Weak Cost Monadic Logic over Infinite Trees

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Syntax

First-order logic with second-order quantification over sets + new predicates $|X| \leq N$ appearing positively ($N \in \mathbb{N}$)

Example

$$block(X) := \forall x, y. (x \in X \land y \in X \land x < y) \rightarrow (\forall Z. (x \in Z \land Z \text{ closed under successor in } X) \rightarrow y \in Z)$$

 $\varphi := \exists X. block(X) \land a(X) \land X \text{ surrounded by } b's \land |X| \leq N$

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Semantics

$$\begin{split} \llbracket \varphi \rrbracket : \text{structures} &\to \mathbb{N} \cup \{\infty\} \\ \llbracket \varphi \rrbracket(u) := \min\{n : u \text{ satisifes } \varphi \text{ when } N \text{ takes value } n\} \\ \text{By convention: } \min \emptyset = \infty \end{split}$$

$$\label{eq:product} \begin{split} ``[\![\varphi]\!] &= n'' \quad : \mbox{ decidable} \\ ``[\![\varphi]\!] &= [\![\psi]\!]'' \colon \mbox{ undecidable [Krob 1994]} \end{split}$$

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A cost function is an equivalence class of \approx .

B-automata

Nondeterministic finite-state automaton \mathcal{A}

+ finite set of counters

(initialized to 0, values range over \mathbb{N})

+ counter operations on transitions

(increment I, reset R, no change ε)

Semantics

 $val(\rho) := \max \text{ value achieved by any counter during run } \rho$ $\llbracket \mathcal{A} \rrbracket(u) := \min\{val(\rho) : \rho \text{ is an accepting run of } \mathcal{A} \text{ on } u\}$

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Example

 $\llbracket A \rrbracket(u) = \min$ length of block of *a*'s surrounded by *b*'s in *u*



Theory of regular cost functions over finite words

Cost MSO





min, max, π_{inf} , π_{sup}



 $f \approx g$ decidable over finite words [Colcombet '09]

> Stabilization Monoids

Theory of regular cost functions over finite trees

Cost MSO

B/S Tree Automata

Regular Cost Functions

min, max, π_{inf} , π_{sup}

B/S Expressions

 $f \approx g$ decidable over finite trees [Colcombet+Löding '10]

Cost Games

Many problems for a regular language L can be reduced to deciding \approx :

Finite power property

[Simon '78, Hashiguchi '79]:

is there some *n* such that $(L + \epsilon)^n = L^*$?

Star-height problem

[Hashiguchi '88, Kirsten '05, Colcombet+Löding '08]:

given n, is there a regular expression for L with at most n nestings of Kleene star operations?

Parity-index problem

[reduction in Colcombet+Löding '08, decidability open]:

given i < j, is there a parity automaton for L which uses only priorities $\{i, i + 1, ..., j\}$?

Weak cost monadic logic over infinite trees

Cost WMSO: interpret second-order quantification over finite sets

$$\llbracket \varphi \rrbracket(t) = \begin{cases} \max a's \text{ on single branch} & \text{if } t \text{ has infinitely many } b's \\ \infty & \text{otherwise} \end{cases}$$

for trees *t* over finite alphabet $\Sigma = \{a, b, c\}$

$$\begin{array}{lll} \varphi & := & \forall X. \exists x. (\neg (x \in X) \land b(x)) & \land \\ & \forall Z. ((\forall z. (z \in Z \rightarrow a(z)) \land chain(Z)) \rightarrow |Z| \leq N) \\ & \text{where } chain(Z) \text{ asserts } Z \text{ is totally ordered} \end{array}$$

Weak automata and games

Alternating parity automaton with priorities $\{1,2\}$ + no cycle in transition function which visits both priorities

Game (\mathcal{A}, t)



Semantics

A strategy σ for Eve is winning if every play in σ stabilizes in priority 2 A accepts t if Eve has a winning strategy from the initial position

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Weak B-automata and games

Alternating parity automaton with priorities $\{1,2\}$ + no cycle in transition function which visits both priorities + finite set of counters and counter actions I, R, ε on transitions

Game (\mathcal{A}, t)



Semantics

 $val(\sigma) := \max$ value of any play in strategy σ $\llbracket \mathcal{A} \rrbracket(t) := \min\{val(\sigma) : \sigma \text{ is a winning strategy for Eve in } (\mathcal{A}, t)\}$

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Do finite-memory strategies guarantee an \approx -equivalent value?

- ▶ finite-duration *B*-games: yes [Colcombet + Löding '10]
- weak B-games and B-Büchi games: yes [VB]

G B-Büchi game k counters

visit priority 2 infinitely-often and minimize cost

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 $\mathcal{T} \\ \text{winning strategy with} \\ \textit{val}(\tau) \leq \textit{n}$



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 \mathcal{T} winning strategy with $\mathit{val}(au) \leq \mathit{n}$



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G B-Büchi game k counters $\mathcal{G}_{ au}$ B-safety game

visit priority 2 infinitely-often and minimize cost

 \mathcal{T} winning strategy with $\mathit{val}(au) \leq \mathit{n}$



visit priority 2 between d_i and d_{i+1} and minimize cost

G B-Büchi game k counters $\mathcal{G}_{ au}$ B-safety game

visit priority 2 infinitely-often and minimize cost

 \mathcal{T} winning strategy with $\mathit{val}(au) \leq n$

visit priority 2 between d_i and d_{i+1} and minimize cost

σ

finite-memory winning strategy with $val(\sigma) \leq (n+1)^k$

G B-Büchi game k counters $\mathcal{G}_{ au}$ B-safety game

visit priority 2 infinitely-often and minimize cost

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 \leftarrow



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₩

- A weak *B*-automaton \mathcal{A} can be **simulated** by a nondeterministic *B*-Büchi automaton \mathcal{B} such that $[\![\mathcal{A}]\!] \approx [\![\mathcal{B}]\!]$.
 - guess a labelling of t with a finite-memory strategy σ in (A, t)
 - run a B-Büchi automaton on each branch which computes the max value of plays from σ which stay on that branch

Theory of weak cost functions [VB]

Cost WMSO

min, max, w. π_{inf}/π_{sup}

Weak *B/S* Automata ↓ Nondeterministic *B/S*-Büchi Automata



 $f \approx g$ decidable over infinite trees Cost MSO Cost WMSO WMSO MSO

Weak Cost Games

Theory of weak cost functions [VB]

Cost WMSO

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Weak *B/S* Automata ↓ Nondeterministic *B/S*-Büchi Automata



 $f \approx g$ decidable over infinite trees



Weak Cost Games

Open Questions

- Is full cost MSO decidable over infinite trees?
- Do finite-memory strategies suffice in B-parity games?

$$\llbracket \varphi(X) \rrbracket (t, V) = \inf \{ n : t \models \varphi[n/N, V/X] \}$$

$$\begin{split} \|X\| &\leq N]\!](t,V) = |V| \\ & \llbracket \varphi \lor \psi \rrbracket(t) = \min(\llbracket \varphi \rrbracket(t), \llbracket \psi \rrbracket(t)) \\ & \llbracket \varphi \land \psi \rrbracket(t) = \max(\llbracket \varphi \rrbracket(t), \llbracket \psi \rrbracket(t)) \\ & \llbracket \exists X. \varphi(X) \rrbracket(t) = \inf\{\llbracket \varphi(X) \rrbracket(t,V) : V \text{ is finite set}\} \\ & \llbracket \forall X. \varphi(X) \rrbracket(t) = \sup\{\llbracket \varphi(X) \rrbracket(t,V) : V \text{ is finite set}\} \end{split}$$

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Lemmas

Weak *B*-automata are closed under min, max, weak inf-projection.

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Lemmas

Weak *B*-automata are closed under min, max, weak inf-projection. Weak *S*-automata closed under min, max, weak sup-projection.

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Lemmas

Weak B-automata are closed under min, max, weak inf-projection.

Weak S-automata closed under min, max, weak sup-projection.

Weak *B*-automata and weak *S*-automata are effectively equivalent (modulo \approx) over infinite trees.