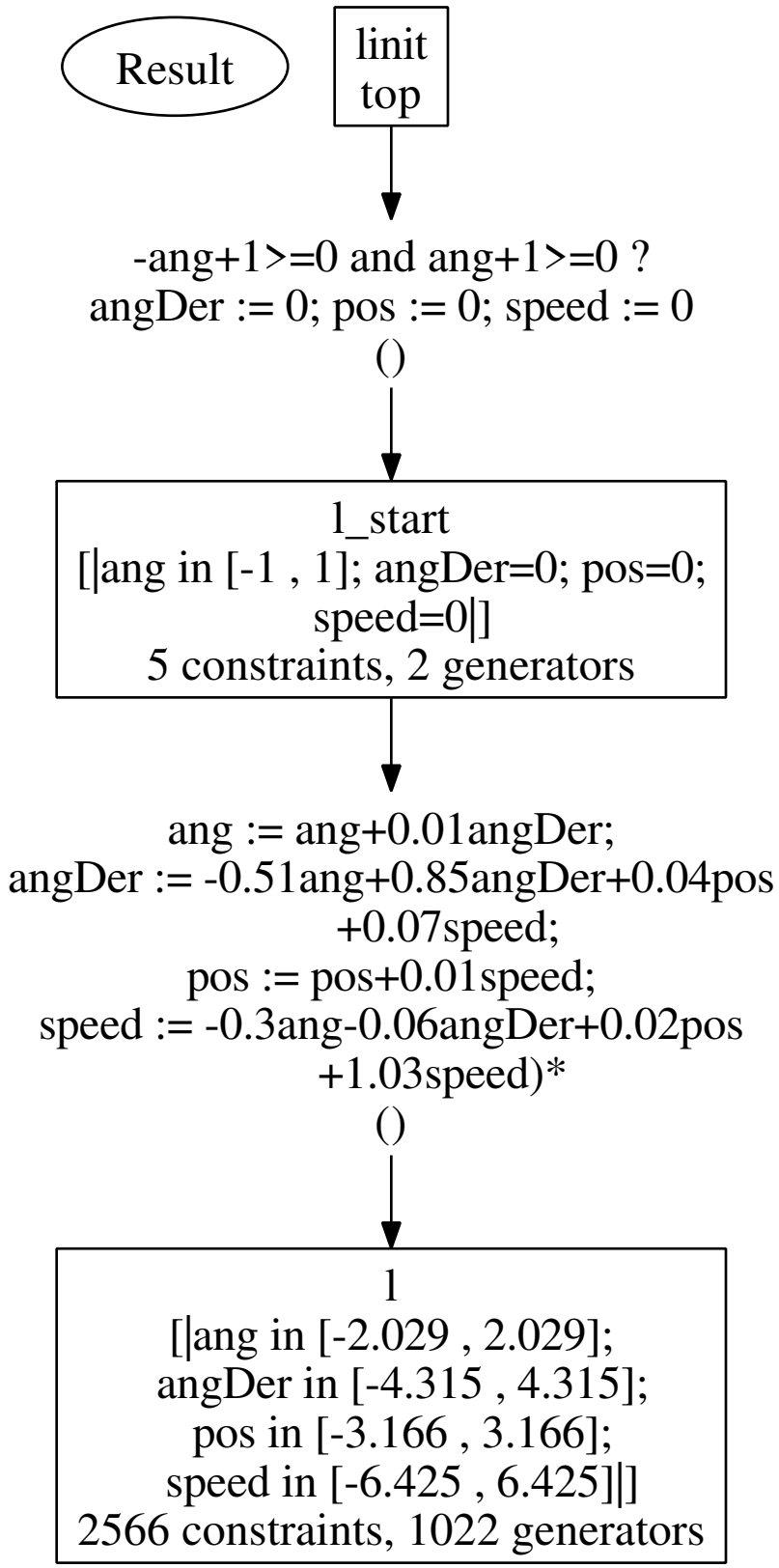
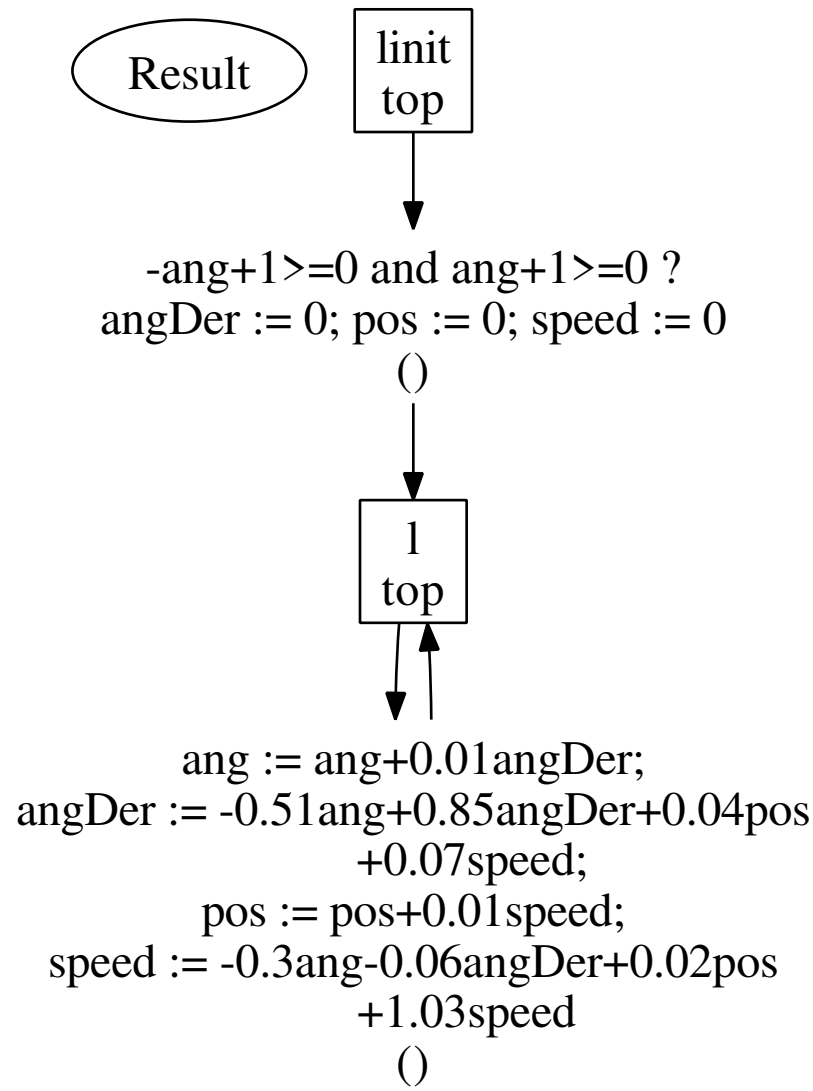
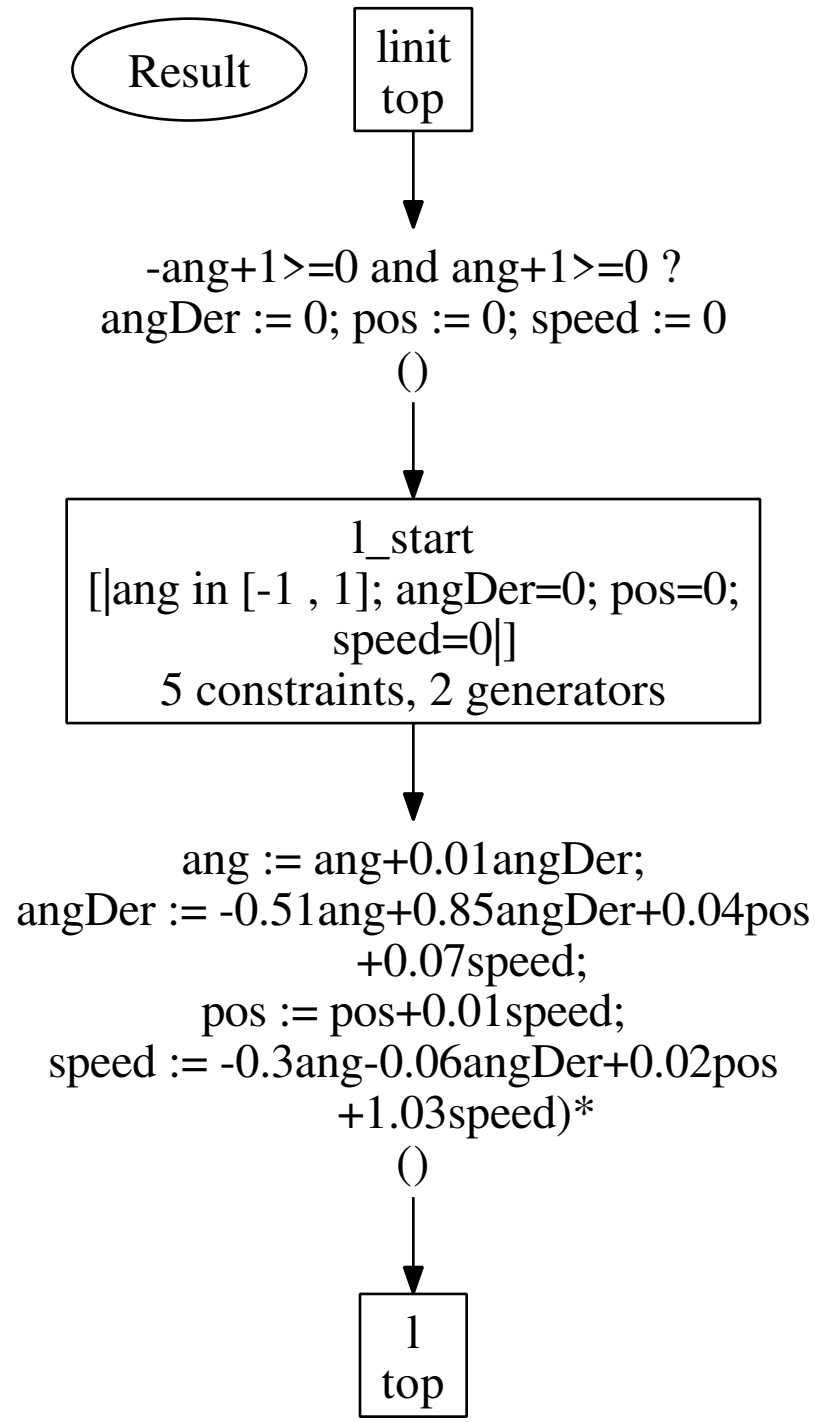

Result
linit
top
-ang+1>=0 and ang+1>=0 ?
angDer := 0; pos := 0; speed := 0
()
l_start
[|ang in [-1 , 1]; angDer=0; pos=0;
speed=0|]
5 constraints, 2 generators
ang := ang+0.01angDer;
angDer := -0.51ang+0.85angDer+0.04pos
+0.07speed;
pos := pos+0.01speed;
speed := -0.3ang-0.06angDer+0.02pos
+1.03speed)*
()
l
[|ang in [-2.029 , 2.029];
angDer in [-4.315 , 4.315];
pos in [-3.166 , 3.166];
speed in [-6.425 , 6.425]|]
2566 constraints, 1022 generators


Result
linit
top
-ang+1>=0 and ang+1>=0 ?
angDer := 0; pos := 0; speed := 0
()
l
top
ang := ang+0.01angDer;
angDer := -0.51ang+0.85angDer+0.04pos
+0.07speed;
pos := pos+0.01speed;
speed := -0.3ang-0.06angDer+0.02pos
+1.03speed
()


Result
linit
top
-ang+1>=0 and ang+1>=0 ?
angDer := 0; pos := 0; speed := 0
()
l_start
[|ang in [-1 , 1]; angDer=0; pos=0;
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5 constraints, 2 generators
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angDer := -0.51ang+0.85angDer+0.04pos
+0.07speed;
pos := pos+0.01speed;
speed := -0.3ang-0.06angDer+0.02pos
+1.03speed)*
()
l
top