕ a bound variable of M .

Higher-Order Grammar

Fix a **typed alphabet** Σ of symbols. Two versions:

- For generating **string languages**: all Σ -symbols of type (o, o) with distinguished end-of-word marker $e : o$. E.g. for $a, b : (o, o)$, $a(be)$ corresponds to word ab .
- For generating **term-trees**: all Σ -symbols of order at most 1 (as “function symbols”).

Level- n Grammar: $G = \langle N, V, \Sigma, \mathcal{R}, S \rangle$

- N set of typed non-terminals, with start $S \in N$; and V set of typed variables
- \mathcal{R} is finite set of rules

$$F x_1 \cdots x_n \rightarrow E$$

where $F : (A_1, \dots, A_m, o) \in N, x_i \in V, x_1 : A_1, \dots, x_m : A_m \vdash E : o$
an **applicative** term-in-context with “constants” from $N \cup \Sigma$.

Say G is **n -level grammar** if highest order of $F \in \mathcal{R}$ is n , and **safe** if all types and terms occurring in the definition are safe.

OI Hierarchy = Maslov Hierarchy

Theorem. (Damm-Goerdt). A string language is accepted by an n PDA iff it is generated by some **safe** n -grammar.

Example: A safe 2-grammar that generates $\{a^n b^n c^n : n \geq 1\}$

$$\left\{ \begin{array}{ll} S \rightarrow a(ACe) & B\phi x \rightarrow b(\phi(Cx)) \\ A\phi x \rightarrow a(A(B\phi)x) & B\phi x \rightarrow cx \\ A\phi x \rightarrow b(\phi x) & Cx \rightarrow cx \end{array} \right.$$

$$\begin{aligned} S &\rightarrow a(ACe) \\ &\rightarrow a^2(A(BC)e) \\ &\rightarrow a^3(A(B(BC))e) \\ &\rightarrow a^3b(B(BC)e) \\ &\rightarrow a^3b^2(BC(Ce)) \\ &\rightarrow a^3b^3(C(C(Ce))) \\ &\rightarrow a^3b^3c(C(Ce)) \\ &\rightarrow a^3b^3c^2(Ce) \\ &\rightarrow a^3b^3c^3e \end{aligned}$$

(An example of an unsafe 2-grammar later on.)

Open problems concerning Maslov Hierarchy

Not much is known about level-3 and above.

1. Pumping Lemma (or Myhill-Nerode-type results)

There are “pumping lemmas” for levels 0, 1 and 2 ([Hay73, Gil96]).

Pace Blumensath '04 for whole Maslov Hierarchy – runs are pumpable, conditions given as lengths of runs and configuration size.

2. Logical Characterization.

Regular languages are exactly those that are MSO definable (Büchi '60).

There is a characterization of context-free languages using quantification over matchings [LST94].

3. Complexity-Theoretic Characterization.

Engelfriet '83, '91: characterizations of languages accepted by alternating / two-way / multi-head / space-auxiliary n PDA's in terms of time-complexity classes (but no result for Maslov Hierarchy itself).

4. Relationship with Chomsky Hierarchy. E.g. Is n PDA context-sensitive, for $n \geq 3$?

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Knapik-Niwiński-Urzyczyn Hierarchy of Pushdown Trees

Let G be a deterministic n -grammar. Define the Σ -tree, $\llbracket G \rrbracket$, to be the possibly infinite “term tree” generated by unfolding the rules in G *ad infinitum*.

Theorem [KNU02]. A Σ -tree is generated by a safe (deterministic) n -grammar iff it is generated by an n PDA.

Fix a typed alphabet Σ of symbols of order at most 1.

A Σ -tree is a map $t : T \rightarrow \Sigma$ where T is a prefix-closed subset of ω^* , and for $k \geq 0$, whenever $t(w) : o^k \rightarrow o$ then w has exactly k successors in T which are $w1, \dots, wk$.

A Σ -tree is just a (possibly infinite) applicative term constructed using symbols from Σ .

Let the maximum of arities of symbols in Σ be m_Σ . A Σ -tree t can be viewed as a **logical structure over the relational vocabulary**

$$R_\Sigma = \{p_f : f \in \Sigma\} \cup \{d_i : 1 \leq i \leq m_\Sigma\}$$

with $\text{ar}(p_f) = 1$ and $\text{ar}(d_i) = 2$:

$$\mathbf{t} = \langle \text{dom}(t), \{p_f^t : f \in \Sigma\}, \{d_i^t : 1 \leq i \leq m_\Sigma\} \rangle$$

where $p_f^t = \{w \in \text{dom}(t) : t(w) = f\}$ and $d_i^t = \{(w, wi) : wi \in \text{dom}(t)\}$.

A remarkable decidability result

Monadic Second-Order Logic (MSO).

Extension of first-order logic with monadic second-order variables (X, Y, Z, \dots) , ranging over sets of elements. Fix a relational vocabulary $R = \{r_1, \dots, r_n\}$ where r_i is a relation symbol with arity $\text{ar}(r_i)$. The atomic formulas over R are

$$X(z), \quad x = y, \quad r_i(x_1, \dots, x_{\text{ar}(r_i)});$$

we have the usual boolean connectives, and quantification over both types of variables.

MSO is expressive: E.g. “a node-set is finite”, or “forms a path”, but MSO cannot count.

Theorem [KNU02]. For $n \geq 0$, for any safe deterministic n -grammar G , the MSO theory of the Σ -tree $\llbracket G \rrbracket$ is decidable.

- Rabin 1969: “Mother of all decidability results”: Second-order theory of two successors (S^2S) has a decidable MSO theory.
- Muller and Schupp 1985: Pushdown graphs have decidable MSO theories.
- Courcelle 1995: Σ -trees generated by 1-grammars have decidable MSO theories.
- Knapik, Niwiński and Urzyczyn 2001: Σ -trees generated by safe deterministic 2-grammars have decidable MSO theories.
- KNU '02: For all n , the MSO theories of Σ -trees generated by safe deterministic n -grammars are decidable.

A reduction argument: They exhibit effective transformations of level- $(n + 1)$ pushdown trees t to level- n pushdown trees \hat{t} , and of MSO-formulas ϕ to $\hat{\phi}$, such that $t \models \phi \iff \hat{t} \models \hat{\phi}$.

Crucial dependence on safety.

The level- n Σ^+ -tree \hat{t} uses additional symbols from

$$\{ @ : (o, o, o) \} \cup \underbrace{\{ x_1 : o, \dots, x_l : o \}}_L \cup \{ \lambda x : (o, o) : x \in L \}$$

and has “back edges” from type-0 x to the binding λx . (So \hat{t} is really the corresponding Lamping graph.)

Both crucial conditions

- L (obtained from G), and hence Σ^+ , is finite
- The structure \hat{t} is MSO-definable in the structure t .

require the generating grammar G to be safe.

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- (1) (String languages) Can every string language generated by an unsafe n -grammar be generated by a **safe** n -grammar?

Expressiveness: Is safety a real or spurious typing constraint for defining languages?

- (1') (Term trees) Can every Σ -tree generated by an unsafe n -grammar be generated by a **safe** n -grammar?

- (2) Is the MSO theory of a Σ -tree generated by an unsafe n -grammar decidable?

Note: Yes to (1') implies yes to (2), thanks to [KNU02].

To date, we have only solved a small part of (1).

Theorem. Every string language generated by an **unsafe** 2-grammar is generated by a (non-deterministic) **safe** 2-grammar.

Example: Urzyczyn's(?) Language U

$$w \underbrace{* \cdots *}_n$$

- w is a **proper** prefix of a well-bracketed word that ends with a (
- each parenthesis in w is **implicitly labelled** with a number, and n is the label of the last parenthesis (of w).

Labelling rules:

- Each (is labelled with the number of ('s read thus far.
- Each) is labelled with the label of the parenthesis that precedes the matching (.

Example.

(((()) (() (())) (()) * *

1 2 3 4 3 2 5 6 5 7 8 7 5 2 9 10 9 2

An unsafe 2-grammar that generates U

Configuration: $\langle \gamma, y, z \rangle$ where

- γ is a list of future)-labels
- y is the number of ('s read thus far
- z is the label of the last parenthesis read,

Note: $|\gamma|$ is the number of unmatched ('s at that point.

Transition rules:

$$\begin{aligned} \langle x : \phi, y, z \rangle &\xrightarrow{(} \langle z : x : \phi, y + 1, y + 1 \rangle \\ \langle x : \phi, y, z \rangle &\xrightarrow{)} \langle \phi, y, x \rangle \\ \langle x : \phi, y, z \rangle &\xrightarrow{*} z \\ z + 1 &\xrightarrow{*} z \end{aligned}$$

An unsafe 2-grammar that generates U

$$\begin{aligned} \Sigma &= \{ (: (o, o),) : (o, o), * : (o, o), e : o \} \\ N &= \{ S : o, D : ((o, o, o), o, o, o, o), G : (o, o, o), F : (o, o) \} \end{aligned}$$

with variables $\phi : (o, o, o)$ and $x, y, z : o$. The corresponding rules are:

$$\begin{aligned} D \phi x y z &\rightarrow ((D(D\phi x)z(Fy)(Fy)) \\ D \phi x y z &\rightarrow)(\phi y x \\ D \phi x y z &\rightarrow * z \\ F x &\rightarrow * x \\ S &\rightarrow D G e e e \end{aligned}$$

Question: Is there a safe 2-grammar that generates U ?

An earlier conjecture(?) was that the answer is no.

A characterization of U -words

Idea: Each U -word has a unique partition into 3 parts:

$$\underbrace{\cdots \cdots (\cdots) \cdots \cdots}_{(1)} \underbrace{\cdots \cdots}_{(2)} \underbrace{* \cdots *}_{(3)}$$

where

- (1) is prefix of a well-bracketed word such that no prefix of it is well-bracketed, and has n occurrences of (
- (2) is well-bracketed
- (3) has length n .

Example

(((()) (() (())) (()) * *

1 2 3 4 3 2 5 6 5 7 8 7 5 2 9 10 9 2

Verify the 3-partition of U -words in three stages:

$$\underbrace{(\dots(\dots(}_{(1)} \underbrace{)\dots)\dots)}_{(2)} \underbrace{*\dots*}_{(3)}$$

(1) Use the top 1-store to check word read thus far is a prefix of a well-bracketed word such that no prefix of it is well-bracketed; use push_2 to count the number of '('s read.

Non-deterministically decide to enter Stage 2 after reading a '('.

(2) Using only the top 1-store, check word read in Stage 2 is well-bracketed.

Enter Stage 3 on reading '*'.

(3) Check the number of '*'s read equals the number of 1-stores stacked, using pop_2 .

Thus U is an indexed language, and thanks to [DG86]

Lemma. There is a safe 2-grammar that generates U .

Transforming a 2-grammar to a 2PDA

Recall [KNU02]: a Σ -tree is generated by a safe 2-grammar iff it is generated by a 2PDA.

Given a 2-grammar G . Define a 2PDA A_G :

- Stack alphabet: subterms of rhs of G -rules
- Control states: q_0, q_1, \dots, q_m where m is largest arities of Σ -symbols.
- **Configurations**
 - { (q_0, s) meaning "evaluating $\text{top}_1(s)$ i.e. working out the head symbol of $\text{top}_1(s)$ "
 - { $(q_i, s), i \geq 1$: meaning "working out (the head symbol of) the i -th argument of $\text{top}_1(s)$ "

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Rules of 2PDA A_G (KNU '02)

Every variable that occurs in a stack item is a formal parameter of the head symbol (which must be a non-terminal) of the item just below in the stack.

$$\begin{aligned} (q_0, D\bar{t}) &\xrightarrow{\epsilon} (q_0, \text{push}_1 \text{rhs}(D)) \\ (q_0, f\bar{t}) &\xrightarrow{[f,i]} (q_i, \text{id}) \quad \text{if } 0 < i \leq \text{ar}(f) \\ (q_0, a) &\xrightarrow{a} \text{accept} \quad \text{if } \text{ar}(a) = 0 \\ (q_0, x_j) &\xrightarrow{\epsilon} (q_j, \text{pop}_1) \\ (q_0, \varphi_j t_1 \dots t_n) &\xrightarrow{\epsilon} (q_j, \text{push}_2 ; \text{pop}_1) \\ j \geq 1, (q_j, \$t_1 \dots t_n) &\xrightarrow{\epsilon} \begin{cases} (q_0, t_j) & \text{if } j \leq n \text{ (argument present)} \\ (q_{j-n}, \text{pop}_2) & \text{if } j > n \text{ (argument missing)} \end{cases} \end{aligned}$$

Example: An unsafe grammar

$S \rightarrow Dgab$
 $D@xz \rightarrow h (D(D@x)z(@z)) (H(fz)x) (@z)$
 $H@x \rightarrow @x$

(To save writing, leave state q_0 and ϵ -transition out.)

$[[Dgab, S]]$
 $h1 \quad [[D(D@x)z(@z), Dgab, S]]$
 $h3 \quad [[@z, D(D@x)z(@z), Dgab, S]]$
 $[[D@x, Dgab, S], [@z, D(D@x)z(@z), Dgab, S]]$
 $h2 \quad [[H(fz)x, D@x, Dgab, S], [@z, D(D@x)z(@z), Dgab, S]]$
 $[[@x, H(fz)x, D@x, Dgab, S], [@z, D(D@x)z(@z), Dgab, S]]$

$D@xz \rightarrow h (D(D@x)z(@z)) (H(fz)x) (@z)$

$H@x \rightarrow @x$

$[[fz, D@x, Dgab, S], [@x, H(fz)x, D@x, Dgab, S],$
 $[@z, D(D@x)z(@z), Dgab, S]]$
 $f1 \quad [[z, D@x, Dgab, S], [@x, H(fz)x, D@x, Dgab, S],$
 $[@z, D(D@x)z(@z), Dgab, S]]$
 $q3 \quad [[D@x, Dgab, S], [@x, H(fz)x, D@x, Dgab, S],$
 $[@z, D(D@x)z(@z), Dgab, S]]$
 $q1 \quad [[@x, H(fz)x, D@x, Dgab, S], [@z, D(D@x)z(@z), Dgab, S]]$
 \dots
 $q2 \quad [[Dgab, S], [@z, D(D@x)z(@z), Dgab, S]]$
 $[[a, S], [@z, D(D@x)z(@z), Dgab, S]]$

2PDAL: 2PDA with Links

The word $h1.h3.h2.f1.a$ is **not** in the branch language of $\llbracket G \rrbracket$. Transformation works only for safe n -grammars.

How to remedy it? Idea:

We do a $push_2$ (followed by a pop_1) on account of a level-1 head variable ϕ of the top of stack.

Why? So that the missing arguments of ϕ , if needed later, can be accessed from the associated 1-store buried somewhere in the stack.

After the $push_2$, make an explicit (and fresh) link from the subterm pointed to by ϕ , to the 1-store just below. So that subsequently when we do a corresponding pop_2 , we will do as many pop_2 as required to reach the 1-store thus linked.

Indicate start and end of a link by superscripts $\langle n+ \rangle$ and $\langle n- \rangle$ respectively, for $n \geq 0$.

Of course, we will need an **unbounded(!)** number of such links.

Example: Running 2PDAL

$$\left\{ \begin{array}{l} S \rightarrow Dgab \\ D\phi xz \rightarrow h (D(D\phi x)z(\phi z)) (H(fz)x) (\phi z) \\ H\phi x \rightarrow \phi x \end{array} \right.$$

$[[Dgab, S]]$
 $\xrightarrow{h1} [[D(D\phi x)z(\phi z), Dgab, S]]$
 $\xrightarrow{h3} [[\phi z, D(D\phi x)z(\phi z), Dgab, S]]$
 $\longrightarrow [[D\phi x^{\langle 1- \rangle}, Dgab, S], [\phi z^{\langle 1+ \rangle}, D(D\phi x)z(\phi z), Dgab, S]]$
 $\xrightarrow{h2} [[H(fz)x, D\phi x^{\langle 1- \rangle}, Dgab, S], [\phi z^{\langle 1+ \rangle}, D(D\phi x)z(\phi z), Dgab, S]]$

$$\begin{array}{l}
\left\{ \begin{array}{l} D\phi x z \rightarrow h(D(D\phi x)z(\phi z))(H(fz)x)(\phi z) \\ H\phi x \rightarrow \phi x \end{array} \right. \longrightarrow [[z, D(D\phi x)z(\phi z), Dgab, S]] \\
\longrightarrow [[\phi x, H(fz)x, D\phi x^{(1-)}, Dgab, S], [\phi z^{(1+)}, D(D\phi x)z(\phi z), Dgab, S]] \longrightarrow q_3 [[D(D\phi z)z(\phi z), Dgab, S]] \\
\longrightarrow [[fz^{(2-)}, D\phi x^{(1-)}, Dgab, S], [\phi x^{(2+)}, H(fz)x, D\phi x^{(1-)}, Dgab, S], \longrightarrow [[\phi z, Dgab, S]] \\
[\phi z^{(1+)}, D(D\phi x)z(\phi z), Dgab, S]] \longrightarrow [[g^{(3-)}, [\phi z^{(3+)}, Dgab, S]] \\
\stackrel{f^1}{\longrightarrow} [[z, D\phi x^{(1-)}, Dgab, S], [\phi x^{(2+)}, H(fz)x, D\phi x^{(1-)}, Dgab, S], \stackrel{g^1}{\longrightarrow} [[z, Dgab, S]] \\
[\phi z^{(1+)}, D(D\phi x)z(\phi z), Dgab, S]] \longrightarrow [[b]] \\
\longrightarrow q_3 [[D\phi x^{(1-)}, Dgab, S], [\phi x^{(2+)}, H(fz)x, D\phi x^{(1-)}, Dgab, S], \\
[\phi z^{(1+)}, D(D\phi x)z(\phi z), Dgab, S]] \\
\longrightarrow q_1 [[\phi z^{(1+)}, D(D\phi x)z(\phi z), Dgab, S]]
\end{array}$$

Simulating 2PDALs by non-deterministic safe 2PDAs

In some cases of push_2 , we will never ever go back down to the associated 1-store (because no missing argument of that type-1 item is required in that particular run).

If we guess that some missing argument of the type-1 item in question will be accessed (later in that particular run), we make an explicit link as before, but always using the **same** pair of start-of-link (−) and end-of-link (+) markers.

However we would be penalised (i.e. force to abort) if at some point a present (as opposed to missing) argument of a (−)-marked is accessed instead.

This will turn out to be enough if we maintain an invariant:

Assume the top 1-store contains at least one item marked with a start marker. If the stack item is closest to the top, then the corresponding + will be found in the first 1-store beneath it whose topmost item is marked +.

Further directions

Extension to level-3 and beyond.

The case of level-2 pushdown trees.

Kasai's Hierarchy of context-sensitive languages.

$$\{a_1^n \cdots a_{l+1}^n : n \geq 1\} \in K_l \setminus K_{l-1}$$