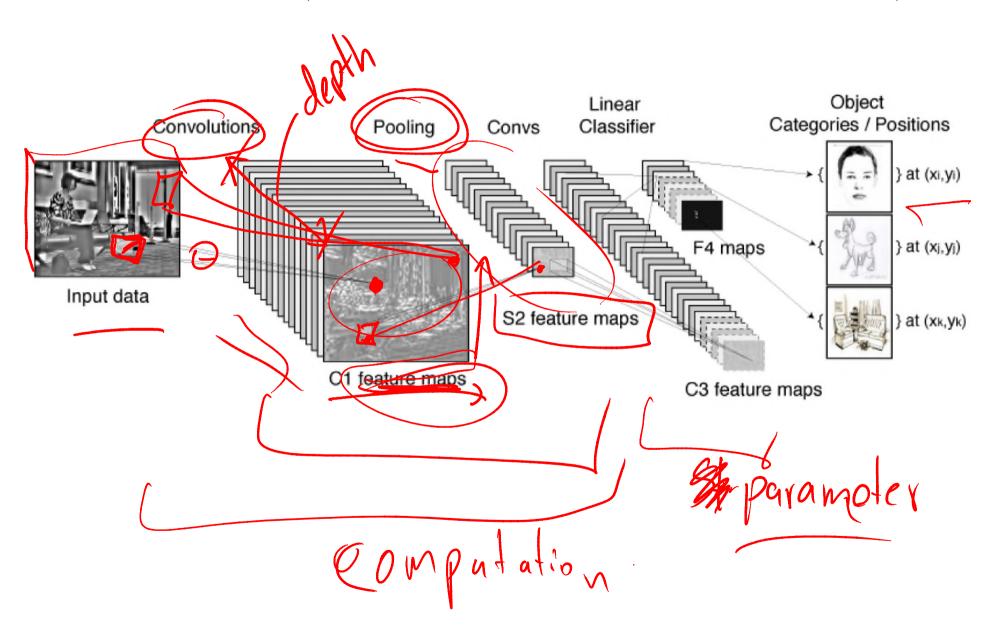


Outline of the lecture

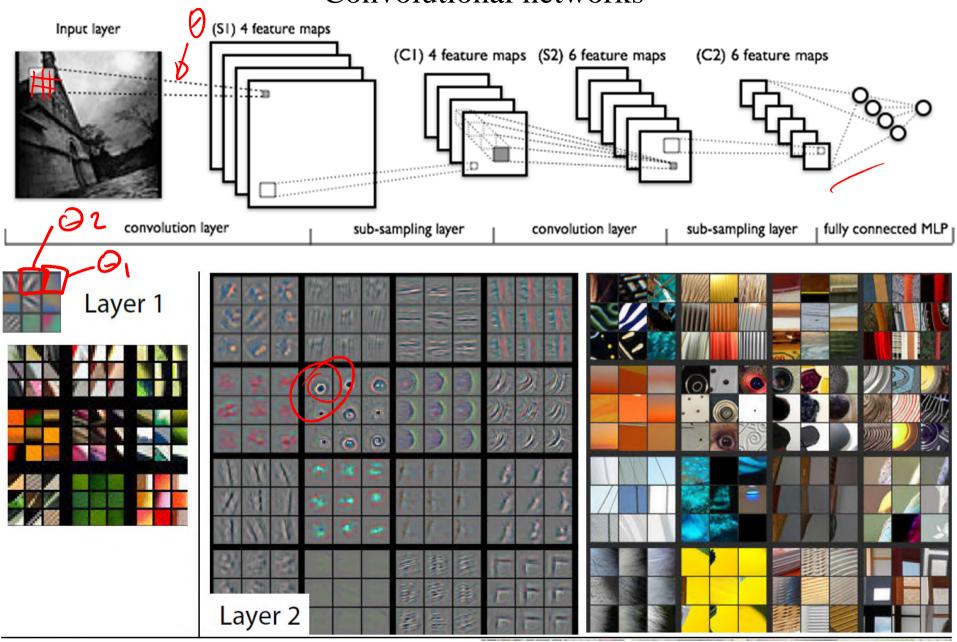
This lecture introduces you to convolutional neural networks. These models have revolutionized speech and object recognition. The goal is for you to learn

- ☐ Convnets for object recognition and language
- ☐ How to design convolutional layers
- ☐ How to design pooling layers
- ☐ How to build convnets in torch

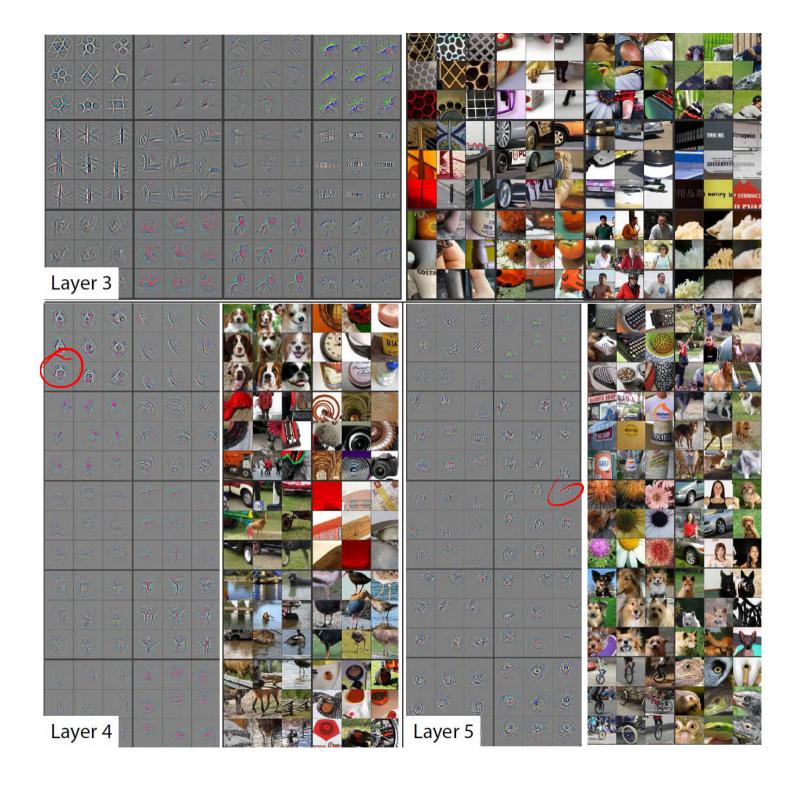
Convnets (Fukushima, LeCun, Hinton)



Convolutional networks



[Matthew Zeiler & Rob Fergus]



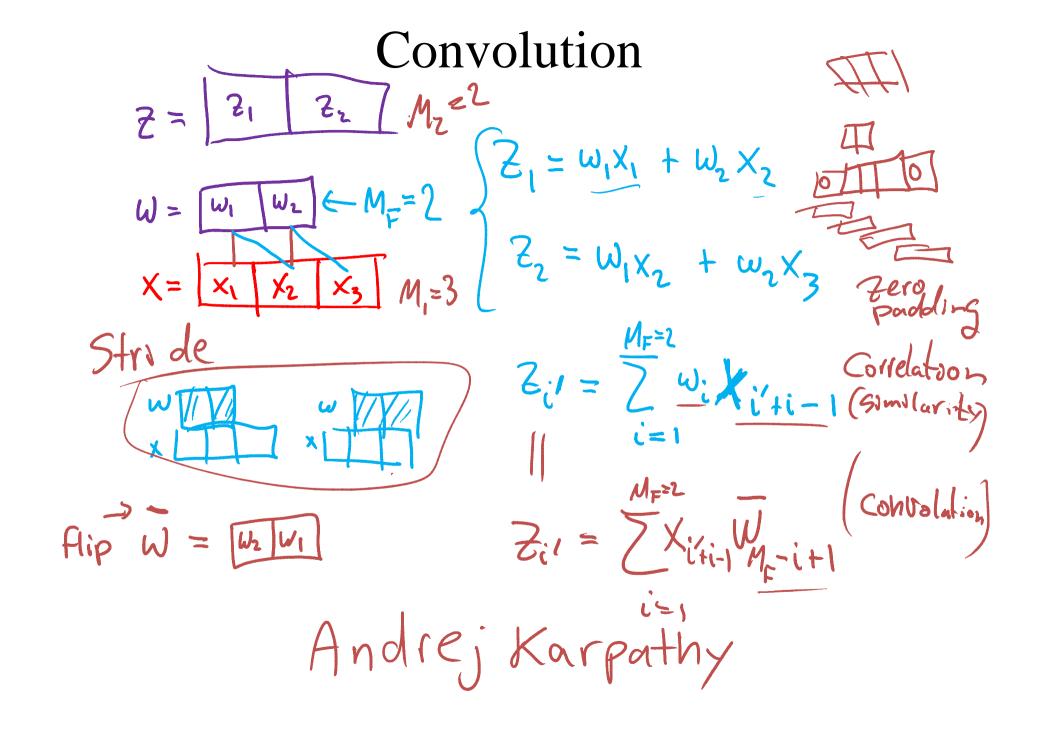
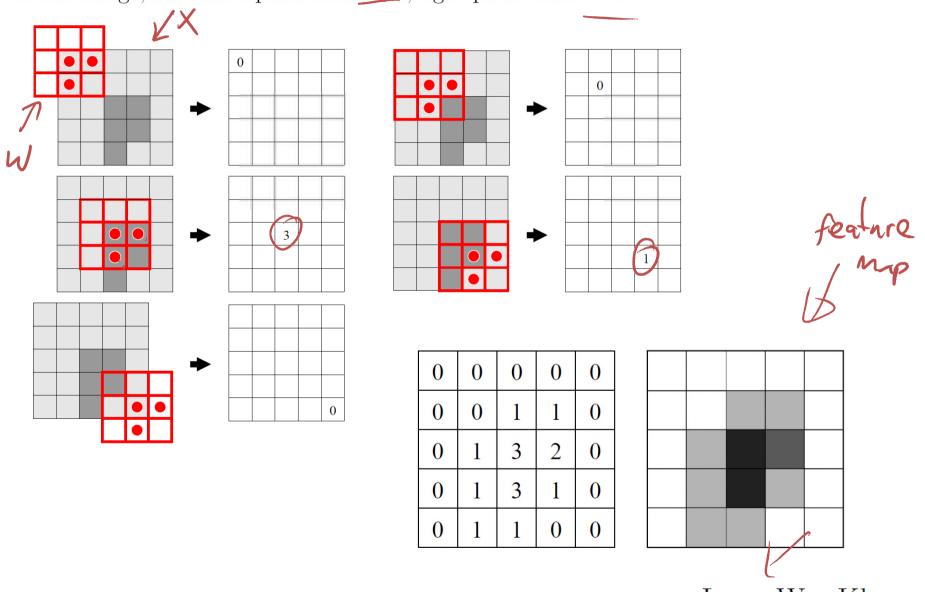


Image convolution

For the image, take dark pixel value = 1, light pixel value = 0.



Leow Wee Kheng

Convnets (Fukushima, LeCun, Hinton)

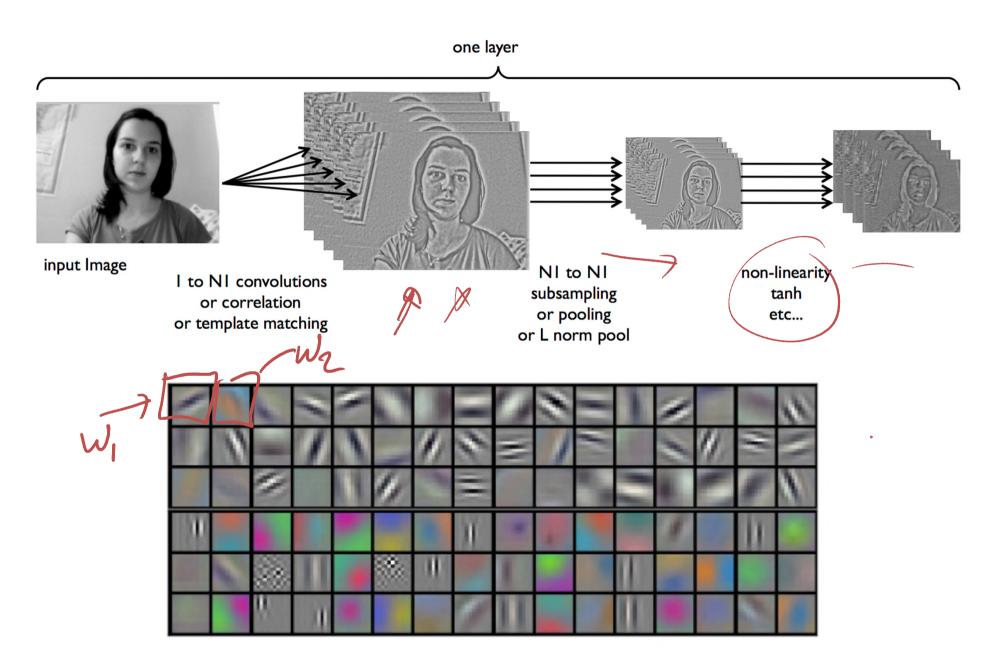


Image convolution layer

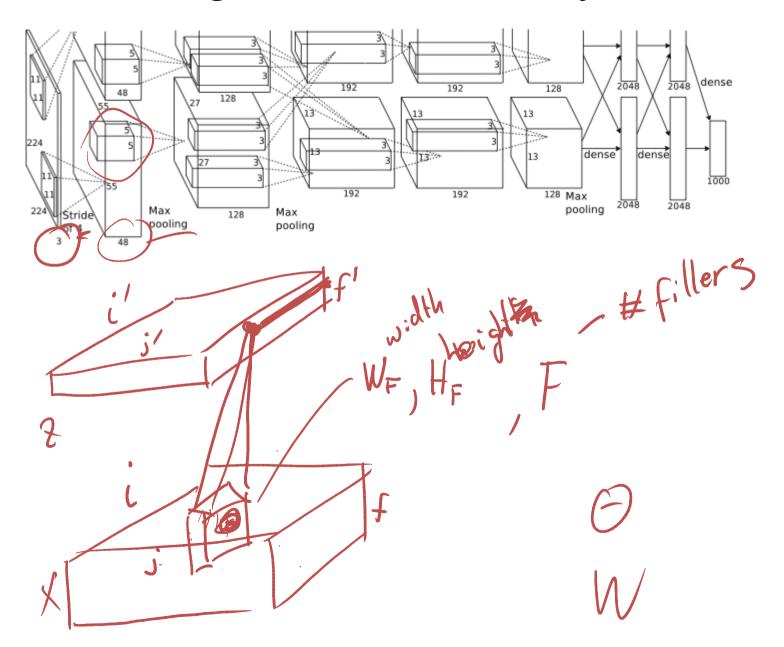


Image convolution layer



$$\int \mathbf{y}_{i',j',f'} = b_{f'} + \sum_{i=1}^{H_f} \sum_{j=1}^{W_f} \sum_{f=1}^{F} \mathbf{x}_{i'+i-1,j'+j-1,f} \boldsymbol{\theta}_{ijff'}$$

$$\frac{\partial E}{\partial \theta_{ijff'}} = \sum_{i'j'f'} \delta_{i'j'f'}^{l+1} \frac{\partial f_{i'j'f'}(\mathbf{x}; \boldsymbol{\theta}_{f'})}{\partial \theta_{ijff'}}$$

$$= \sum_{i'j'} \delta_{i'j'f'}^{l+1} \mathbf{x}_{i'+i-1,j'+j-1,f}$$

Image convolution layer

$$\mathbf{y}_{i',j',f'} = b_{f'} + \sum_{i''=1}^{H_f} \sum_{j''=1}^{W_f} \sum_{f''=1}^{F} \mathbf{x}_{i'+i''-1,j'+j''-1,f''} \boldsymbol{\theta}_{i''j''f''}^{\mathbf{y}}$$

$$= \sum_{i'j'f'} \delta_{i'j'f'}^{l+1} \frac{\partial f_{i'j'f'}(\mathbf{x};\boldsymbol{\theta}_{f'})}{\partial \mathbf{x}_{ijf}} \qquad \underbrace{\underline{i} = \underline{i'} + \underline{i''} - 1}_{i'' = \underline{i} - \underline{i'} + 1}$$

$$= \sum_{i'j'f'} \delta_{i'j'f'}^{l+1} \theta_{i-i'+1,j-j'+1,f,f'}$$

Image max-pooling layer

$$\mathbf{y}_{i',j'} = \max_{ij \in \Omega(i'j')} \mathbf{x}_{ij}$$

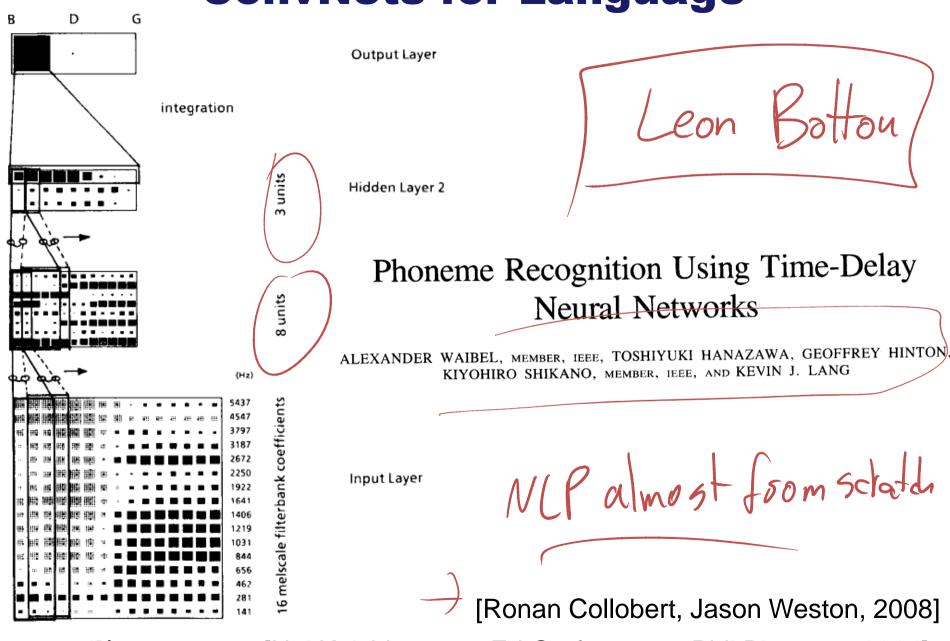
$$\begin{array}{lll} \delta_{ij}^{l} & = & \sum_{i'j'} \delta_{i'j'}^{l+1} \frac{\partial f_{i'j'}(\mathbf{x})}{\partial \mathbf{x}_{ij}} & & \\ & = & \delta_{ij}^{l+1} \mathbb{I}_{ij=\arg\max_{i''j''\in\Omega(i'j')}} \mathbf{x}_{i''j''} \end{array}$$

$$= \delta_{ij}^{l+1} \mathbb{I}_{\underline{ij} = \arg\max_{\underline{i''j''} \in \Omega(i'j')}} \mathbf{x}_{\underline{i''j''}}$$

Convnets in Torch

Xavjer Horat $model = nn.Sequential()^{\triangle}$ model:add(nn.Reshape(1,32,32)) -- layer 1: model:add(nn.SpatialConvolution(1,) 16, 5, 5)) model:add(nn.Tanh()) _ model:add(nn.SpatialMaxPooling(2, 2, 2, 2)) 6 layer 2: model:add(nn.SpatialConvolution(16, 128, 5, 5)) model:add(nn.Tanh()) model:add(nn.SpatialMaxPooling(2,/2, 2, 2)) 10 -- layer 3, a simple 2-layer neural net: 11 model:add(nn.Reshape(128*5*5)) 12 model:add(nn.Linear(128*5*5, 200)) 13 model:add(nn.Tanh()) 14 model:add(nn.Linear(200,10)) 15 model:add(nn.LogSoftMax()) 16

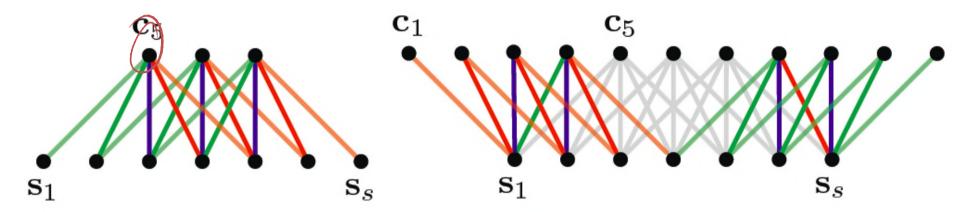
ConvNets for Language



15 frames [Nal Kalch

[Nal Kalchbrenner, Ed Grefenstette, Phil Blunsom, 2014]

Sentence ConvNets

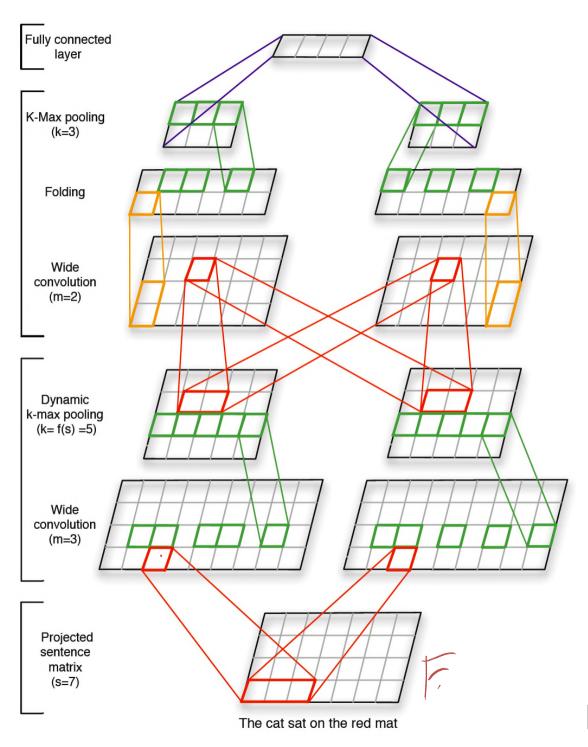


$$\mathbf{c}_j = \mathbf{m}^\mathsf{T} \mathbf{s}_{j-m+1:j}$$

m is the *filter* of the convolution

$$\mathbf{s} = \begin{bmatrix} \mathbf{w}_1 & \dots & \mathbf{w}_s \\ \mathbf{w}_1 & \dots & \mathbf{w}_s \end{bmatrix} \quad \mathbf{v}_{\mathbf{v}} \begin{bmatrix} \mathbf{w}_1 & \dots & \mathbf{w}_s \\ \mathbf{v}_i & \mathbf{v}_i \end{bmatrix} \leftarrow \underbrace{\mathbf{cat}}_{\mathbf{v}} \mathbf{v}_{\mathbf{v}} \mathbf{v}_{\mathbf{$$

[Kalchbrenner, Grefenstette, Blunsom, 2014]



Sentence DynConvNet

[Kalchbrenner et al, 2014]

Document models (Misha Denil)

