

Polyhedral Compilation and the Integer Set Library

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Outline

- 1 Motivation (Cerebras)
- 2 Polyhedral Compilation
- 3 Integer Set Library (`isl`)
 - Interface
 - Internal Representation and Parametric Integer Programming
 - Operations
- 4 Conclusion



Cerebras Wafer-Scale Engine (WSE-2)

The Largest Chip in the World

850,000 cores optimized for sparse linear algebra

46,225 mm² silicon

2.6 trillion transistors

40 Gigabytes of on-chip memory

20 PByte/s memory bandwidth

220 Pbit/s fabric bandwidth

7nm process technology

Cluster-scale acceleration on a single chip

Automatic Code Generation

Given

- high-level algorithm description
- size of PE rectangle
- description of input and output

generate low-level (C) code exploiting hardware features

- powerful SIMD engine
- filtering
- FIFOs
- ...

⇒ Cerebras DTG tool

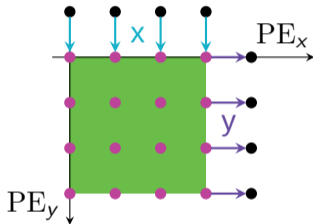
(for kernels for which no hand-written code is available)

Automatic Code Generation

[15]

```
forall MV<T=float16>(M, N): T W[M][N], T x[N] -> T y[M] {  
  all (i, j) in (M, N)  
    y[i] += W[i][j] * x[j]  
}
```

Mapping of 32×16 matrix vector multiplication
to 4×4 PEs.



```
size: { PE[4, 4] }
```

```
compute_map: { MV[i, j] -> PE[j//4, i//8] }
```

```
import_map: { x[i=0:15] -> [PE[i//4, -1] -> index[i%4]] }
```

```
oport_map: { y[i=0:31] -> [PE[4, i//8] -> index[i%8]] }
```

Affine Constraints

Computation instances, tensor elements, PE coordinates, ordering

⇒ represented by a tuple of integers

- Set of computation instances $\{ MV[i, j] : 0 \leq i < M \wedge 0 \leq j < N \}$
⇒ rectangle of fixed size
- Accesses $\{ MV[i, j] \rightarrow x[j] \} \cup \{ MV[i, j] \rightarrow y[i] \} \cup \{ MV[i, j] \rightarrow W[i, j] \}$
⇒ affine in instance identifiers
- Placement $\{ MV[i, j] \rightarrow PE[\lfloor j/4 \rfloor, \lfloor i/8 \rfloor] \}$
⇒ quasi affine (may involve integer divisions)
- Communication $\{ x[i = 0:15] \rightarrow [PE[\lfloor i/4 \rfloor, -1] \rightarrow \text{index}[i \bmod 4]] \}$
⇒ quasi affine

Sets and relations of integer tuples bounded by (quasi) affine constraints

Code Generation Process

Decision process involves questions of the form

- which tensor elements are needed on which PEs?
- which tensor elements are computed on which PEs?
- which computation instances can be performed on the arrival of a tensor element?
- do these computation instances form a box?
- can they be approximated by a box?
- ...

Manipulation of sets and relations of integer tuples bounded by (quasi) affine constraints

⇒ Polyhedral Compilation

Polyhedral Compilation

Polyhedral Compilation

Analyzing and/or transforming programs using the *polyhedral model*

Polyhedral Model

Abstract representation of a program

- instance based
 - ⇒ statement *instances*
 - ⇒ array *elements*
- compact representation based on polyhedra or similar objects
 - ⇒ integer points in unions of parametric polyhedra
 - ⇒ **Presburger sets and relations**
- parametric
 - ⇒ description may depend on constant symbols

Polyhedral Model

Typical constituents of program representation

- **Instance Set**
 - ⇒ the set of all statement instances
- **Access Relations**
 - ⇒ the array elements accessed by a statement instance
- **Dependences**
 - ⇒ the statement instances that depend on a statement instance
- **Schedule**
 - ⇒ the relative execution order of statement instances

Illustrative Example: Matrix Multiplication

```

for (int i = 0; i < M; i++)
  for (int j = 0; j < N; j++) {
S1:   C[i][j] = 0;
      for (int k = 0; k < K; k++)
S2:   C[i][j] = C[i][j] + A[i][k] * B[k][j];
      }

```

- **Instance Set** (set of statement instances)

$$\{ \mathbf{S1}[i,j] : 0 \leq i < M \wedge 0 \leq j < N; \mathbf{S2}[i,j,k] : 0 \leq i < M \wedge 0 \leq j < N \wedge 0 \leq k < K \}$$

- **Access Relations** (accessed array elements; *W*: write, *R*: read)

$$W = \{ \mathbf{S1}[i,j] \rightarrow C[i,j]; \mathbf{S2}[i,j,k] \rightarrow C[i,j] \}$$

$$R = \{ \mathbf{S2}[i,j,k] \rightarrow C[i,j]; \mathbf{S2}[i,j,k] \rightarrow A[i,k]; \mathbf{S2}[i,j,k] \rightarrow B[k,j] \}$$

- **Schedule** (relative execution order)

$$\{ \mathbf{S1}[i,j] \rightarrow [i,j,0,0]; \mathbf{S2}[i,j,k] \rightarrow [i,j,1,k] \}$$

Presburger Sets and Relations

Examples

$$\{ \mathbf{S1}[i, j] : 0 \leq i < M \wedge 0 \leq j < N; \mathbf{S2}[i, j, k] : 0 \leq i < M \wedge 0 \leq j < N \wedge 0 \leq k < K \}$$

$$\{ \mathbf{S1}[i, j] \rightarrow \mathbf{C}[i, j]; \mathbf{S2}[i, j, k] \rightarrow \mathbf{C}[i, j] \}$$

General form

- Sets

$$\{ \mathbf{S}_1[\mathbf{i}] : f_1(\mathbf{i}); \mathbf{S}_2[\mathbf{i}] : f_2(\mathbf{i}); \dots \},$$

with f_k Presburger formulas

\Rightarrow set of elements of the form $\mathbf{S}_1[\mathbf{i}]$, one for each \mathbf{i} satisfying $f_1(\mathbf{i})$, ...

- Binary relations

$$\{ \mathbf{S}_1[\mathbf{i}] \rightarrow \mathbf{T}_1[\mathbf{j}] : f_1(\mathbf{i}, \mathbf{j}); \mathbf{S}_2[\mathbf{i}] \rightarrow \mathbf{T}_2[\mathbf{j}] : f_2(\mathbf{i}, \mathbf{j}); \dots \}$$

\Rightarrow set of pairs of elements of the form $\mathbf{S}_1[\mathbf{i}] \rightarrow \mathbf{T}_1[\mathbf{j}]$

Note: despite " \rightarrow ", not necessarily (single valued) functions

Quasi-affine Expressions and Presburger Formulas

- quasi-affine expression (no multiplication; only constant functions)

- ▶ variable
- ▶ constant integer number
- ▶ constant symbol
- ▶ addition (+), subtraction (-)
- ▶ integer division by integer constant d ($\lfloor \cdot / d \rfloor$)

 x 3 N $x + 3$ $\lfloor (x + 3) / 16 \rfloor$

- Presburger formula

- ▶ true
- ▶ quasi-affine expression
- ▶ less-than-or-equal relation (\leq)
- ▶ equality ($=$)
- ▶ first order logic connectives: $\wedge, \vee, \neg, \exists, \forall$

 $0 \leq x$ $0 \leq x \wedge x < N$

- not allowed: multiplication, functions with arity greater than zero

 $x * x, x * N, f(x)$

- allowed: repeated addition

 $3 * x \equiv x + x + x$

Presburger Sets and Relations

General form

- Sets

$$\{ S_1[\mathbf{i}] : f_1(\mathbf{i}); S_2[\mathbf{i}] : f_2(\mathbf{i}); \dots \},$$

where $f_k(\mathbf{i})$ are Presburger formulas with \mathbf{i} as only free variables

\Rightarrow set of elements of the form $S_1[\mathbf{i}]$, one for each \mathbf{i} such that $f_1(\mathbf{i})$ is true, ...

Note: may depend on interpretation of symbolic constants

$$\{ S[i] : 0 \leq i \leq n \}$$

is equal to

$$\begin{cases} \emptyset & \text{if } n < 0 \\ \{ S[0] \} & \text{if } n = 0 \\ \{ S[0]; S[1] \} & \text{if } n = 1 \\ \{ S[0]; S[1]; S[2] \} & \text{if } n = 2 \\ \dots & \end{cases}$$

Overview of isl

isl is a thread-safe C library for manipulating **integer sets and relations**

- bounded by *affine constraints*
- involving *symbolic constants* and
- *existentially quantified variables*

plus **quasi-affine** and **quasi-polynomial functions** on such domains

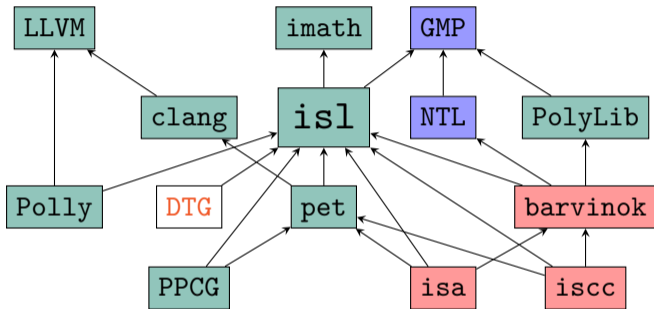
Supported operations by core library include

- *intersection*
- *union*
- *set difference*
- *integer projection*
- *coalescing*
- *closed convex hull*
- *sampling, scanning*
- *integer affine hull*
- *lexicographic optimization*
- *transitive closure* (approx.)
- *parametric vertex enumeration*
- *bounds on quasi polynomials*

Polyhedral compilation library

- *schedule trees*
- *scheduling*
- *dataflow analysis*
- *AST generation*

Connection with other Libraries and Tools



Licenses:

BSD/MIT/

Apache

GPL

GPL

isl: manipulates parametric affine sets and relations

barvinok: counts elements in Presburger sets and relations

pet: extracts polyhedral model from clang AST

PPCG: Polyhedral Parallel Code Generator

iscc: interactive calculator

Set Representation

[10]

```
S:  A[0] = 1;
    for (i = 1; i < N; ++i)
T:  A[i] = 2 * A[i - 1];
```

- isl: named (and nested) spaces

```
[N] -> { S[]; T[i]: 1 <= i < N }
```

- Omega:

```
symbolic N; padding T
{ [0, 0] } union { [1, i]: 1 <= i < N }
```

- PolyLib:

(deals with **rational** sets, polyhedra)

```
2
2 5
0 1 0 0 0
0 0 1 0 0
3 5 equality/inequality N
0 1 0 0 -1
1 0 1 0 -1
1 0 -1 1 -1
```


Spaces

Recall general form

- Sets

$$\{ S_1[\mathbf{i}] : f_1(\mathbf{i}); S_2[\mathbf{i}] : f_2(\mathbf{i}); \dots \},$$

- Binary relations

$$\{ S_1[\mathbf{i}] \rightarrow T_1[\mathbf{j}] : f_1(\mathbf{i}, \mathbf{j}); S_2[\mathbf{i}] \rightarrow T_2[\mathbf{j}] : f_2(\mathbf{i}, \mathbf{j}); \dots \}$$

Tuple **space**:

- the **identifier** (e.g., S_1 , S_2 , T_1 , T_2), combined with
- the **size**, i.e., the number of elements in the tuple (e.g., \mathbf{i} , \mathbf{j})

A statement $S_2[\mathbf{i}] = T_1[\mathbf{j}]$ means

- the **identifiers** S_2 and T_1 are the same, and
- the **sizes** of \mathbf{i} and \mathbf{j} are the same

Examples: $S[] \neq S[i]$, $S[a] = S[b]$, $S[] \neq T[]$

Nested Relations

isl currently supports

- sets

$$\{ S_1[\mathbf{i}] : f_1(\mathbf{i}); S_2[\mathbf{i}] : f_2(\mathbf{i}); \dots \},$$

- binary relations

$$\{ S_1[\mathbf{i}] \rightarrow T_1[\mathbf{j}] : f_1(\mathbf{i}, \mathbf{j}); S_2[\mathbf{i}] \rightarrow T_2[\mathbf{j}] : f_2(\mathbf{i}, \mathbf{j}); \dots \}$$

but not

- n-ary relations

$$\{ A[\mathbf{i}] \rightarrow B[\mathbf{j}] \rightarrow C[\mathbf{k}] \rightarrow \dots \}$$

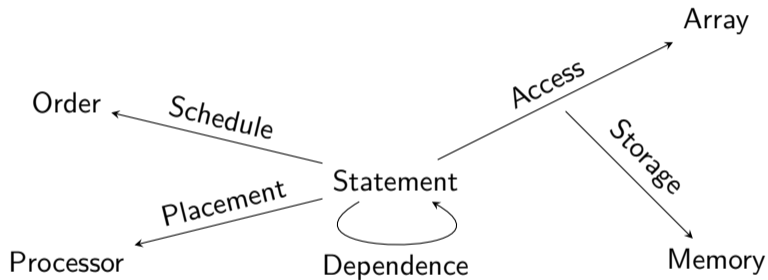
However, **nested** relations are supported

For example: statement instance specific memory map

$$\{ [S[i, j] \rightarrow A[i]] \rightarrow \text{Mem}[i, j] \}$$

In some cases, there is no clear binary decomposition and a real n-ary relation would be useful

Polyhedral Objects



+ many more

Polyhedral Compiler and Types

A sufficiently advanced polyhedral compiler needs to handle many kinds of polyhedral objects

This can cause confusion:

- exactly what kind of object does this function expect?
- does this operation on these objects make sense?

In statically typed languages (such as C++)

⇒ use **types**

In **PolyLib**, every set or binary relation is represented by a **Polyhedron**.

- ⇒ no differentiation at compile time
- ⇒ even at run time, only dimensionality can be checked

In **Omega**, every set or binary relation is represented by a **Relation**.

- ⇒ no differentiation at compile time
- ⇒ at run time, differentiation between tuple size(s) as well as between
 - ▶ sets, and
 - ▶ binary relations

Types Offered by Plain C++ Interface to isl

In `isl`, every set is represented by an `isl::set` or an `isl::union_set` and every binary relation is represented by an `isl::map` or an `isl::union_map`.

- ⇒ differentiation between sets and binary relations at compile time
- ⇒ at run time, differentiation between tuple size(s) and `tuple name(s)`
(for `isl::set` and `isl::map`)

```
{ S2[i, j, k] : 0 <= i < M and 0 <= j < N and 0 <= k < K }
{ S1[i, j] -> C[i, j] }
```

`isl::union_set` and `isl::union_map` objects may contain elements with different tuple sizes and/or names.

```
{ S1[i, j] -> C[i, j]; S2[i, j, k] -> C[i, j] }
```

- ⇒ no run-time checks
- ⇒ still maps *statement instances* to *array elements*
- ⇒ need for more fine-grained types

Types Offered by Templated C++ Interface to isl

[17]

- Template type for each plain type involving tuples
- Every type has 0 or more template parameters, one for each tuple,
- Template arguments are specified by application specifying tuple *kind*

For example,

```
struct ST {}; // statement  
struct AR {}; // array
```

```
isl::typed::map<ST, AR> access_relation;  
isl::typed::map<ST, ST> dependence_relation;
```

Benefits

- compile-time checks
- documentation

Drawbacks

- increase in compilation time
- increase in binary size

Internal Representation of Sets and Relations

Each set or relation is stored as disjunction of conjunctions (with local variables)

$$R = \bigcup_i R_i \quad R_i = \{ S[\mathbf{i}] \rightarrow T[\mathbf{j}] : \exists \mathbf{k} : A_0 \mathbf{c} + A_1 \mathbf{i} + A_2 \mathbf{j} + A_3 \mathbf{k} \geq \mathbf{a} \}$$

Each disjunct consists of

- affine equality and inequality constraints
- symbolic constants \mathbf{c}
- local variables \mathbf{k}
 - ▶ existentially quantified, or,
 - ▶ integer division $k_i = \lfloor e_i/d_i \rfloor$

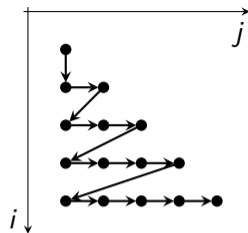
Conversion to disjunction of conjunctions

$$\neg(\exists \mathbf{a} : f(\mathbf{x}, \mathbf{a})) \rightarrow \neg f(\mathbf{x}, g(\mathbf{x}))$$

- ⇒ determine a single value of \mathbf{a} satisfying $f(\mathbf{x}, \mathbf{a})$ and write it as an explicit piecewise quasi affine expression $g(\mathbf{x})$ of \mathbf{x}
- ⇒ using parametric integer linear programming

Lexicographical Order

```
#define N 5
for (i = 1; i <= N; ++i)
  for (j = 1; j <= i; ++j)
    a[i][j] =
```



$$S = \{ [i, j] : 1 \leq j \leq i \leq N \}$$

Execution order:

[1,1], [2,1], [2,2], [3,1], [3,2], [3,3], [4,1], [4,2], [4,3], [4,4] [5,1], [5,2], [5,3], [5,4], [5,5]

Lexicographical order:

$$\mathbf{a} \prec \mathbf{b} \equiv \bigvee_{i=1}^n \left(a_i < b_i \wedge \bigwedge_{j=1}^{i-1} a_j = b_j \right)$$

⇒ smaller in first position where tuples differ

Parametric Integer Programming

[3]

Given a parametric polyhedron (no disjunction; no local variables),
give a description in terms of the parameters
of the lexicographically minimal (or maximal) integer point

E.g., first/last iteration of a loop nest satisfying some constraints

Technique: dual simplex + Gomory cuts

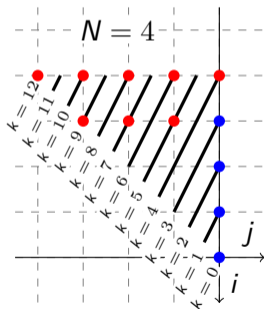
Result:

- Subdivision of parameter domain
- For each cell in subdivision an affine expression in terms of the parameters
- May include “new parameters”

$$q = \left\lfloor \frac{\sum_i a_i p_i + c}{d} \right\rfloor$$

Parametric Integer Programming Example

$$R = \{ [i, j] : 0 \leq -i \leq N \wedge 0 \leq -j \leq -i \wedge 0 \leq k \leq 3N \wedge k = -i - 2j \}$$



lexmin $R =$

if $k < N$

$$[-k, 0]$$

else

if $3 \lfloor \frac{k+N}{2} \rfloor \geq 2k$

$$\left[k - 2 \lfloor \frac{k+N}{2} \rfloor, -k + \lfloor \frac{k+N}{2} \rfloor \right]$$

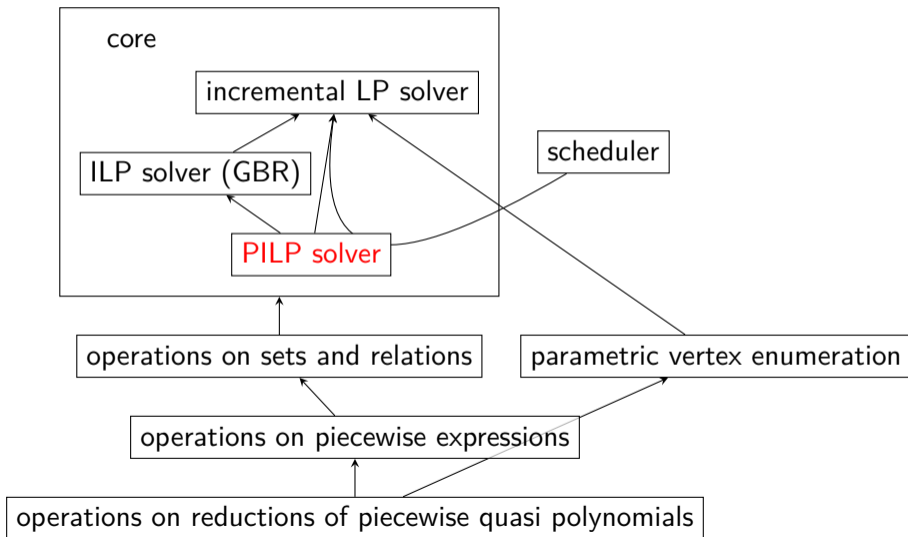
Parametric Integer Programming on Presburger Sets and Relations

$$R = \bigcup_i R_i \quad R_i = \{ S[\mathbf{i}] \rightarrow T[\mathbf{j}] : \exists \mathbf{k} : A_0 \mathbf{c} + A_1 \mathbf{i} + A_2 \mathbf{j} + A_3 \mathbf{k} \geq \mathbf{a} \}$$

- Compute lexmin R
 - \Rightarrow treat R_i as a parametric polyhedron with
 - ▶ parameters \mathbf{c} and \mathbf{i}
 - ▶ variables \mathbf{j} and \mathbf{k}
 - \Rightarrow combine results over multiple disjuncts
- Quantifier elimination
 - \Rightarrow treat R_i as a parametric polyhedron with
 - ▶ parameters \mathbf{c} , \mathbf{i} and \mathbf{j}
 - ▶ variables \mathbf{k}

Internal Structure of isl

[1, 2, 3, 8, 9, 13]



The Importance of Heuristics

Heuristics are used on top of core algorithms to *avoid computation* or produce *simpler results*

Parametric Integer Programming

- tighten constraints: $2x - 5 \geq 0 \Rightarrow x - 3 \geq 0$
- detect implicit equality constraints
- exploit equality constraints to reduce dimension of tableau
- look for variables with fixed value in terms of parameters
 - $\{ [i] \rightarrow [j, k] : i - 3 \leq 4j \leq i \wedge j \leq k \leq j + 1 \}$
 - ▶ j has fixed value $\lfloor i/4 \rfloor$
 - ▶ compute minimum of k in terms of i and j and plug in $j = \lfloor i/4 \rfloor$

\Rightarrow avoid potentially splitting up domain
- detect symmetries $\sum_i a_i x_i \leq f_j(\mathbf{n})$
 - \Rightarrow replace by $\sum_i a_i x_i \leq u$ with $u \leq f_j(\mathbf{n})$ extra parameter
 - \Rightarrow avoid considering all orderings of $f_j(\mathbf{n})$
- combine cells with same expression for minimum

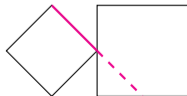
Choice of Internal Representation

Quantifier elimination

- isl uses $\lfloor \cdot / d \rfloor$ function symbols for quantifier elimination (obtained from parametric integer programming)
- traditionally, divisibility predicate symbols “ $d \mid \cdot$ ” used instead (e.g., Omega)

Decomposition

- isl uses disjunction of conjunctions
- tree can be alternative (e.g., obtained from parametric integer programming)
 - ▶ single constraint used to separate two groups of cells
 - ▶ forces further subdivisions



- a graph?

Constraints

isl (like other polyhedral libraries) has explicit representation for equality constraints

- In theory, equality constraint can be represented by pair of inequality constraints

$$f(\mathbf{i}) = 0 \quad \Rightarrow \quad f(\mathbf{i}) \geq 0 \wedge f(\mathbf{i}) \leq 0$$

- However, explicit equality constraint more easily exploited to reduce dimensionality

Other “redundant” types of constraints could also be useful

- disequality constraint

$$f(\mathbf{i}) \neq 0 \quad \Leftrightarrow \quad f(\mathbf{i}) \geq 1 \vee f(\mathbf{i}) \leq -1$$

- lexicographic constraint

$$\mathbf{a} \prec \mathbf{b} \quad \Leftrightarrow \quad \bigvee_{i=1}^n \left(a_i < b_i \wedge \bigwedge_{j=1}^{i-1} a_j = b_j \right)$$

⇒ adjust core algorithms or expand before applying

Piecewise Expressions

- Integer quasi affine expression

$$\lfloor x/2 \rfloor + 3N$$

⇒ Presburger term

That is, a term constructed from variables, symbolic constants, integer constants, addition (+), subtraction (−) and integer division by a constant ($\lfloor \cdot / d \rfloor$)

- Rational polynomial expression

$$x^2 - N/2$$

⇒ a term constructed from variables, symbolic constants,

rational constants, addition (+), subtraction (−) and multiplication (·)

- Quasi polynomial expression

$$(\lfloor x/2 \rfloor + 3N)^2 - N/2$$

⇒ a rational polynomial expression with variables replaced by integer quasi affine expressions

- Piecewise quasi affine/polynomial expression

⇒ a list of pairs of Presburger sets and

quasi affine/polynomial expressions $E = (S_i, e_i)_i$, with S_i disjoint

$$E(\mathbf{j}) = \begin{cases} e_i(\mathbf{j}) & \text{if } \mathbf{j} \in S_i \\ \perp/0 & \text{otherwise} \end{cases}$$

Piecewise Expressions

- Piecewise quasi **affine**/**polynomial** expression
 - ⇒ a list of pairs of Presburger sets and quasi **affine**/**polynomial** expressions $E = (S_i, e_i)_i$, with S_i disjoint

$$E(\mathbf{j}) = \begin{cases} e_i(\mathbf{j}) & \text{if } \mathbf{j} \in S_i \\ \perp/0 & \text{otherwise} \end{cases}$$

- Piecewise quasi **affine** expression *typically* represents element of set (e.g., lexmin)
 - ⇒ undefined when set is empty
- Piecewise quasi **polynomial** expression *typically* represents cardinality of set
 - ⇒ zero when set is empty

But: faithful conversion from partially defined piecewise quasi **affine** expression to piecewise quasi **polynomial** expression is currently not possible in `isl`

Value Semantics

Conceptually, each `isl` operation produces new object, leaving inputs untouched

However, internally,

- objects are reference counted
- an operation may return (a copy of) one of its inputs
- an input with a single reference may be reused and modified for result
- **representation** of shared object may get changed (not meaning)

For example,

- ▶ redundant constraints
 - ▶ implicit equality constraints
 - ▶ coalescing
- properties are shared among copies of same object (e.g., emptiness)

Deltas

$$R = \{ S[\mathbf{i}] \rightarrow S[\mathbf{j}] : P(\mathbf{i}, \mathbf{j}) \}$$

$$\Delta R = \{ S[\mathbf{k}] : \exists \mathbf{i}, \mathbf{j} : S[\mathbf{i}] \rightarrow S[\mathbf{j}] \in R \wedge \mathbf{k} = \mathbf{j} - \mathbf{i} \}$$

Example:

$$R = \{ S[i_1, i_2] \rightarrow S[0, j_2] : 0 \leq i_1 \leq 10 \wedge 0 \leq i_2 \leq 10 \wedge i_2 \leq j_2 \leq i_2 + 2 \}$$

$$\Delta R = \{ S[k_1, k_2] : -10 \leq k_1 \leq 0 \wedge 0 \leq k_2 \leq 2 \}$$

- Elements of ΔR live in same space as domain and range of R
Does it make sense to intersect ΔR with $\text{dom } R$?
- In templated interface, method only available for relations with two identical tuple kinds
 - ▶ result has same tuple kind
 - ▶ does not guarantee that tuple spaces are the same

$$\{ S1[i_1, i_2] \rightarrow S2[j_1, j_2] : \dots \}$$

Set Coalescing

[11]

After many applications of projection, set difference, union,
 a set may be represented as a union of many disjuncts
 \Rightarrow try to combine several disjuncts into a single disjunct

$$S_1 = \{ \mathbf{x} : A\mathbf{x} \geq \mathbf{c} \} \quad S_2 = \{ \mathbf{x} : B\mathbf{x} \geq \mathbf{d} \}$$

PolyLib way:

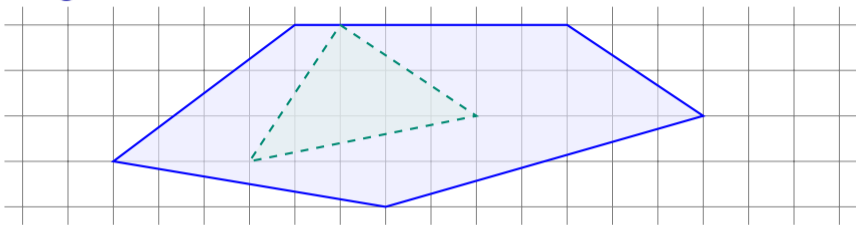
- 1 Compute $H = \text{conv.hull}(S_1 \cup S_2)$
- 2 Replace $S_1 \cup S_2$ by $H \setminus (H \setminus (S_1 \cup S_2))$

isl way:

- 1 Classify constraints
 - ▶ redundant: $\min \langle \mathbf{a}_i, \mathbf{x} \rangle > c_i - 1$ over remaining constraints of S_1
 - ▶ valid: $\min \langle \mathbf{a}_i, \mathbf{x} \rangle > c_i - 1$ over S_2
 - ▶ separating: $\max \langle \mathbf{a}_i, \mathbf{x} \rangle < c_i$ over S_2 ; special cases:
 - ★ adjacent to equality: $\langle \mathbf{a}_i, \mathbf{x} \rangle = c_i - 1$ over S_2
 - ★ adjacent to inequality: $\langle (\mathbf{a}_i + \mathbf{b}_j), \mathbf{x} \rangle = (c_i + d_j) - 1$ over S_2
 - ▶ cut: otherwise

Set Coalescing

[11]

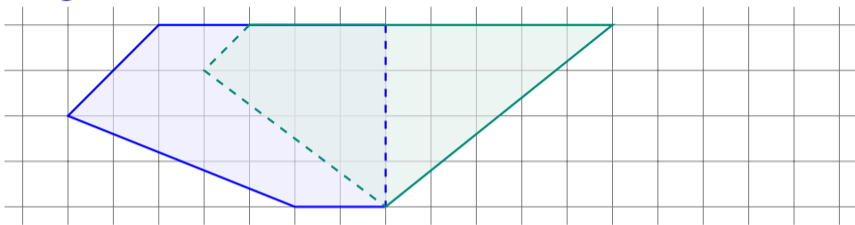


2 Case distinction

- 1 non-redundant constraints of S_1 are valid for S_2 , i.e., $S_2 \subseteq S_1$
 $\Rightarrow S_2$ can be dropped

Set Coalescing

[11]

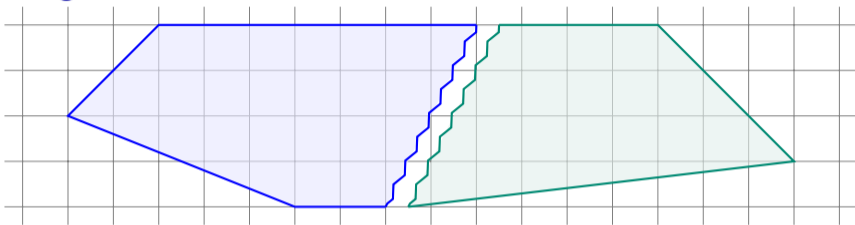


2 Case distinction

- 1 non-redundant constraints of S_1 are valid for S_2 , i.e., $S_2 \subseteq S_1$
- 2 no separating constraints and cut constraints of S_2 are valid for cut facets of S_1
 \Rightarrow replace S_1 and S_2 by disjunct with all valid constraints

Set Coalescing

[11]

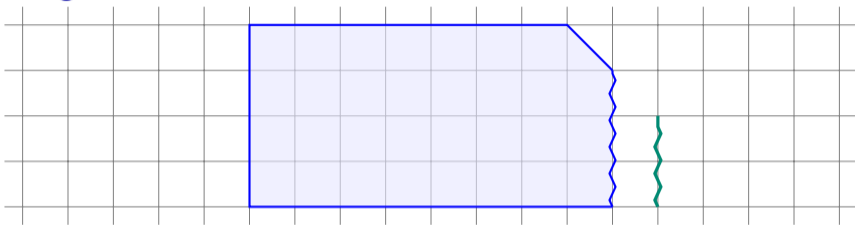


2 Case distinction

- 1 non-redundant constraints of S_1 are valid for S_2 , i.e., $S_2 \subseteq S_1$
- 2 no separating constraints and cut constraints of S_2 are valid for cut facets of S_1
- 3 single pair of adjacent inequalities (other constraints valid)
 \Rightarrow replace S_1 and S_2 by disjunct with all valid constraints

Set Coalescing

[11]

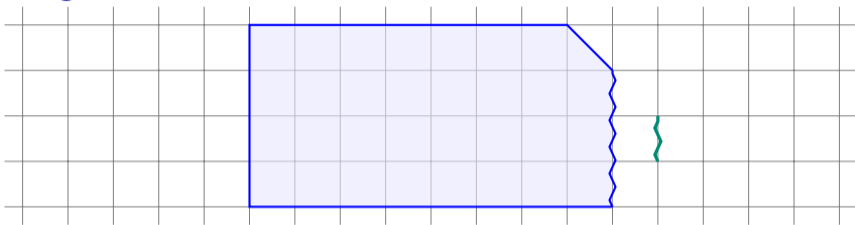


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- 1 non-redundant constraints of S_1 are valid for S_2 , i.e., $S_2 \subseteq S_1$
- 2 no separating constraints and cut constraints of S_2 are valid for cut facets of S_1
- 3 single pair of adjacent inequalities (other constraints valid)
- 4 single adjacent pair of an inequality (S_1) and an equality (S_2)
 - + other constraints of S_1 are valid
 - + constraints of S_2 valid for facet of relaxed inequality
 - \Rightarrow drop S_2 and relax adjacent inequality of S_1

Set Coalescing

[11]

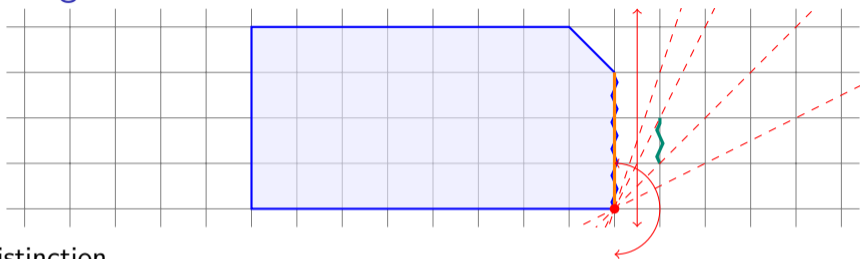


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 - + constraints of S_2 valid for facet of relaxed inequality
- 5 single adjacent pair of an inequality (S_1) and an equality (S_2)
 - + other constraints of S_1 are valid
 - + inequality and equality can be wrapped to include union
 - \Rightarrow replace S_1 and S_2 by valid and wrapping constraints

Set Coalescing

[11]

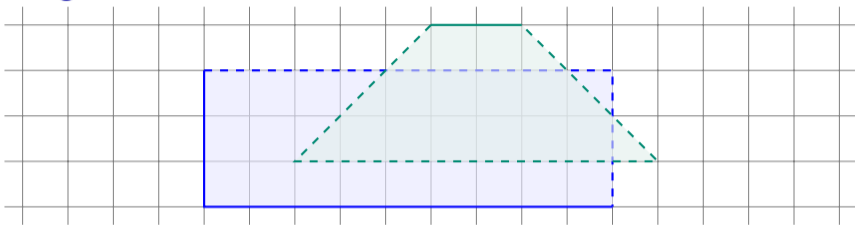


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Set Coalescing

[11]



2 Case distinction

- ① non-redundant constraints of S_1 are valid for S_2 , i.e., $S_2 \subseteq S_1$
- ② no separating constraints and cut constraints of S_2 are valid for cut facets of S_1
- ③ single pair of adjacent inequalities (other constraints valid)
- ④ single adjacent pair of an inequality (S_1) and an equality (S_2)
+ constraints of S_2 valid for facet of relaxed inequality
- ⑤ single adjacent pair of an inequality (S_1) and an equality (S_2)
+ inequality and equality can be wrapped to include union
- ⑥ S_2 extends beyond S_1 by at most one and all cut constraints of S_1 and parallel slices of S_2 can be wrapped to include union
⇒ replace S_1 and S_2 by valid and wrapping constraints

Positive Powers

Definition (Power of a Relation)

Let R be a Presburger relation and k a positive integer, then power k of relation R is defined as

$$R^k := \begin{cases} R & \text{if } k = 1 \\ R \circ R^{k-1} & \text{if } k \geq 2. \end{cases}$$

Example

$$R = \{ [x] \rightarrow [x + 1] \}$$
$$R^k = \{ [x] \rightarrow [x + k] : k \geq 1 \}$$

Transitive Closures

Definition (Transitive Closure of a Relation)

Let R be a Presburger relation, then the transitive closure R^+ of R is the union of all positive powers of R ,

$$R^+ := \bigcup_{k \geq 1} R^k.$$

Example

$$R = \{ [x] \rightarrow [x + 1] \}$$

$$R^k = \{ [x] \rightarrow [x + k] : k \geq 1 \}$$

$$R^+ = \{ [x] \rightarrow [y] : \exists k \geq 1 : y = x + k \} = \{ [x] \rightarrow [y] : y \geq x + 1 \}$$

Definition (Transitive Closure of a Relation, Alternative)

Inductive definition:

$$R^+ := R \cup (R \circ R^+)$$

Transitive Closures — Approximation

Fact

Given a Presburger relation R , the power R^k (with k a parameter) and the transitive closure R^+ may not be Presburger relations.

Example

$$R = \{ [x] \rightarrow [2x] \}$$
$$R^k = \{ [x] \rightarrow [2^k x] \}$$

- ⇒ need for approximation
- ▶ overapproximation R^+
 - ▶ underapproximation R^\pm

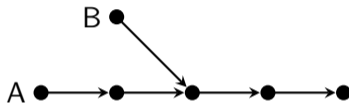
Note

Do not use transitive closures if there is an alternative.

Transitive Closures — Graph Example

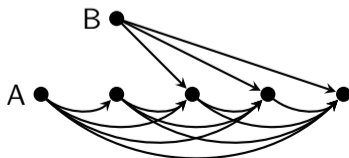
Given a graph (represented as a Presburger relation)

$$M = \{ A[i] \rightarrow A[i + 1] : 0 \leq i \leq 3; B[] \rightarrow A[2] \}$$



What is the transitive closure?

$$\Rightarrow M^+ = \{ A[i] \rightarrow A[i'] : 0 \leq i < i' \leq 4; B[] \rightarrow A[i] : 2 \leq i \leq 4 \}$$



Conclusion

isl is a versatile tool for polyhedral compilation and beyond

Combination of

- high-level interface
- core algorithms
- heuristics

Possible future extensions

- function symbols
- n-ary relations
- other constraint types
- partially defined piecewise quasi polynomial expression
- cardinality

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