
Vellvm: Verifying Transformations of the LLVM IR

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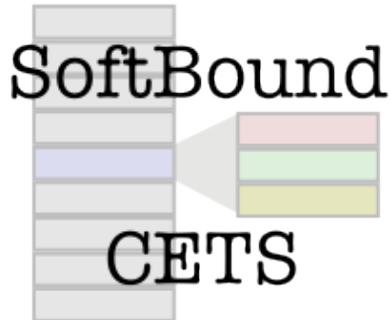
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Motivation: SoftBound/CETS

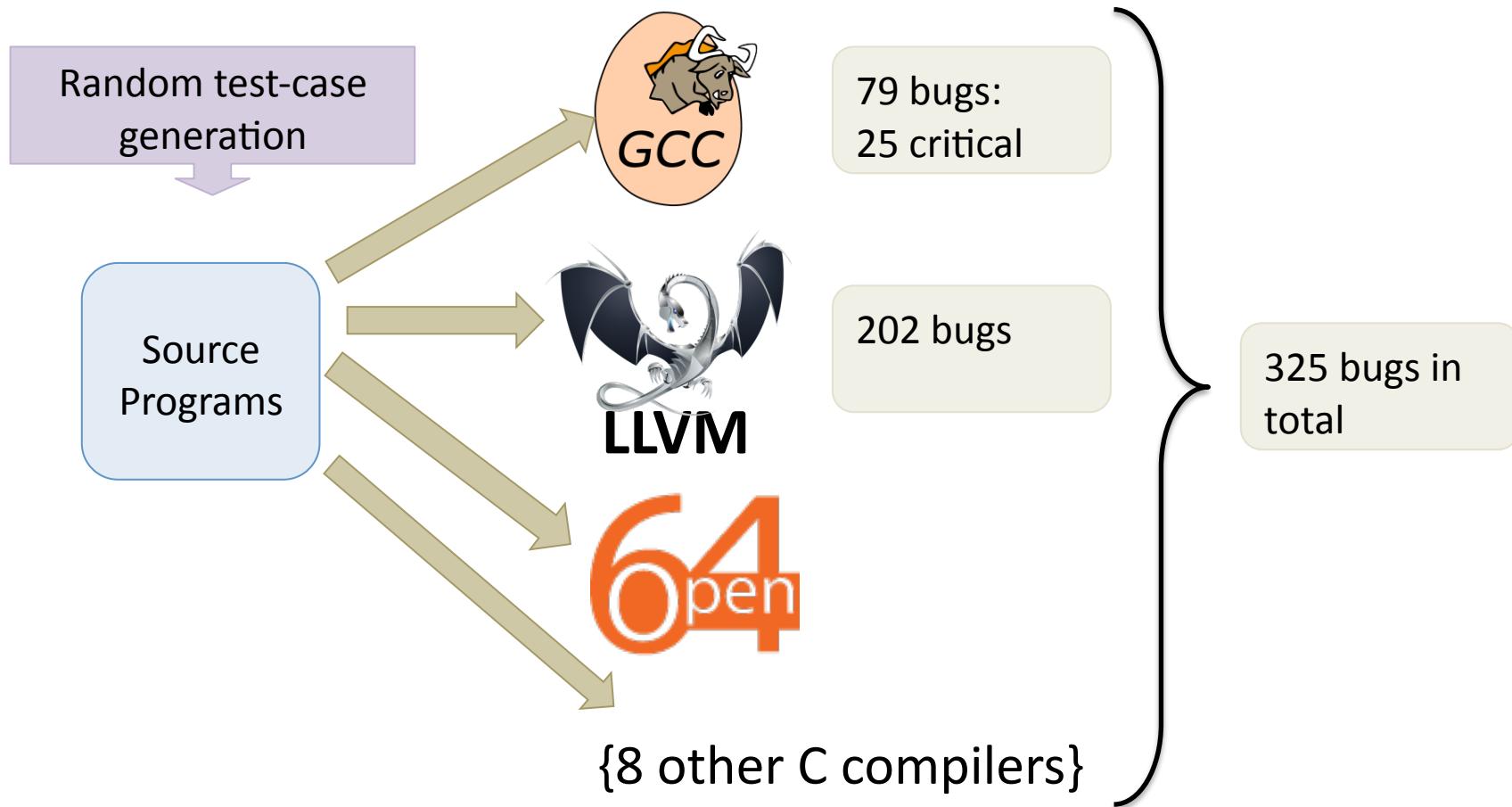
[Nagarakatte, et al. *PLDI '09, ISMM '10*]



- Buffer overflow vulnerabilities.
- Detect spatial/temporal memory safety violations in legacy C code.
- Implemented as an LLVM pass.
- What about correctness?

Motivation: Compiler Bugs

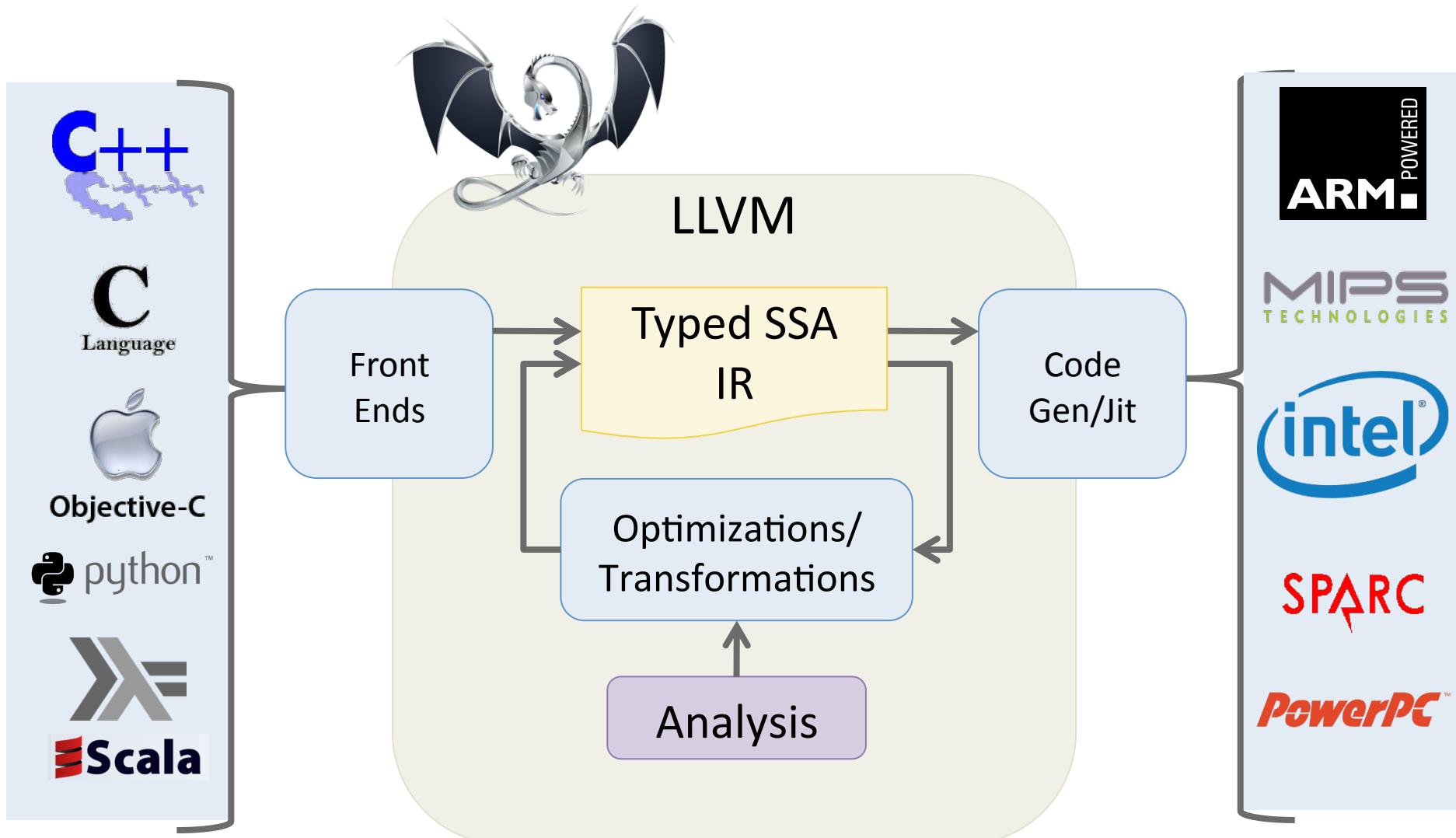
[Yang et al. PLDI 2011]



Verified Compilation: CompCert [Leroy et al.]
(Not directly applicable to LLVM)

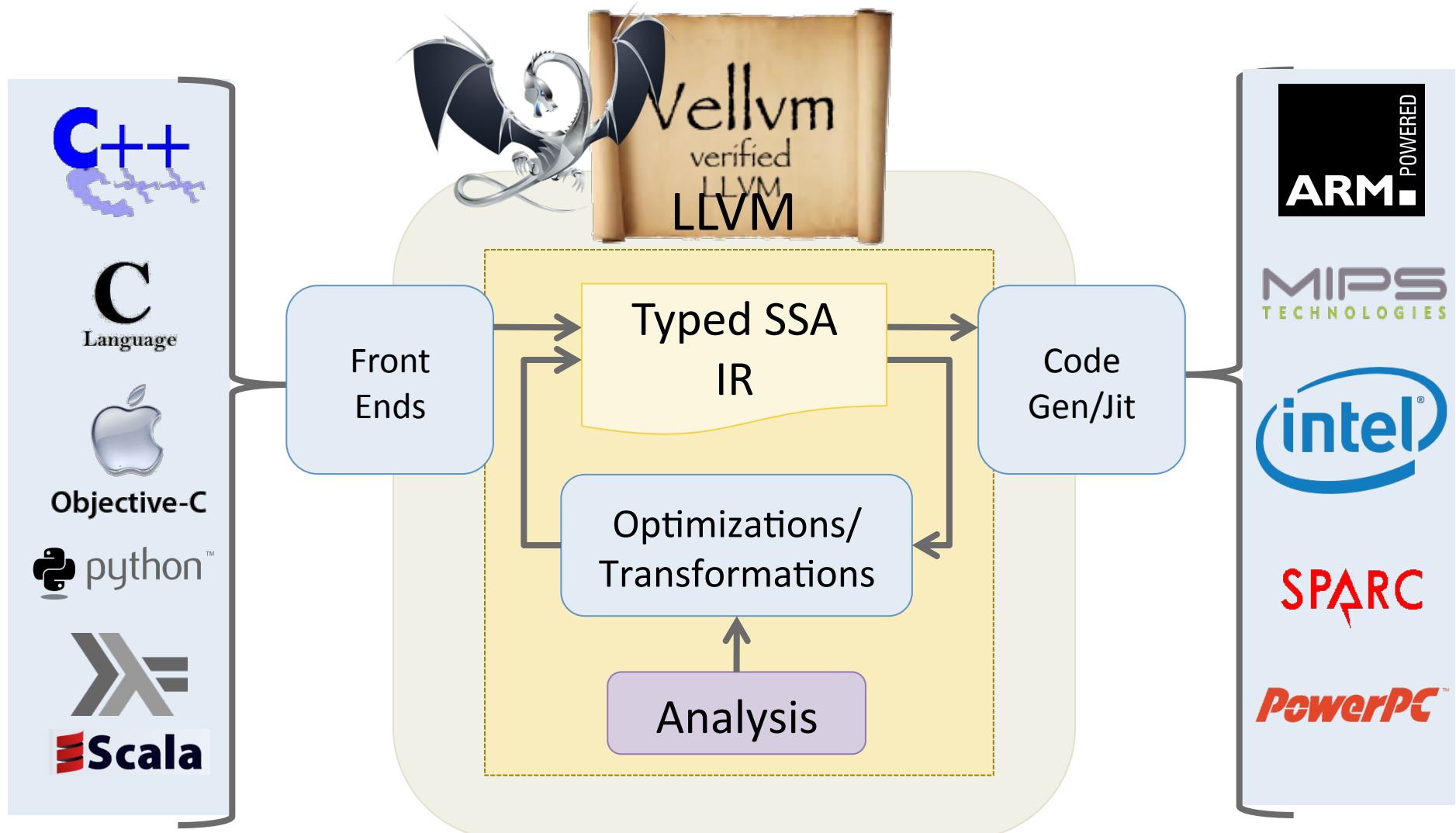
LLVM Compiler Infrastructure

[Lattner et al.]



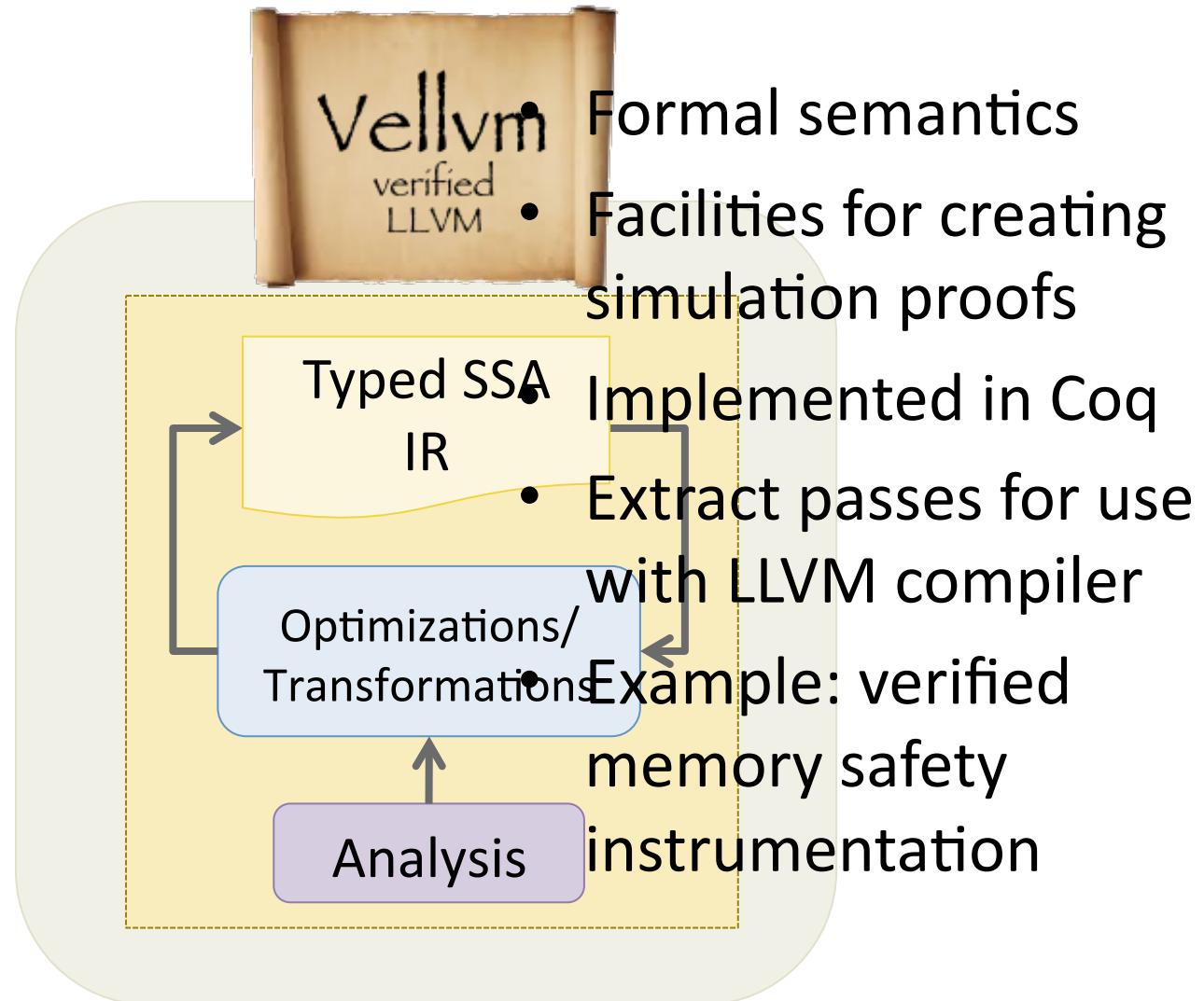
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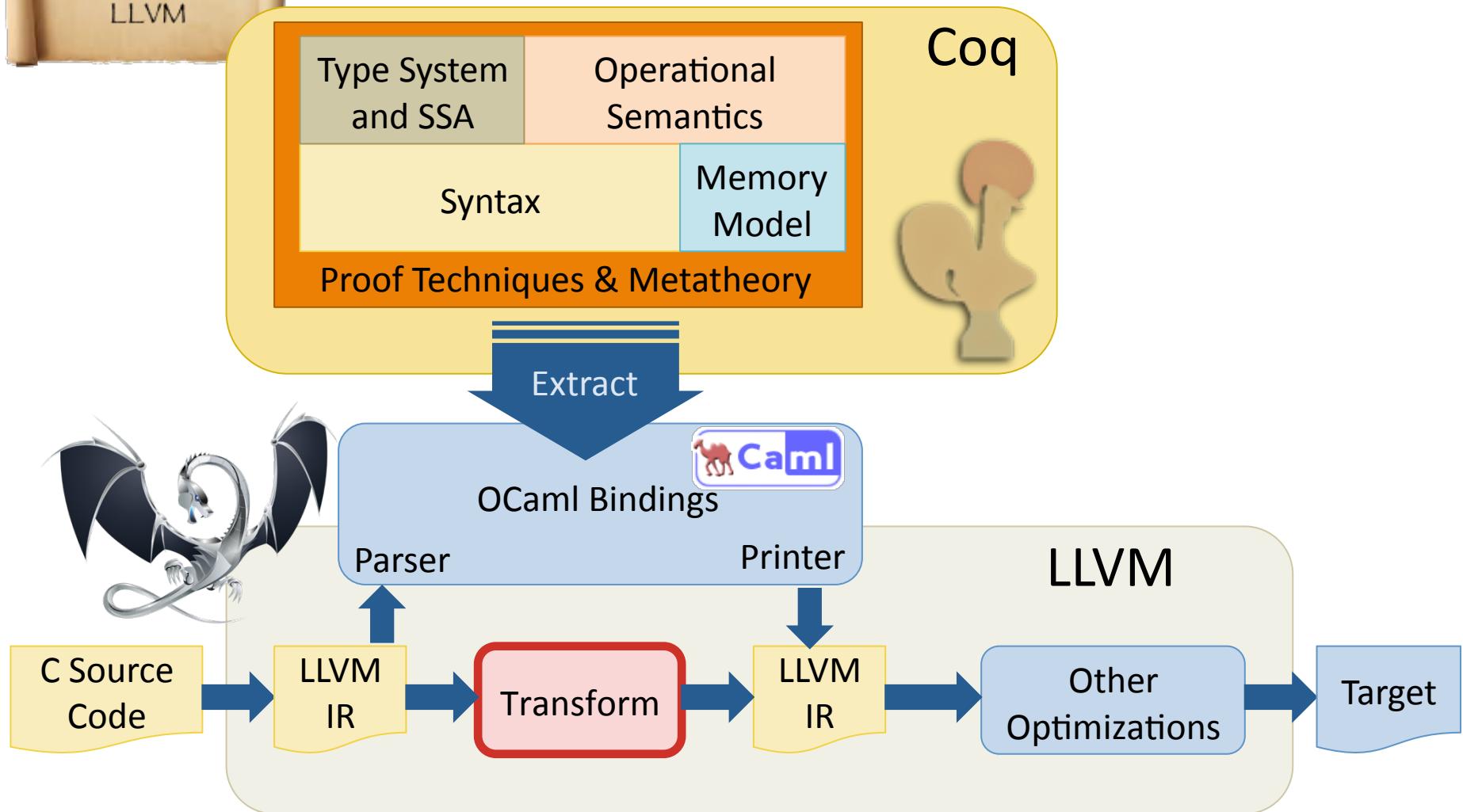
The Vellvm Project

[Zhao et al. POPL 2012, CPP 2012, PLDI 2013]



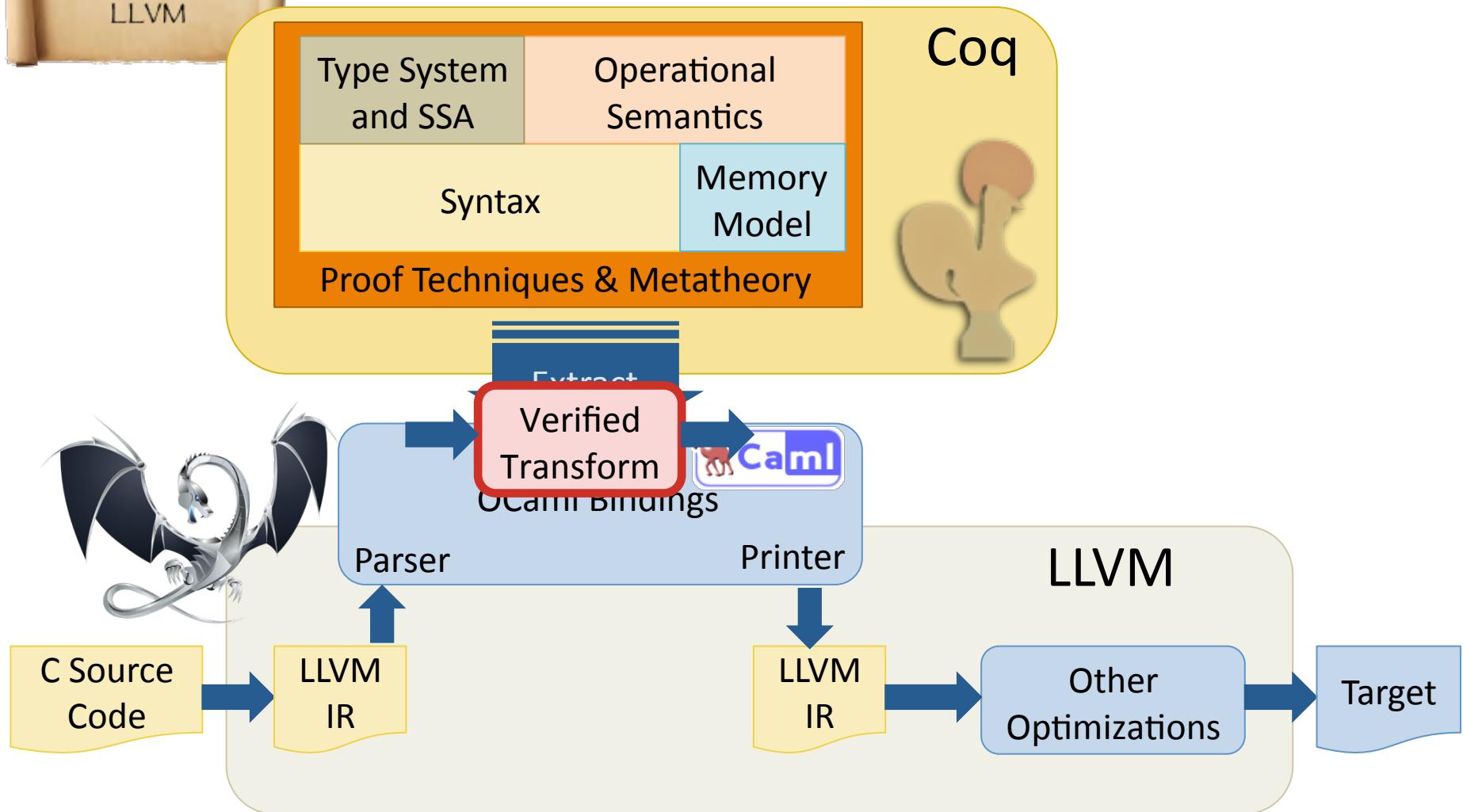


Vellvm Framework





Vellvm Framework



Plan

- Tour of the LLVM IR
- Vellvm infrastructure
 - Operational Semantics
 - SSA Metatheory + Proof Techniques
- Case studies:
 - SoftBound memory safety
 - mem2reg
- Conclusion

LLVM IR by Example

entry:

Control-flow Graphs:
+ Labeled blocks

loop:

exit:

LLVM IR by Example

entry:

```
r0 = ...
r1 = ...
r2 = ...
```

loop:

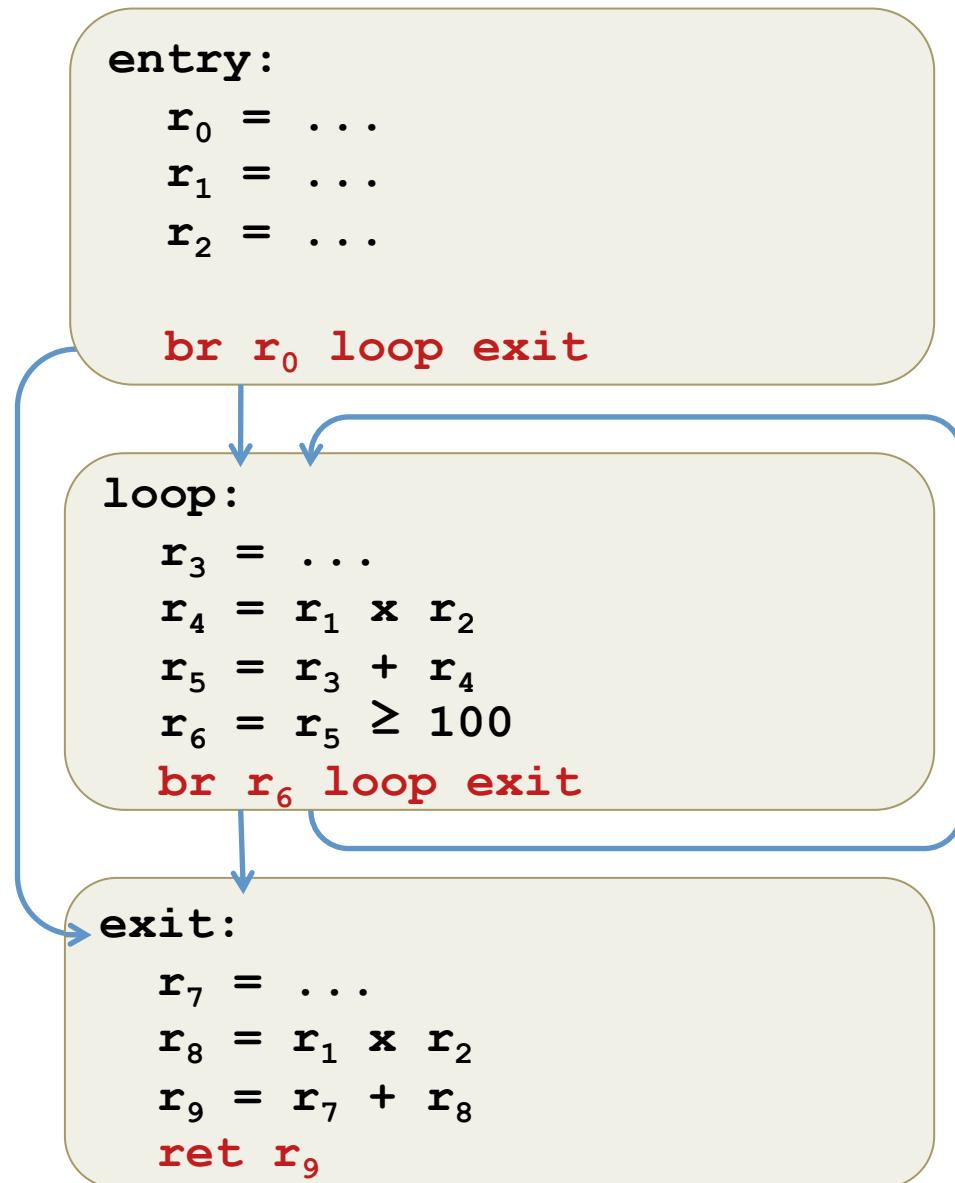
```
r3 = ...
r4 = r1 × r2
r5 = r3 + r4
r6 = r5 ≥ 100
```

exit:

```
r7 = ...
r8 = r1 × r2
r9 = r7 + r8
```

Control-flow Graphs:
+ Labeled blocks
+ Binary Operations

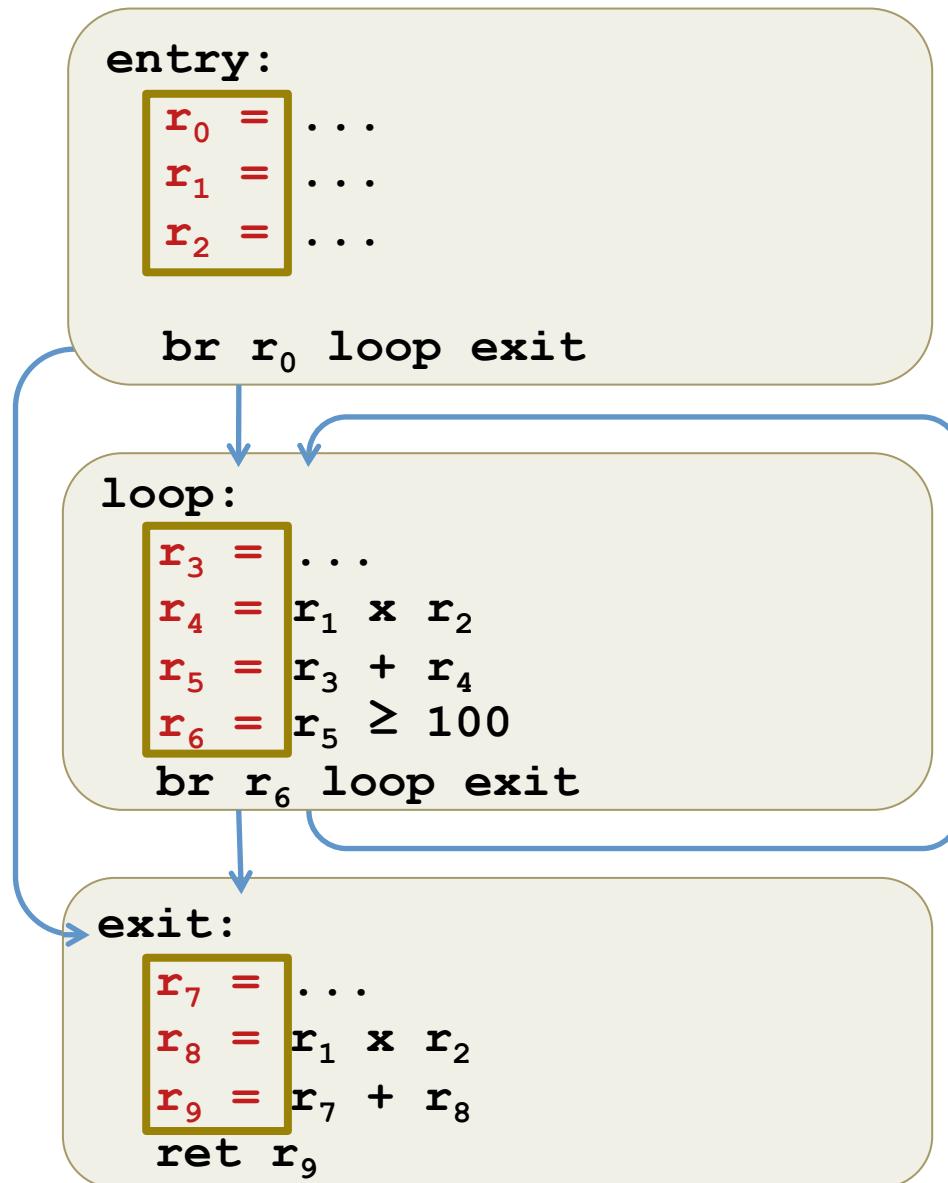
LLVM IR by Example



Control-flow Graphs:

- + Labeled blocks
- + Binary Operations
- + Branches/Return

LLVM IR by Example

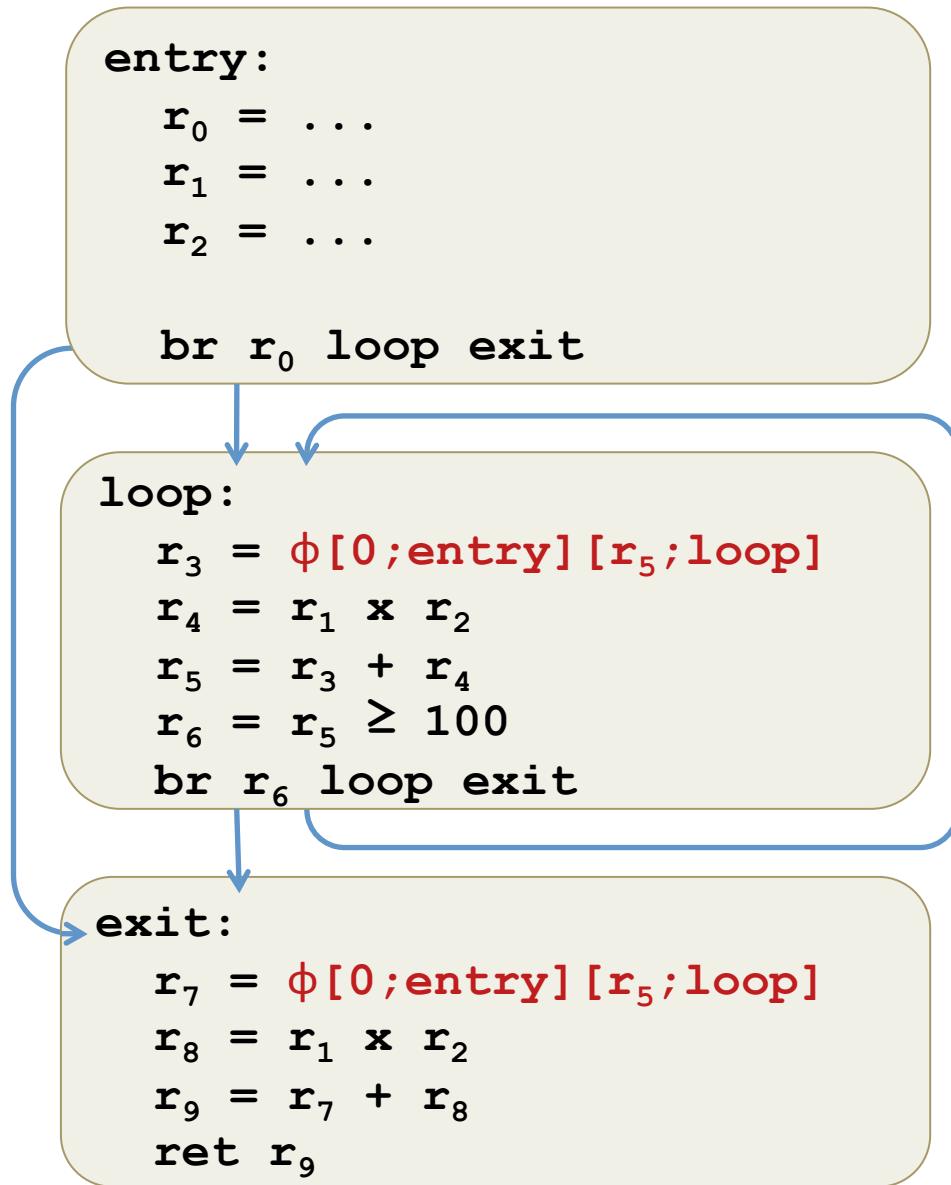


Control-flow Graphs:

- + Labeled blocks
- + Binary Operations
- + Branches/Return
- + Static Single Assignment

(each variable assigned
only *once*, statically)

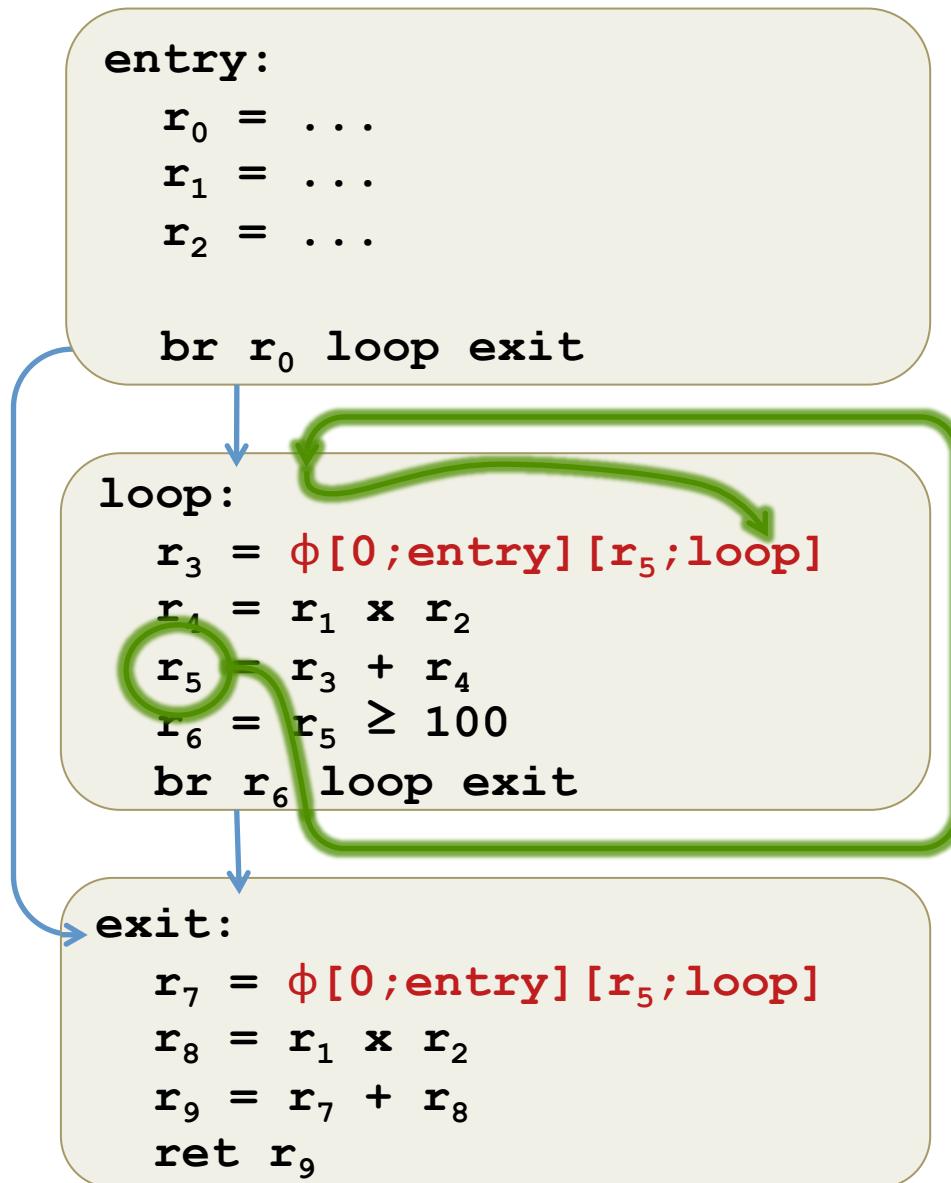
LLVM IR by Example



Control-flow Graphs:

- + Labeled blocks
- + Binary Operations
- + Branches/Return
- + Static Single Assignment
- + ϕ nodes

LLVM IR by Example



Control-flow Graphs:

- + Labeled blocks
- + Binary Operations
- + Branches/Return
- + Static Single Assignment
- + ϕ nodes

(choose values based
on predecessor blocks)

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Structured Data in LLVM

- LLVM's IR uses types to describe the structure of data.

ty ::=	
i1 i8 i32 ...	<i>N-bit integers</i>
[<#elts> x t]	<i>arrays</i>
r (ty ₁ , ty ₂ , ..., ty _n)	<i>function types</i>
{ty ₁ , ty ₂ , ..., ty _n }	<i>structures</i>
ty*	<i>pointers</i>
%Tident	<i>named (identified) type</i>
r ::=	<i>Return Types</i>
ty	<i>first-class type</i>
void	<i>no return value</i>

- <#elts> is an integer constant ≥ 0
- (Recursive) Structure types can be named at the top level:

```
%T1 = type {ty1, ty2, ..., tyn}
```

LLVM's memory model

```
%ST = type {i10,[10 x i8*]}
```

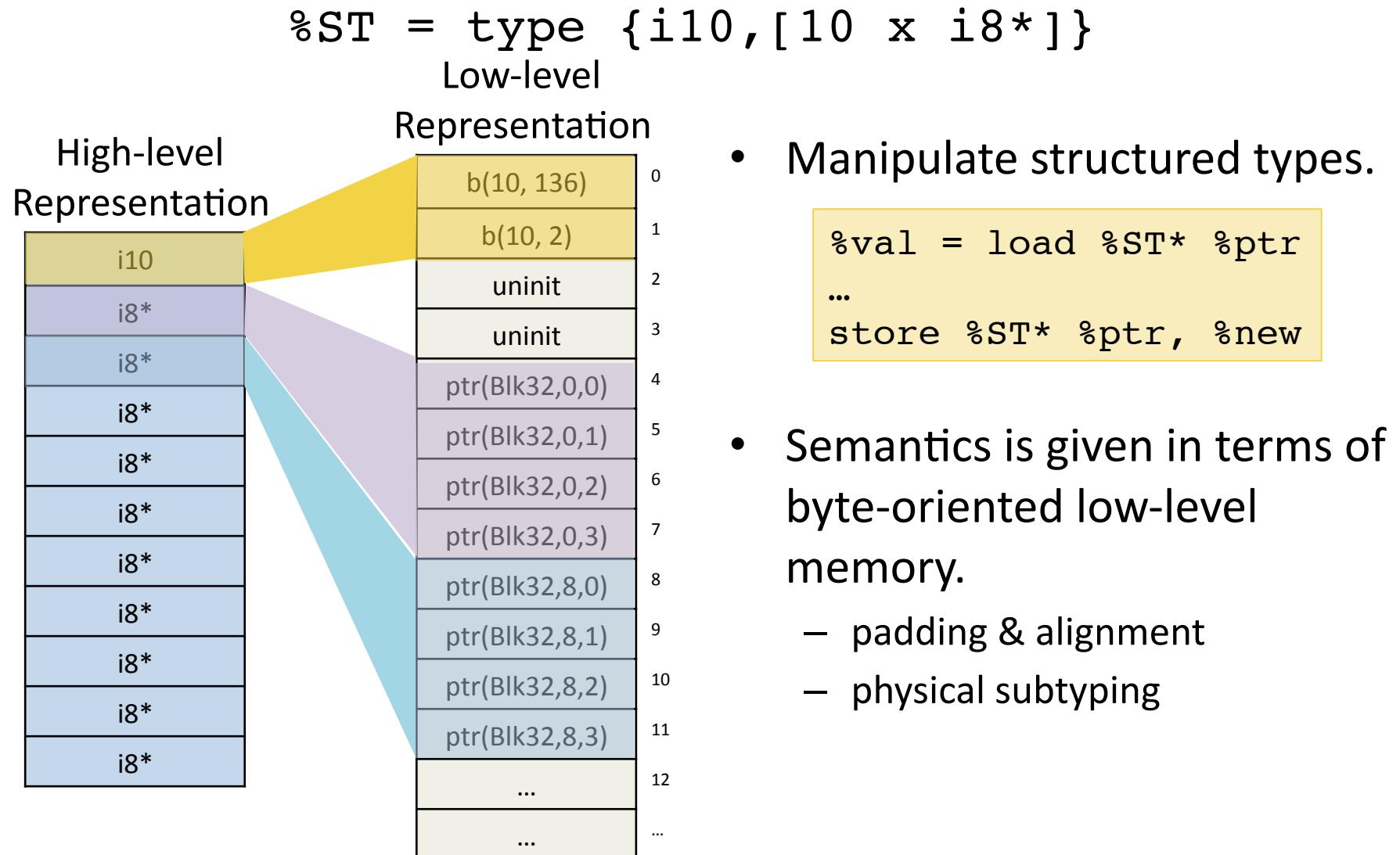
High-level
Representation

i10
i8*

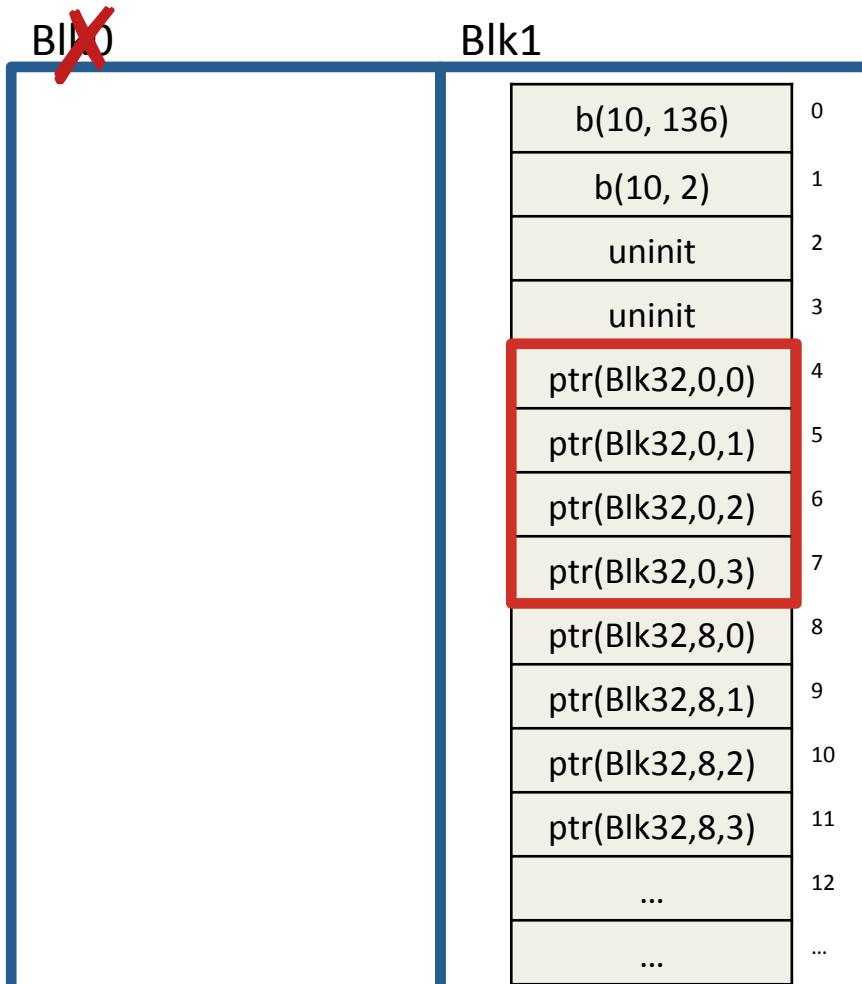
- Manipulate structured types.

```
%val = load %ST* %ptr  
...  
store %ST* %ptr, %new
```

LLVM's memory model

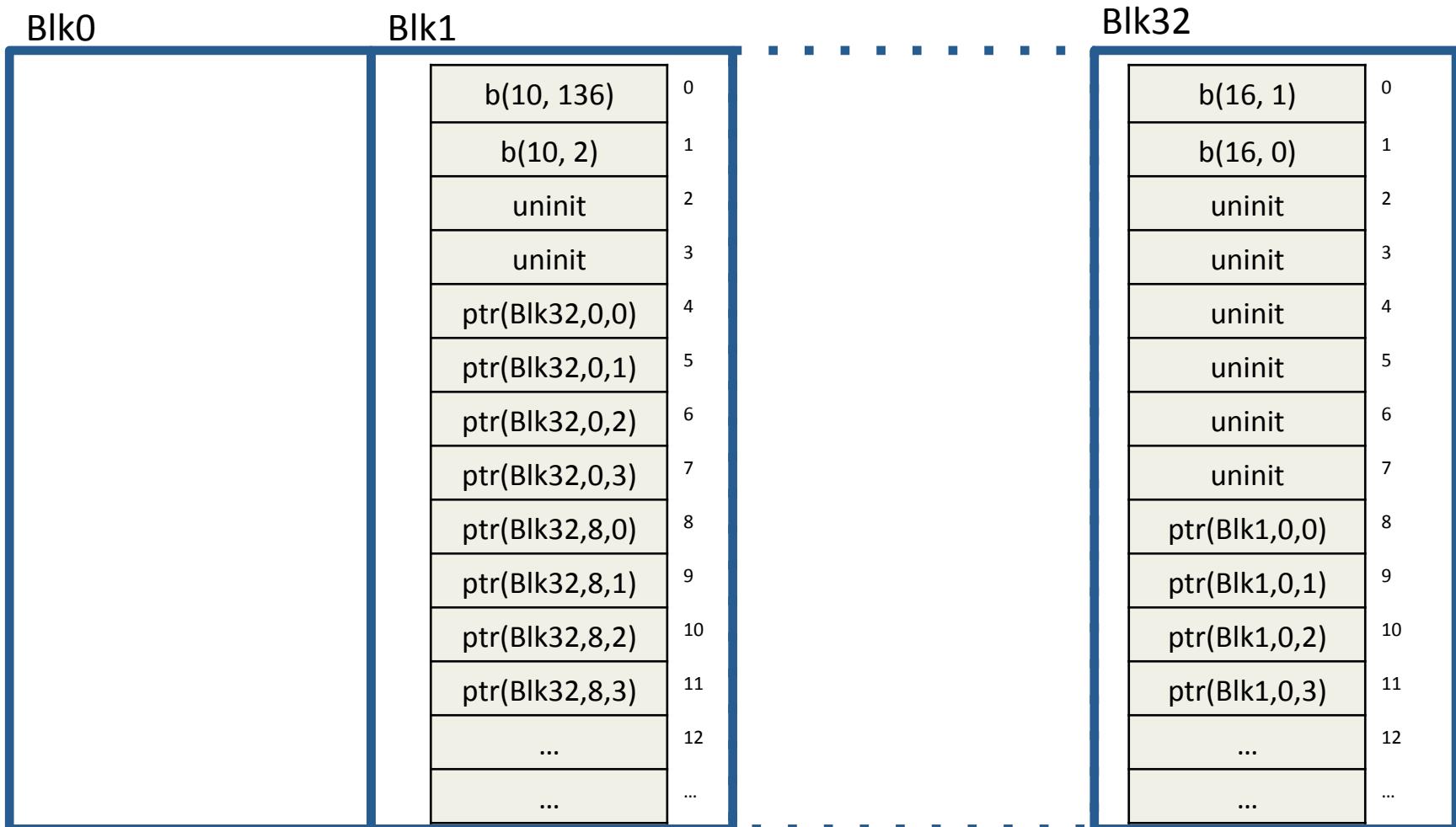


Adapting CompCert's Memory Model



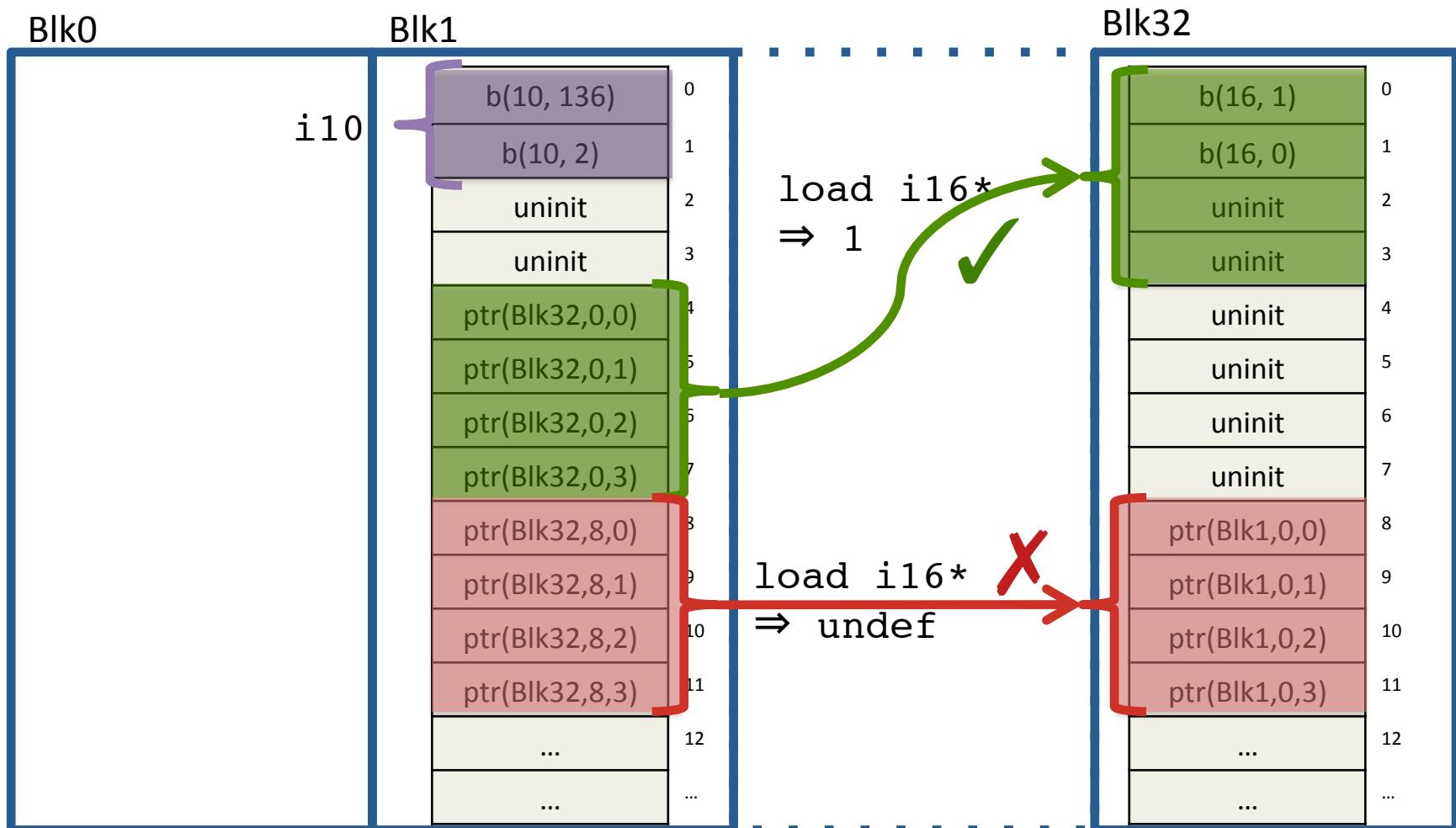
- Code lives in blocks
- Represent pointers abstractly
 - block + offset
- Deallocate by invalidating blocks
- Allocate by creating new blocks
 - infinite memory available

Adapting CompCert's Memory Model



Dynamic Physical Subtyping

[Nita, et al. POPL '08]



Sources of Undefined Behavior

Target-dependent Results

- Uninitialized variables:

```
%v = add i32 %x, undef
```

- Uninitialized memory:

```
%ptr = alloca i32  
%v = load (i32*) %ptr
```

- Ill-typed memory usage

Nondeterminism

Fatal Errors

- Out-of-bounds accesses
- Access dangling pointers
- Free invalid pointers
- Invalid indirect calls

Stuck States

Sources of Undefined Behavior

Target-dependent Results

- Uninitialized variables:

```
%v = add i32 %x, undef
```

- Uninitialized memory:

```
%ptr = alloca i32  
%v = load (i32*) %ptr
```

- Ill-typed memory usage

Nondeterminism

Defined by a predicate on the program configuration.

$\text{Stuck}(f, \sigma) = \text{BadFree}(f, \sigma)$
 $\vee \text{BadLoad}(f, \sigma)$
 $\vee \text{BadStore}(f, \sigma)$
 $\vee \dots$
 $\vee \dots 0$

Stuck States

undef

- What is the value of `%y` after running the following?

```
%x = or i8 undef, 1  
%y = xor i8 %x %x
```

- One plausible answer: 0
- Not LLVM's semantics!
(LLVM is more liberal to permit more aggressive optimizations)

undef

- Partially defined values are interpreted *nondeterministically* as sets of possible values:

```
%x = or i8 undef, 1  
%y = xor i8 %x %x
```

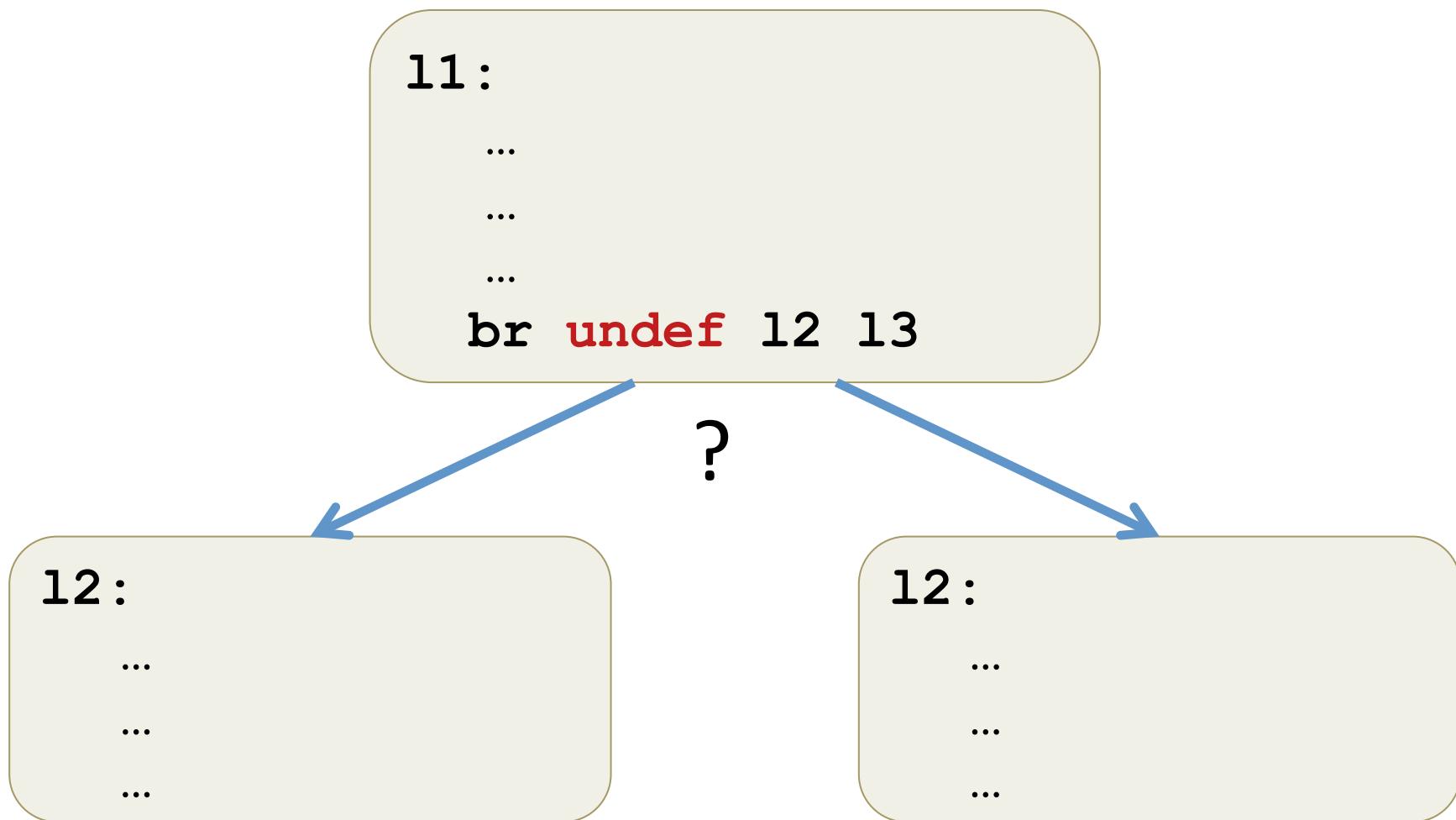
$$[\![\text{i8 undef}]\!] = \{0, \dots, 255\}$$

$$[\![\text{i8 1}]\!] = \{1\}$$

$$\begin{aligned} [\![\%x]\!] &= \{a \text{ or } b \mid a \in [\![\text{i8 undef}]\!], b \in [\![1]\!]\} \\ &= \{1, 3, 5, \dots, 255\} \end{aligned}$$

$$\begin{aligned} [\![\%y]\!] &= \{a \text{ xor } b \mid a \in [\![\%x]\!], b \in [\![\%x]\!]\} \\ &= \{0, 2, 4, \dots, 254\} \end{aligned}$$

Nondeterministic Branches



LLVM_{ND} Operational Semantics

- Define a transition relation:

$$f \vdash \sigma_1 \longrightarrow \sigma_2$$

- f is the program
- σ is the program state: pc, locals(δ), stack, heap
- Nondeterministic
 - δ maps local %uids to sets.
 - Step relation is nondeterministic
- Mostly straightforward (given the heap model)
 - One wrinkle: phi-nodes executed atomically

Operational Semantics

	Small Step	Big Step
Nondeterministic	LLVM_{ND}	
Deterministic		

Deterministic Refinement

	Small Step	Big Step
Nondeterministic	LLVM_{ND}	
Deterministic	LLVM_D	

Instantiate ‘undef’ with default value (0 or null) \Rightarrow deterministic.

Big-step Deterministic Refinements

	Small Step	Big Step
Nondeterministic	LLVM_{ND}	
Deterministic	$\text{LLVM}_{\text{Interp}} \approx \text{LLVM}_D$	

Bisimulation up to “observable events”:

- external function calls

Big-step Deterministic Refinements

	Small Step	Big Step
Nondeterministic	LLVM_{ND}	
Deterministic	$\text{LLVM}_{\text{Interp}} \approx \text{LLVM}_D \gtrapprox \text{LLVM}^*_{DFn} \gtrapprox \text{LLVM}^*_{DB}$	

Simulation up to “observable events”:

- useful for encapsulating behavior of function calls
- large step evaluation of basic blocks

[Tristan, et al. *POPL '08*, Tristan, et al. *PLDI '09*]

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Reasoning about SSA Transforms

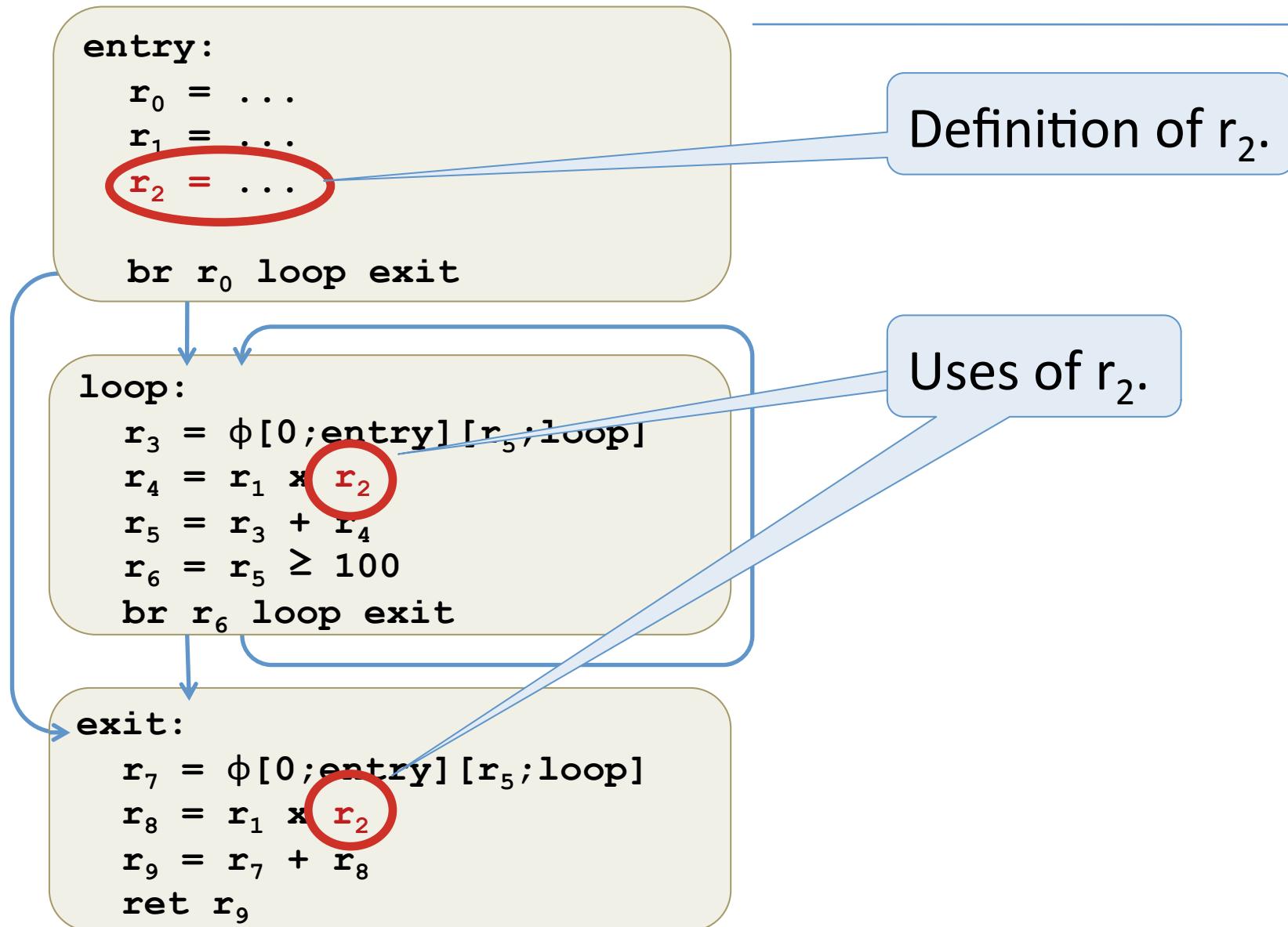
- Dynamic semantics of LLVM
 - Memory model
 - Nondeterminism
 - Handle groups of phi-nodes atomically
- Static semantics of LLVM
 - Computing dominators is crucial

[Zhao, et al. *POPL '12*]

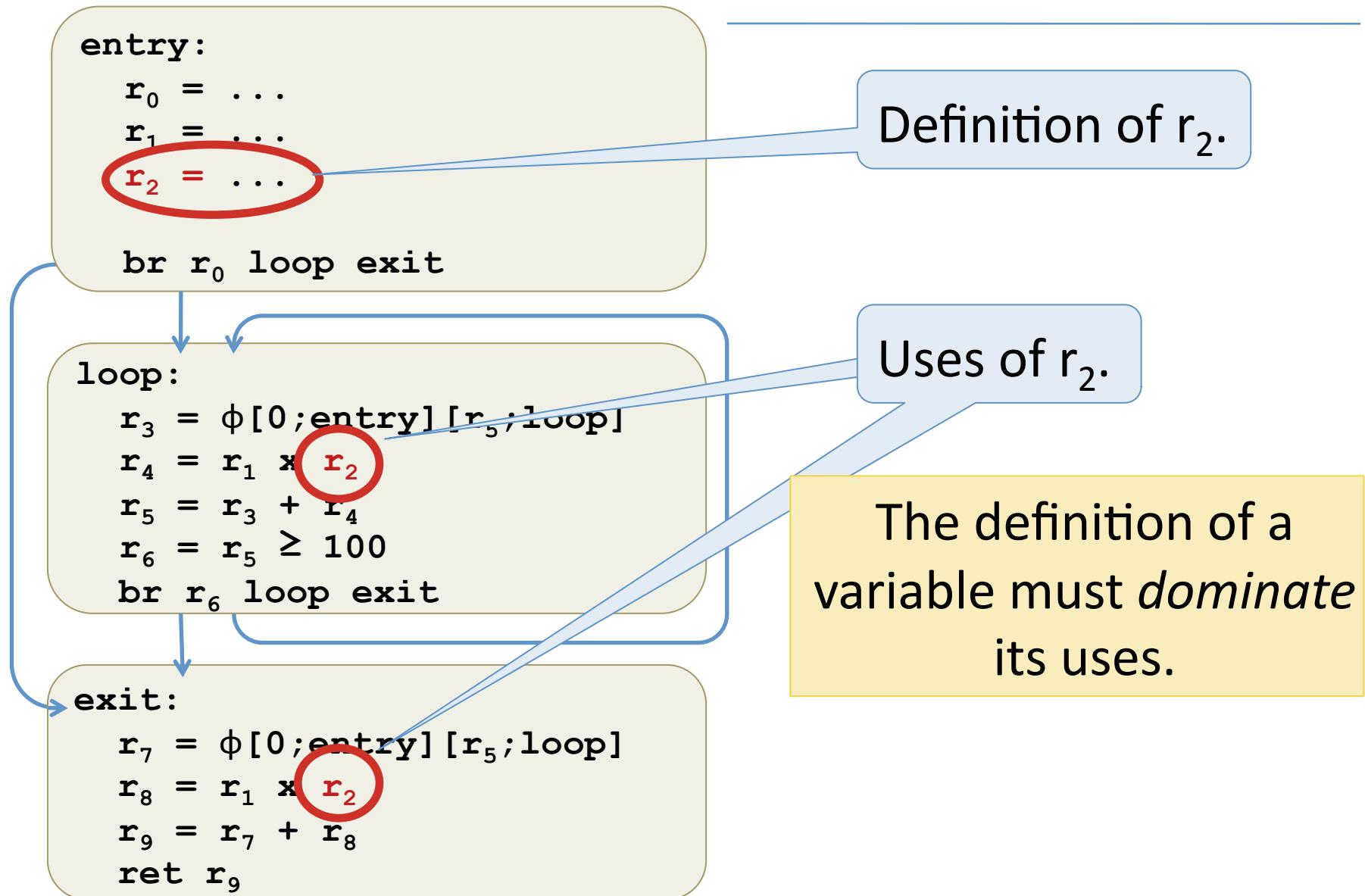
[Zhao & Zdancewic *CPP '12*]

- Use them to justify correctness of program transformations
 - Simulation proofs

Key SSA Invariant



Key SSA Invariant



Safety Properties

- A well-formed program never accesses undefined variables.

If $\vdash f$ and $f \vdash \sigma_0 \xrightarrow{*} \sigma$ then σ is not stuck.

$\vdash f$ program f is well formed

σ program state

$f \vdash \sigma \xrightarrow{*} \sigma$ evaluation of f

- *Initialization:*

If $\vdash f$ then $wf(f, \sigma_0)$.

- *Preservation:*

If $\vdash f$ and $f \vdash \sigma \xrightarrow{} \sigma'$ and $wf(f, \sigma)$ then $wf(f, \sigma')$

- *Progress:*

If $\vdash f$ and $wf(f, \sigma)$ then $f \vdash \sigma \xrightarrow{} \sigma'$

Safety Properties

- A well-formed program never accesses undefined variables.

If $\vdash f$ and $f \vdash \sigma_0 \xrightarrow{*} \sigma$ then σ is not stuck.

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- *Initialization:*

If $\vdash f$ then $wf(f, \sigma_0)$

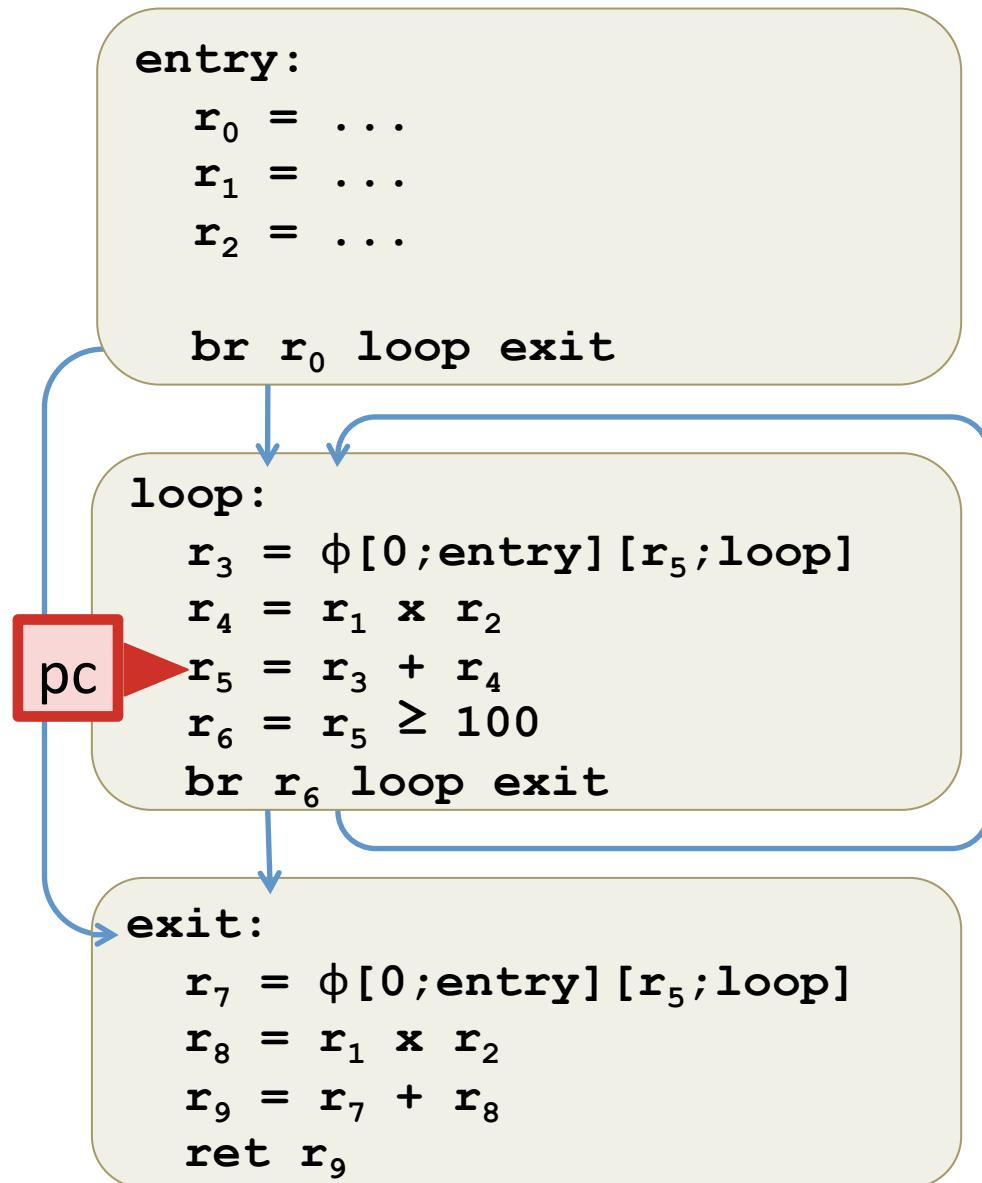
- *Preservation:*

If $\vdash f$ and $f \vdash \sigma \xrightarrow{} \sigma'$ and $wf(f, \sigma)$ then $wf(f, \sigma')$

- *Progress:*

If $\vdash f$ and $wf(f, \sigma)$ then done(f, σ) or stuck(f, σ) or $f \vdash \sigma \xrightarrow{} \sigma'$

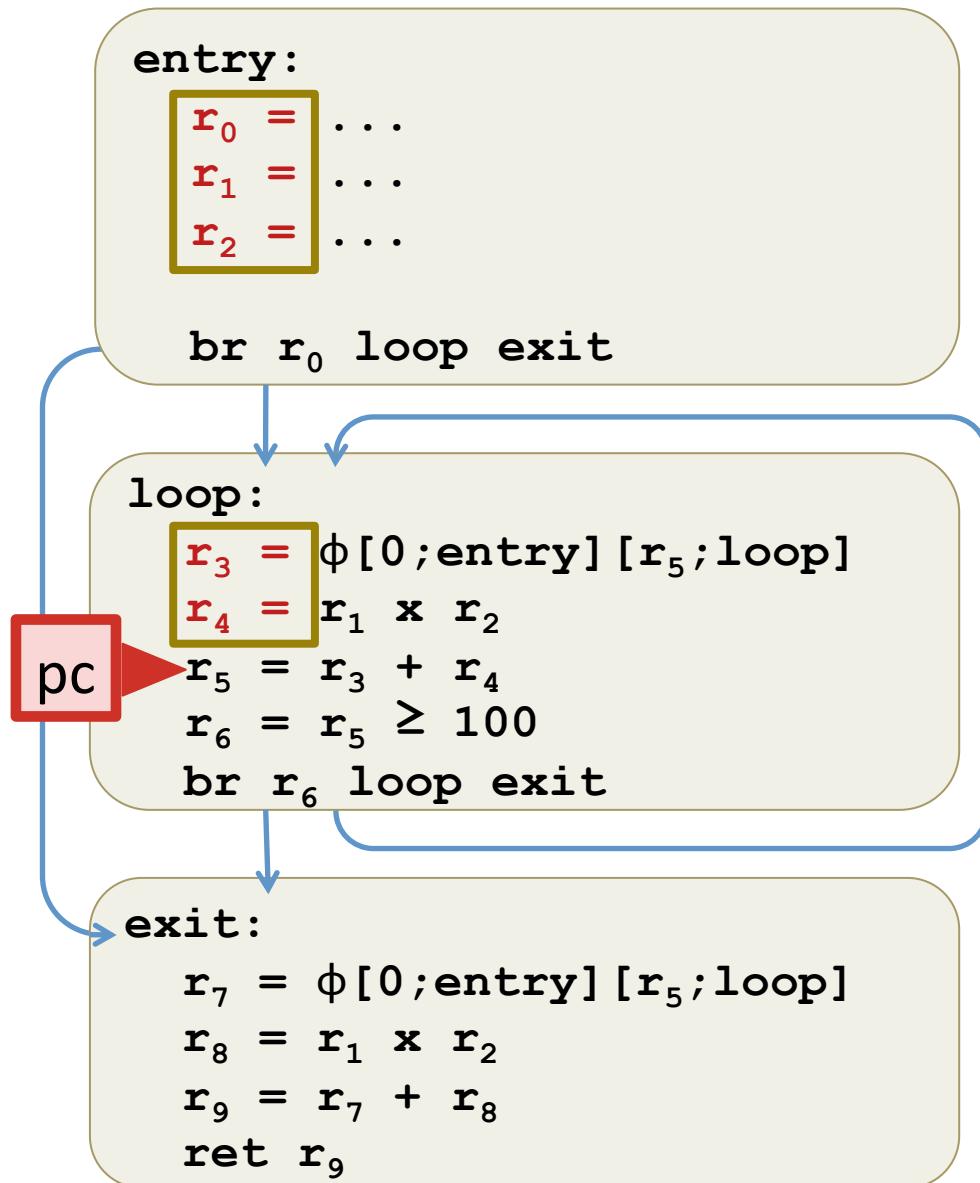
Well-formed States



State σ is:

pc = program counter
 δ = local values

Well-formed States

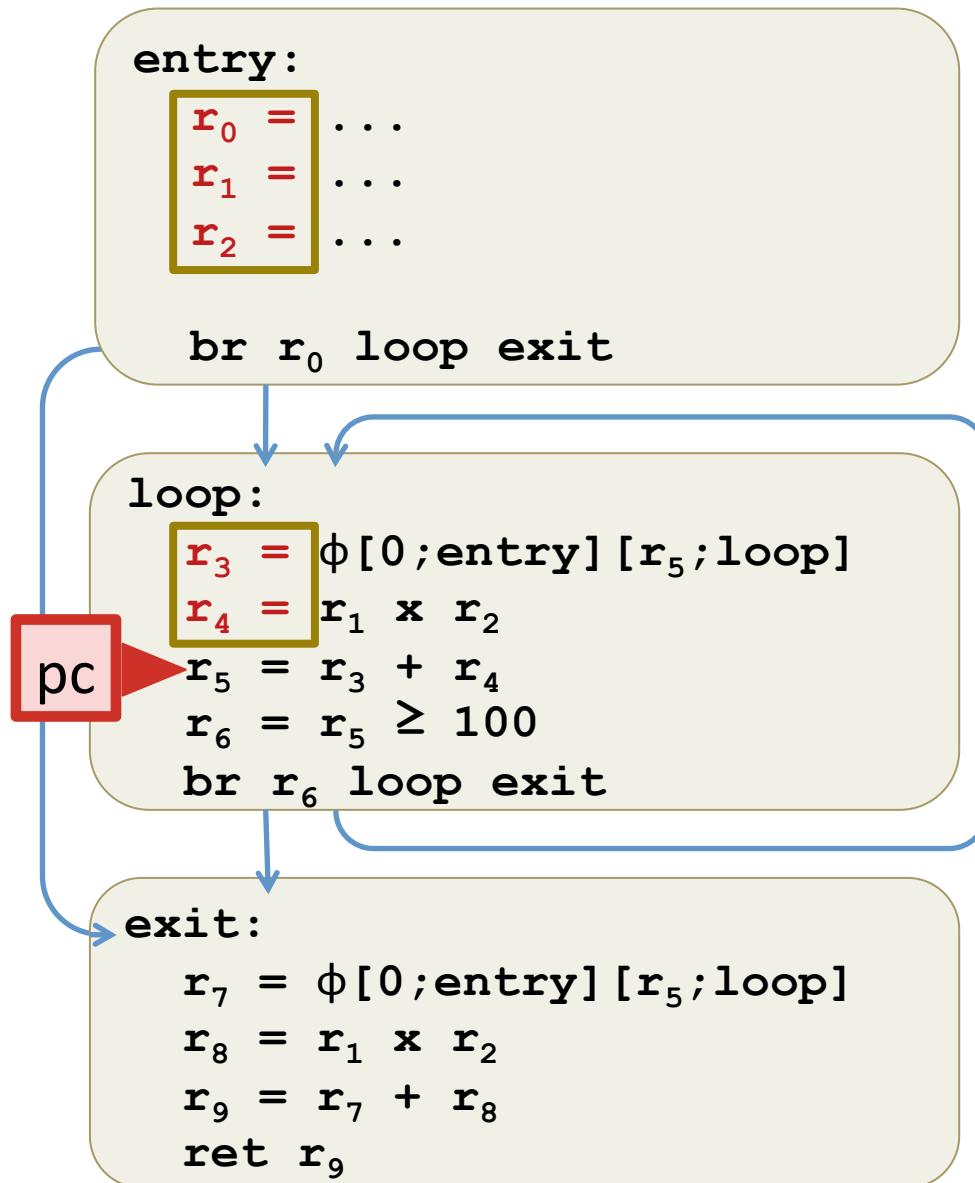


State σ is:

$\text{pc} = \text{program counter}$
 $\delta = \text{local values}$

$\text{sdom}(f, \text{pc}) = \text{variable defns.}$
that *strictly dominate* pc.

Well-formed States



State σ contains:

$\text{pc} = \text{program counter}$
 $\delta = \text{local values}$

$\text{sdom}(f, \text{pc}) = \text{variable defns.}$
that *strictly dominate* pc.

$\text{wf}(f, \sigma) =$
 $\forall r \in \text{sdom}(f, \text{pc}). \exists v. \delta(r) = [v]$

“All variables in scope
are initialized.”

Generalizing Safety

- Definition of wf:

$$wf(f, (pc, \delta)) = \forall r \in sdom(f, pc). \exists v. \delta(r) = [v]$$

- Generalize like this:

$$wf(f, (pc, \delta)) = P_f (\delta|_{sdom(f, pc)})$$

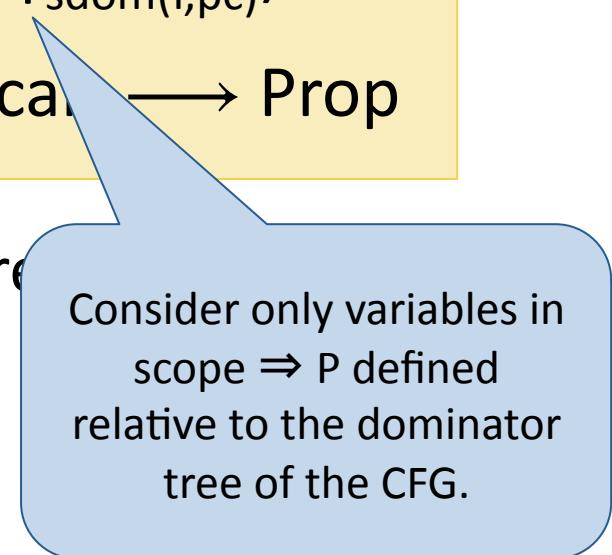
where $P : \text{Program} \longrightarrow \text{Locals} \longrightarrow \text{Prop}$

- Methodology: for a given P prove three properties:

Initialization(P)

Preservation(P)

Progress(P)



Consider only variables in scope $\Rightarrow P$ defined relative to the dominator tree of the CFG.

Instantiating

- For usual safety:

$$P_{\text{safety}} f \delta = \forall r \in \text{dom}(\delta). \exists v. \delta(r) = [v]$$

- For semantic properties:

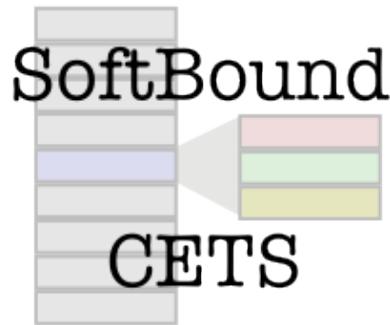
$$P_{\text{sem}} f \delta = \forall r. f[r] = [\text{rhs}] \Rightarrow \delta(r) = [\text{rhs}]_\delta$$

- Useful for verifying correctness of:
 - code motion, dead variable elimination, common expression elimination, etc.

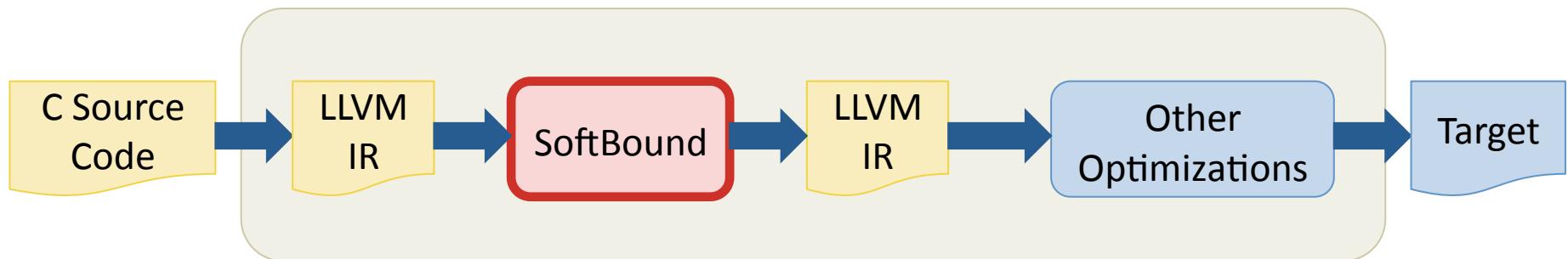
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SoftBound

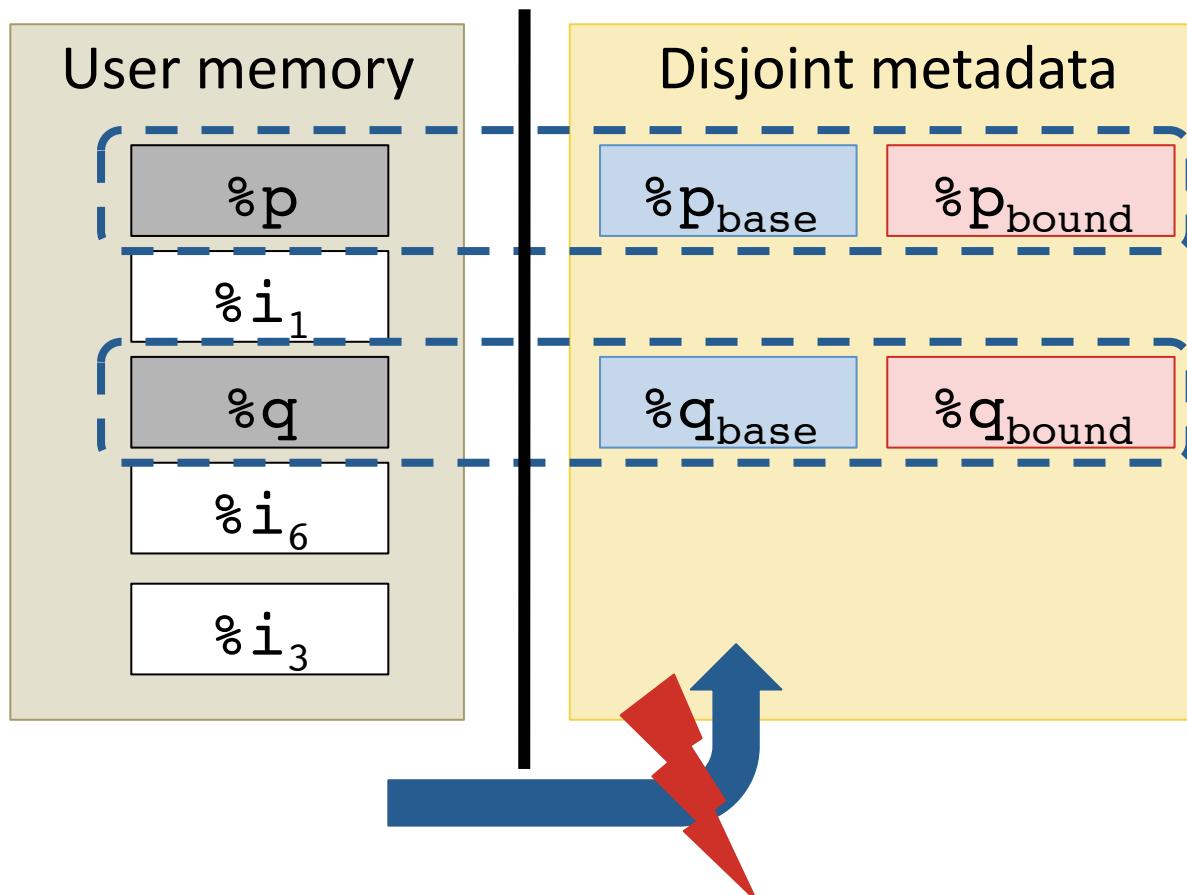


- Implemented as an LLVM pass.
- Detect spatial/temporal memory safety violations in legacy C code.
- Good test case:
 - Safety Critical \Rightarrow Proof cost warranted
 - Non-trivial Memory transformation

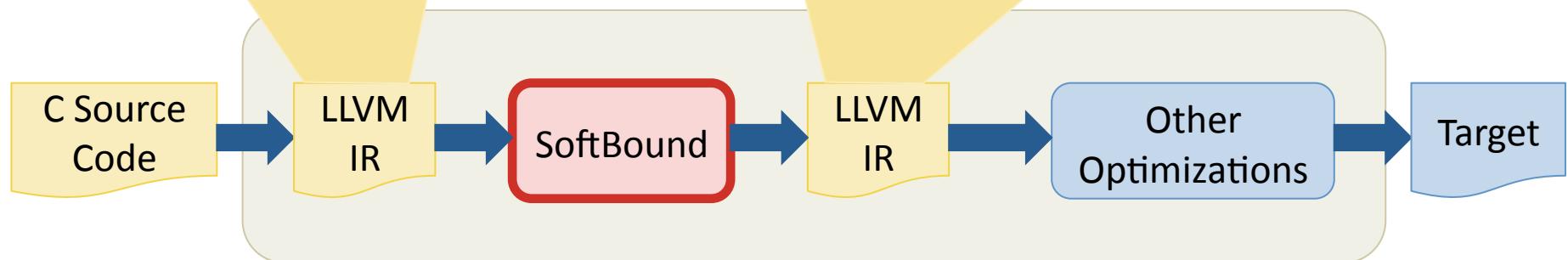
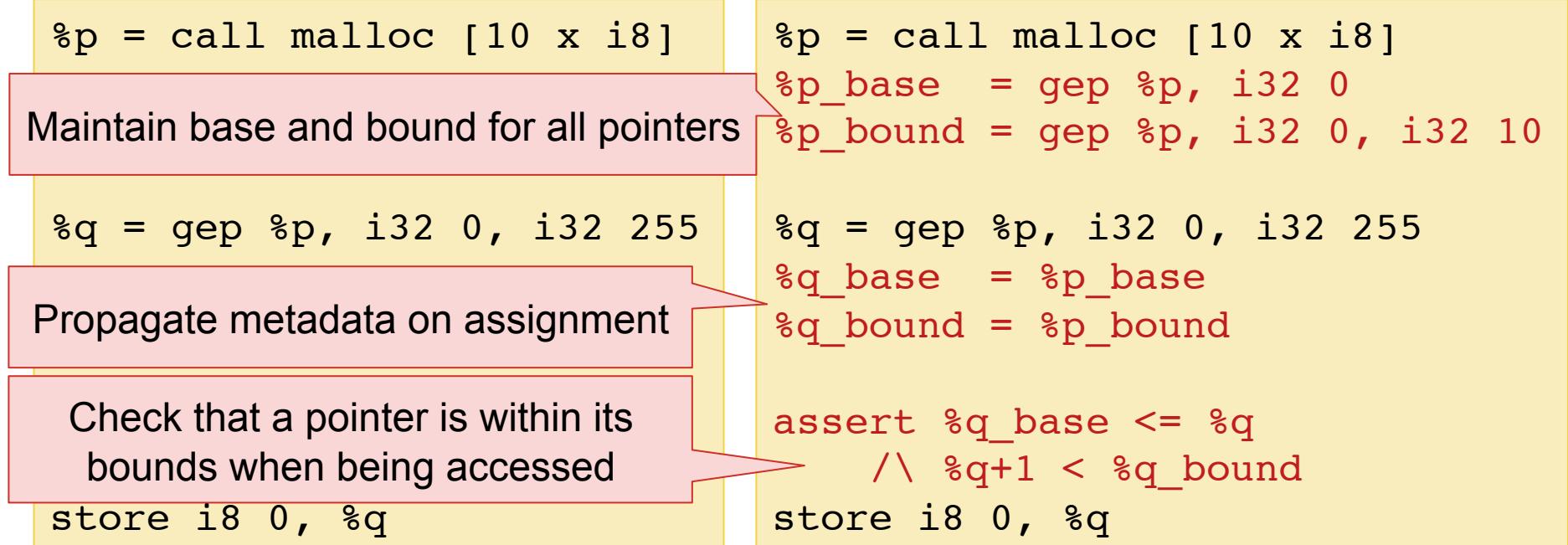


Disjoint Metadata

- Maintain pointer bounds in a separate memory space.
- Key Invariant: Metadata cannot be corrupted by bounds violation.



SoftBound



Proving SoftBound Correct

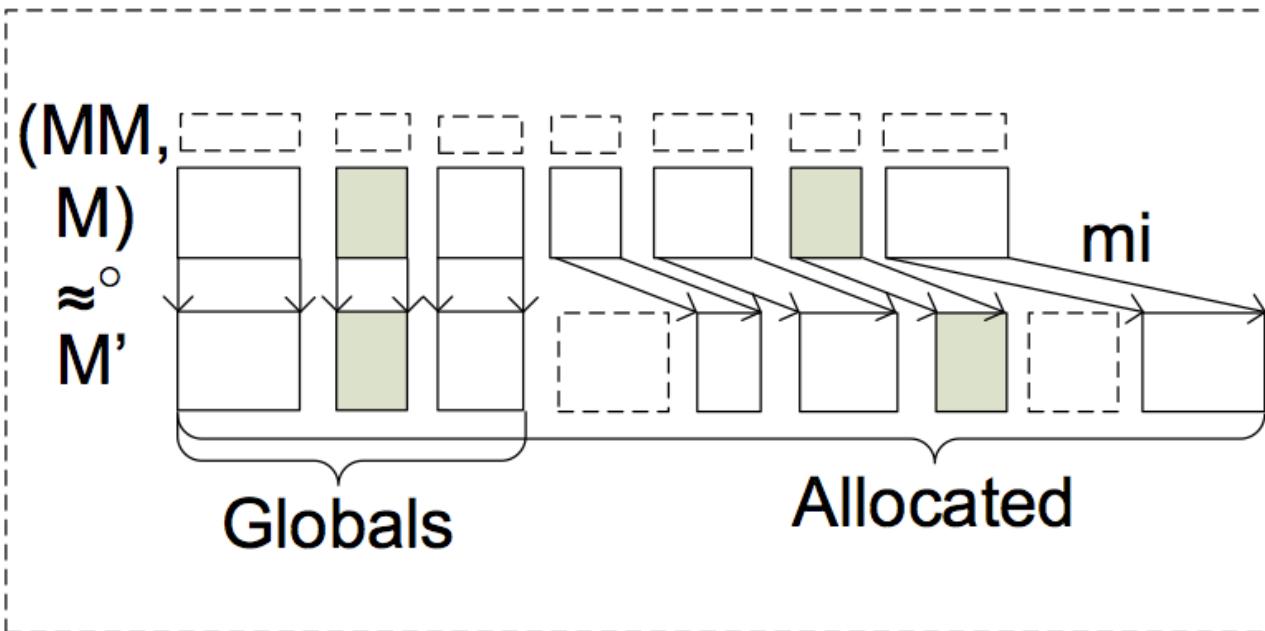
1. Define $\text{SoftBound}(f, \sigma) = (f_s, \sigma_s)$
 - Transformation pass implemented in Coq.
2. Define predicate: $\text{MemoryViolation}(f, \sigma)$
3. Construct a *non-standard* operational semantics:

$$f \vdash \sigma \xrightarrow{\text{SB}} \sigma'$$

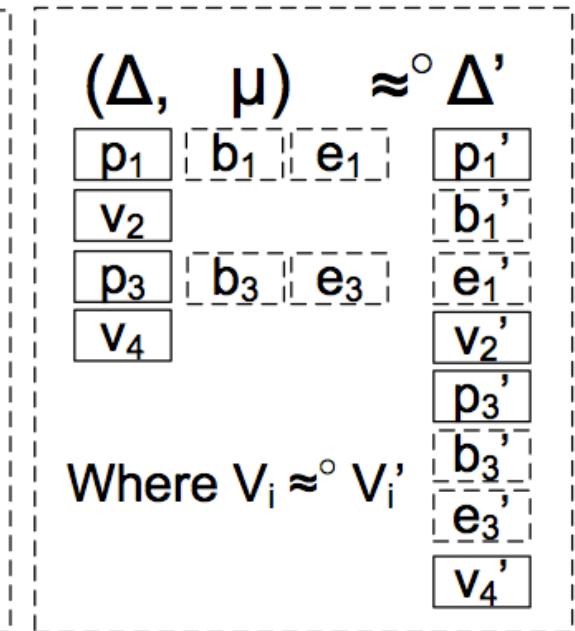
- Builds in safety invariants “by construction”
- $$f \vdash \sigma \xrightarrow{\text{SB}}^* \sigma' \Rightarrow \neg \text{MemoryViolation}(f, \sigma')$$
4. Show that the instrumented code simulates the “correct” code:

$$\text{SoftBound}(f, \sigma) = (f_s, \sigma_s) \Rightarrow [f \vdash \sigma \xrightarrow{\text{SB}}^* \sigma'] \gtrsim [f_s \vdash \sigma_s \xrightarrow{\text{SB}}^* \sigma'_s]$$

Memory Simulation Relation



Memory simulation

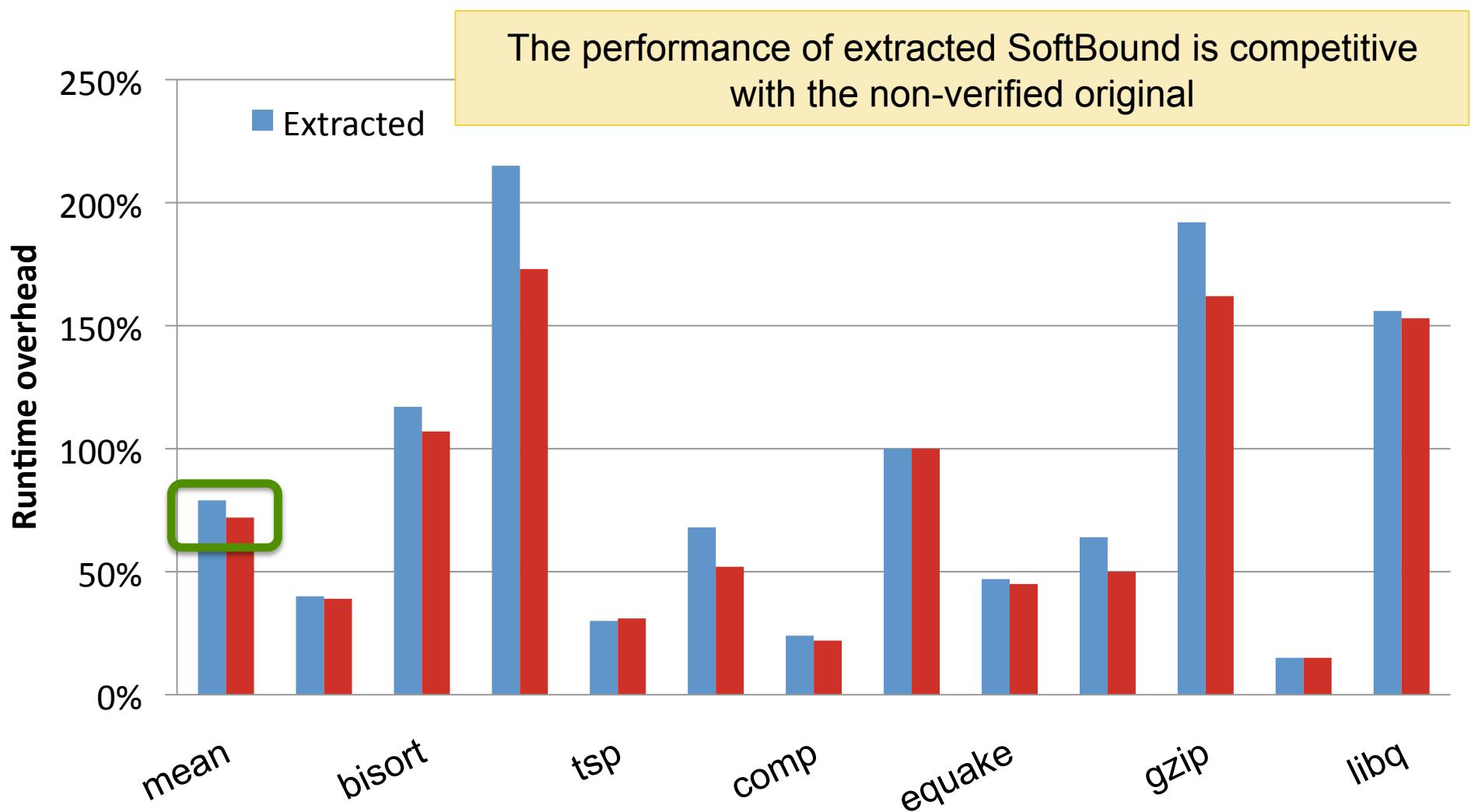


Frame simulation

Lessons About SoftBound

- Found several bugs in our C++ implementation
 - Interaction of undef, ‘null’, and metadata initialization.
- Simulation proofs suggested a redesign of SoftBound’s handling of stack pointers.
 - Use a “shadow stack”
 - Simplify the design/implementation
 - Significantly more robust (e.g. varargs)

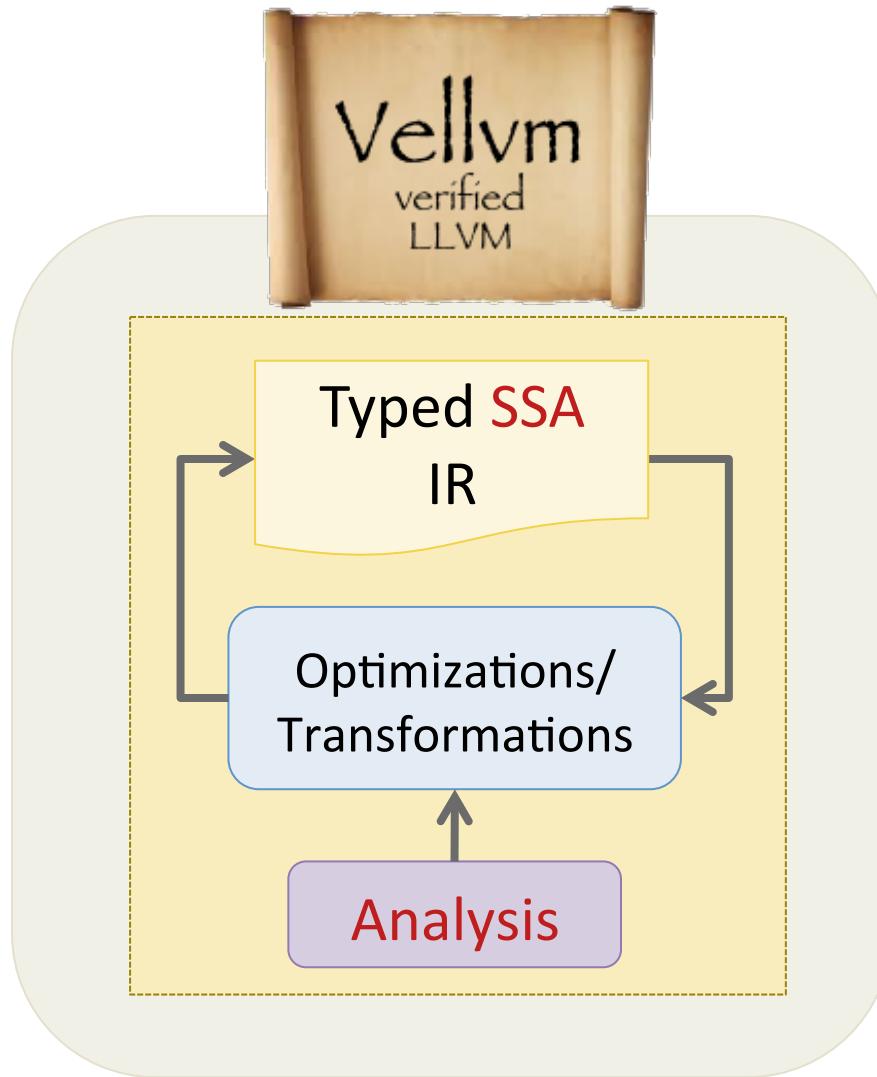
Competitive Runtime Overhead



Plan

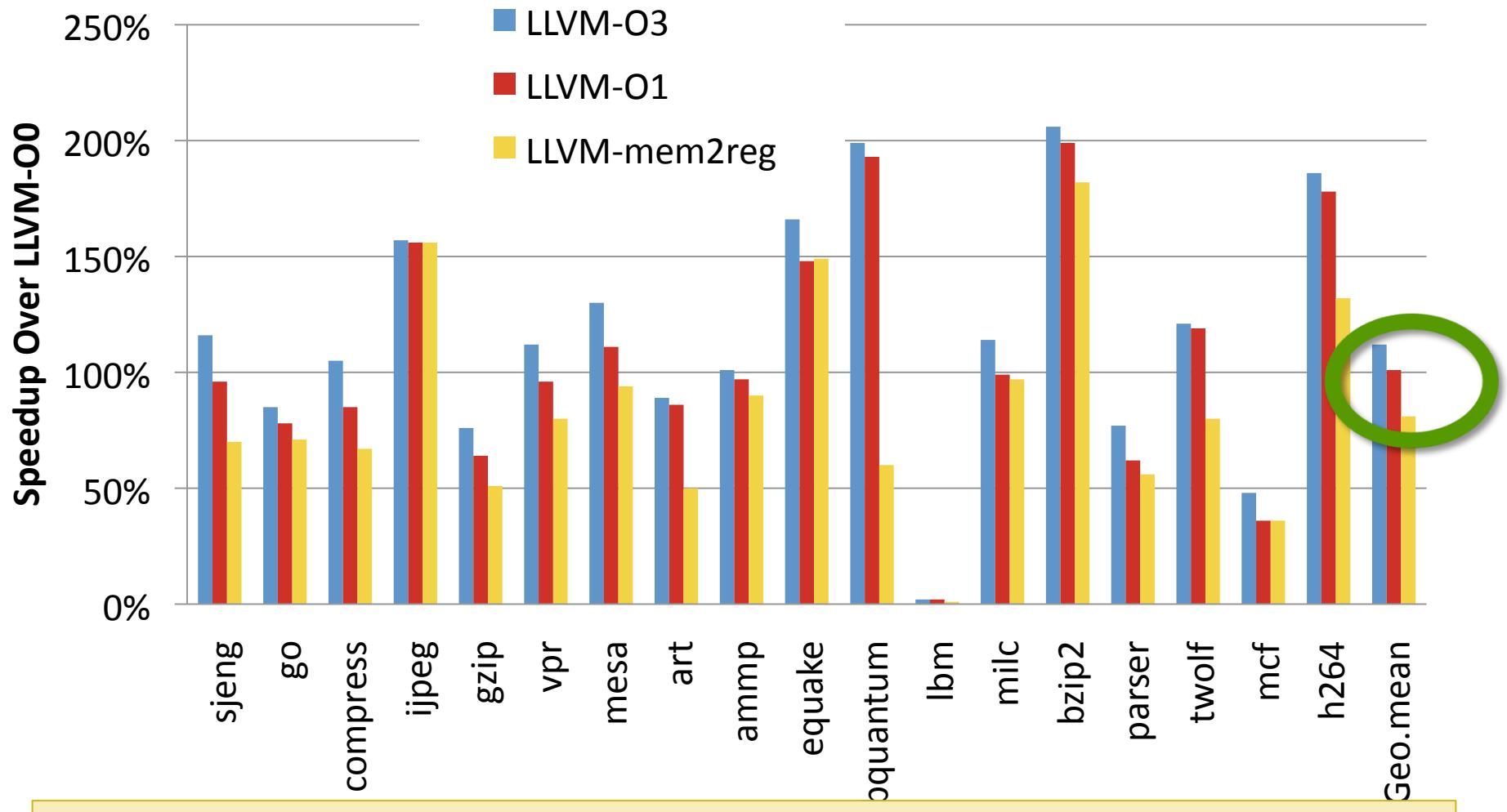
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Performance Critical Optimization



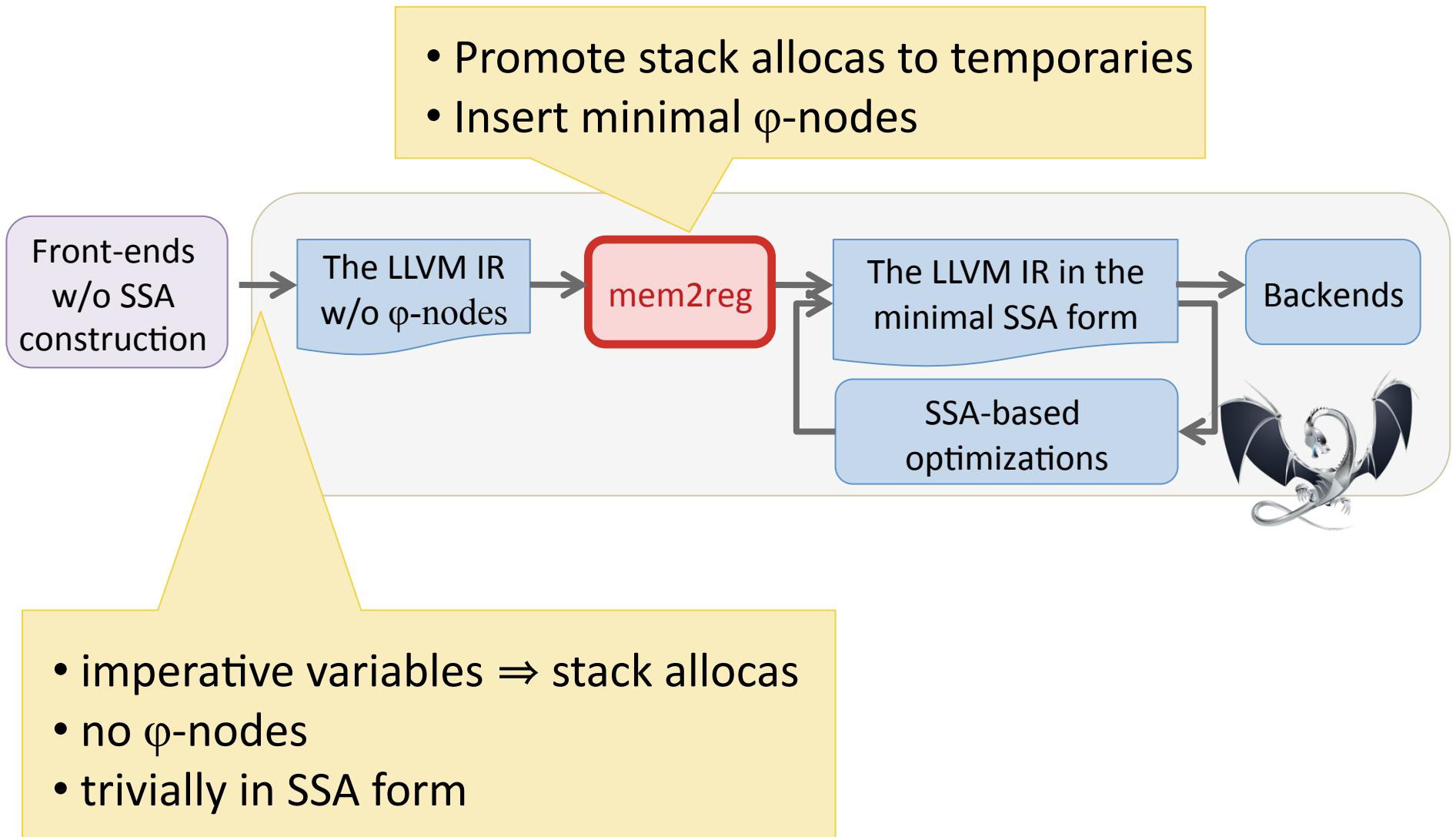
- LLVM compiler runs numerous optimizations
- Proving cost vs speedup
- Which optimization has the most performance impact?

Critical Optimization in LLVM



O1 speeds up the program by 101%.
mem2reg speeds it up by 81%

mem2reg in LLVM



mem2reg Example

```
int x = 0;  
if (y > 0)  
    x = 1;  
return x;
```

```
l1: %p = alloca i32  
      store 0, %p  
      %b = %y > 0  
      br %b, %l2, %l3
```

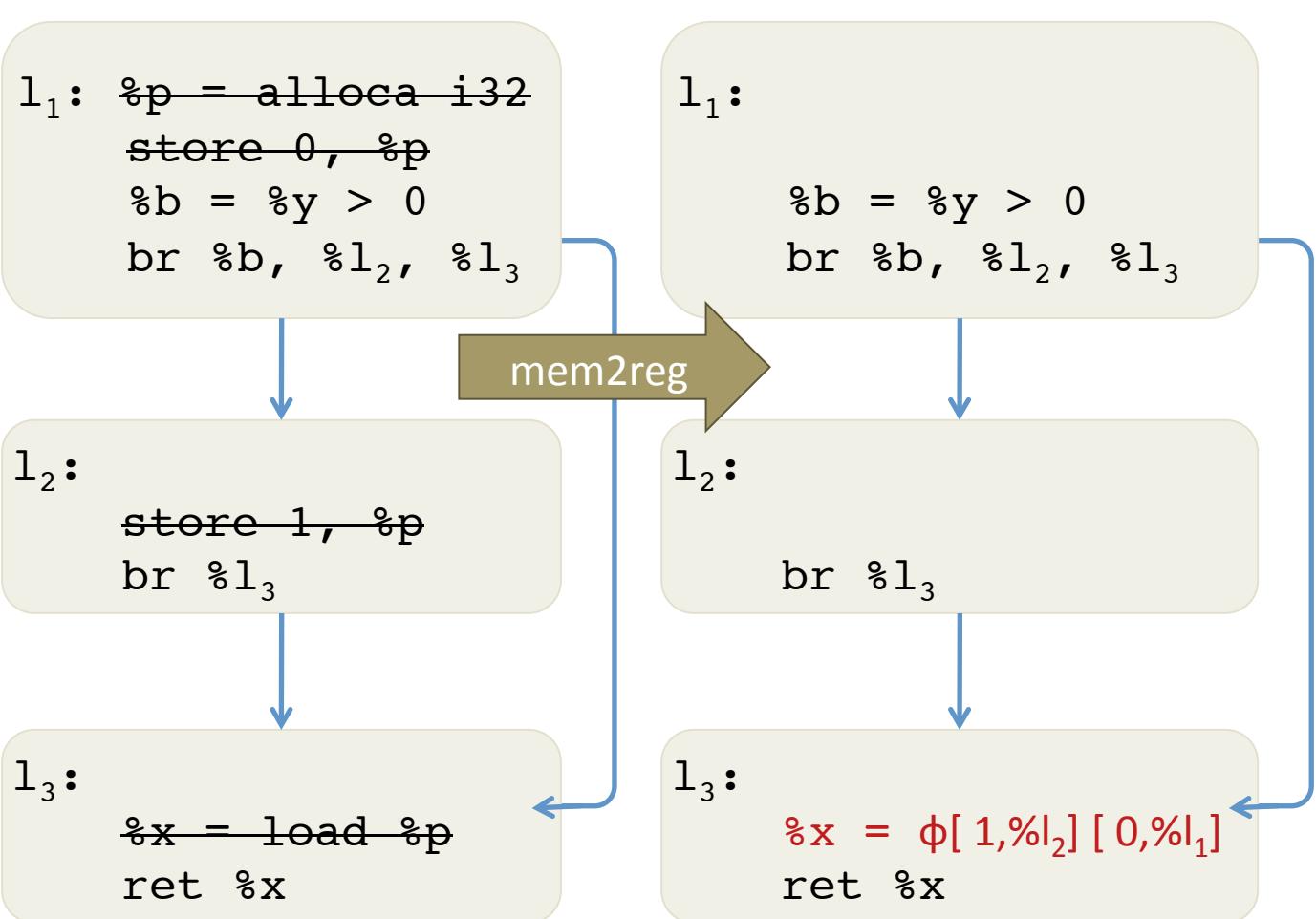
```
l2:  
      store 1, %p  
      br %l3
```

```
l3:  
      %x = load %p  
      ret %x
```

The LLVM IR in the trivial SSA form

mem2reg Example

```
int x = 0;  
if (y > 0)  
    x = 1;  
return x;
```



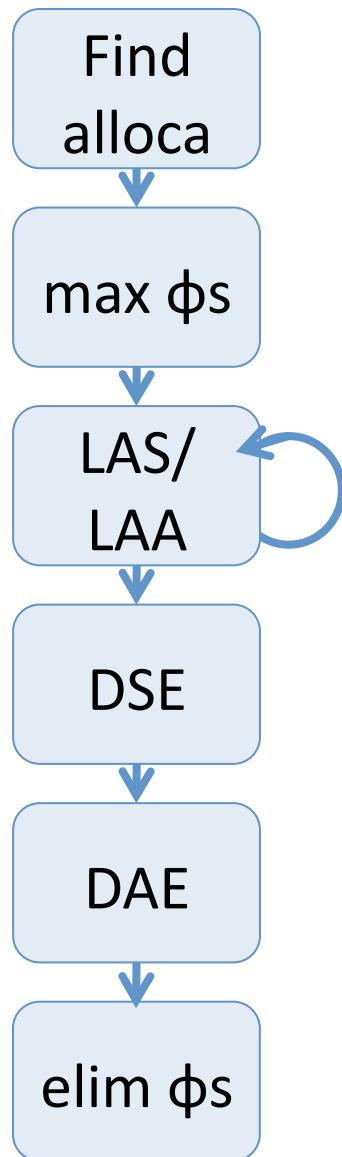
The LLVM IR in the trivial SSA form

Minimal SSA after mem2reg

mem2reg Algorithm

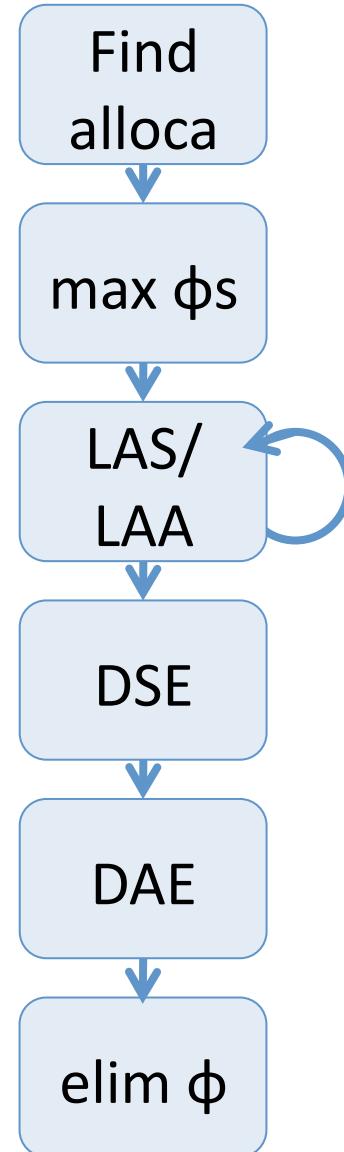
- Two main operations
 - Phi placement (Lengauer-Tarjan algorithm)
 - Renaming of the variables
- Intermediate stage breaks SSA invariant
 - Defining semantics & well formedness non-trivial

vmem2reg Algorithm

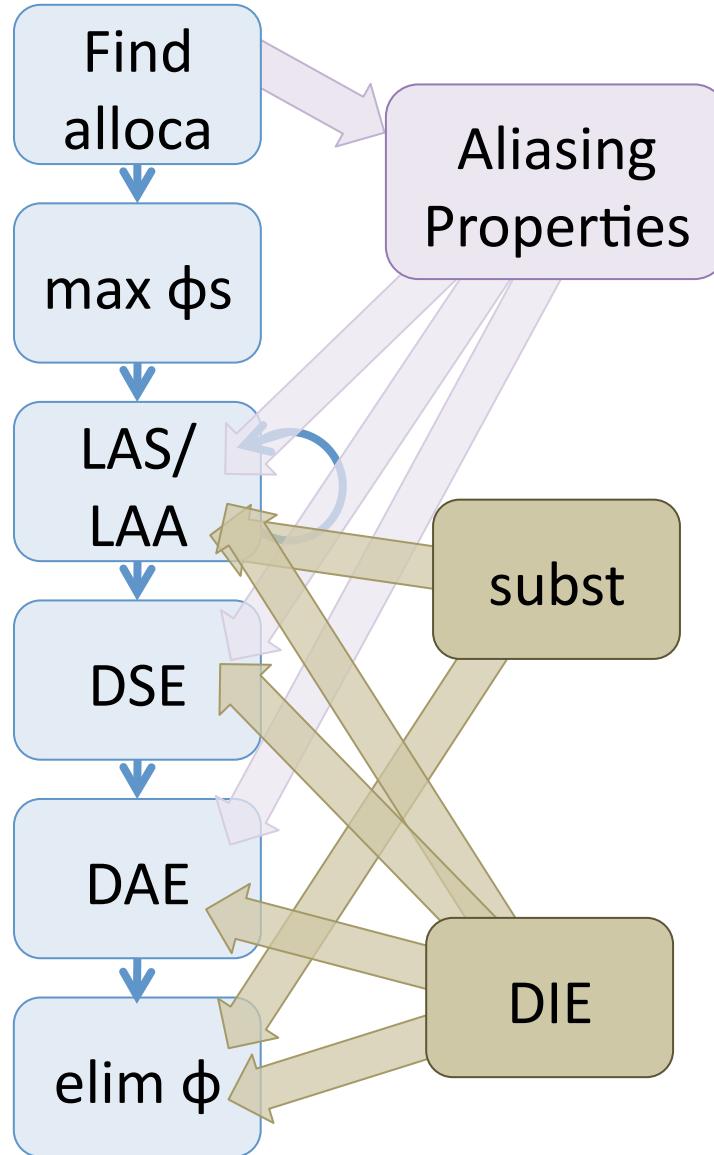


- Incremental algorithm
- Pipeline of micro-transformations
 - Preserves SSA semantics
 - Preserves well-formedness
- Inspired by Aycock & Horspool 2002.

How to Establish Correctness?



How to Establish Correctness?



1. Simple aliasing properties (e.g. to determine promotability)
2. Instantiate proof technique for
 - Substitution
 - Dead Instruction Elimination $P_{DIE} = \dots$
Initialize(P_{DIE})
Preservation(P_{DIE})
Progress(P_{DIE})
4. Put it all together to prove composition of “pipeline” correct.

vmem2reg is Correct

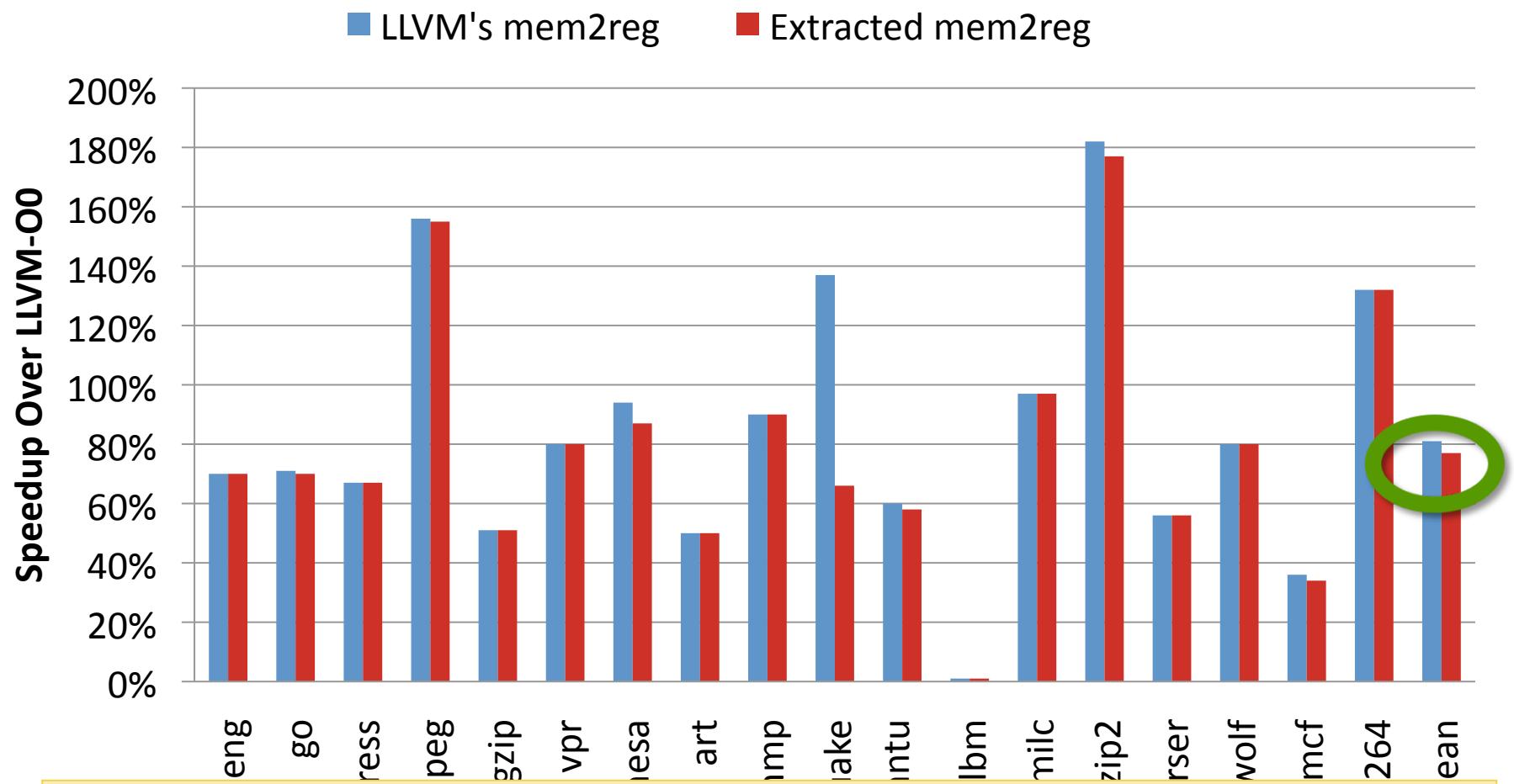
Theorem: The vmem2reg algorithm preserves the semantics of the source program.

Proof:

Composition of simulation relations from the “mini” transformations, each built using instances of the sdom proof technique.

(See Coq Vellvm development.) \square

Runtime overhead of verified mem2reg



Vmem2reg: 77% LLVM's mem2reg: 81%

(LLVM's mem2reg promotes allocas used by intrinsics)

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Related Work

- CompCert [Leroy et al.]
- CompCertSSA [Barthe, Demange et al. ESOP 2012]
 - Translation validate the SSA construction
- Verified Software Toolchain [Appel et. al]
- Verifiable SSA Representation [Menon et al. POPL 2006]
 - Identify the well-formedness safety predicate for SSA
- Specification of SSA
 - Temporal checking & model checking for proving SSA transforms [Mansky et al, ITP 2010]
 - Matrix representation of ϕ nodes [Yakobowski, INRIA]
 - Type system equivalent to SSA [Matsuno et al]

Conclusions

- Proof techniques for verifying SSA transformations
 - Generalize the SSA scoping predicate
 - Preservation/progress + simulations.
- Verified:
 - Softbound & vmem2reg
 - Similar performance to native implementations
- See the papers/coq sources for details!
- Future:
 - Clean up + make more accessible
 - Tutorial for Oregon PL Summer School
 - Alias analysis? Concurrency?
 - Applications to more LLVM-SSA optimizations



<http://www.cis.upenn.edu/~stevez/vellvm/>



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