

Computational Complexity; slides 12, HT 2022

A Brief Introduction to randomisation

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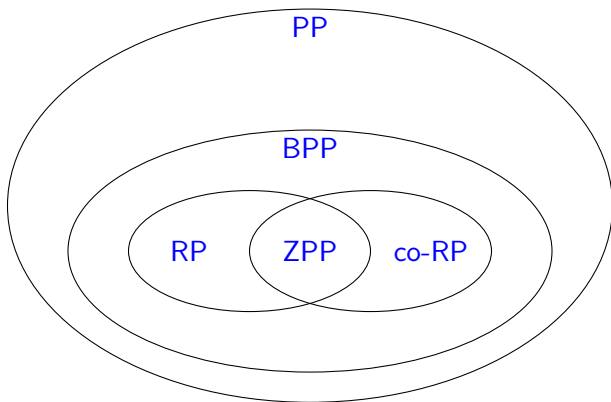
Randomised algorithms have access to a stream of random bits.

The running time and even the outcome may depend on random choices.

We may allow randomised algorithms to

- produce the wrong result, but only with small probability.
- take more than polynomially many steps, but “not too often”
 \rightsquigarrow expected running time is polynomial.

Some randomised classes



ZPP: “Las Vegas algorithms”; contains P. Poly *expected* time

RP: one-sided error; no-instance \mapsto “no”, yes-instance \mapsto “yes” with probability $\geq p$ (for some constant $p > 0$)

PP: “majority-P”, contains NP, within PSPACE

BPP: allow error either way (constant probability $< \frac{1}{2}$)

Usage of randomised algorithms

In practice, not so much for language recognition, more for simulation, crypto, stats/ML, or sampling for probability from probability distributions of interest

search for approximate average via sampling

Find median element of list $\{a_1, \dots, a_n\}$: To find k -th highest element, randomly select “pivot” element and find k' -th highest element of sublist (for suitable k')

Miller-Rabin test for primality, subsequently superseded by 2002 AKS primality test (deterministic)

- given prime number as input, says “prime”
- Given composite number as input, with prob. $1/4$ says “prime” (correct with prob. $3/4$).

One-sided error; co-RP. Run it k times, say “composite” if we ever get that result, else “prime”. Error prob is only $(1/4)^k$.

Language recognition problem where randomisation seems to help

Polynomial identity testing:

$$\text{E.g. } (x^2 + y)(x^2 - y) \equiv x^4 - y^2$$

where \equiv means equality holds for $x, y \in \mathbb{N}$.

In general, if we have many variables, no known deterministic and efficient algorithm, but notice you can try plugging in random x, y and checking for equality: if we find answer is “no” we are done; moreover it turns out that for all no-instances you have good chance of verifying that.

works for arithmetic circuits; consider question $p(x_1, \dots, x_n) \equiv 0$ for circuit with n inputs, 1 output, gates are $+, -, \times$.

$RP \subseteq NP$: accepting computation of an RP machine is a certificate of yes-instance.

It's unknown whether $BPP \subseteq NP$, but we argue that BPP represents problems that are in a sense solvable in practice (we expect NP-complete problems to lie outside BPP).

PP (Gill, 1977):

Languages recognised by a probabilistic TM for which yes-instances are accepted with prob. $> \frac{1}{2}$; no-instance with prob. $\leq \frac{1}{2}$.

- PP contains BPP (almost follows directly from the definitions)
- It also contains NP: we can make a PP algorithm that solves SAT. (consider $X \vee \varphi$ where φ is a SAT-instance)
- PP is a subset of PSPACE.

Probability amplification

BPP: problems that can be solved by a randomised algorithm

- with polynomial worst-case running time
- which has an error probability of $\epsilon < \frac{1}{2}$.

For RP, easy to see how we can improve error probability of algorithm (and evaluate the improvement):

RP: one-sided error; no-instance \mapsto “no”, yes-instance \mapsto “yes” with probability $\geq p$ (for some constant $p > 0$)

For problem X with RP algorithm having (say) $p = 10^{-6}$, run the algorithm 10^6 times, finally output “yes” iff we see at least one “yes” output. Error probability goes down to $< \frac{1}{2}$!

co-RP algorithm: similar trick, output “no” iff we see at least one “no”

Corollary for RP algorithms:

Suppose A solves problem X in polynomial time $p(n)$ and the probability that a yes-instance gives answer “yes” is only $1/p'(n)$ (p' a polynomial), and no-instances always give answer “no”. Then $X \in \text{RP}$.

Corollary for RP algorithms:

Suppose \mathcal{A} solves problem X in polynomial time $p(n)$ and the probability that a yes-instance gives answer “yes” is only $1/p'(n)$ (p' a polynomial), and no-instances always give answer “no”. Then $X \in \text{RP}$.

Warm-up for BPP: BPP algorithm with error prob $\frac{1}{2} - \delta$:
suppose we run it 3 times and take majority vote.

$$\begin{aligned}\Pr[\text{error}] &= \left(\frac{1}{2} - \delta\right)^3 + 3\left(\frac{1}{2} - \delta\right)^2\left(\frac{1}{2} + \delta\right) \\ &= \left(\frac{1}{2} - \delta\right)^2\left(\frac{1}{2} - \delta + \frac{3}{2} + 3\delta\right) = \left(\frac{1}{4} - \delta + \delta^2\right)(2 + 2\delta) = \frac{1}{2} - \frac{3}{2}\delta + 2\delta^3\end{aligned}$$

Theorem. If a problem can be solved by a BPP algorithm \mathcal{A}

- with polynomial worst-case running time
- which has an error probability of $0 < \epsilon < \frac{1}{2}$.

then it can also be solved by a poly-time randomised algorithm with error probability $2^{-p(n)}$ for any fixed polynomial $p(n)$.

Proof.

Algorithm \mathcal{B} : On input w of length n ,

- 1 Calculate number k (to be determined; details to follow)
- 2 Run $2k$ independent simulations of \mathcal{A} on input w
- 3 **accept** if more calls to the algorithm accept than reject.

Probability Amplification

$S := a_1, \dots, a_{2k}$: sequence of results obtained by running \mathcal{A} $2k$ times.

Suppose c of these are correct and $i = 2k - c$ are incorrect.

S is a **bad sequence** if $c \leq i$ so that \mathcal{B} gives the wrong answer.

The probability p_S for any individual bad sequence S to occur is

$$p_S \leq \varepsilon^i (1 - \varepsilon)^c \leq \varepsilon^k (1 - \varepsilon)^k$$

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Hence: $\Pr[\mathcal{B} \text{ gives wrong result on input } w] =$

$$\sum_{S \text{ bad}} p_S \leq 2^{2k} \cdot \varepsilon^k (1 - \varepsilon)^k = (4\varepsilon(1 - \varepsilon))^k$$

As $\varepsilon < \frac{1}{2}$ we get $4\varepsilon(1 - \varepsilon) < 1$. Hence, to obtain probability $2^{-p(n)}$ we let

$$\alpha = -\log_2(4\varepsilon(1 - \varepsilon)) \text{ and choose } k \geq p(n)/\alpha. \quad \square$$

So, every problem that can be solved with error probability $\epsilon < \frac{1}{2}$ can be solved with error probability $< 2^{-p(n)}$.

...practically useful?

So, every problem that can be solved with error probability $\varepsilon < \frac{1}{2}$ can be solved with error probability $< 2^{-p(n)}$.

...practically useful?

Arguably yes:

- the probability that an algorithm with error probability of 2^{-100} has bad luck with the coin tosses is much smaller than the chance that any algorithm fails due to
 - hardware failures,
 - random bit mutations in the memory
 - ...

Hoeffding's inequality

Consider a (biased) coin that comes up heads with probability p . So, if we toss it n times, should get $p \cdot n$ heads on average. Letting random variable $H(n)$ be number of heads seen after n coin tosses, it turns out that

$$\Pr[H(n) \leq (p - \varepsilon)n] \leq \exp(-2\varepsilon^2 n)$$

and similarly,

$$\Pr[H(n) \geq (p + \varepsilon)n] \leq \exp(-2\varepsilon^2 n)$$

Probability that we're off by a constant factor, is inverse-exponential in n . Often useful in analysing randomised algorithms!

Relationships to other complexity classes

Recall we noted that $RP \subseteq NP$.

(convert a randomised algorithm to a non-deterministic one by replacing coin flips with non-deterministic guesses.)

Doesn't work for BPP.

We do have $BPP \subseteq \Sigma_2^P \cap \Pi_2^P$ (Sipser-Gács-Lautemann theorem)

Consequently, if $P=NP$, it would follow that $P=BPP$ since if $P=NP$, the polynomial hierarchy collapses to P .

We also know: $BPP \subseteq P/poly$ (Adleman's theorem).

"Any BPP language has polynomial-size circuits."

Next: A randomised algorithms for reducing a (satisfiable) SAT instance to one having a unique solution

Then, a quick look at probabilistically checkable proofs