

Computational Complexity; slides 9, HT 2022 PSPACE-complete problems, alternating TMs

Prof. Paul W. Goldberg (Dept. of Computer Science,
University of Oxford)

HT 2022

Example of PSPACE-completeness (the “geography” game)
Then, alternative characterisation of PSPACE (as poly-time “alternating” TM). Recall general point that when there are various characterisations of a complexity class, it suggests the class is important.
Afterwards, polynomial hierarchy (classes between NP/co-NP and PSPACE)

The Formula Game

Players: Played by two Players \exists and \forall

Board: A formula φ in conjunctive normal form with variables X_1, \dots, X_n

Moves: Players take turns in assigning truth values to X_1, \dots, X_n in order.

That is, player \exists assigns values to “odd” variables X_1, X_3, \dots

Winning condition: After all variables have been instantiated, \exists wins if the formula evaluates to true. Otherwise \forall wins.

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Formula Game

Input: A CNF formula φ in the variables X_1, \dots, X_n

Problem: Does \exists have a winning strategy in the game on φ ?

Theorem. FORMULA GAME is PSPACE-complete.

Formula Game (extended version)

Board: A formula φ in conjunctive normal form with variables X_1, \dots, X_n

- After players have chosen values for the variables, player \forall chooses a clause
- Then player \exists chooses a literal within that clause
- *exists* wins if the literal is satisfied, else \forall wins

Example

$$\exists X_1 \forall X_2 \exists X_3 \forall X_4 \forall X_5 \left((X_1 \vee 0 \vee \neg X_5) \wedge (\neg X_2 \vee 1 \vee \neg X_5) \wedge (X_2 \vee X_3 \vee X_4) \right)$$

if \exists -player makes right choices, for all clauses C , there exists, within C , a satisfied literal

A generalised version of “Geography”:

The board is a directed graph G and a start node $s \in V(G)$

Initially the token is on the start node.

Players take turns in pushing this token along a directed edge.

Edges may not be used more than once. If a player cannot move, he loses.

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GEOGRAPHY

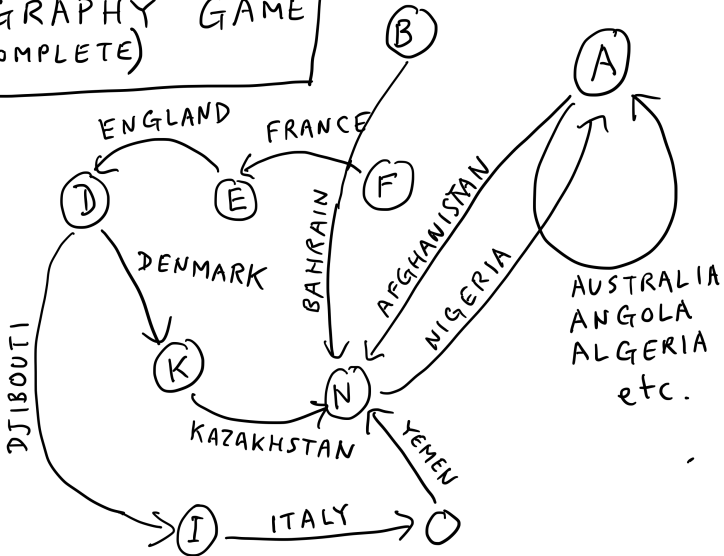
Input: Directed graph G , start node $s \in V(G)$

Problem: Does Player 1 have a winning strategy?

Theorem. GEOGRAPHY is PSPACE-complete.

(Sipser Theorem 8.14)

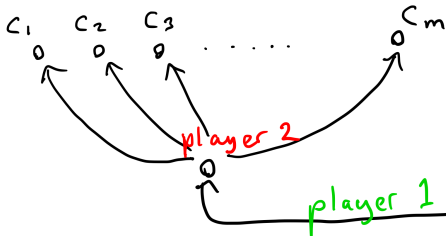
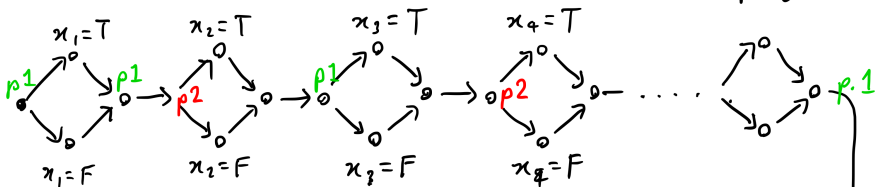
GEOGRAPHY GAME (INCOMPLETE)



$$\exists x_1 \forall x_2 \exists x_3 \forall x_4 \dots \phi(x)$$

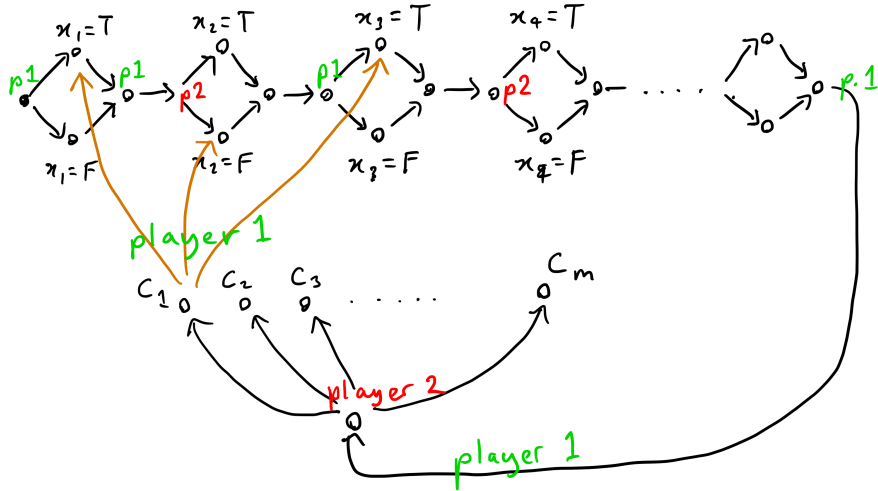
$$\phi = C_1 \wedge C_2 \wedge \dots \wedge C_m$$

player 1 wants T
 player 2 wants F
 winner plays last



Suppose $C_1 = x_1 \vee \neg x_2 \vee x_3$

player 1 wants T
 player 2 wants F
 winner plays last



Next: Alternating Turing Machines

general idea: a class of automata whose languages are all the PSPACE languages. They can be a useful way to prove membership of problems in PSPACE.

They also give alternative characterisations of P, EXPTIME

Alternating Turing Machines

Definition. An **alternating** Turing machine M is a non-deterministic Turing acceptor whose set of non-final states is partitioned into **existential** and **universal** states.

Q_{\exists} : set of existential states Q_{\forall} : set of universal states

Acceptance: Consider the computation tree \mathcal{T} of M on w

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A configuration C in \mathcal{T} is **eventually accepting** if

- C is an accepting stop configuration: an accepting leaf of \mathcal{T}
- $C = (q, p, w)$ with $q \in Q_{\exists}$ and there is at least one eventually accepting successor configuration in \mathcal{T}
- $C = (q, p, w)$ with $q \in Q_{\forall}$ and all successor configurations of C in \mathcal{T} are eventually accepting

M accepts w if start configuration on w is eventually accepting.

Example: Alternating Algorithm for GEOGRAPHY

Input: Directed graph G $s \in V(G)$ start node.

Set $VISITED := \{s\}$ Mark s as current node.

repeat

existential move: choose successor $v \notin VISITED$ of current node s

if not possible **then reject.**

$VISITED := VISITED \cup \{v\}$

set current node $s := v$

universal move: choose successor $v \notin VISITED$ of current node s

if not possible **then accept.**

$VISITED := VISITED \cup \{v\}$

set current node $s := v$

Note. This algorithm runs in alternating polynomial time.

Basic definitions of alternating time/space complexity

Recall $\mathcal{L}(M)$ denotes words (in Σ^*) accepted by M .

For function $T : \mathbb{N} \rightarrow \mathbb{N}$, an alternating TM is T **time-bounded** if every computation of M on input w of length n halts after $\leq T(n)$ steps.

Analogously for T **space-bounded**.

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Analogously for T **space-bounded**.

For $T : \mathbb{N} \rightarrow \mathbb{N}$ a monotone increasing function, define

- 1 $\text{ATIME}(T)$ as the class of languages \mathcal{L} for which there is a T -time bounded k -tape alternating Turing acceptor deciding \mathcal{L} , $k \geq 1$.
- 2 $\text{ASPACE}(T)$ as the class of languages \mathcal{L} for which there is a T -space bounded alternating k -tape Turing acceptor deciding \mathcal{L} , $k \geq 1$.

Alternating Complexity Classes:

Time classes:

- $\text{APTIME} := \bigcup_{d \in \mathbb{N}} \text{ATIME}(n^d)$ alternating poly time
- $\text{AEXPTIME} := \bigcup_{d \in \mathbb{N}} \text{ATIME}(2^{n^d})$ alternating exp. time
- $2\text{-AEXPTIME} := \bigcup_{d \in \mathbb{N}} \text{ATIME}(2^{2^{n^d}})$

Space classes:

- $\text{ALOGSPACE} := \bigcup_{d \in \mathbb{N}} \text{ASPACE}(d \log n)$
- $\text{APSPACE} := \bigcup_{d \in \mathbb{N}} \text{ASPACE}(n^d)$
- $\text{AEXPSPACE} := \bigcup_{d \in \mathbb{N}} \text{ASPACE}(2^{n^d})$

Examples.

$\text{GEOGRAPHY} \in \text{APTIME}$.

$\text{MONOTONE CVP (coming up next)} \in \text{ALOGSPACE}$.

Similar alg.: $\text{CVP} \in \text{ALOGSPACE}$.

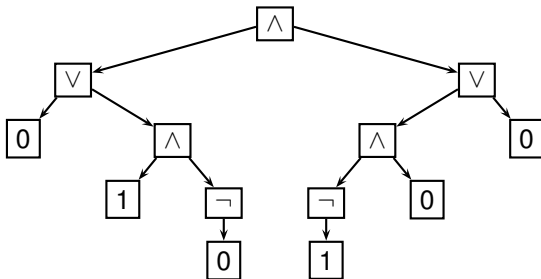
Circuit Value Problem

Circuit. A connected directed acyclic graph with exactly one vertex of in-degree 0.

The vertices are labelled by:

label	no. of successors
\wedge	2
\vee	2
\neg	1
1	0
0	0

Example.



Evaluation of Circuits. A node v in a circuit C evaluates to 1 if

- v is a leaf labelled by 1
- v is a node labelled by \vee and one successor evaluates to 1
- v is a node labelled by \neg and its successor evaluates to 0
- v is a node labelled by \wedge and both successors evaluate to 1

C evaluates to 1 if its root evaluates to 1 .

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Circuit Value Problem.

CVP

Input: Circuit C

Problem: Does C evaluate to 1 ?

Monotone Circuit Value Problem.

Monotone CVP

Input: Monotone circuit C without negation \neg .

Problem: Does C evaluate to 1 ?

Monotone Circuit Value Problem

Input: Monotone circuit C with root s .

Set $Current := s$.

while $Current$ is not a leaf **do**

if current node v is a \vee -node **then**

 existential move: choose successor v' of v

else if current node v is a \wedge -node **then**

 universal move: choose successor v' of v

end if

 set current node $Current := v'$

if $Current$ is labelled by 1 **then** **accept** **else** **reject**.

Monotone Circuit Value Problem

Input: Monotone circuit C with root s .

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Note. This algorithm runs in alternating logarithmic space. Can be extended to general CVP

Basic general properties of alternating TMs/complexity

Non-determinism. A non-deterministic Turing acceptor **is** an alternating TM (without universal states).

$$\mathcal{L} \in \text{NP} \implies \mathcal{L} \in \text{APTIME}$$

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Reductions. If $\mathcal{L} \in \text{ATIME}(T)$ and $\mathcal{L}' \leq_p \mathcal{L}$ then $\mathcal{L}' \in \text{ATIME}(T + f)$ where f is a polynomial.

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Complementation. Alternating Turing acceptors are easily “negated”.

Let M be an alternating TM accepting language \mathcal{L}

Let M' be obtained from M by swapping

- the accepting and rejecting state
- swapping existential and universal states.

Then $\mathcal{L}(M') = \overline{\mathcal{L}(M)}$

Example of complementation

Satisfiability for formulae $\varphi := \exists X_1 \forall X_2 \psi$, where ψ is quantifier-free:

Algorithm 1:

existential move. choose assignment $\beta : X_1 \mapsto 1$ or $\beta : X_1 \mapsto 0$.

universal move.

choose assignment $\beta := \beta \cup \{X_2 \mapsto 1\}$ and $\beta := \beta \cup \{X_2 \mapsto 0\}$.

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Algorithm 2:

universal move. choose assignment $\beta : X_1 \mapsto 1$ or $\beta : X_1 \mapsto 0$.

existential move.

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if β satisfies ψ **then** reject **else** accept.

Note: Algorithm 1 accepts φ iff Algorithm 2 rejects φ

Theorem

$$\text{APTIME} = \text{PSPACE}$$

Proof.

- 1 We have already seen that $\text{GEOGRAPHY} \in \text{APTIME}$.
As GEOGRAPHY is PSPACE -complete,
$$\text{PSPACE} \subseteq \text{APTIME}.$$

Alternating vs. Sequential Time and Space

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- 2 $\text{APTIME} \subseteq \text{PSPACE}$ follows from the following more general result.

Lemma. For $f(n) \geq n$ we have

$$\text{ATIME}(f(n)) \subseteq \text{DSPACE}(f(n))$$

To prove this, explore configuration tree of ATM of depth $f(n)$

Theorem.

- ① For $f(n) \geq n$ we have

$$\text{ATIME}(f(n)) \subseteq \text{DSPACE}(f(n)) \subseteq \text{ATIME}(f^2(n))$$

- ② For $f(n) \geq \log n$ we have $\text{ASPACE}(f(n)) = \text{DTIME}(2^{\mathcal{O}(f(n))})$

(see Sipser Thm. 10.21)

Deterministic Space vs. Alternating Time

(c.f. Savitch's theorem)

Lemma. For $f(n) \geq n$ we have $DSPACE(f(n)) \subseteq ATIME(f^2(n))$.

Proof. Let \mathcal{L} be in $DSPACE(f(n))$ and M be an $f(n)$ space-bounded TM deciding \mathcal{L} .

On input w , M makes at most $2^{\mathcal{O}(f(n))}$ computation steps.

Alternating Algorithm. $Reach(C_1, C_2, t)$

Returns 1 if C_2 is reachable from C_1 in $\leq 2^t$ steps.

if $t = 0$

if $C_1 = C_2$ or $C_1 \vdash C_2$ do return 1 else return 0

else

existential step. choose configuration C with $|C| \leq \mathcal{O}(f(n))$

universal step. choose $(D_1, D_2) = (C_1, C)$ or $(D_1, D_2) = (C, C_2)$

return $Reach(D_1, D_2, t - 1)$.

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Corollaries.

- $\text{ALOGSPACE} = \text{PTIME}$
- $\text{APTIME} = \text{PSPACE}$
- $\text{APSPACE} = \text{EXPTIME}$

Alternating TMs give us a different characterisation of complexity classes we have seen.

Next: the polynomial hierarchy: a sequence of classes that are intermediate between NP and PSPACE. They represent some important problems that are “above” NP and “below” PSPACE