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# Strategy Improvement for Parity Games

*A Combinatorial Perspective*

Paul Hunter

# Outline

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- Parity Games
- Strategy Improvement Algorithm
- Completely Unimodal Hypercubes
- Results – Old and New
- Conclusion

# Parity Games

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# Parity Games

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- Two player, zero-sum, non-cooperative, infinite game.
- Played on a finite, directed graph  $(V, E)$ .
  - Bi-partite
  - Maximum out-degree 2

# Parity Games

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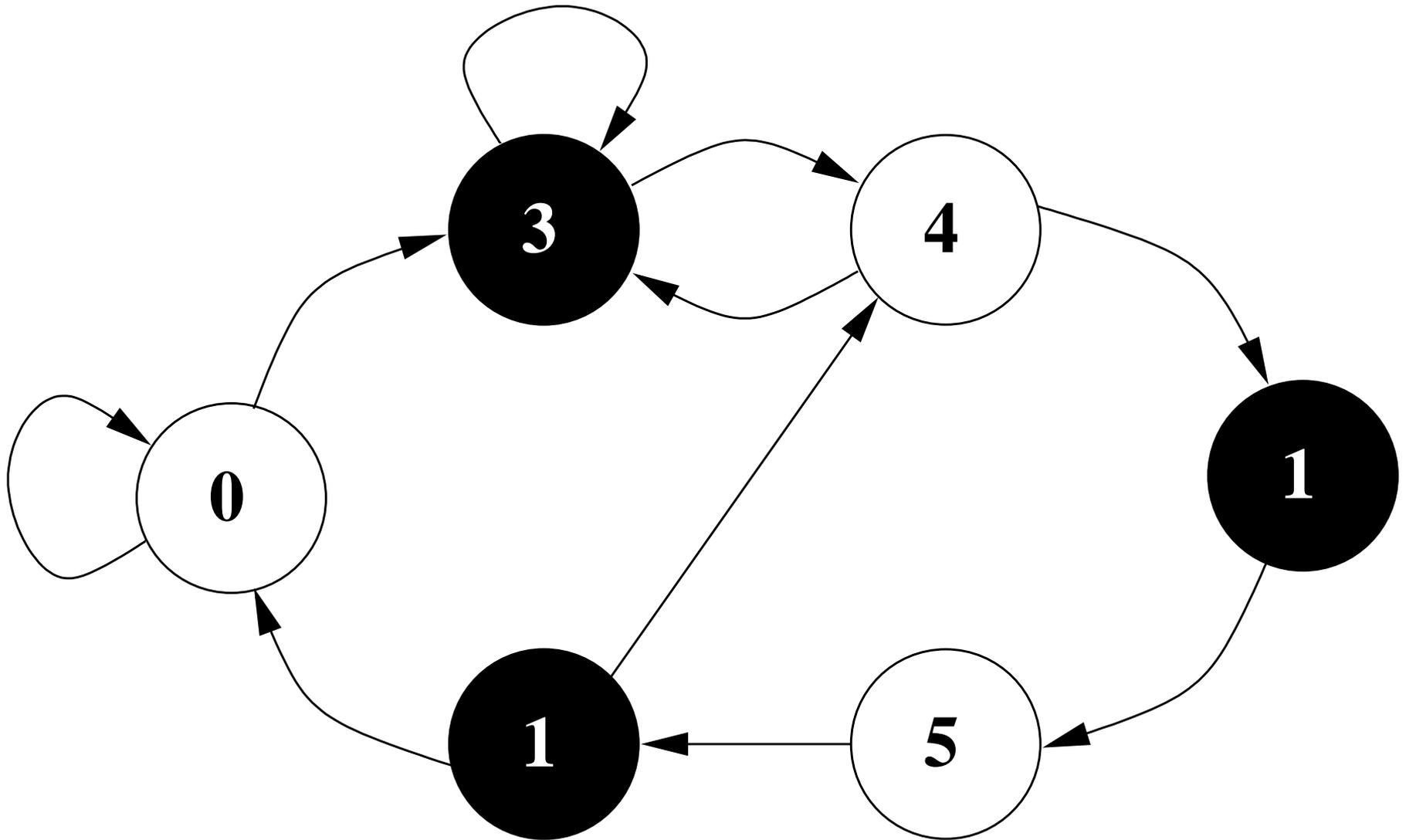
- Two player, zero-sum, non-cooperative, infinite game.
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Players (Player 0 and Player 1) alternately move a token around the graph for an infinite number of turns, generating an infinite sequence  $S$  of vertices visited. Winner is determined by a parity condition:

- Priority function  $\chi : V \rightarrow \mathbb{P} \quad (\mathbb{P} \leq \omega)$
- Player 0 wins if and only if  $\max_{v \in S} \chi(v)$  is even.

# Parity Games – Example

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# Parity Games – Facts

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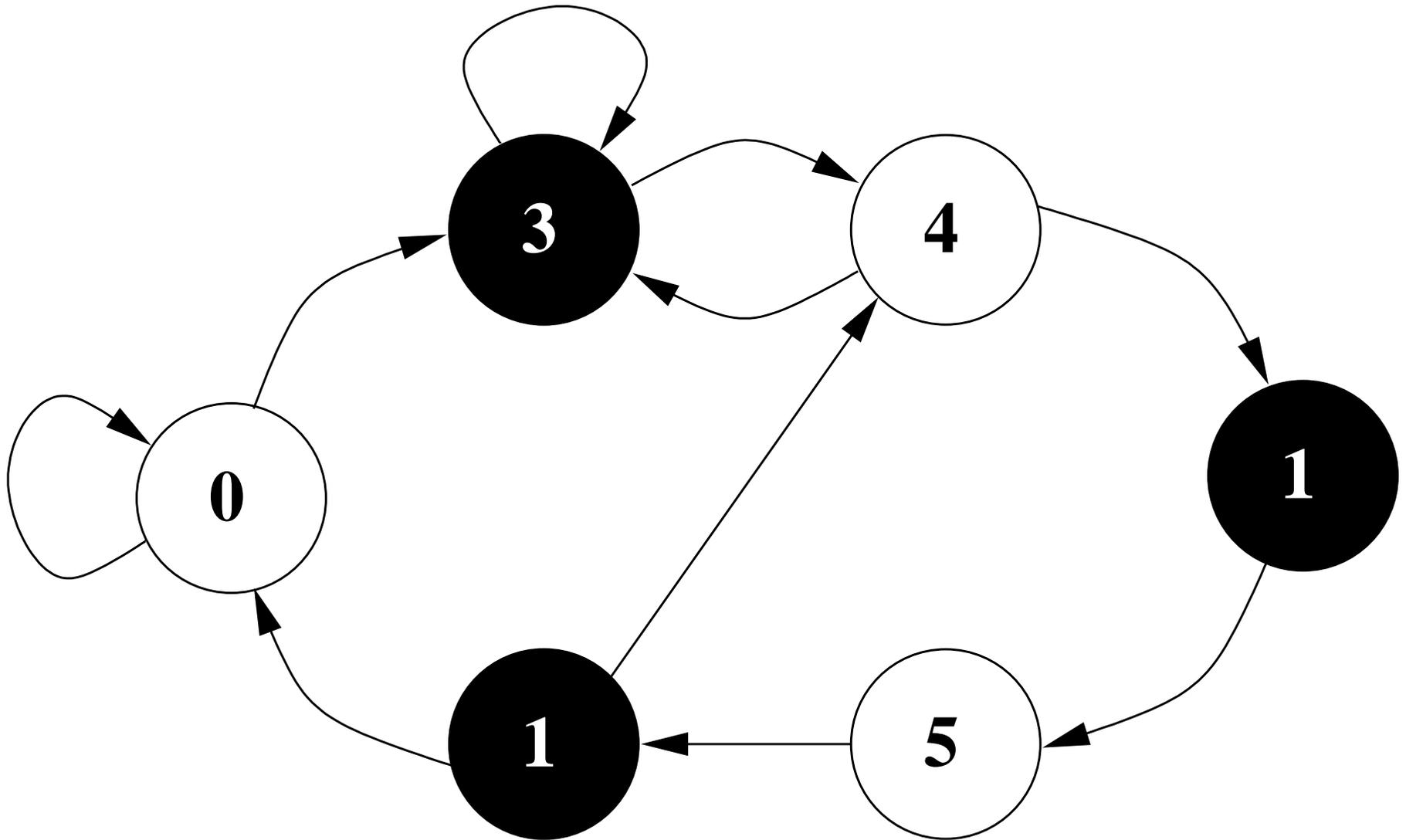
# Parity Games – Facts

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- Determined – from any vertex one player has a strategy to defeat any play by the other player
- Polynomially equivalent to  $\mu$ -calculus model checking
- Whichever player has a winning strategy has a positional (memoryless) winning strategy

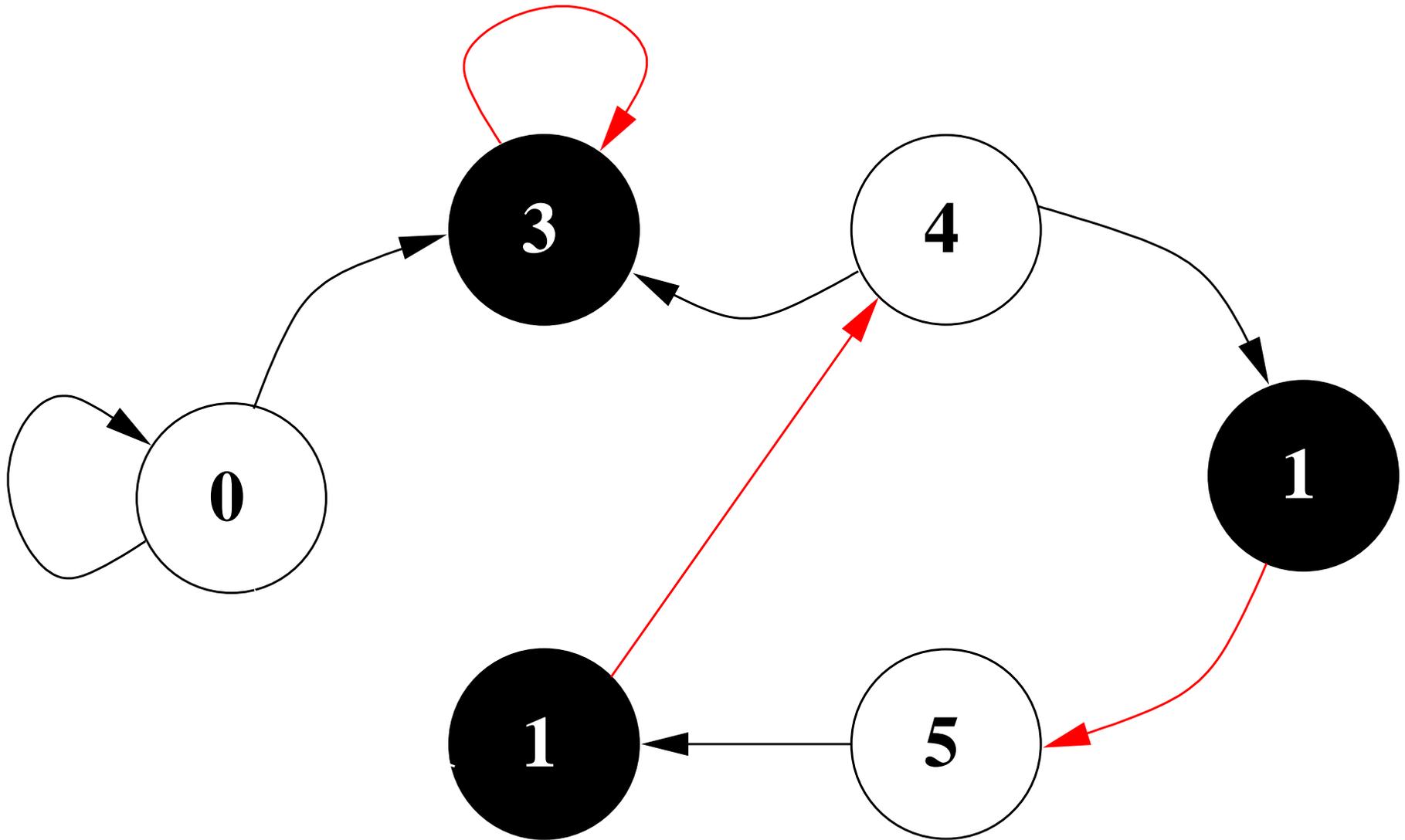
# Parity Games – Winning strategy

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# Parity Games – Complexity

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Memoryless strategies imply that deciding Parity games is in  $NP \cap co-NP$ .

**Open problem:** *Is deciding Parity games in P?*

Best known algorithm (Jurdziński 2000)

$$O\left(d|E|\left(\frac{|V|}{\lfloor d/2 \rfloor}\right)^{\lfloor d/2 \rfloor}\right)$$

where  $d$  is the number of priorities.

Recent approach is strategy improvement.

# Strategy Improvement

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Introduced by Vöge and Jurdziński, 2000.

Works by “improving” memoryless strategies until optimum is reached.

Naïve time complexity analysis gives  $O(|V||E|2^{|V|})$  upper bound, but no known example worse than linear time has been found!

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**Question:** *What is the exact complexity of this algorithm?*

# Strategy Improvement – Valuations

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A valuation is a function

$$\varphi : V \rightarrow \mathbb{P} \times \mathcal{P}(\mathbb{P}) \times \omega$$

which assigns to each vertex:

- A loop priority
- A set of priorities, and
- A natural number

Intuitively, a valuation corresponds to a “best-play” counter-strategy.

# Strategy Improvement – Valuations

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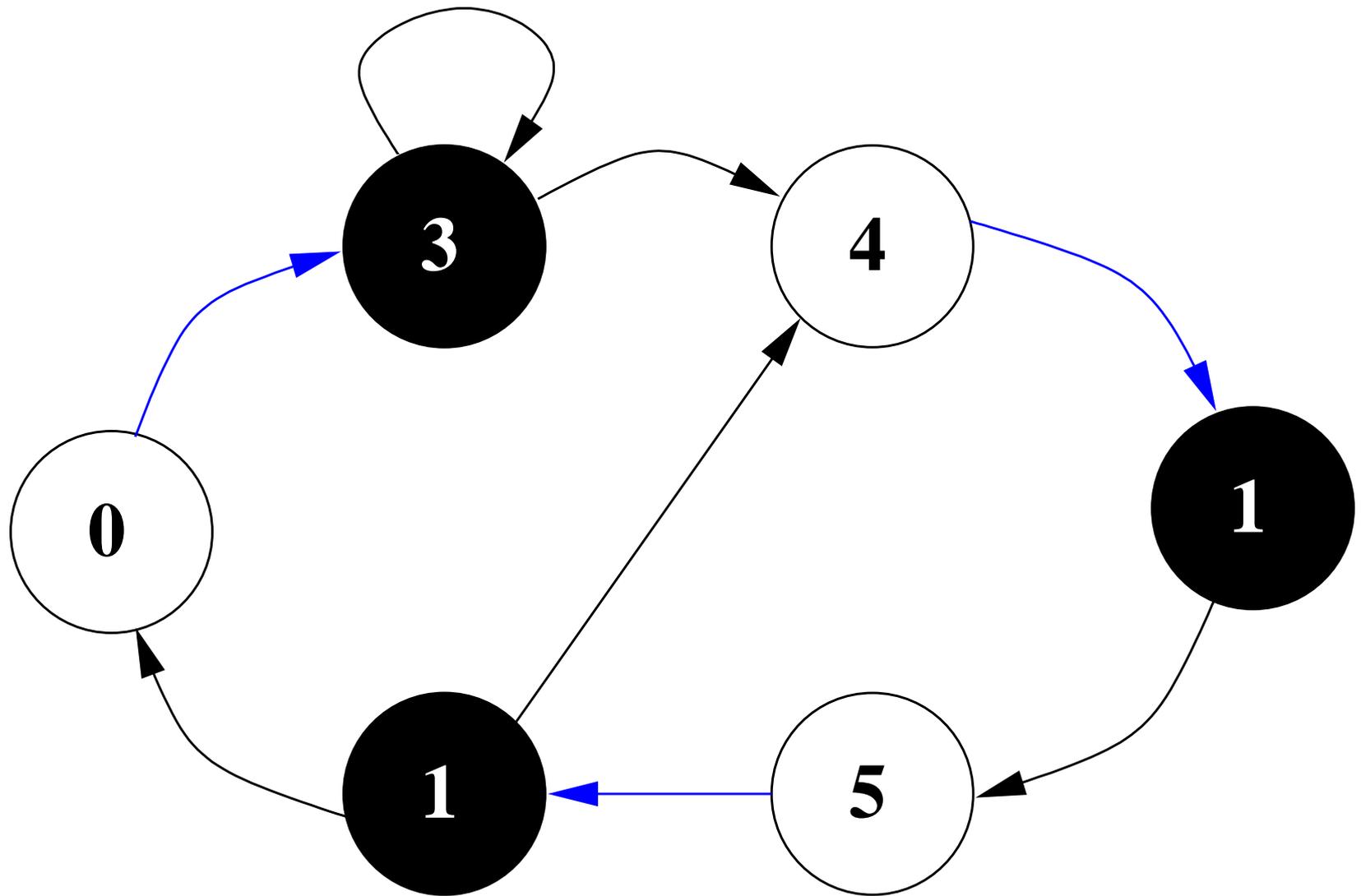
We can partially order valuations lexicographically according to what is best for Player 1

- High even priorities  $\preceq$  Low even  $\preceq$  Low odd  $\preceq$  High odd
- For sets  $P$  and  $Q$ ,  $P \prec Q$  if  $\max(P \Delta Q)$  is odd and in  $Q$  or even and in  $P$
- Path lengths depend on the loop priority – short paths are better if the loop priority is odd

A  $\preceq$ -maximal valuation is 1-optimal.

# Valuation example

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# Strategy Improvement – Algorithm

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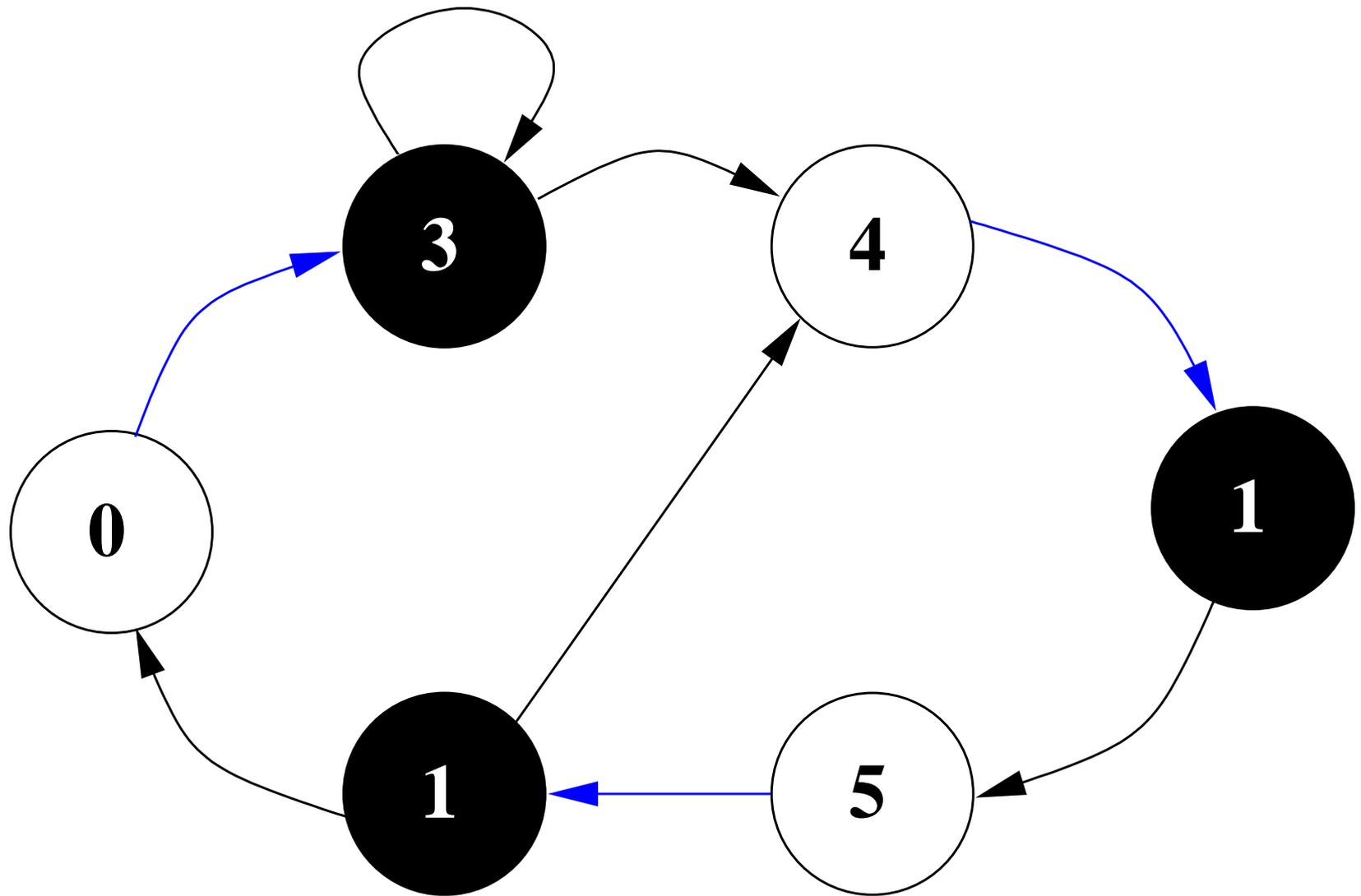
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- Return to step 2 until no changes are made.

At this point  $\sigma$  is the best Player 0 can do, so it is straightforward to determine each player's winning sets.

Note that we are changing the strategy at different vertices simultaneously.

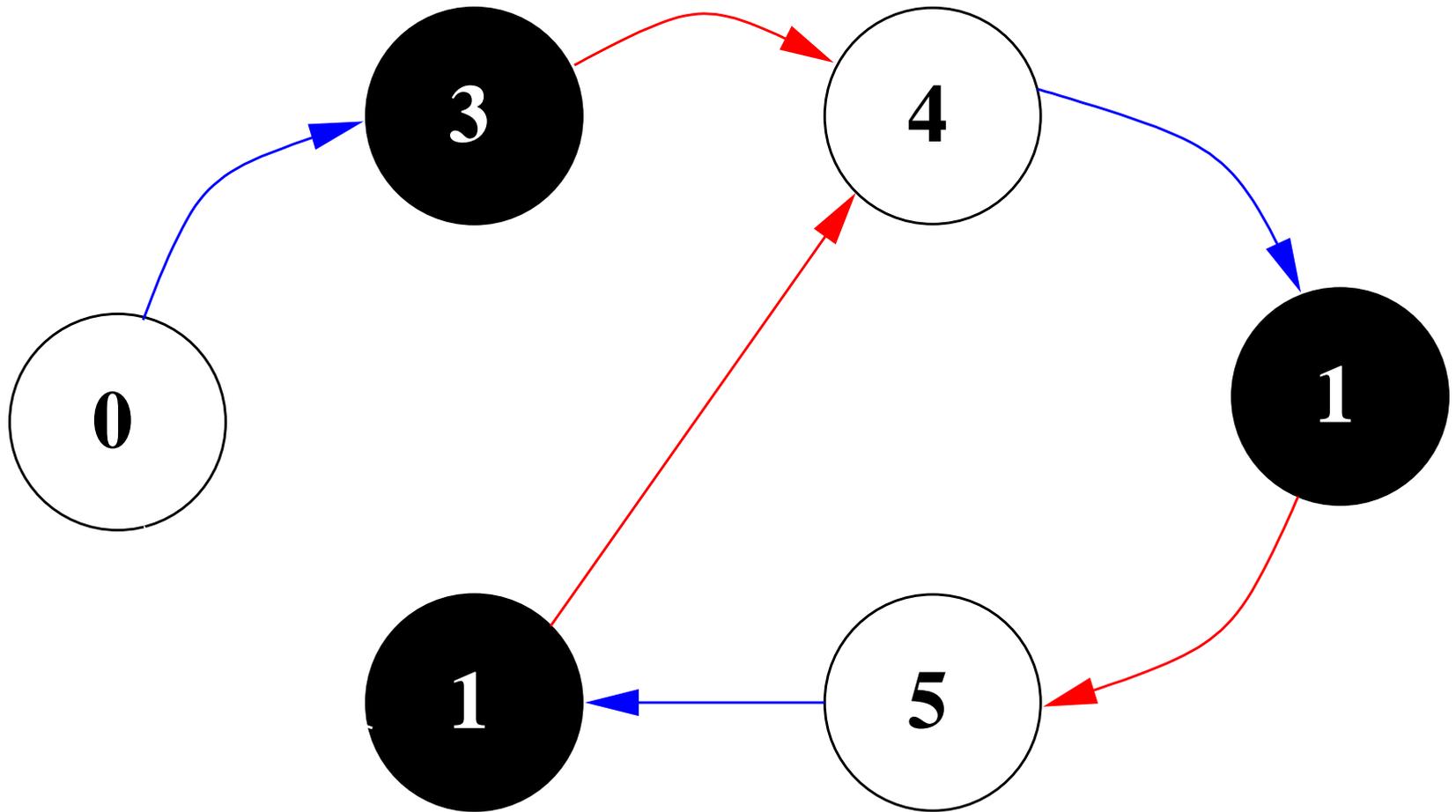
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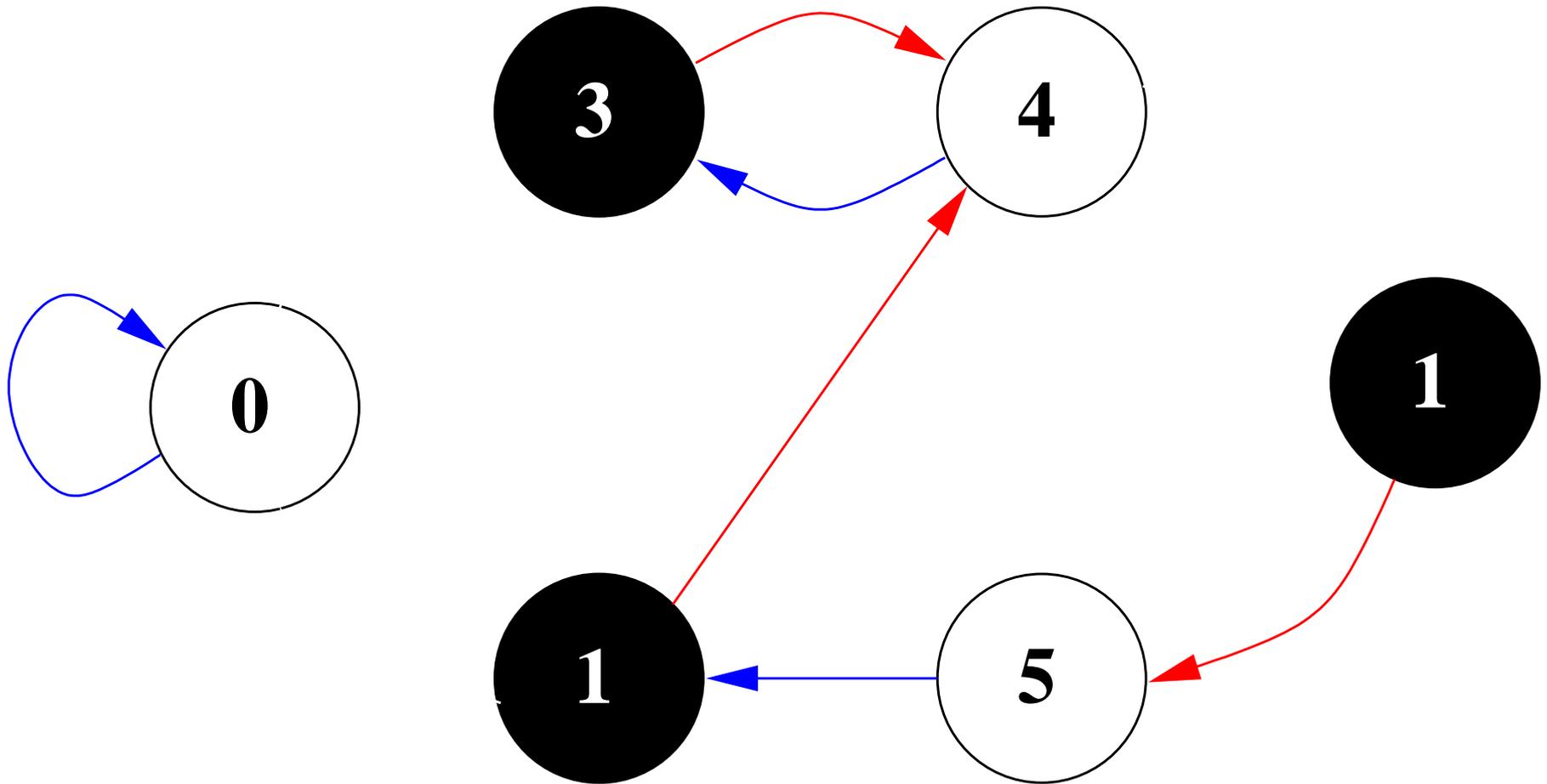
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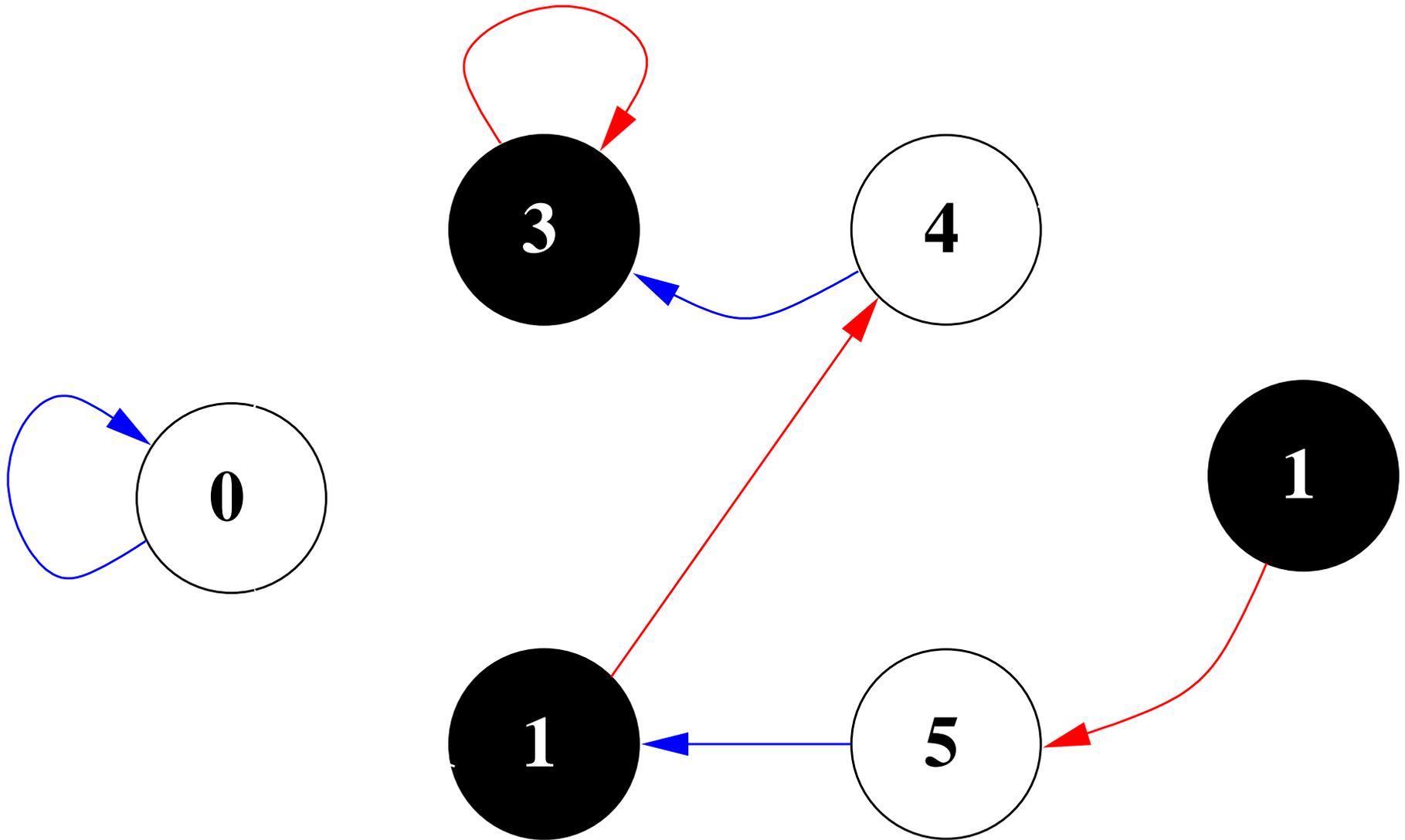
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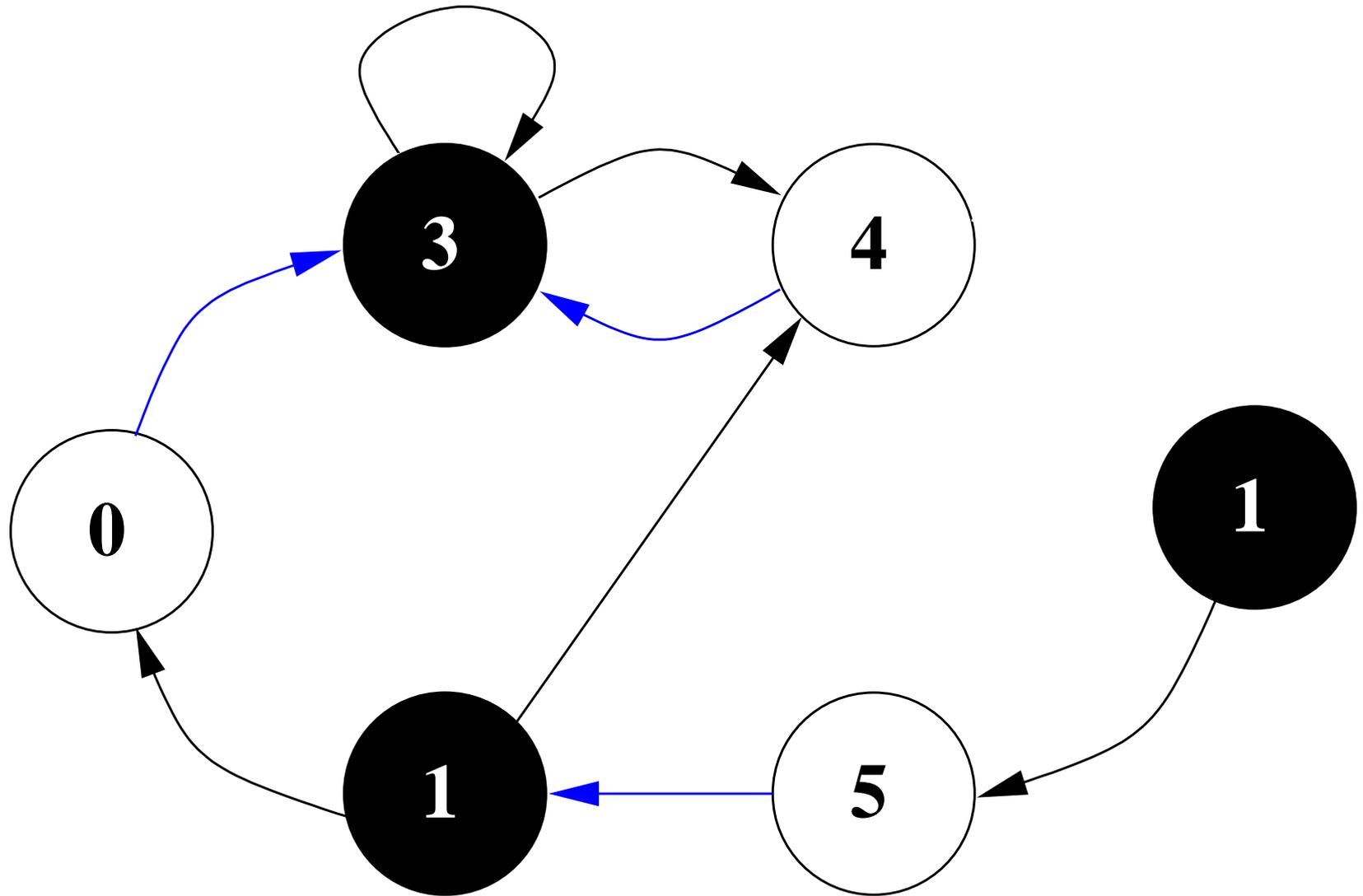
# Strategy Improvement – Comments

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Inherent asymmetry in algorithm. We can extract a strategy from a valuation, so why not compute a 0-optimal valuation and use this to improve  $\sigma$ ?

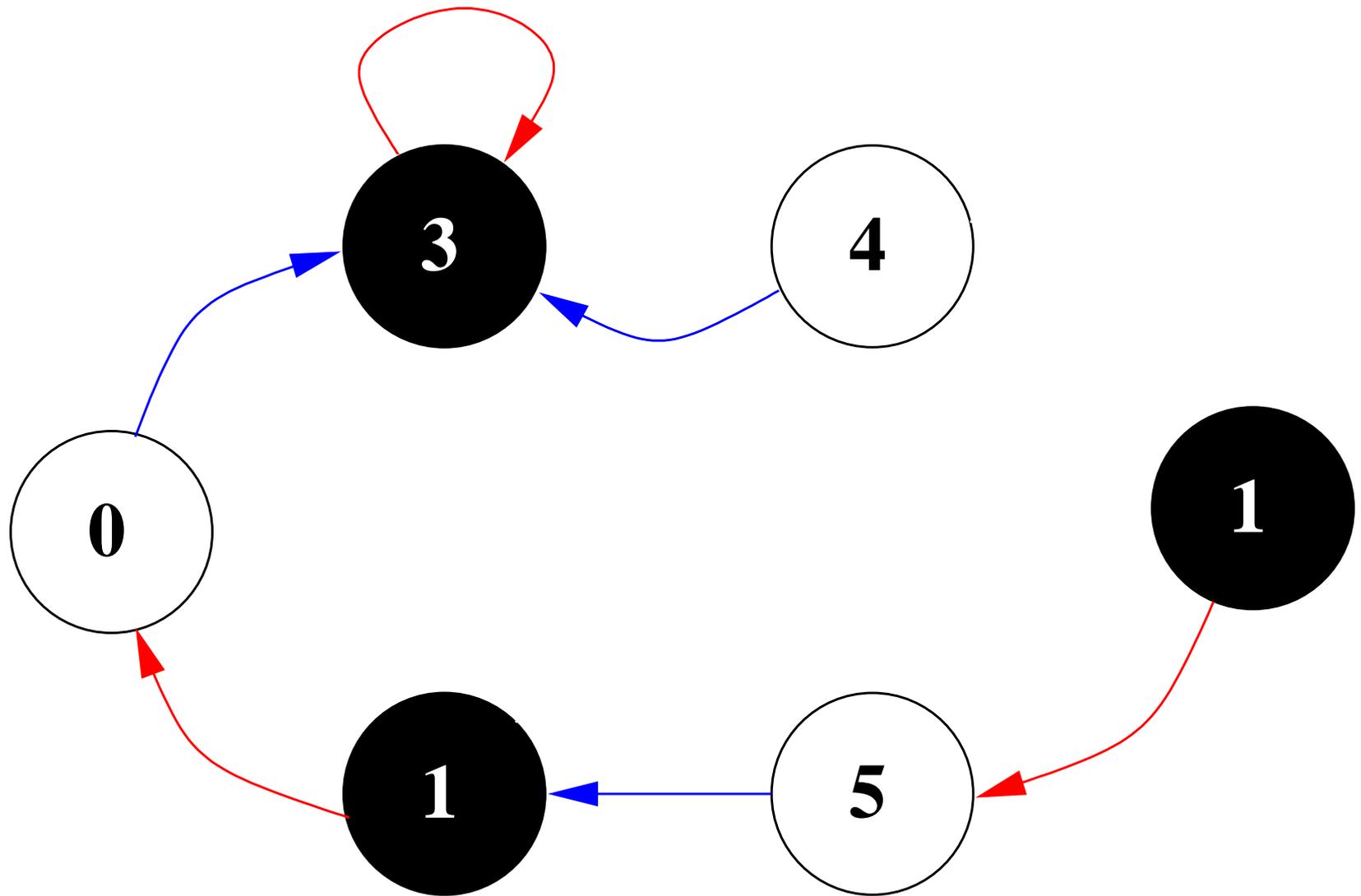
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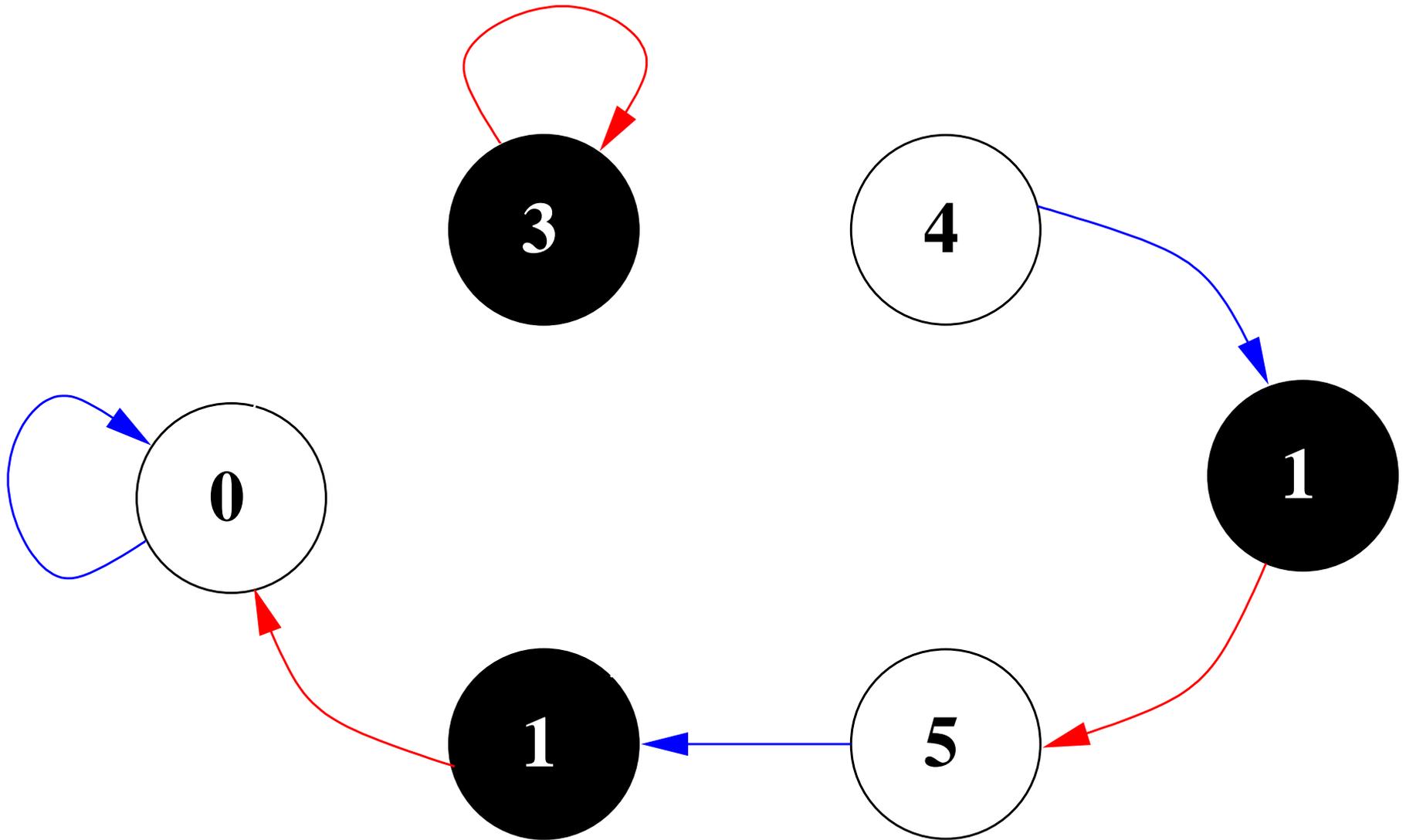
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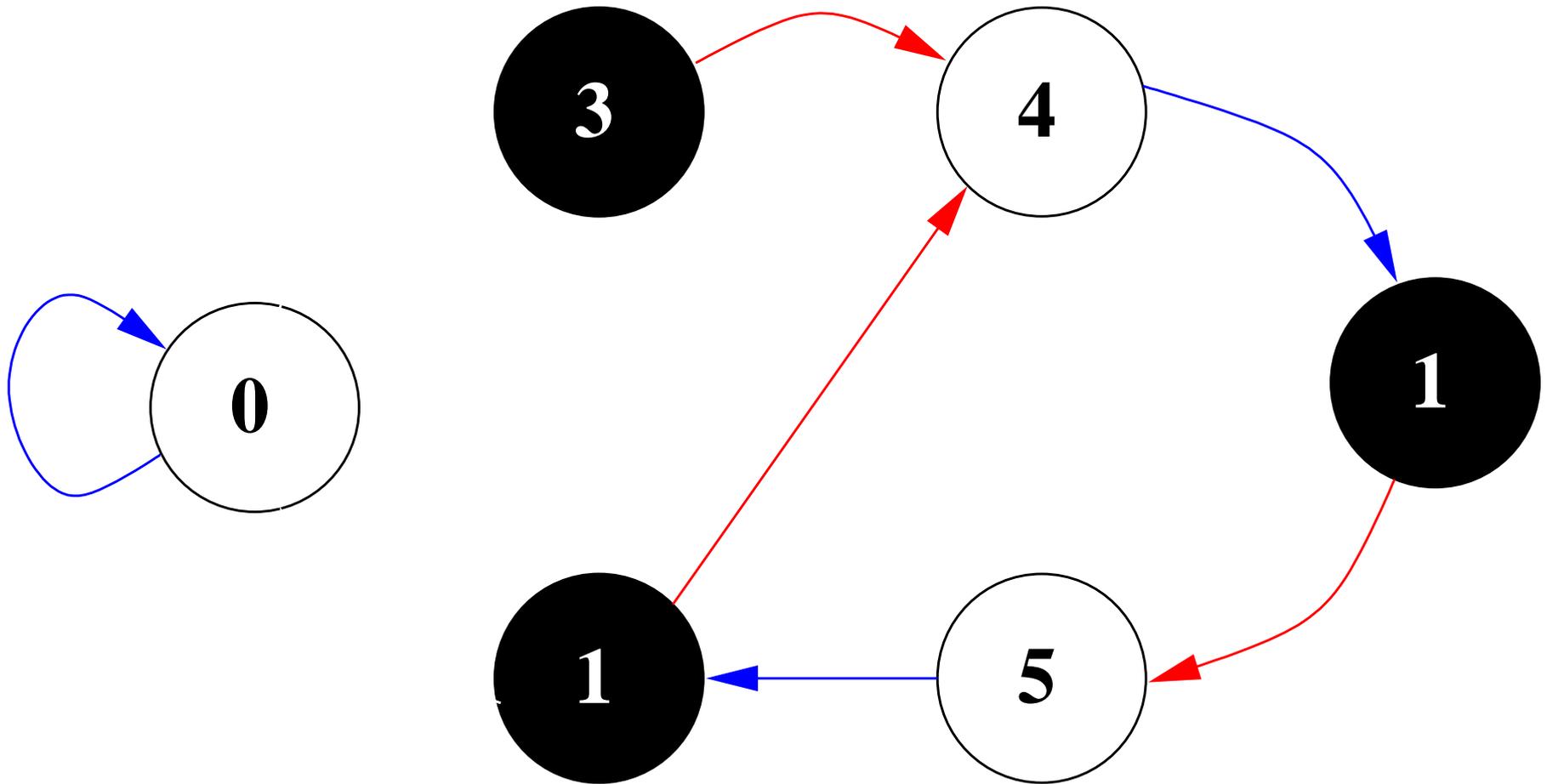
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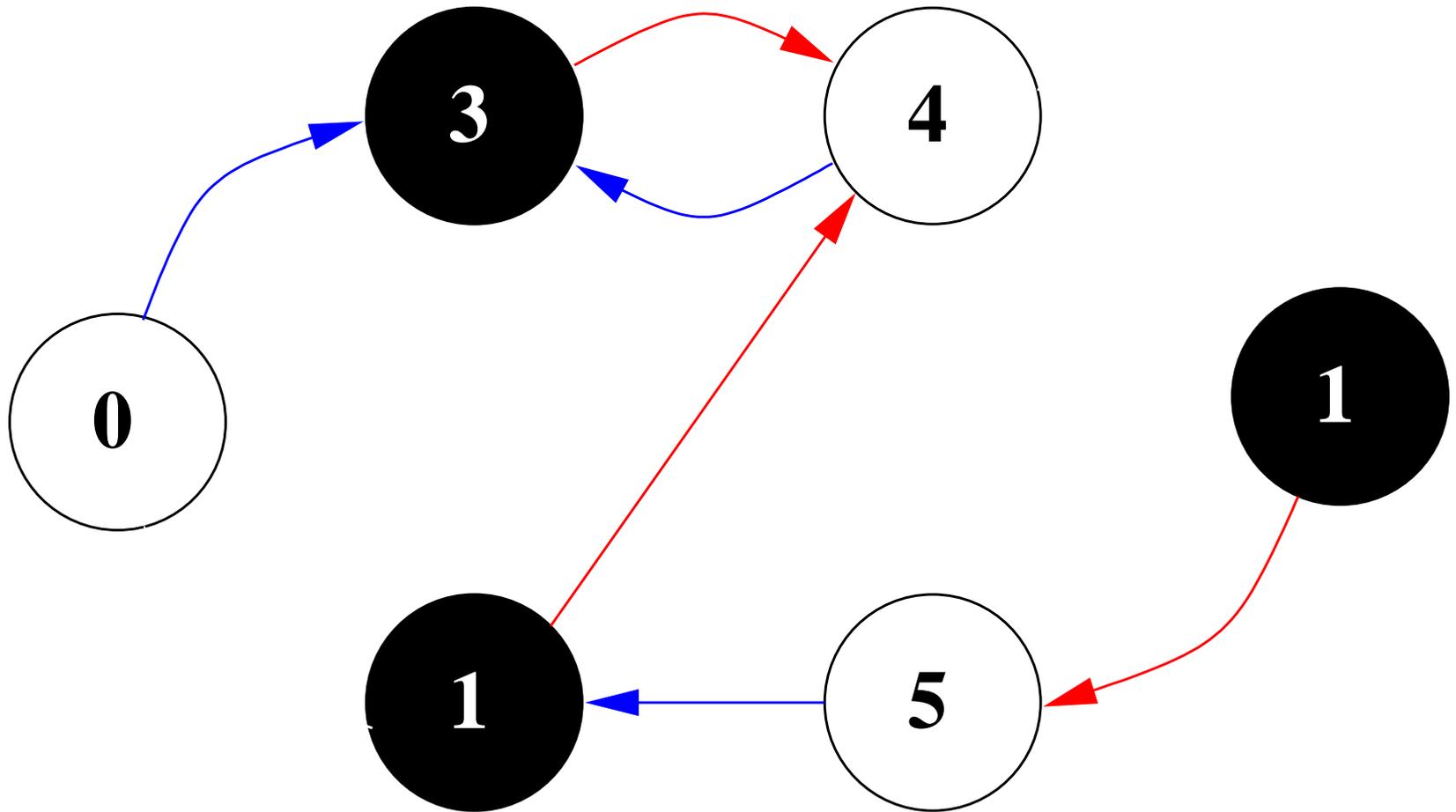
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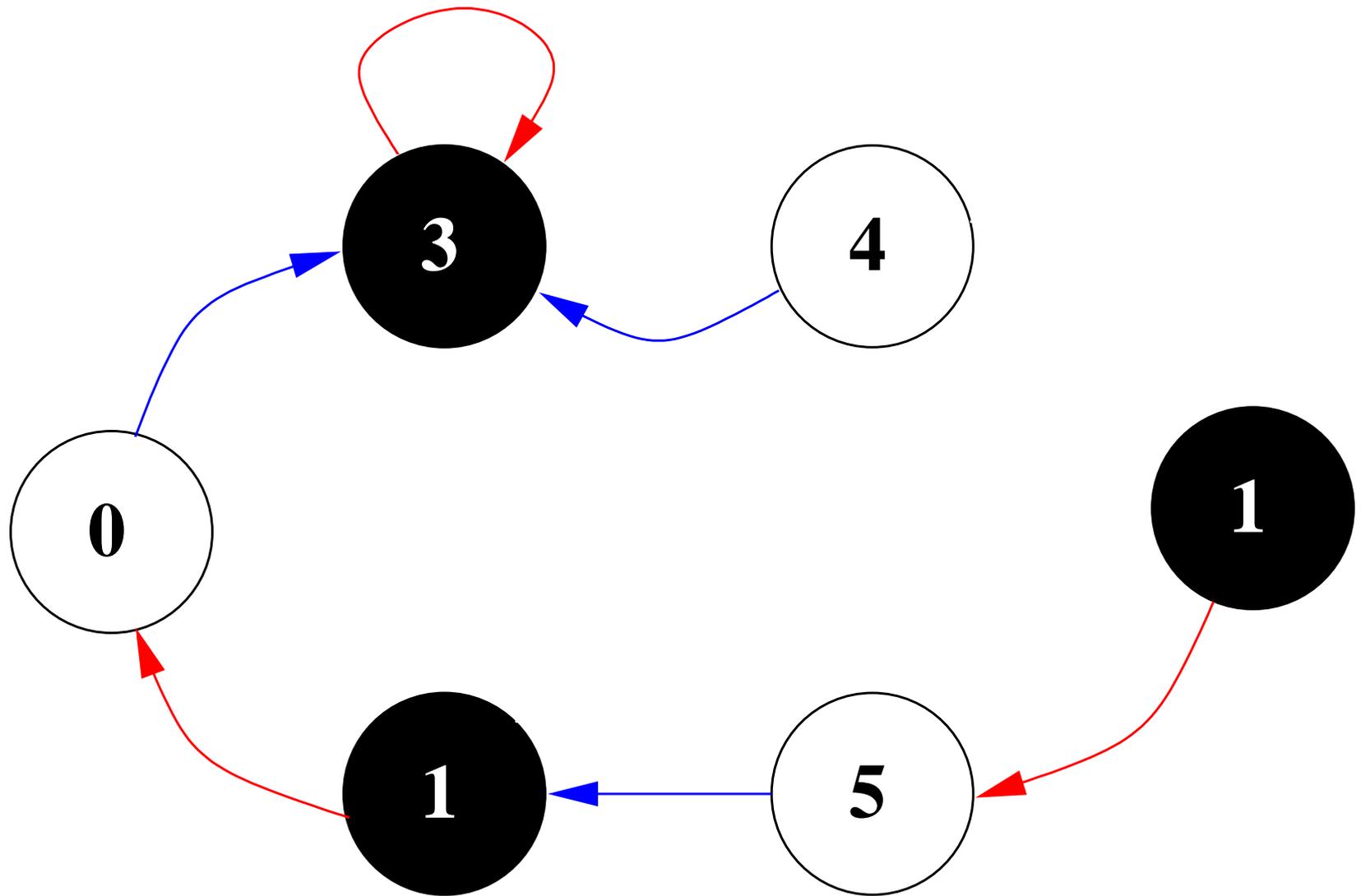
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# Completely Unimodal Hypercubes

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A pseudo-boolean function (PBF) of dimension  $n$  is a function from the  $n$ -dimensional boolean hypercube  $\{0, 1\}^n$  to  $\omega$ .

**Standard problem:** *Find a local/global minimum/maximum*

This problem motivated the Polynomial Local Search (PLS) complexity class.

# Completely Unimodal Hypercubes

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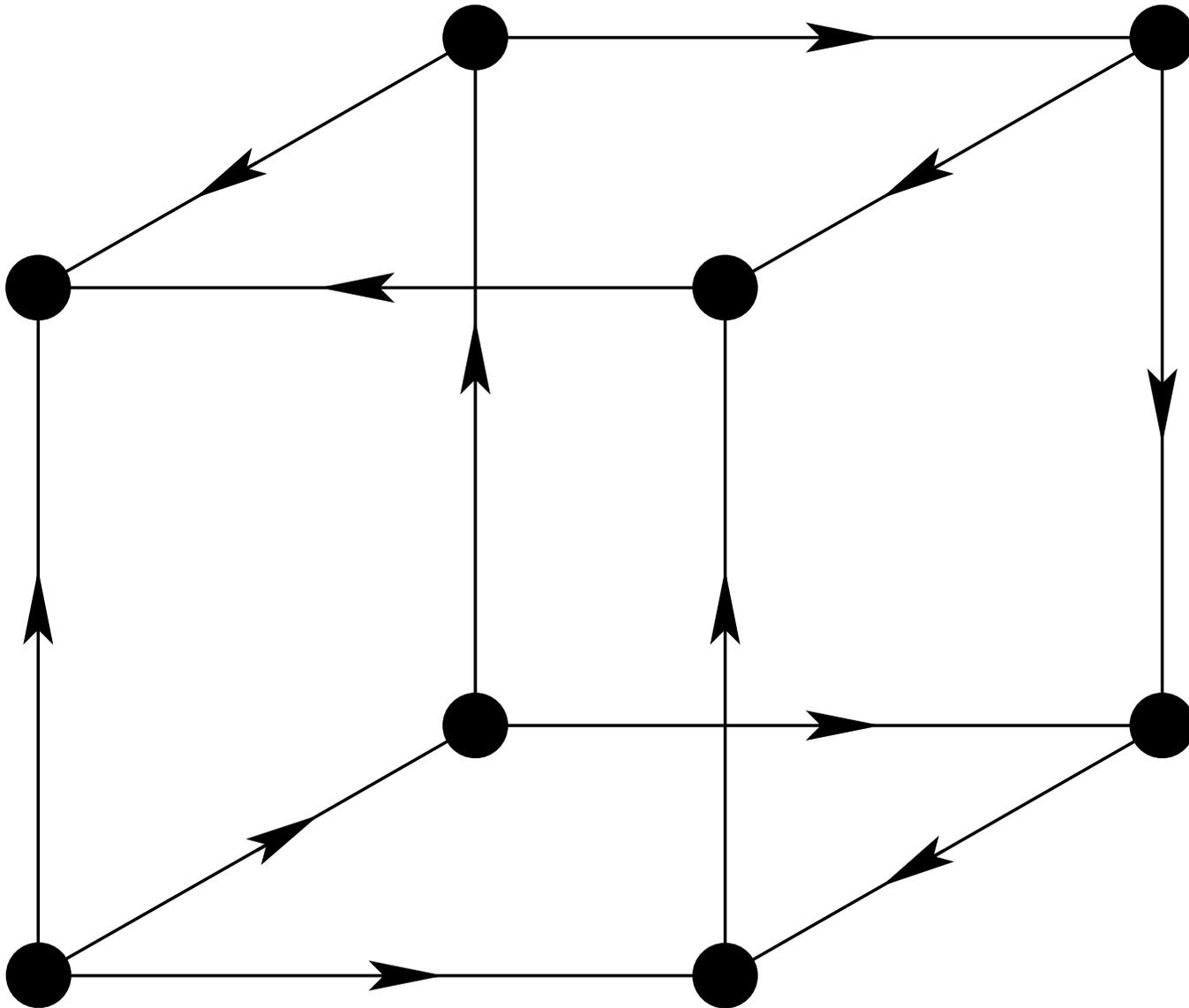
A PBF is completely unimodal (CU) if it has exactly one maximum on every face of the hypercube.

Completely unimodal functions are also known as

- Completely Unimodal numberings, and
- Acyclic Unique Sink Orders.

# CU Hypercubes – Example

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# CU Hypercubes – Properties

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- All local optima are global
- A sufficient condition is for all 2-faces to be Completely Unimodal
- A CU numbering corresponds to a shelling of the dual polytope
- An  $n$ -dimensional CU Hypercube satisfies the Hirsch Conjecture. That is, from every vertex there is a path of length  $\leq n$  to the global maximum.
- The Vector of Improving Directions is injective.

# CU Hypercubes – Algorithms

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Algorithms to find the global maximum:

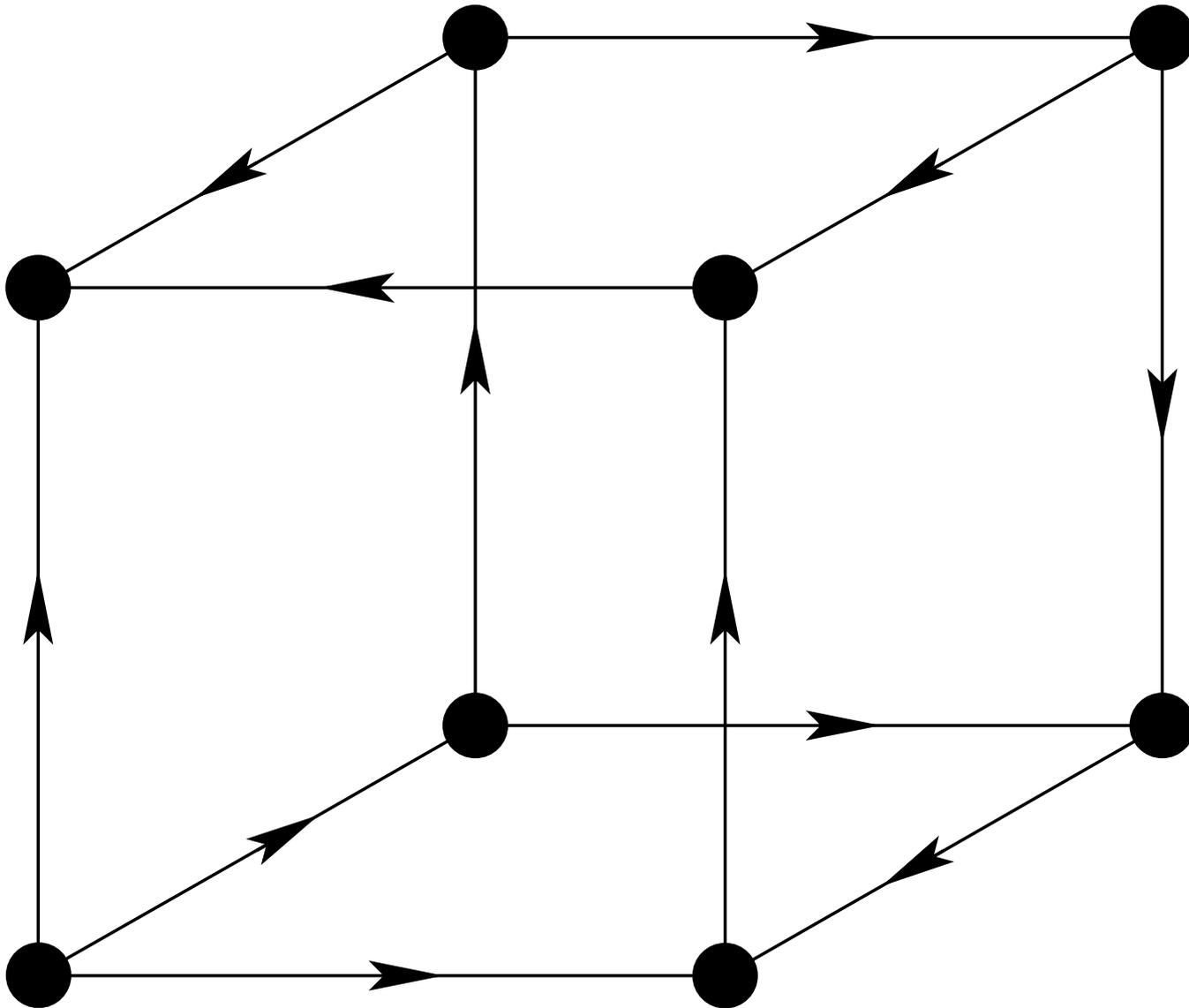
**Greedy Local Improvement (GLI):** While there are better neighbours of the current position, change in all co-ordinates that are improving.

The complete unimodality condition guarantees that every change results in an improved position.

**Fibonacci See-Saw (FSS):** Store the maxima of opposite  $i$ -faces as  $i$  goes from 0 to  $n$ . To proceed from  $i$  to  $i + 1$  choose a direction which is improving for only one maximum (such a direction exists by the injectivity of the VID).

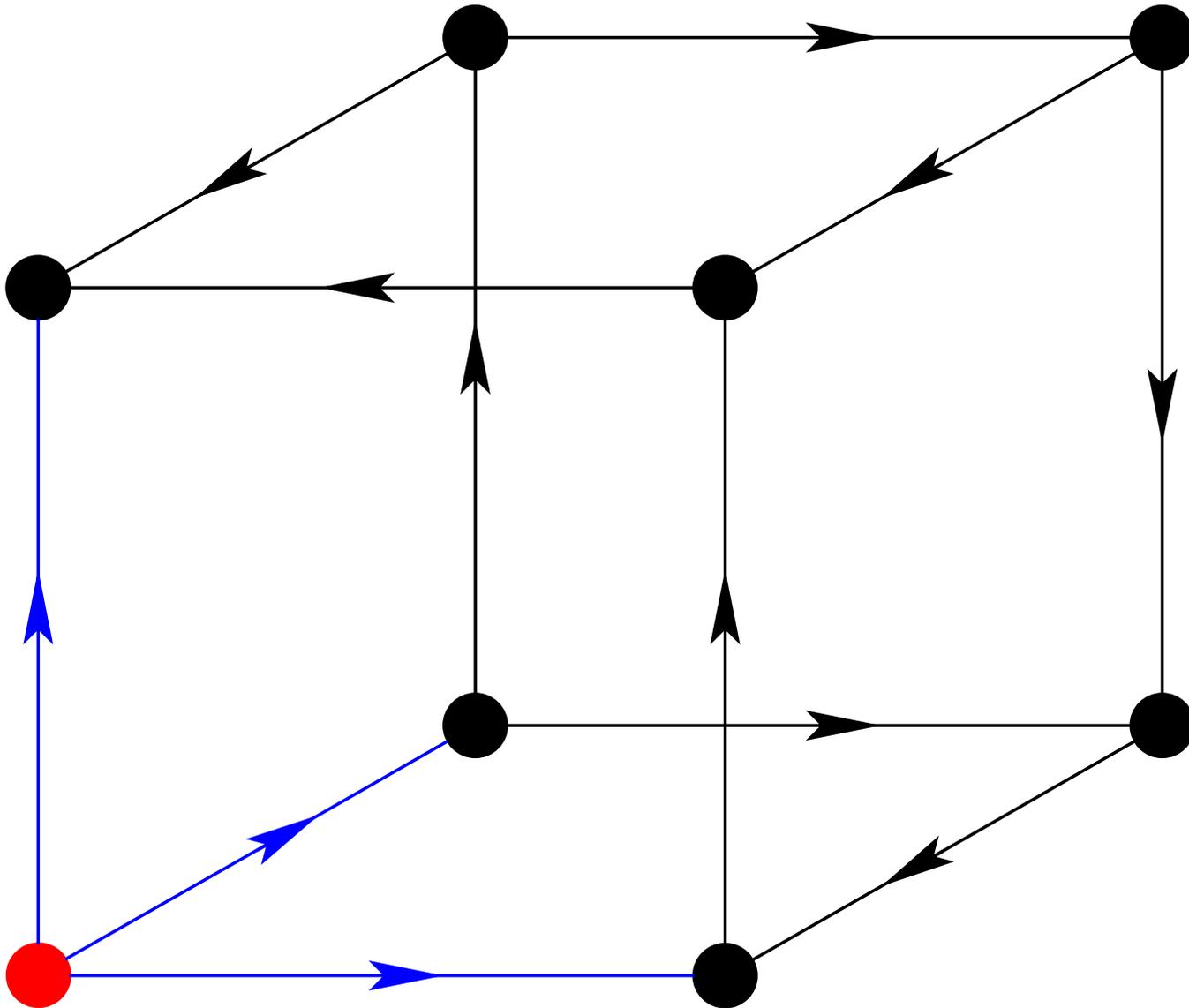
# CU Hypercubes – GLI Example

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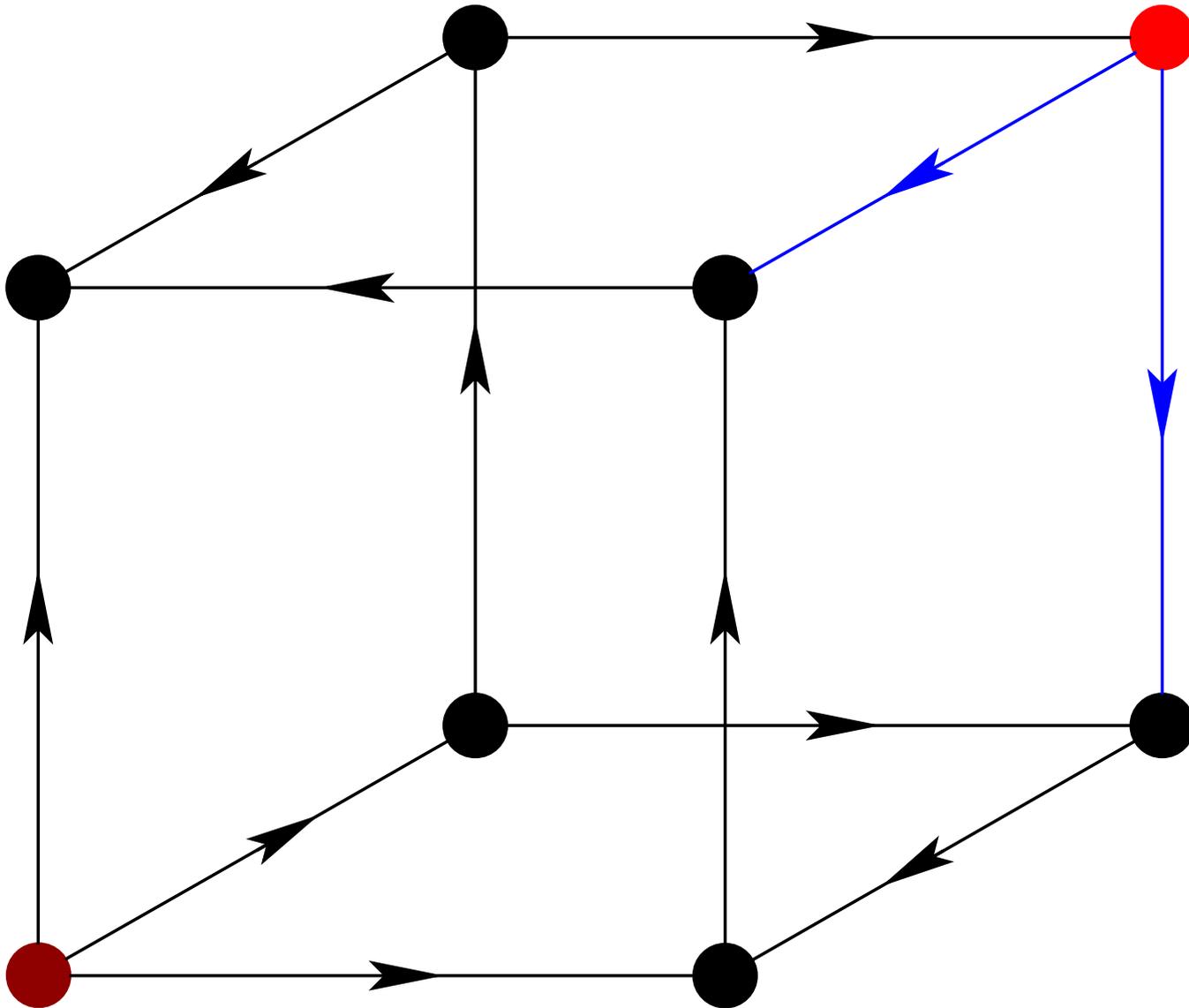
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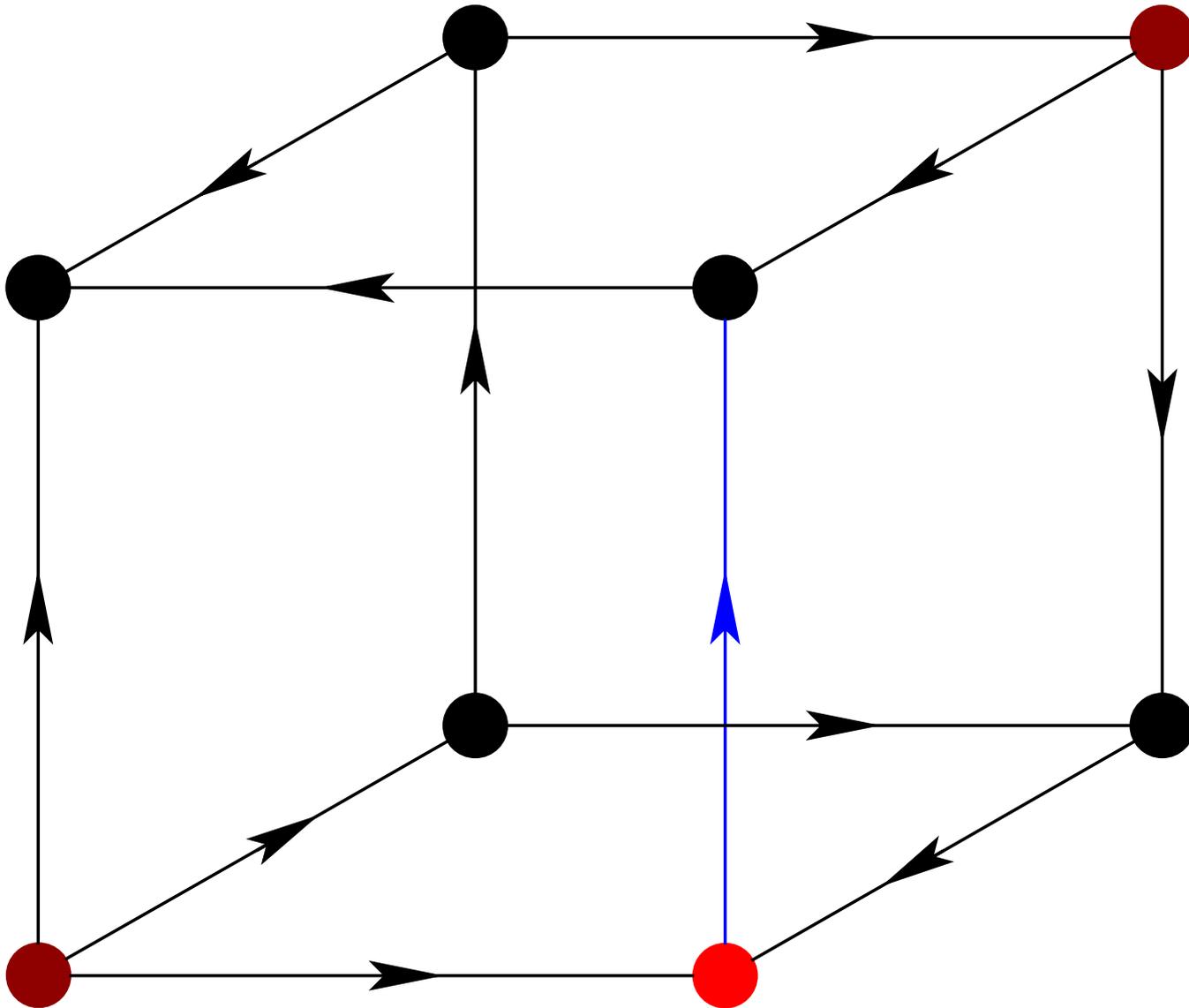
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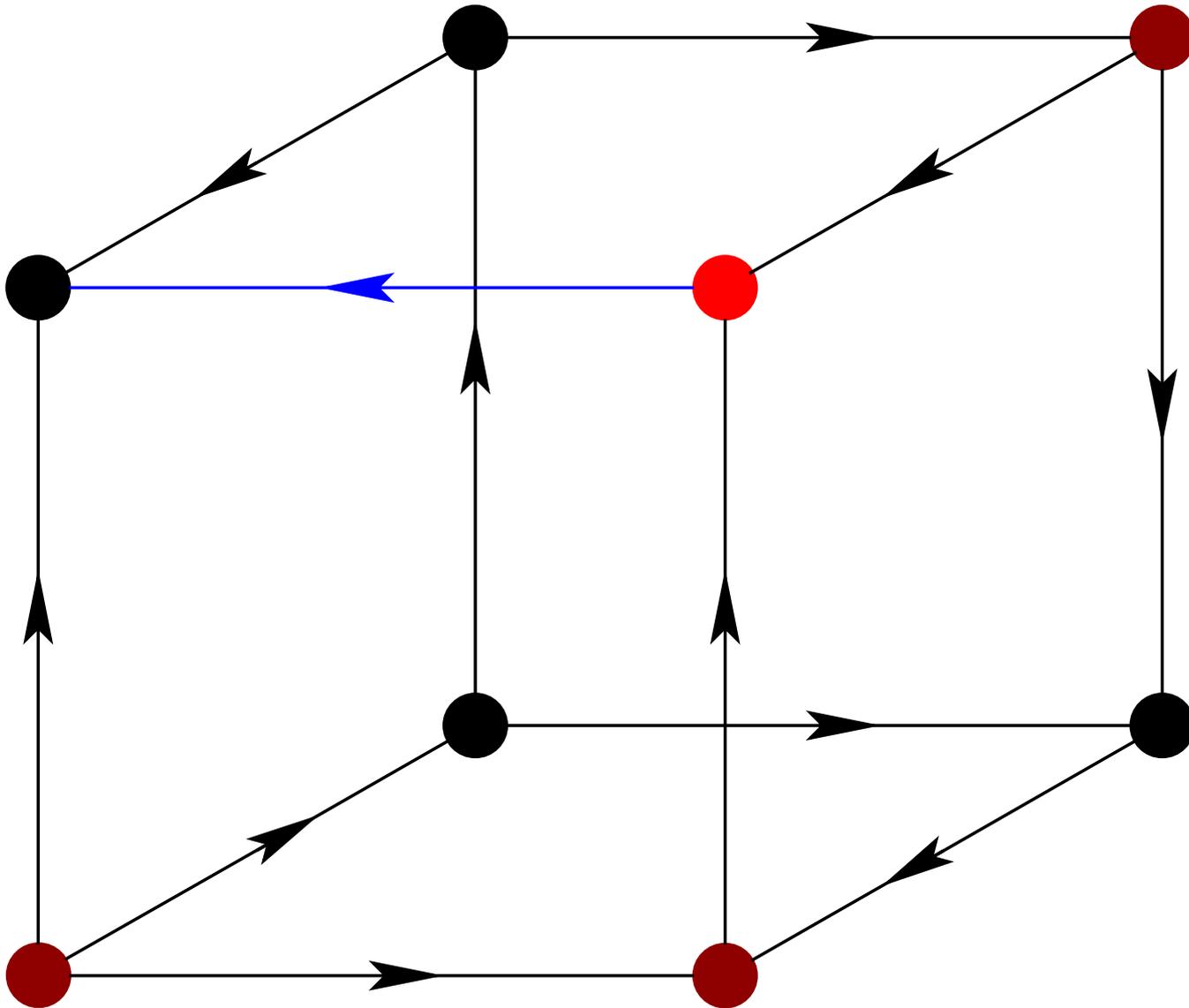
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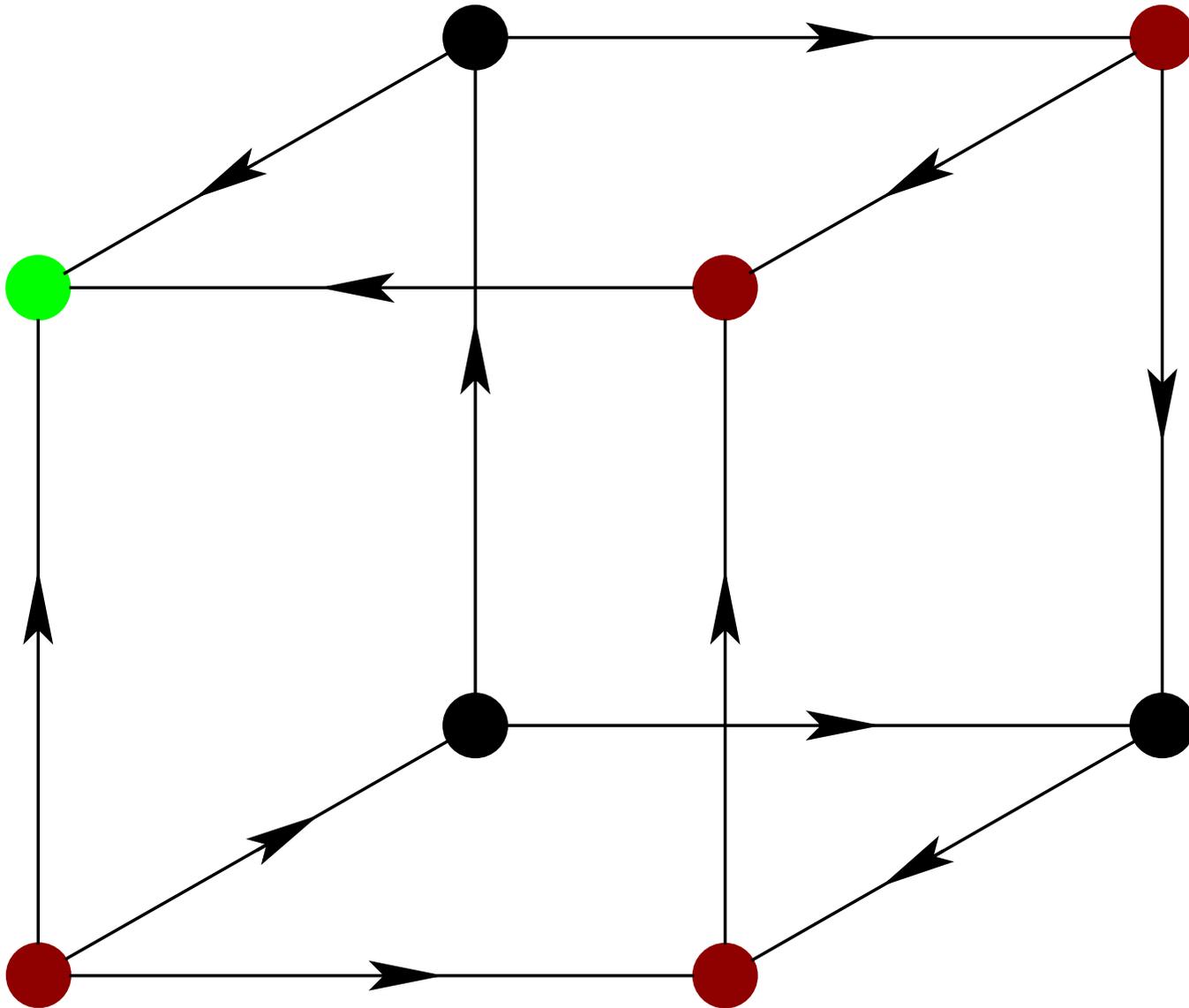
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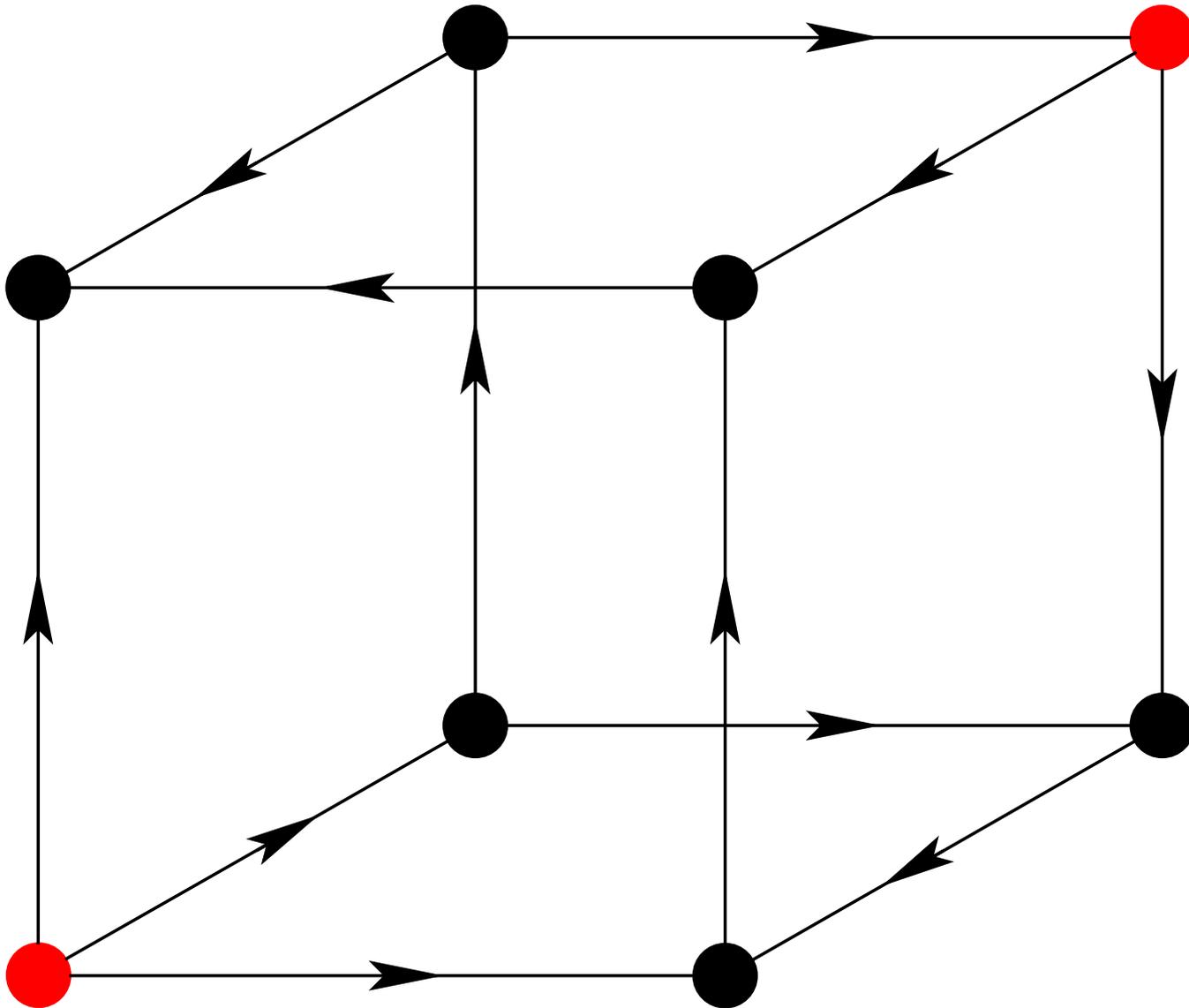
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# CU Hypercubes – FSS Example

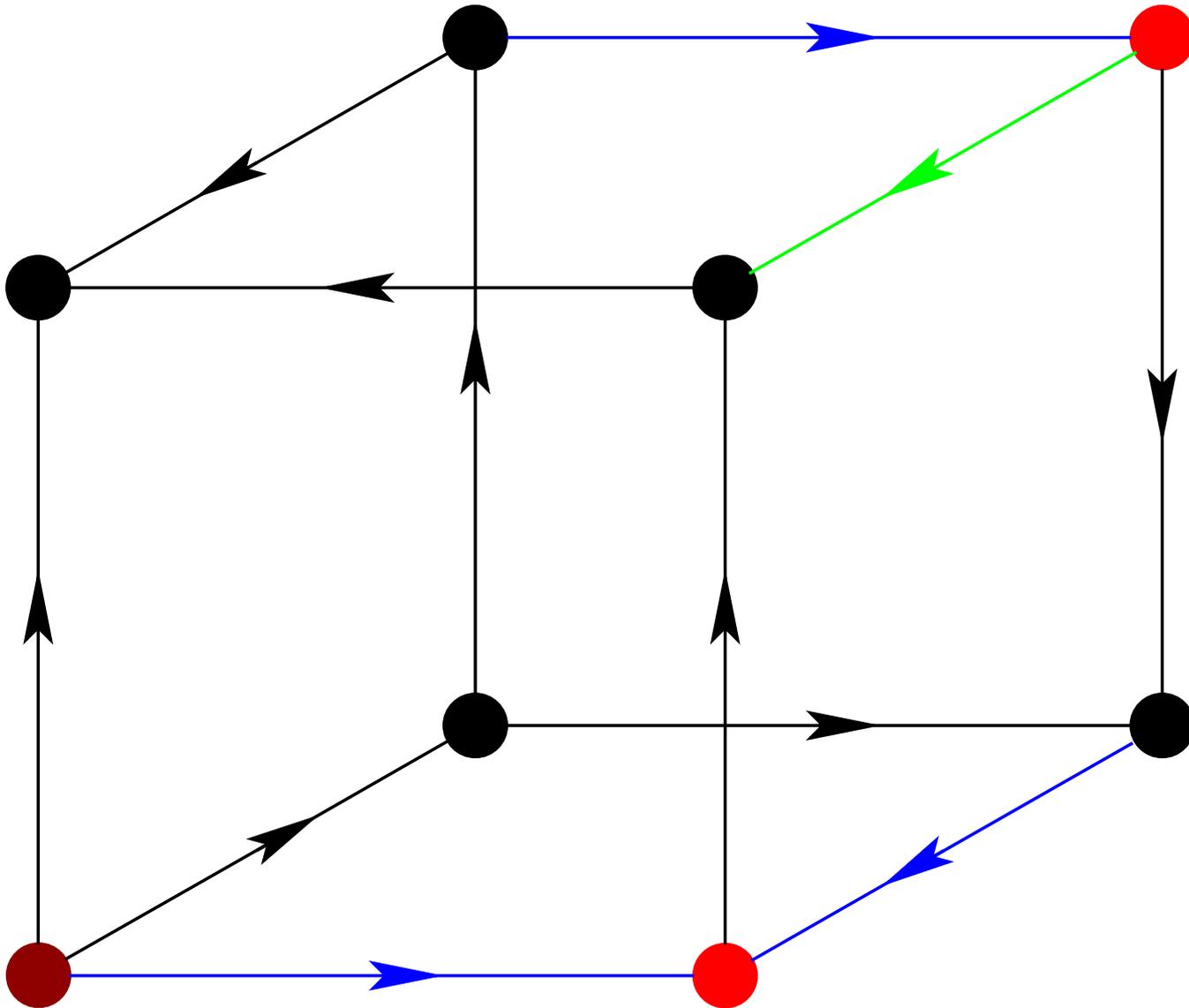
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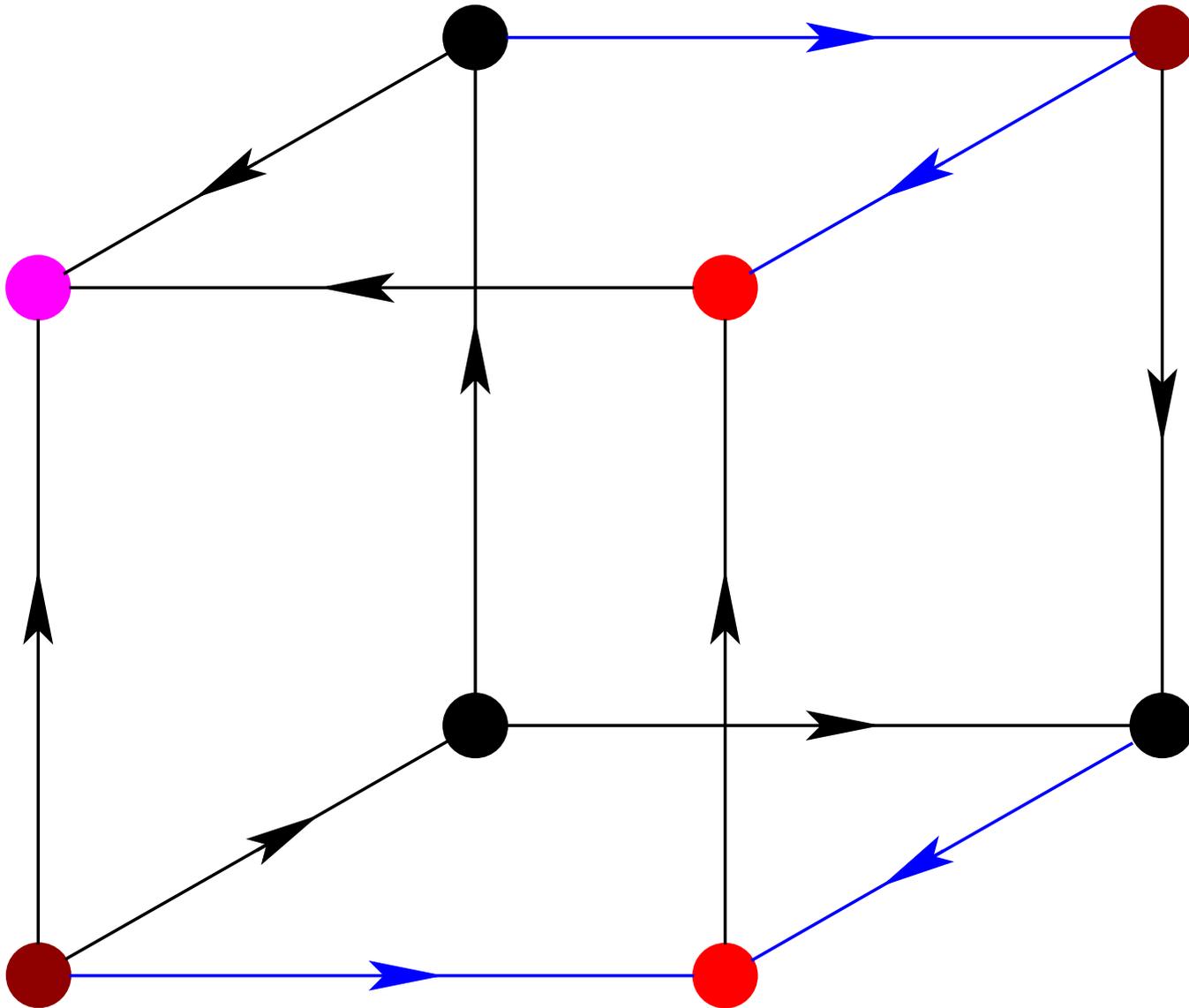
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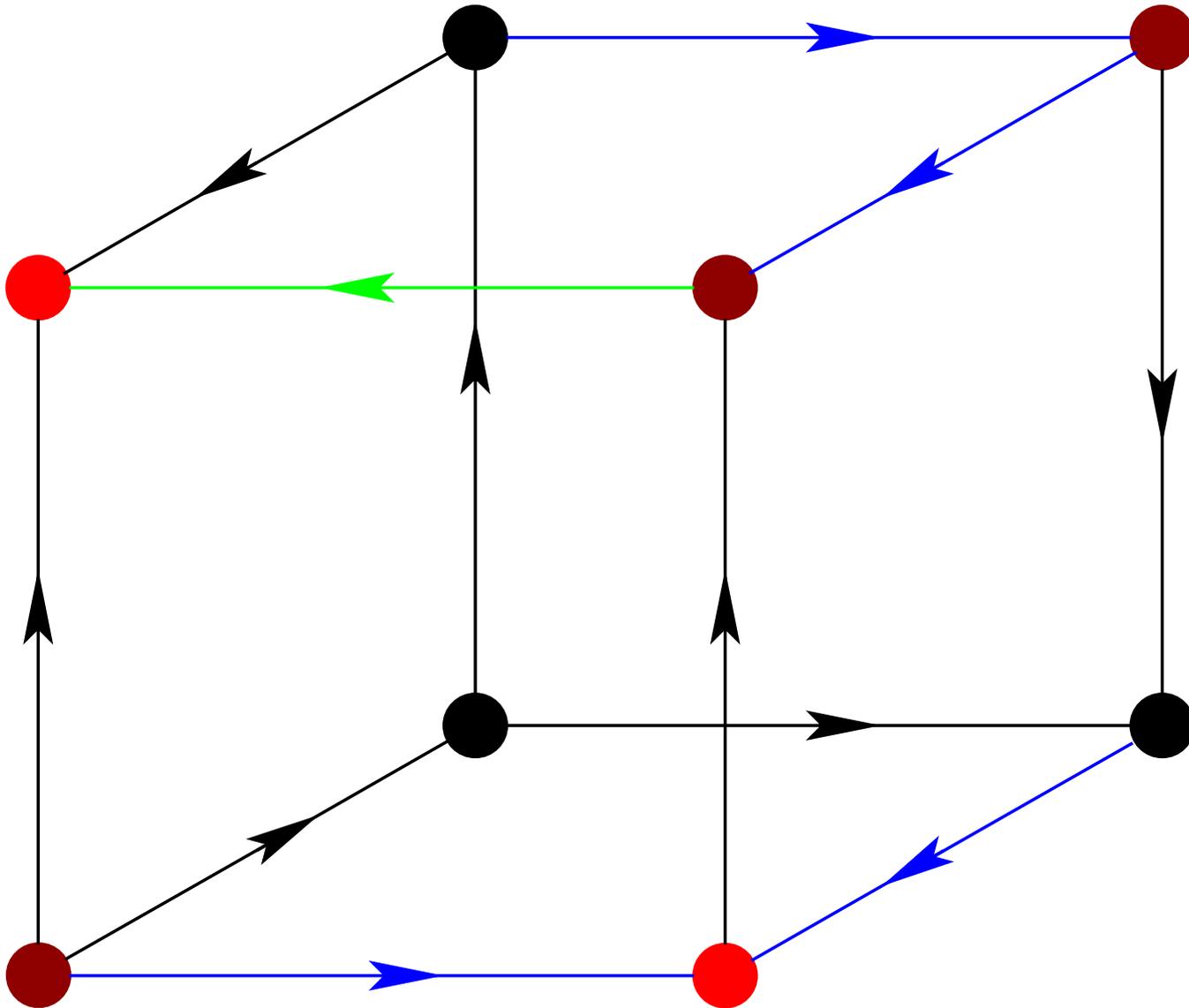
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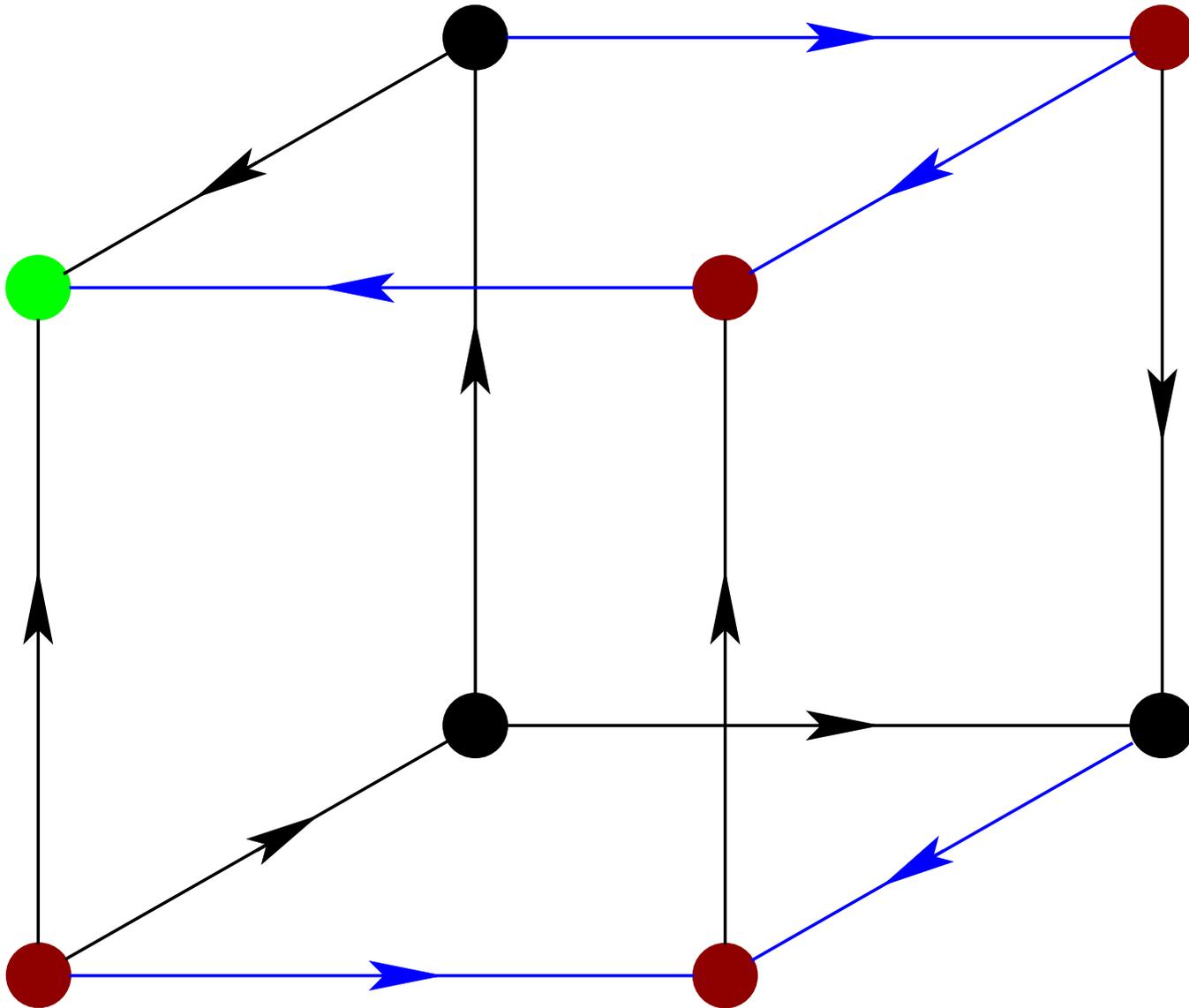
# CU Hypercubes – FSS Example

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# CU Hypercubes – Parity Games

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The strategy space of Player 0's strategies forms a hypercube.

Björklund, Sandberg and Vorobyov (2004) showed that the valuation of Vöge and Jurdziński is a CU function on this hypercube.

Their algorithm is then an instance of a GLI.

# CU Hypercubes – Problems

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**Question:** *What are the bounds for a GLI?*

**Question:** *Does every GLI arise from an instance of the Strategy Improvement algorithm?*

# Results

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**Upper bounds:** Find necessary conditions for GLI

**Lower bounds:** Find sufficient conditions for GLI

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**Notation:** If  $x_0, x_1, \dots$  is a sequence of hypercube vertices,

- $\Delta_{ij}$  is the set of co-ordinates on which  $x_i$  and  $x_j$  differ
- $\Delta_i := \Delta_{i(i+1)}$

# Results – Necessary conditions

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Mansour and Singh (1999):

- $\Delta_i \not\subseteq \Delta_j$  for  $i < j$
- There are at least  $|\Delta_i|$  hypercube vertices valued between  $x_i$  and  $x_{i+1}$

These imply that a GLI has at most  $O\left(\frac{2^n}{n}\right)$  steps.

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Madani (1999), H. (2004):

- For  $i < j$ ,  $x_j$  is not in the face defined at  $x_i$  by the directions not improving at  $x_i$  ( $\Delta_{ij} \not\subseteq \overline{\Delta_i}$ )

This implies a GLI has at most  $2^{n-1}$  steps.

# Results – Necessary conditions

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H. (2004):

**PI:** For  $i < j$ ,  $\Delta_i \cap \Delta_{ij} \not\subseteq \Delta_j$

Implies first condition of Mansour and Singh as well as condition of Madani.

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**Question:** *What are the bounds for a PI sequence?*

<b>Dimension</b>	1	2	3	4	5	6	7
<b>Longest PI sequence</b>	2	3	5	8	13	21	$\geq 26$

**Conjecture:**  *$n$ -dimensional PI sequences are bounded by  $F_{n+1}$  and this bound is attained.*

# Results – Sufficient conditions

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Conjecture: *PI is sufficient for GLI.*

# Results – Other

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FSS has worst case running time  $F_{n+1}$  (Szabó and Welzl, 2001)

**Question:** *Is this bound attained?*

**Question:** *Does this worst case coincide with that of PI?*

# Conclusion

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- Identified several algorithms (Strategy Improvement, GLI, PI) for which upper and lower bounds remain elusive

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- Improved bound on Strategy Improvement algorithm to  $O(|E|2^{|V|})$
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- Identified several algorithms (Strategy Improvement, GLI, PI) for which upper and lower bounds remain elusive
- Improved bound on Strategy Improvement algorithm to  $O(|E|2^{|V|})$
- Can improve Strategy Improvement algorithm to  $O(|V||E|F_{|V|}) = O(|V||E|(1.62)^{|V|})$  by using FSS
- Conjectured that the complexity of the Strategy Improvement algorithm is  $O(|V||E|F_{|V|})$ , and this bound is attained.

# One last thing...

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