Linear regression

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Outline

This lecture introduces us to the topic of supervised learning. Here the data consists of input-output pairs. Inputs are also often referred to as covariates, predictors and features; while outputs are known as variates, targets and labels. The goal of the lecture is for you to:

□ Understand the supervised learning setting.

- Understand linear regression (aka least squares)
- Understand how to apply linear regression models to make predictions.
- □ Learn to derive the least squares estimate.

Linear supervised learning

□ Many real processes can be approximated with linear models.

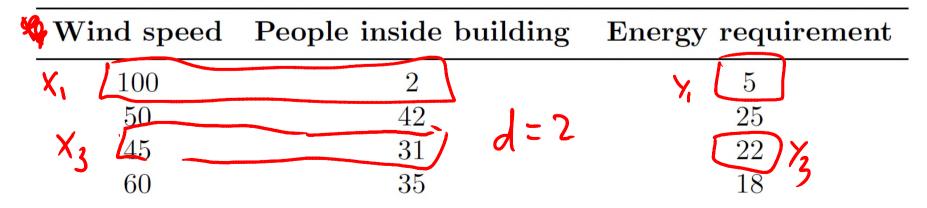
□ Linear regression often appears as a module of larger systems.

□ Linear problems can be solved analytically.

□ Linear prediction provides an introduction to many of the core concepts of machine learning.

We are given a training dataset of *n* instances of input-ouput pairs $\mathbf{x}_{1:n}, \mathbf{y}_{1:n}$. Each input $\mathbf{x}_i \in \mathbb{R}^{1 \times d}$ is a vector with *d* attributes. The inputs are also known as predictors or covariates. The output, often referred to as the target, will be assumed to be univariate, $\mathbf{y}_i \in \mathbb{R}$, for now.

A typical dataset with n = 4 instances and 2 attributes would look like the following table:

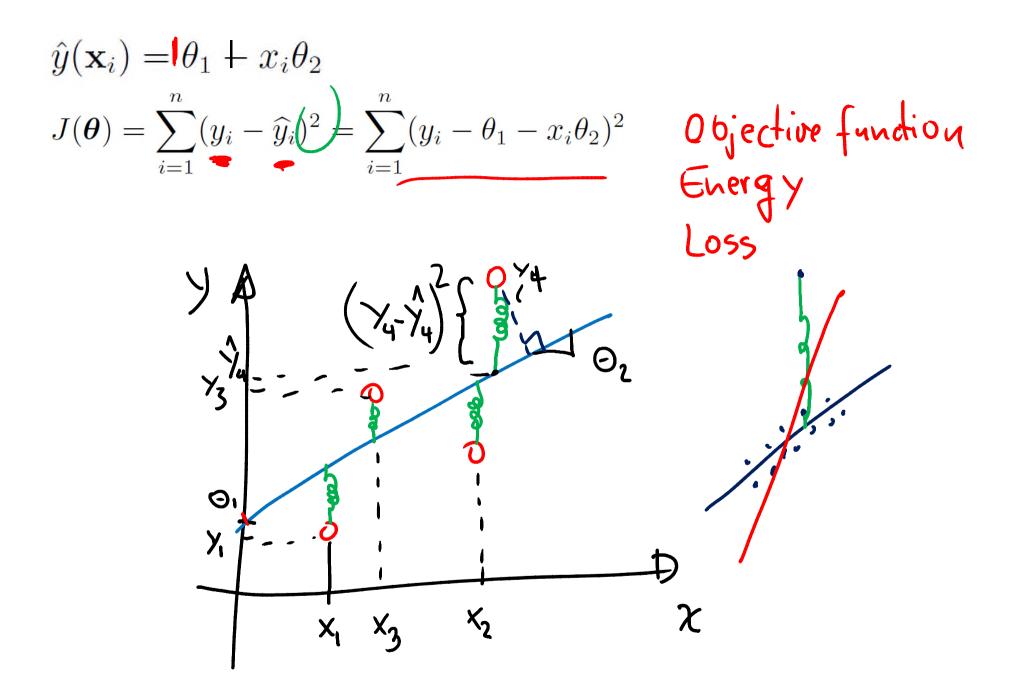


Energy demand prediction



Given the training set $\{\mathbf{x}_{1:n}, \mathbf{y}_{1:n}\}$, we would like to learn a model of how the inputs affect the outputs. Given this model and a new value of the input \mathbf{x}_{n+1} , we can use the model to make a prediction $\hat{y}(\mathbf{x}_{n+1})$.

modet DATA {x_{1:n}, y_n} TRAINING learni-g Parameters Learner Xnti, O -Predictor prediction



Linear prediction

In general, the linear model is expressed as follows:

$$\widehat{y}_i = \sum_{j=1}^d x_{ij}\theta_j, = \chi_{i}\Theta_1 + \chi_{i2}\Theta_2 + \cdots + \chi_{iq}\Theta_{iq}$$

where we have assumed that $x_{i1} = 1$ so that θ_1 corresponds to the intercept of the line with the vertical axis. θ_1 is known as the bias or offset.

In matrix form, the expression for the linear model is:

$$\widehat{\mathbf{y}} = \mathbf{X}\boldsymbol{\theta},$$

with $\widehat{\mathbf{y}} \in \mathbb{R}^{n \times 1}$, $\mathbf{X} \in \mathbb{R}^{n \times d}$ and $\boldsymbol{\theta} \in \mathbb{R}^{d \times 1}$. That is,

$$\begin{bmatrix} \widehat{y}_1 \\ \vdots \\ \widehat{y}_n \end{bmatrix} = \begin{bmatrix} x_{11} & \cdots & x_{1d} \\ \vdots & \vdots & \vdots \\ x_{n1} & \cdots & x_{nd} \end{bmatrix} \begin{bmatrix} \theta_1 \\ \vdots \\ \theta_d \end{bmatrix}.$$

Wind speed	People inside building	Energy requirement
100	2	5
50	42	25
45	31	22
60	35	18
		\sim

For our energy prediction example, we would form the following matrices with n = 4 and d = 3:

$$\mathbf{y} = \begin{bmatrix} 5\\25\\22\\18 \end{bmatrix}, \quad \mathbf{X} = \begin{bmatrix} 1 & 100 & 2\\1 & 50 & 42\\1 & 45 & 31\\1 & 60 & 35 \end{bmatrix}, \quad \boldsymbol{\theta} = \begin{bmatrix} \theta_1\\\theta_2\\\theta_3 \end{bmatrix}.$$

Suppose that $\boldsymbol{\theta} = \begin{bmatrix} 1 & 0 & 0.5 \end{bmatrix}^T$. Then, by multiplying **X** times $\boldsymbol{\theta}$, we would get the following predictions on the training set:

$$\widehat{\mathbf{y}} = \begin{bmatrix} 2\\22\\16.5\\18.5 \end{bmatrix} = \begin{bmatrix} 1 & 100 & 2\\1 & 50 & 42\\1 & 45 & 31\\1 & 60 & 35 \end{bmatrix} \begin{bmatrix} 1\\0\\0.5 \end{bmatrix}.$$

Linear prediction on test data

Likewise, for a point that we have never seen before, say $x = [50 \ 20]$, we generate the following prediction:

$$\hat{\mathbf{y}}(\mathbf{x}) = \begin{bmatrix} 1 & 50 & 20 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0.5 \end{bmatrix} = 1 + 0 + 10 = 11.$$

$$J(\theta) = \underbrace{(\mathbf{y} - \mathbf{X}\theta)^{T}}_{=} \underbrace{(\mathbf{y} - \mathbf{X}\theta)}_{=} \underbrace{\sum_{i=1}^{n} (y_{i} - \mathbf{x}_{i}^{T}\theta)^{2}}_{i=1}$$

$$\underbrace{\mathbf{X} = (\mathbf{x}_{i} \ \mathbf{x}_{i})^{T}}_{=} \underbrace{\mathbf{Y} = (\mathbf{Y}_{i} \ \mathbf{Y}_{i})^{T}}_{=} \underbrace{\mathbf{X}^{T}}_{=} \underbrace{\mathbf{Y}_{i} \ \mathbf{x}_{i}}_{=} \underbrace{\mathbf{X}_{i} \ \mathbf{Y}_{i}}_{=} \underbrace{\mathbf{X}_{i} \ \mathbf{X}_{i}}_{i}$$

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Optimization approach

Our aim is to minimise the quadratic cost between the output labels and the model predictions

$$J(\theta) = (\mathbf{y} - \mathbf{X}\theta)^{T}(\mathbf{y} - \mathbf{X}\theta) = \sum_{i=1}^{n} (y_{i} - \mathbf{x}_{i}^{T}\theta)^{2}$$

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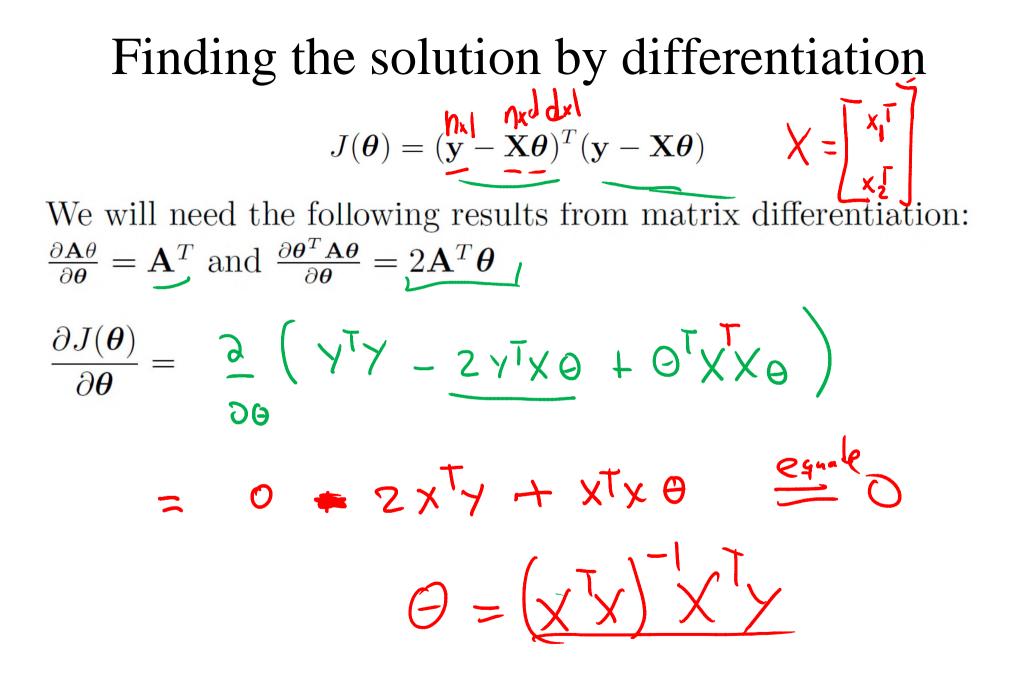
$$(\mathbf{y} - \mathbf{X}\theta)^{T}(\mathbf{y} - \mathbf{X}\theta) = \sum_{i=1}^{n} (y_{i} - \mathbf{X}\theta)^{T}(\mathbf{y} - \mathbf{X}\theta)$$

$$(\mathbf{y} - \mathbf{X}\theta)^{T}(\mathbf{y} - \mathbf{$$

Finding the solution by differentiation

$$J(\theta) = \sum_{i=1}^{n} (y_i - \hat{y}_i)^2 = \sum_{i=1}^{n} (y_i - \theta_1 - x_i \theta_2)^2$$

$$\frac{1}{d\theta_1} \xrightarrow{\mathcal{J}} \left\{ \begin{array}{c} \theta_1 \\ \theta_2 \end{array}\right\} \xrightarrow{\mathcal{J}} \left\{ \begin{array}{c} \theta_1 \\ \theta_2 \end{array}\right\} \xrightarrow{\mathcal{J}} \left\{ \begin{array}{c} \mathcal{J}(\theta) \\ \mathcal{J}(\theta) \\ \mathcal{J}(\theta) \end{array}\right\} \xrightarrow{\mathcal{J}} \left\{ \begin{array}{c} \theta_1 \\ \theta_2 \end{array}\right\} \xrightarrow{\mathcal{J}} \left\{ \begin{array}{c} \mathcal{J}(\theta) \\ \mathcal{J}(\theta) \\ \mathcal{J}(\theta) \end{array}\right\} \xrightarrow{\mathcal{J}} \left\{ \begin{array}{c} \mathcal{J}(\theta) \\ \mathcal{J}(\theta) \\ \mathcal{J}(\theta) \end{array}\right\} \xrightarrow{\mathcal{J}} \left\{ \begin{array}{c} \mathcal{J}(\theta) \\ \mathcal{J}(\theta) \\ \mathcal{J}(\theta) \end{array}\right\} \xrightarrow{\mathcal{J}} \left\{ \begin{array}{c} \mathcal{J}(\theta) \\ \mathcal{J}(\theta) \\ \mathcal{J}(\theta) \end{array}\right\} \xrightarrow{\mathcal{J}} \left\{ \begin{array}{c} \mathcal{J}(\theta) \\ \mathcal{J}(\theta) \\ \mathcal{J}(\theta) \\ \mathcal{J}(\theta) \end{array}\right\} \xrightarrow{\mathcal{J}} \left\{ \begin{array}{c} \mathcal{J}(\theta) \\ \mathcal{J}(\theta) \\ \mathcal{J}(\theta) \\ \mathcal{J}(\theta) \\ \mathcal{J}(\theta) \end{array}\right\} \xrightarrow{\mathcal{J}} \left\{ \begin{array}{c} \mathcal{J}(\theta) \\ \mathcal{J}($$





Torch: Data

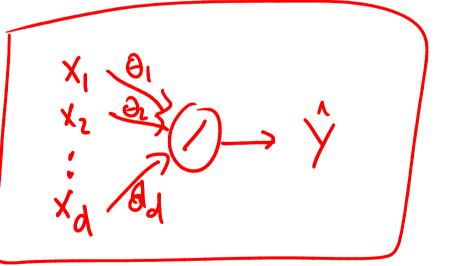
Torch 7

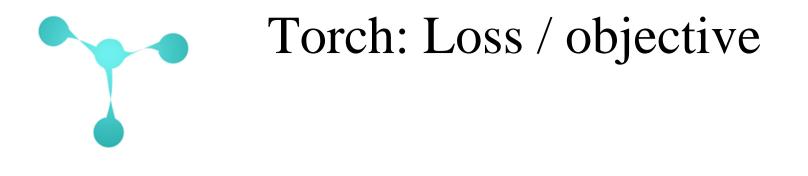
55	{corn, fertilizer, insecticide}
56	<pre>data = torch.Tensor{</pre>
57	$\{40, 6, 4\},\$
58	$\{44, 10, 4\},\$
59	$\{46, 12, 5\},\$
60	$\{48, 14, 7\},\$
61	$\{52, 16, 9\},\$
62	{58, 18, 12},
63	$\{60, 22, 14\},\$
64	<i>{</i> 68 <i>,</i> 24 <i>,</i> 20 <i>},</i>
65	{74, 26, 21},
66	{ 80 , 32, 24}
67	}



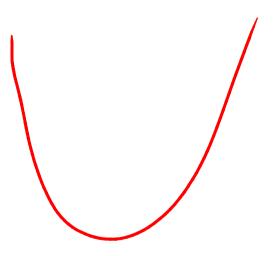
Torch: Model

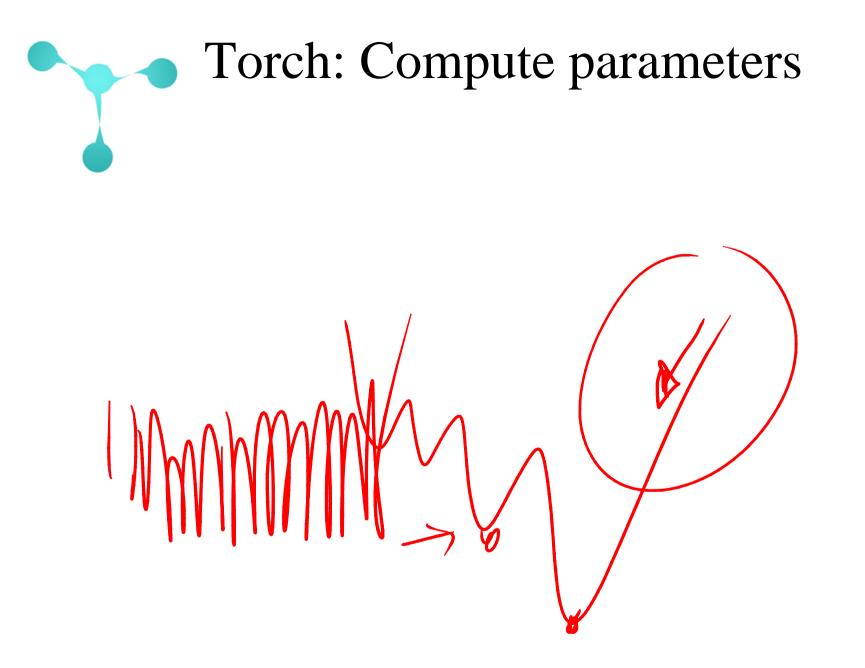
model = nn.Sequential()
ninputs = 2; noutputs = 1
model:add(nn.Linear(ninputs, noutputs))





109 criterion = nn.MSECriterion()





Next lecture

In the next lecture, we learn to derive the linear regression estimates by maximum likelihood with multivariate Gaussian distributions.

Please go to the Wikipedia page for the multivariate Normal distribution beforehand or, even better, read Chapter 4 of Kevin Murphy's book and attempt the first three questions of the exercise sheet.