

Games for Logics with Partial Order Models

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GaLoP, March, 2009

Motivation

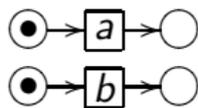
Avoid the use of interleaving models of concurrency.

But why?

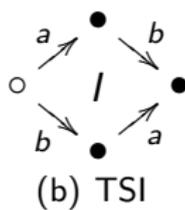
1. Model-checking I: suffer from state explosion problem.
2. Model-checking II: use of partial order reduction methods.
3. Model-checking III: verification beyond temporal properties.
4. Equivalence-checking: verification of infinite state systems.
5. Synthesis: produce “global” components (automata).
6. Analysis: local reasoning on parallel components.
7. Game semantics: perhaps not the right models for logics with an explicit notion of concurrency or independence.

Interleaving and Partial Order Models of Concurrency

$$a.b + b.a \equiv_{intm} a \parallel b \equiv_{pom} a \mid b$$



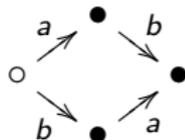
(a) Petri Nets



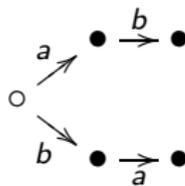
(b) TSI



(c) Event Structures



(d) LTS



(e) ST

Partial Order Models of Concurrency: Features

Behaviour:

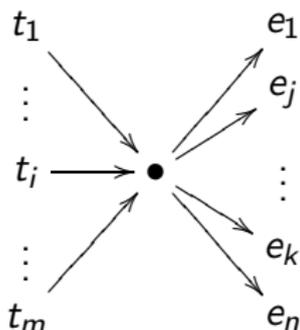
1. Concurrency: parallel computations.
2. Causality: sequential computation.
3. Conflict: deterministic and nondeterministic choices.

Structure:

1. A set of states S .
2. A set of events or transitions T .
3. An independence relation I on elements of T .
4. An alphabet of labels Σ (only for labelled models).

Local Dualities in Partial Order Models of Concurrency

A new approach to observing concurrent behaviour introduced in [Gut09] - FoSSaCS'09.



1. First duality: concurrency vs. causality.

$$t_i \parallel e_j \Leftrightarrow t_i \ominus e_j \quad \text{concurrent, but linearized.}$$

$$\neg(t_i \parallel e_j) \Leftrightarrow t_i \leq e_j \quad \text{causally dependent.}$$

2. Second duality: concurrency vs. conflict.

$$e_j \parallel e_k \Leftrightarrow e_j \otimes e_k \quad \text{immediately concurrent (same trace).}$$

$$\neg(e_j \parallel e_k) \Leftrightarrow e_j \# e_k \quad \text{in conflict (different traces).}$$

Traces and Sets of Transitions

Support sets:

- ▶ Maximal Set: $P_{max}(s) = \{t \in T \mid src(t) = s\}$ (all traces).
- ▶ Conflict-free set: $E \subseteq P_{max}(s)$ s.t.
 $\forall t_1, t_2 \in E. t_1 \neq t_2 \Rightarrow t_1 \otimes t_2$ (one single trace).

Notation:

$E \sqsubseteq R \stackrel{\text{def}}{=} E \subseteq R$, s.t. E is a conflict-free set, i.e., a trace.

$P_1 \uplus P_2 \stackrel{\text{def}}{=} P_1 \cup P_2$, s.t. $P_1 \cap P_2 = \emptyset \wedge P_1 \neq \emptyset \wedge P_2 \neq \emptyset$

Separation Fixpoint Logic (SFL)

SFL is an extension of the Modal Mu-Calculus that can express properties of partial order models of concurrency.

Syntax: SFL has formulae ϕ built from a set Var of variables Y, Z, \dots and a set \mathcal{L} of labels a, b, \dots by the following grammar:

ϕ	::=	Z	Variables
		$ \neg\phi_1 \mid \phi_1 \wedge \phi_2$	Boolean operators
		$ \langle K \rangle_c \phi_1 \mid \langle K \rangle_{nc} \phi_1$	Modal operators (Duality conc. vs. caus.)
		$ \phi_1 * \phi_2$	Structural operator (Duality conc. vs. conf.)
		$ \mu Z. \phi_1$	Fixpoint operator

SFL: Derived Operators and Notation

1. Derived Operators:

- ▶ $\phi_1 \vee \phi_2 \stackrel{\text{def}}{=} \neg(\neg\phi_1 \wedge \neg\phi_2)$
- ▶ $\phi_1 \bowtie \phi_2 \stackrel{\text{def}}{=} \neg(\neg\phi_1 * \neg\phi_2)$
- ▶ $[K]_c \phi_1 \stackrel{\text{def}}{=} \neg\langle K \rangle_c \neg\phi_1$
- ▶ $[K]_{nc} \phi_1 \stackrel{\text{def}}{=} \neg\langle K \rangle_{nc} \neg\phi_1$
- ▶ $\nu Z.\phi_1 \stackrel{\text{def}}{=} \neg\mu Z.\neg\phi_1 [\neg Z/Z]$

2. Abbreviations:

- ▶ $\text{ff} \stackrel{\text{def}}{=} \mu Z.Z$
- ▶ $\text{tt} \stackrel{\text{def}}{=} \nu Z.Z$
- ▶ $[-]\phi \stackrel{\text{def}}{=} [\mathcal{L}]\phi$

3. Formulae in Positive Normal Form.

A Concrete Model

A *TSI-based SFL model* \mathfrak{M} is a TSI $\mathfrak{T} = (S, T, \Sigma, I)$ together with a valuation $\mathcal{V} : \text{Var} \rightarrow 2^{\mathfrak{G}}$, where:

- ▶ $\mathfrak{G} = S \times \mathfrak{P} \times \mathfrak{A}$ is the set of tuples (s, P, t_a) s.t.:
- ▶ $s \in S$ is a state of the TSI,
- ▶ $P \in \mathfrak{P}$ is a support set at s ,
- ▶ $t_a \in \mathfrak{A} = T \cup \{t_\epsilon\}$ is a transition, and
- ▶ a is an action label in $\Sigma \cup \{\epsilon\}$.

Remarks:

- ▶ A tuple (s, P, t_a) of a model \mathfrak{M} is called a *process*.
- ▶ The initial process of the system is the tuple $H = (s_0, P_{max}, t_\epsilon)$.

SFL Sublogics

Logic	Synt. rest.	\ominus vs. \leq	\otimes vs. $\#$
$L\mu$	plain modalities only/*-free	NO	NO
$CL\mu$	*-free	YES	NO
$SL\mu$	plain modalities only	NO	YES
SFL	none	YES	YES

Encoding plain modalities:

$$\begin{aligned}\langle K \rangle \phi &= \langle K \rangle_c \phi \vee \langle K \rangle_{nc} \phi \\ [K] \phi &= [K]_c \phi \wedge [K]_{nc} \phi\end{aligned}$$

Trace MSO Model Checking Games

Main idea behind the game: a player can see independence and therefore can play traces, i.e., sets of independent transitions. This is reflected in the rules and winning conditions of the game.

1. Players: Adam (Falsifier) and Eve (Verifier).
2. Board: A set of configurations in $\mathfrak{B} = \mathfrak{G} \times \text{Sub}(\phi)$.
3. Rules: next slide...
4. Winning conditions: In finite plays a player wins if the other cannot make a move. In infinite plays the winner depends on the fixpoints.

A play is NOT alternating. The player to make a move is defined by $\text{Sub}(\phi)$.

Trace MSO Model Checking Games: Rules

FIXPOINT OPERATORS			
(FP)	$\frac{H \vdash \sigma Z. \phi}{H \vdash Z}$	$\sigma \in \{\mu, \nu\}$	(VAR) $\frac{H \vdash Z}{H \vdash \phi}$ $fp(Z) = \sigma Z. \phi$
BOOLEAN OPERATORS			
(\vee)	$\frac{H \vdash \phi_0 \vee \phi_1}{H \vdash \phi_i}$	$\exists i : i \in \{0, 1\}$	(\wedge) $\frac{H \vdash \phi_0 \wedge \phi_1}{H \vdash \phi_i}$ $\forall i : i \in \{0, 1\}$
MODAL OPERATORS			
	$(\langle \rangle_c) \frac{(s, R, t_a) \vdash \langle K \rangle_c \phi}{(s', R'_{max}, t_b) \vdash \phi}$	$\exists b : b \in K, s \xrightarrow{b} s' = t_b \in R, t_a \leq t_b$	
	$(\langle \rangle_{nc}) \frac{(s, R, t_a) \vdash \langle K \rangle_{nc} \phi}{(s', R'_{max}, t_b) \vdash \phi}$	$\exists b : b \in K, s \xrightarrow{b} s' = t_b \in R, t_a \ominus t_b$	
	$([]_c) \frac{(s, R, t_a) \vdash [K]_c \phi}{(s', R'_{max}, t_b) \vdash \phi}$	$\forall b : b \in K, s \xrightarrow{b} s' = t_b \in R, t_a \leq t_b$	
	$([]_{nc}) \frac{(s, R, t_a) \vdash [K]_{nc} \phi}{(s', R'_{max}, t_b) \vdash \phi}$	$\forall b : b \in K, s \xrightarrow{b} s' = t_b \in R, t_a \ominus t_b$	
STRUCTURAL OPERATORS			
(*)	$\frac{(s, R, t) \vdash \phi_0 * \phi_1}{(s, R_i, t) \vdash \phi_i}$	$\exists f, \forall i : f \in \mathfrak{P}^{\{0,1\}}, R_i \uplus R_{1-i} \sqsubseteq R, i \in \{0, 1\}$	
(\boxtimes)	$\frac{(s, R, t) \vdash \phi_0 \boxtimes \phi_1}{(s, R_i, t) \vdash \phi_i}$	$\forall f, \exists i : f \in \mathfrak{P}^{\{0,1\}}, R_i \uplus R_{1-i} \sqsubseteq R, i \in \{0, 1\}$	

Trace MSO Model Checking Games: Properties

- ▶ Closed under dual games.
- ▶ Eve preserves falsity and can preserve truth with her choices.
- ▶ Adam preserves truth and can preserve falsity with his choices.
- ▶ In any infinite play there is a unique syntactically outermost variable that occurs infinitely often.
- ▶ In infinite plays rule (VAR) must be applied infinitely often (important: infinite state systems with finite-branching).
- ▶ Winning conditions ensure a unique winner.

Main Results

Theorem: Trace MSO Model-Checking Games are Sound.

Theorem: Trace MSO Model-Checking Games are Complete.

Corollary: Trace MSO Model Checking Games are Determined.

Other Results

1. The winning strategies in the Trace MSO model-checking game of Separation Fixpoint Logic (SFL) are history-free.
2. In interleaving models of concurrency, the Trace MSO Model-checking games for SFL coincide with Stirling's Local Model-checking games for the Modal Mu-Calculus.

A Hintikka Game Semantics for SFL

$H \models_{\mathcal{V}} \phi$ iff Eve has a history-free winning strategy in the Trace MSO model-checking game $\mathcal{G}_{\text{M}}(H, \phi)$

1. This game model does not make use of the one-step interleaving semantics of the partial order model being considered.
2. Since Trace MSO Model-Checking Games are determined, this Game Theoretic Semantics (*à la* Hintikka) is, as well as the denotational one (*à la* Tarski), compositional.

Beyond Temporal Properties: Multi-Agent Systems

Agents:

- ▶ Γ is a finite set of agents, and
- ▶ $\mathcal{A} : T \rightarrow \Gamma$ is a mapping from transitions to agents.

Consistency of global actions:

- ▶ if $t_1 \sim t_2$ then $\mathcal{A}(t_1) = \mathcal{A}(t_2)$.

A distributed system:

- ▶ if $\mathcal{A}(t_1) \neq \mathcal{A}(t_2)$ then $lbl(t_1) \neq lbl(t_2)$.

Consistency of formulae:

- ▶ $\langle a \rangle^\alpha \phi$ is *well-defined* iff $a = lbl(t)$ and $\alpha = \mathcal{A}(t)$ for some $t \in T$ and $\alpha \in \Gamma$.
- ▶ $\langle K \rangle^\alpha \phi = \bigvee_{a \in K} \langle a \rangle^\alpha \phi$.

Multi-Agent Systems - Example

$$\psi = [-]^{\beta} \langle - \rangle_{nc}^{\alpha} \mu Z. \phi \vee \langle - \rangle_c^{\alpha} Z$$

Formula ψ expresses that there is an agent α (the system) that can satisfy ϕ regardless the behaviour of an adversarial agent β (the environment). Informally, ψ says “whatever you (the environment) do, I (the system) can get to ϕ , though I may first have to do some things that do not depend on what you did.”

Conclusions and Current/Future Work

1. The approach to defining games presented here, i.e., players allowed to play sets of elements, can help define:
 - ▶ Sound and complete, and therefore determined, games in partial order models of concurrency.
 - ▶ compositional game semantics for logics of concurrency.
2. The games presented here naturally capture the behaviour of partial order models, since the one-step interleaving semantics of those systems need not be considered.
3. Trace MSO Model-checking games deal equally well with both interleaving and partial order models of concurrency.
4. Temporal verification of regular but infinite partial order models.
5. Synthesis of asynchronous circuits.