# Machine Learning (AIMS) - MT 2017 2. Clustering

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## Outline

This week, we will study some approaches to clustering

- Defining an objective function for clustering
- k-Means formulation for clustering
- Multidimensional Scaling
- Hierarchical clustering
- Spectral clustering

England pushed towards Test defeat by India

France election: Socialists scramble to avoid split after Fillon win

Giants Add to the Winless Browns' Misery

Strictly Come Dancing: Ed Balls leaves programme

Trump Claims, With No Evidence, That 'Millions of People' Voted Illegally

Vive 'La Binoche', the reigning queen of French cinema

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## Clustering

Often data can be grouped together into subsets that are coherent. However, this grouping may be subjective. It is hard to define a general framework.

Two types of clustering algorithms

- 1. Feature-based Points are represented as vectors in  $\mathbb{R}^D$
- 2. (Dis)similarity-based Only know pairwise (dis)similarities

Two types of clustering methods

- 1. Flat Partition the data into k clusters
- 2. Hierarchical Organise data as clusters, clusters of clusters, and so on

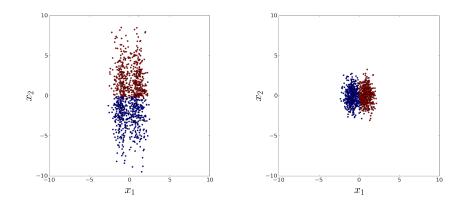
### **Defining Dissimilarity**

Weighted dissimilarity between (real-valued) attributes

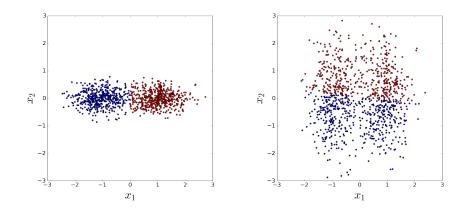
$$d(\mathbf{x}, \mathbf{x}') = f\left(\sum_{i=1}^{D} w_i d_i(x_i, x'_i)\right)$$

- ► In the simplest setting w<sub>i</sub> = 1 and d<sub>i</sub>(x<sub>i</sub>, x'<sub>i</sub>) = (x<sub>i</sub> x'<sub>i</sub>)<sup>2</sup> and f(z) = z, which corresponds to the squared Euclidean distance
- Weights allow us to emphasise features differently
- If features are ordinal or categorical then define distance suitably
- Standardisation (mean 0, variance 1) may or may not help

## Helpful Standardisation



## Unhelpful Standardisation



#### Partition Based Clustering

Want to partition the data into subsets  $C_1, \ldots, C_k$ , where k is fixed in advance

Define quality of a partition by

$$W(C) = \frac{1}{2} \sum_{j=1}^{k} \frac{1}{|C_j|} \sum_{i,i' \in C_j} d(\mathbf{x}_i, \mathbf{x}_{i'})$$

If we use  $d(\mathbf{x},\mathbf{x}') = \|\mathbf{x}-\mathbf{x}'\|^2$  , then

$$W(C) = \sum_{j=1}^{k} \sum_{i \in C_j} \|\mathbf{x}_i - \boldsymbol{\mu}_j\|^2$$

where  $oldsymbol{\mu}_j = rac{1}{|C_j|} \sum_{i \in C_j} \mathbf{x}_i$ 

The objective is minimising the sum of squares of distances to the mean within each cluster

#### Outline

#### **Clustering Objective**

#### k-Means Formulation of Clustering

**Multidimensional Scaling** 

**Hierarchical Clustering** 

Spectral Clustering

#### Partition Based Clustering : k-Means Objective

Minimise jointly over partitions  $C_1, \ldots, C_k$  and  $\mu_1, \ldots, \mu_k$ 

$$W(C) = \sum_{j=1}^{k} \sum_{i \in C_j} \left\| \mathbf{x}_i - \boldsymbol{\mu}_j \right\|^2$$

This problem is NP-hard even for k = 2 for points in  $\mathbb{R}^D$ 

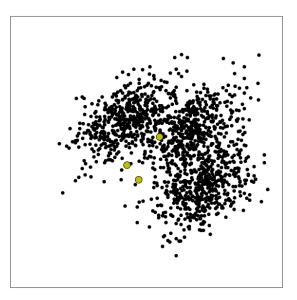
If we fix  $\mu_1, \ldots, \mu_j$ , finding a partition  $(C_j)_{j=1}^k$  that minimises W is easy

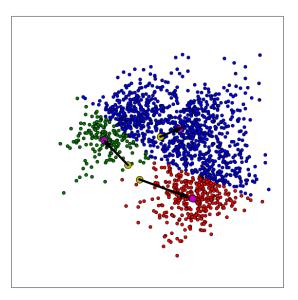
$$C_{j} = \{i \mid ||\mathbf{x}_{i} - \boldsymbol{\mu}_{j}|| = \min_{j'} ||\mathbf{x}_{i} - \boldsymbol{\mu}_{j'}||\}$$

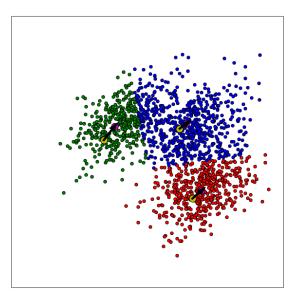
If we fix the clusters  $C_1,\ldots,C_k$  minimising W with respect to  $(\mu_j)_{j=1}^k$  is easy

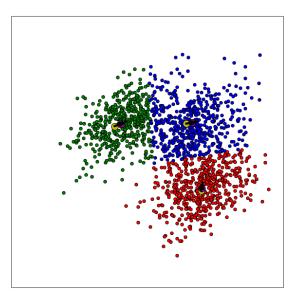
$$\boldsymbol{\mu}_j = rac{1}{|C_j|} \sum_{i \in C_j} \mathbf{x}_i$$

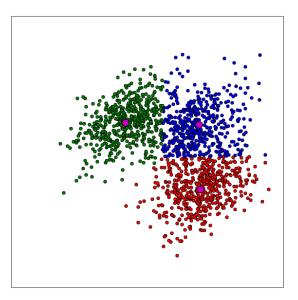
Iteratively run these two steps - assignment and update



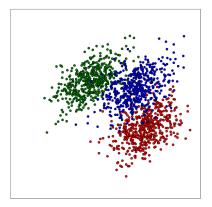




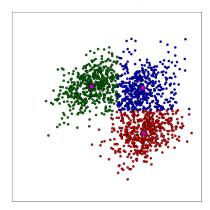




#### Ground Truth Clusters



k-Means Clusters (k = 3)



#### The *k*-Means Algorithm

- 1. Intialise means  $\mu_1, \ldots, \mu_k$  "randomly"
- 2. Repeat until convergence:
  - a. Find assignments of data to clusters represented by the mean that is closest to obtain,  $C_1, \ldots, C_k$ :

$$C_{j} = \{i \mid j = \operatorname*{argmin}_{j'} \left\| \mathbf{x}_{i} - \boldsymbol{\mu}_{j'} \right\|^{2} \}$$

b. Update means using the current cluster assignments:

$$\mu_j = \frac{1}{|C_j|} \sum_{i \in C_j} \mathbf{x}_i$$

Note 1: Ties can be broken arbitrarily

Note 2: Choosing k random datapoints to be the initial k-means is a good idea

#### The *k*-Means Algorithm

Does the algorithm always converge?

Yes, because the W function decreases every time a new partition is used; there are only finitely many partitions

$$W(C) = \sum_{j=1}^{k} \sum_{i \in C_j} \|\mathbf{x}_i - \boldsymbol{\mu}_j\|^2$$

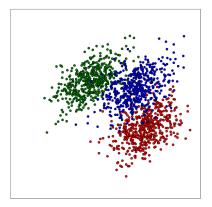
Convergence may be very slow in the worst-case, but typically fast on real-world instances

Convergence is probably to a local minimum. Run multiple times with random initialisation.

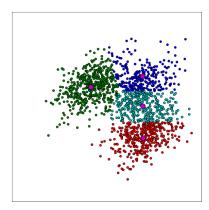
Can use other criteria: *k*-medoids, *k*-centres, etc.

Selecting the right k is not easy: plot W against k and identify a "kink"

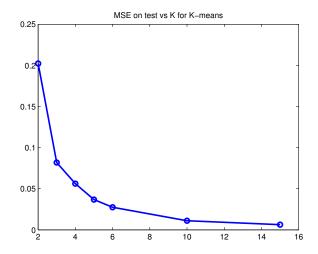
#### Ground Truth Clusters



k-Means Clusters (k = 4)



#### Choosing the number of clusters k



- ▶ As in the case of PCA, larger k will give better value of the objective
- Choose suitable k by identifying a "kink" or "elbow" in the curve (Source: Kevin Murphy, Chap 11)

#### Outline

**Clustering Objective** 

k-Means Formulation of Clustering

**Multidimensional Scaling** 

**Hierarchical Clustering** 

Spectral Clustering

#### Multidimensional Scaling (MDS)

In certain cases, it may be easier to define (dis)similarity between objects than embed them in Euclidean space

Algorithms such as k-means require points to be in Euclidean space

Ideal Setting: Suppose for some N points in  $\mathbb{R}^D$  we are given all pairwise Euclidean distances in a matrix  $\mathbf{D}$ 

Can we reconstruct  $\mathbf{x}_1, \ldots, \mathbf{x}_N$ , i.e., all of X?



Distances are preserved under translation, rotation, reflection, etc.

We cannot recover  ${\bf X}$  exactly; we can aim to determine  ${\bf X}$  up to these transformations

If  $D_{ij}$  is the distance between points  $\mathbf{x}_i$  and  $\mathbf{x}_j$ , then

$$D_{ij}^{2} = \|\mathbf{x}_{i} - \mathbf{x}_{j}\|^{2}$$
  
=  $\mathbf{x}_{i}^{\mathsf{T}}\mathbf{x}_{i} - 2\mathbf{x}_{i}^{\mathsf{T}}\mathbf{x}_{j} + \mathbf{x}_{j}^{\mathsf{T}}\mathbf{x}_{j}$   
=  $M_{ii} - 2M_{ij} + M_{jj}$ 

Here  $\mathbf{M} = \mathbf{X}\mathbf{X}^{\mathsf{T}}$  is the  $N \times N$  matrix of dot products

Exercise: Show that assuming  $\sum_i \mathbf{x}_i = \mathbf{0}$ ,  $\mathbf{M}$  can be recovered from  $\mathbf{D}$ 

### Multidimensional Scaling

Consider the (full) SVD:  $\mathbf{X} = \mathbf{U} \mathbf{\Sigma} \mathbf{V}^{\mathsf{T}}$ 

We can write  ${\bf M}$  as

$$\mathbf{M} = \mathbf{X}\mathbf{X}^{\mathsf{T}} = \mathbf{U}\mathbf{\Sigma}\mathbf{\Sigma}^{\mathsf{T}}\mathbf{U}^{\mathsf{T}}$$

Starting from  ${\bf M},$  we can reconstruct  ${\bf \tilde{X}}$  using the eigendecomposition of  ${\bf M}$ 

$$\mathbf{M} = \mathbf{U} \boldsymbol{\Lambda} \mathbf{U}^\mathsf{T}$$

Because, M is symmetric and positive semi-definite,  $\mathbf{U}^{\mathsf{T}} = \mathbf{U}^{-1}$  and all entries of (diagonal matrix) A are non-negative

Let  $\tilde{\mathbf{X}} = \mathbf{U} \mathbf{\Lambda}^{1/2}$ 

If we are satisfied with approximate reconstruction, we can use truncated eigendecomposition

In general if you define (dis)similarities on objects such as text documents, genetic sequences, *etc.*, we cannot be sure that the generated similarity matrix **M** will be positive semi-definite or that the dissimilarity matrix **D** is a valid squared Euclidean distance

If such cases, we cannot always find a Euclidean embeddding that recovers the (dis)similarities exactly

Minimize stress function: Find  $\mathbf{z}_1, \ldots, \mathbf{z}_N$  that minimizes

$$S(\mathbf{Z}) = \sum_{i \neq j} (D_{ij} - \|\mathbf{z}_i - \mathbf{z}_j\|)^2$$

Several other types of stress functions can be used

## Multidimensional Scaling: Summary

- In certain applications, it may be easier to define pairwise similarities or distances, rather than construct a Euclidean embedding of discrete objects, *e.g.*, genetic data, text data, *etc*.
- Many machine learning algorithms require (or are more naturally expressed with) data in some Euclidean space
- Multidimensional Scaling gives a way to find an embedding of the data in Euclidean space that (approximately) respects the original distance/similarity values

#### Outline

**Clustering Objective** 

k-Means Formulation of Clustering

Multidimensional Scaling

**Hierarchical Clustering** 

Spectral Clustering

## Hierarchical Clustering

Hierarchical structured data exists all around us

- Measurements of different species and individuals within species
- Top-level and low-level categories in news articles
- Country, county, town level data

Two Algorithmic Strategies for Clustering

- Agglomerative: Bottom-up, clusters formed by merging smaller clusters
- Divisive: Top-down, clusters formed by splitting larger clusters

Visualise this as a dendrogram or tree

#### Measuring Dissimilarity at Cluster Level

To find hierarchical clusters we need to define dissimilarity at cluster level, not just at datapoints

Suppose we have dissimilarity at datapoint level, *e.g.*,  $d(\mathbf{x}, \mathbf{x}') = \|\mathbf{x} - \mathbf{x}'\|$ 

Different ways to define dissimilarity at cluster level, say C and C'

Single Linkage

$$D(C, C') = \min_{\mathbf{x} \in C, \mathbf{x}' \in C'} d(\mathbf{x}, \mathbf{x}')$$

Complete Linkage

$$D(C, C') = \max_{\mathbf{x} \in C, \mathbf{x}' \in C'} d(\mathbf{x}, \mathbf{x}')$$

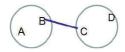
Average Linkage

$$D(C,C') = \frac{1}{|C| \cdot |C'|} \sum_{\mathbf{x} \in C, \mathbf{x}' \in C'} d(\mathbf{x}, \mathbf{x}')$$

#### Measuring Dissimilarity at Cluster Level

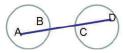
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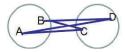
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Average Linkage

$$D(C,C') = \frac{1}{|C| \cdot |C'|} \sum_{\mathbf{x} \in C, \mathbf{x}' \in C'} d(\mathbf{x}, \mathbf{x}')$$



## Linkage-based Clustering Algorithm

- 1. Initialise clusters as singletons  $C_i = \{i\}$
- 2. Initialise clusters available for merging  $S = \{1, \dots, N\}$
- 3. Repeat
  - a. Pick 2 most similar clusters,  $(j,k) = \underset{\substack{i,k \in S}}{\operatorname{argmin}} D(j,k)$

**b.** Let 
$$C_l = C_j \cup C_k$$

- c. If  $C_l = \{1, ..., N\}$ , break;
- d. Set  $S = (S \setminus \{j, k\}) \cup \{l\}$
- e. Update D(i, l) for all  $i \in S$  (using desired linkage property)

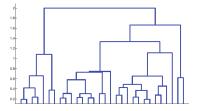
## Hierarchical Clustering: Dendogram

Outputs of hierarchical clustering algorithms are typically represented using dendrograms

A dendrogram is a binary tree, representing clusters as they were merged

The height of a node represents dissimilarity

Cutting the dendrogram at some level gives a partition of data



#### Outline

**Clustering Objective** 

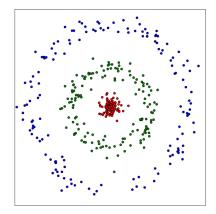
k-Means Formulation of Clustering

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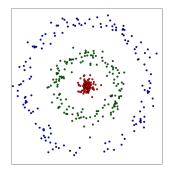
**Hierarchical Clustering** 

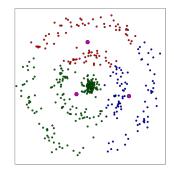
Spectral Clustering

## Spectral Clustering



## Spectral Clustering: Limitations of *k*-Means





k-means will typically form clusters that are spherical, elliptical, convex

Kernel PCA followed by k-means can result in better clusters

Spectral clustering is a (related) alternative that often works better

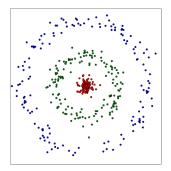
Construct a graph from data; one node for every point in dataset

Use similarity measure, *e.g.*,  $s_{i,j} = \exp(-\|\mathbf{x}_i - \mathbf{x}_j\|^2 / \sigma)$ 

Construct mutual K-nearest neighbour graph, *i.e.*, (i, j) is an edge if either i is among the K nearest neighbours of j or vice versa

The weight of edge (i, j), if it exists is  $s_{i,j}$ 

## Spectral Clustering





## Spectral Clustering



Use graph partitioning algorithms

Mincut can give bad cuts (only one node on one side of the cut)

Multi-way cuts, balanced cuts, are typically NP-hard to compute

Relaxations of these problems give eigenvectors of Laplacian

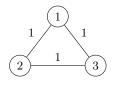
 ${f W}$  is the weighted adjacency matrix

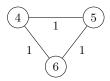
 $\mathbf{D}$  is (diagonal) degree matrix:  $D_{ii} = \sum_{j} W_{ij}$ 

 $\mathsf{Laplacian}\ \mathbf{L} = \mathbf{D} - \mathbf{W}$ 

Normalised Laplacian:  $\tilde{\mathbf{L}} = \mathbf{I} - \mathbf{D}^{-1} \mathbf{W}$ 

# The weighted adjacency matrix, the degree matrix and the Laplacian are given by

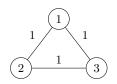


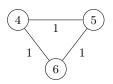


Suppose all edge weights are 1 (0 for missing edges)

$$\mathbf{W} = \begin{bmatrix} 0 & 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 & 1 & 0 \end{bmatrix}$$
$$\mathbf{D} = \begin{bmatrix} 2 & 0 & 0 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 & 0 & 2 \end{bmatrix}$$
$$\mathbf{L} = \mathbf{D} - \mathbf{W} = \begin{bmatrix} 2 & -1 & -1 & 0 & 0 & 0 \\ -1 & 2 & -1 & 0 & 0 & 0 \\ -1 & -1 & 2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 2 & -1 & -1 \\ 0 & 0 & 0 & 0 & -1 & 2 & -1 \\ 0 & 0 & 0 & 0 & -1 & 2 & -1 \end{bmatrix}$$

Let us consider some eigenvectors of  ${f L}$ 





Suppose all edge weights are 1 (0 for missing edges)

$$\mathbf{L} = \mathbf{D} - \mathbf{W} = \begin{vmatrix} 2 & -1 & -1 & 0 & 0 & 0 \\ -1 & 2 & -1 & 0 & 0 & 0 \\ -1 & -1 & 2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 2 & -1 & -1 \\ 0 & 0 & 0 & -1 & 2 & -1 \\ 0 & 0 & 0 & -1 & -1 & 2 \end{vmatrix}$$

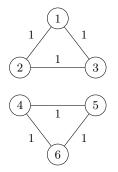
 $\mathbf{v}_1 = [1, 1, 1, 1, 1]^{\mathsf{T}}$  is an eigenvector with

eigenvalue 0

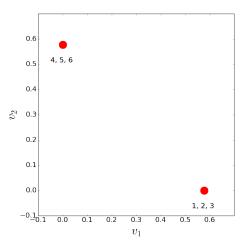
 $\mathbf{v}_2 = [1, 1, 1, -1, -1, -1]^\mathsf{T}$  is also an eigenvector with eigenvalue 0

 $\alpha_1 {\bf v}_1 + \alpha_2 {\bf v}_2$  for any  $\alpha_1, \alpha_2$  is also an eigenvector with eigenvalue 0

We can use the matrix  $[\mathbf{v}_1\mathbf{v}_2]$  as the  $N\times 2$  feature matrix and perform k-means

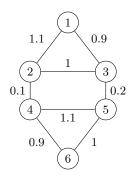


Suppose all edge weights are 1 (0 for missing edges)



Let us consider some eigenvectors of  ${\bf L}$ 

г.



$$\mathbf{L} = \mathbf{D} - \mathbf{W} = \begin{bmatrix} 2 & -1.1 & -0.9 & 0 & 0 & 0 \\ -1.1 & 2.2 & -1 & -0.1 & 0 & 0 \\ -0.9 & -1 & 2.1 & 0 & -0.2 & 0 \\ 0 & -0.1 & 0 & 2.1 & -1.1 & -0.9 \\ 0 & 0 & -0.2 & -1.1 & 2.3 & -1 \\ 0 & 0 & 0 & -0.9 & -1 & 1.9 \end{bmatrix}$$

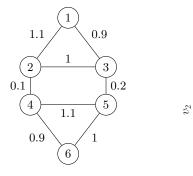
When the weights are slightly perturbed,  $\mathbf{v}_1 = [1, \dots, 1]^{\mathsf{T}}$  is still an eigenvector with eigenvalue 1

We can't compute the second eigenvector  $\mathbf{v}_2$  by hand

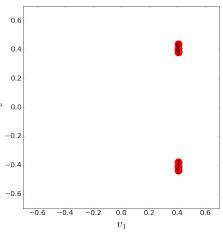
Suppose all edge weights are 1 (0 for missing edges)

Nevertheless, we expect that the eigenspace corresponding to similar eigenvalues is relatively stable

We can still use the matrix  $[{\bf v}_1 {\bf v}_2]$  as the  $N\times 2$  feature matrix and perform k-means



Suppose all edge weights are 1 (0 for missing edges)



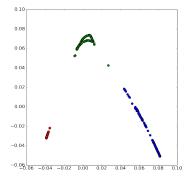
#### Spectral Clustering Algorithm

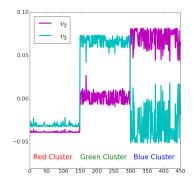
Input: Weighted graph with weighted adjacency matrix  ${f W}$ 

- 1. Construct Laplacian  $\mathbf{L} = \mathbf{D} \mathbf{W}$
- 2. Find  $\mathbf{v}_1 = \mathbf{1}, \mathbf{v}_2, \dots, \mathbf{v}_{l+1}$  the *k*-eigenvectors
- 3. Construct the  $N \times l$  feature matrix  $\mathbf{V}_l = [\mathbf{v}_2, \cdots, \mathbf{v}_l]$
- 4. Apply clustering algorithm using  $V_l$  as features, *e.g.*, *k*-means

Note: If the degrees of nodes are not balanced, using the normalised Laplacian,  $\tilde{\mathbf{L}}=\mathbf{I}-\mathbf{D}^{-1}\mathbf{W}$  may be a better idea

## Spectral Clustering





Clustering is grouping together similar data in a larger collection of heterogeneous data

Definition of good clusters often user-dependent

Clustering algorithms in feature space, e.g., k-Means

Clustering algorithms that only use (dis)similarities: *k*-Medoids, hierarchical clustering

Spectral clustering when clusters may be non-convex