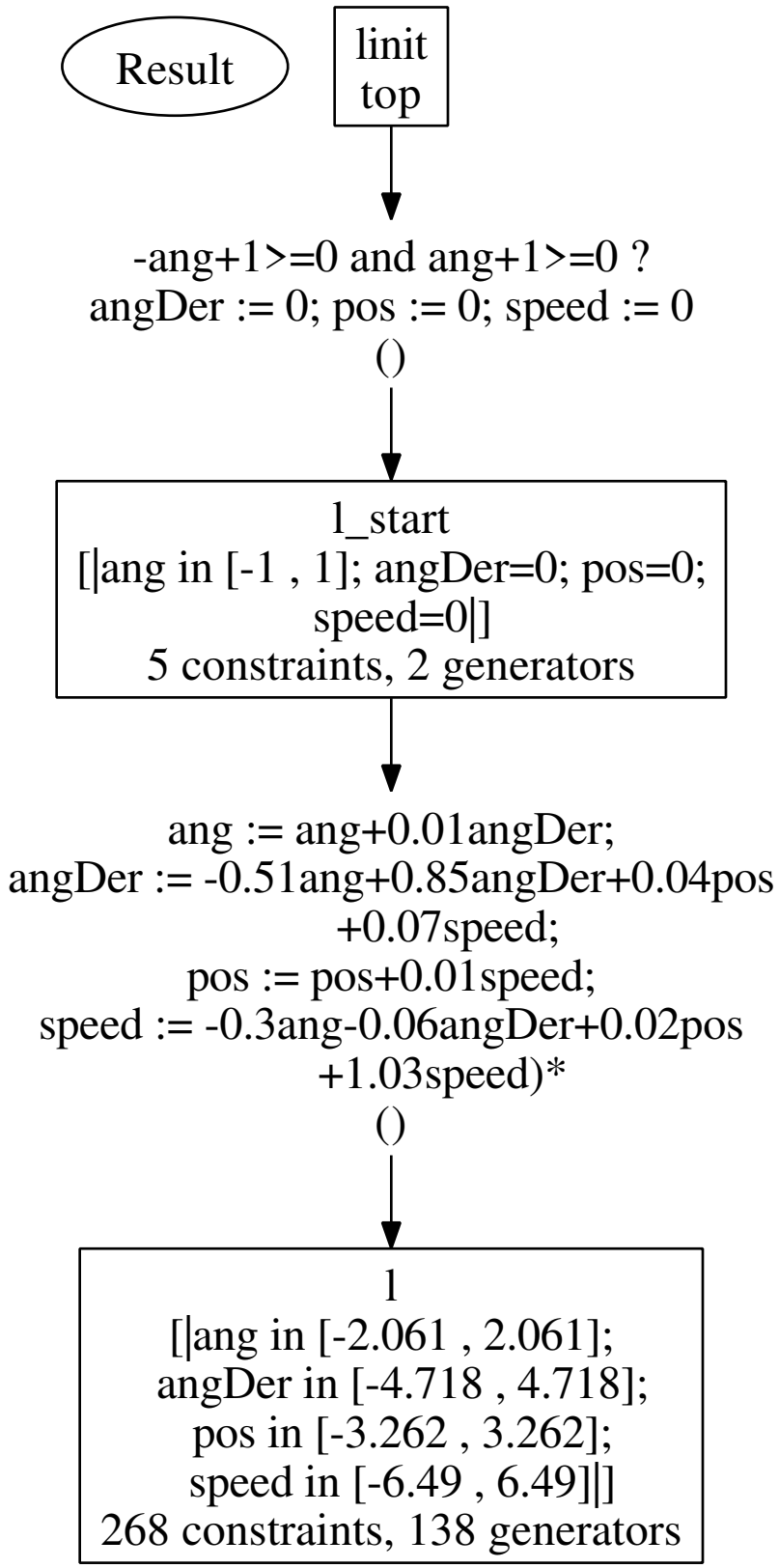
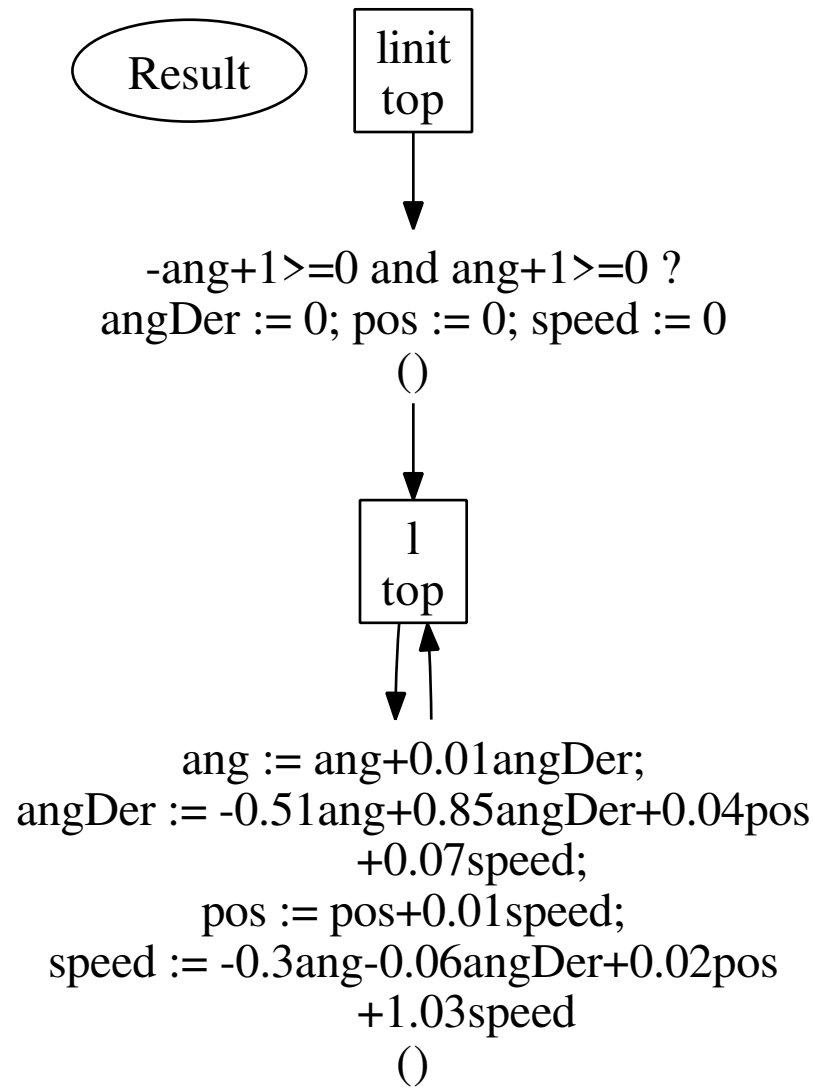
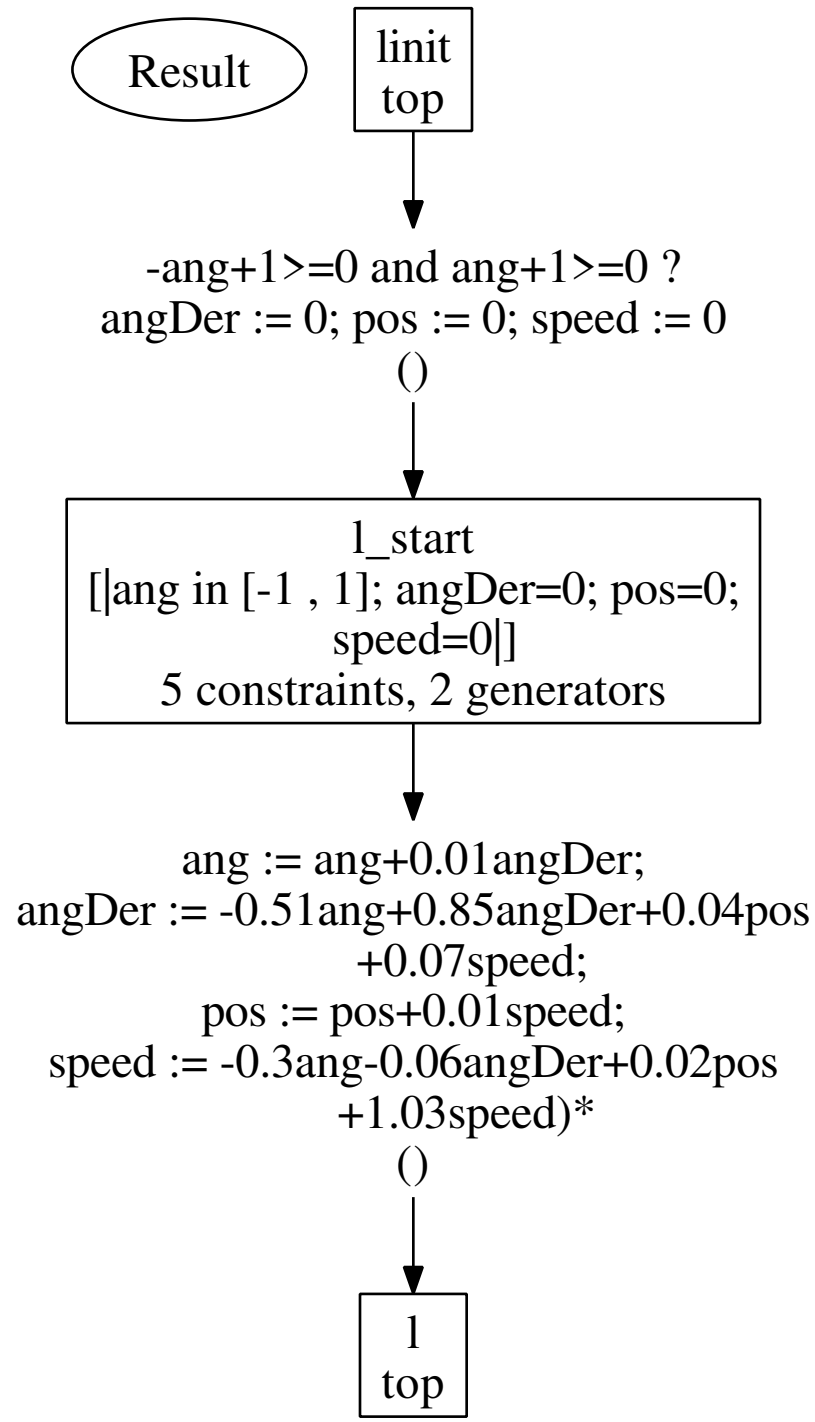

Result
linit
top
-ang+1>=0 and ang+1>=0 ?
angDer := 0; pos := 0; speed := 0
()
l_start
[|ang in [-1 , 1]; angDer=0; pos=0;
speed=0|]
5 constraints, 2 generators
ang := ang+0.01angDer;
angDer := -0.51ang+0.85angDer+0.04pos
+0.07speed;
pos := pos+0.01speed;
speed := -0.3ang-0.06angDer+0.02pos
+1.03speed)*
()
l
[|ang in [-2.061 , 2.061];
angDer in [-4.718 , 4.718];
pos in [-3.262 , 3.262];
speed in [-6.49 , 6.49]|]
268 constraints, 138 generators


Result
linit
top
-ang+1>=0 and ang+1>=0 ?
angDer := 0; pos := 0; speed := 0
()
l
top
ang := ang+0.01angDer;
angDer := -0.51ang+0.85angDer+0.04pos
+0.07speed;
pos := pos+0.01speed;
speed := -0.3ang-0.06angDer+0.02pos
+1.03speed
()


Result
linit
top
-ang+1>=0 and ang+1>=0 ?
angDer := 0; pos := 0; speed := 0
()
l_start
[|ang in [-1 , 1]; angDer=0; pos=0;
speed=0|]
5 constraints, 2 generators
ang := ang+0.01angDer;
angDer := -0.51ang+0.85angDer+0.04pos
+0.07speed;
pos := pos+0.01speed;
speed := -0.3ang-0.06angDer+0.02pos
+1.03speed)*
()
l
top