



Architecture, Design (and a little Verification) for BX

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Migrating Uber from MySQL to PostgreSQL

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Uber, Inc.

March 13, 2013

ARCHITECTURE

WHY UBER ENGINEERING SWITCHED FROM POSTGRES TO MYSQL

JULY 26, 2016

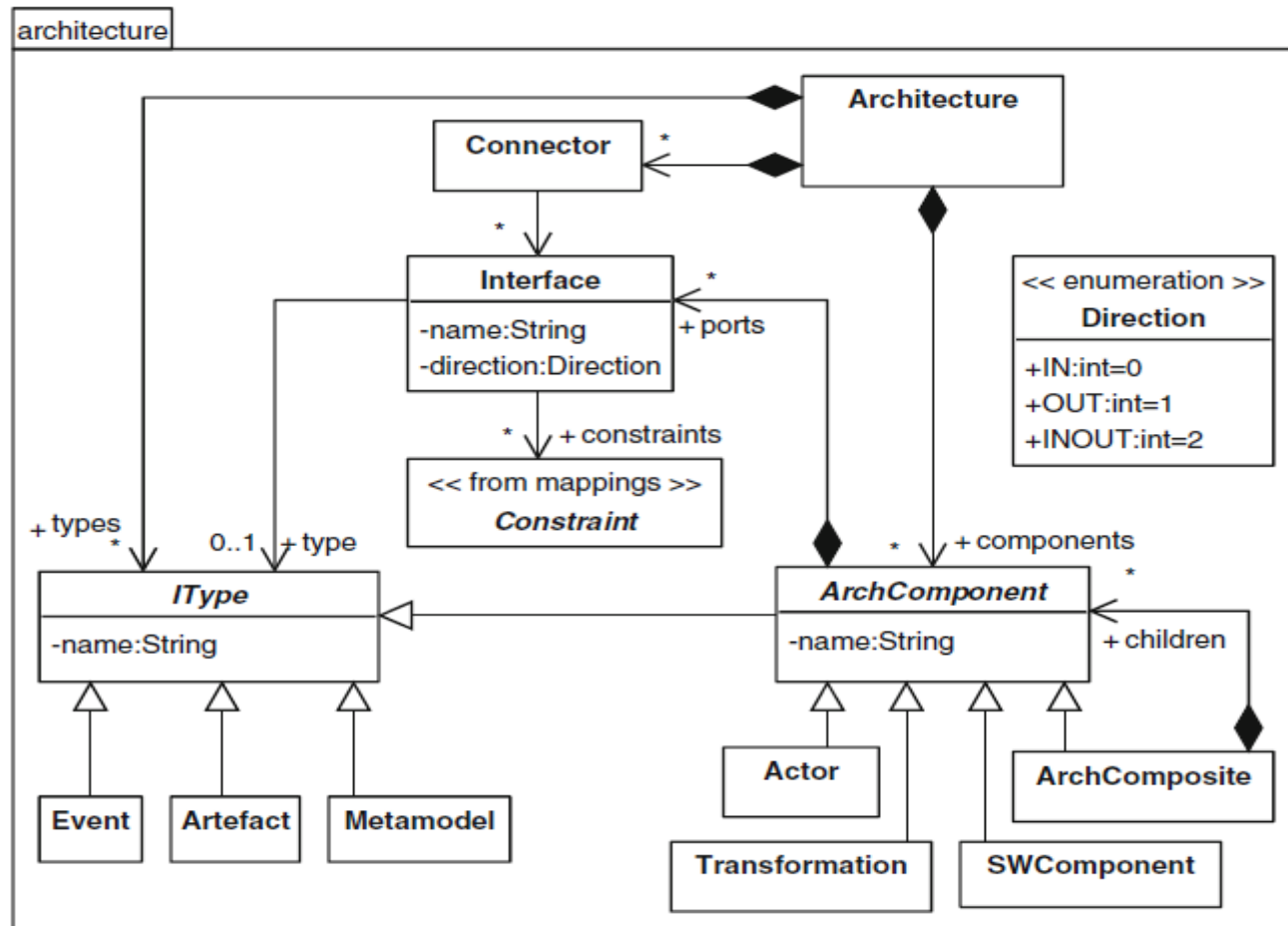
BY EVAN KLITZKE

- What is architecture and design for transformations and BX?
- Architecture specification for BX.
- Detailed design specification for BX.
- Design patterns for BX.
- (just a little on...) Verification for BX.

- Large and complicated BX are like large and complicated software systems:
 - Many parts
 - Complex interrelationships and dependencies
 - Sophisticated behaviour (often implicit)
 - Difficult to get right, difficult to verify.
- Large software is seldom monolithic.
 - Decomposed into interdependent components

- Architecture for BX and transformations is complicated:
 - What are the constituent blocks?
 - How can they be related? (ports, protocols, buffers)
 - How can a transformation architecture be integrated with other components
 - e.g., code generators, visualisations (e.g., non-MDE).

Architecture in *trans*ML



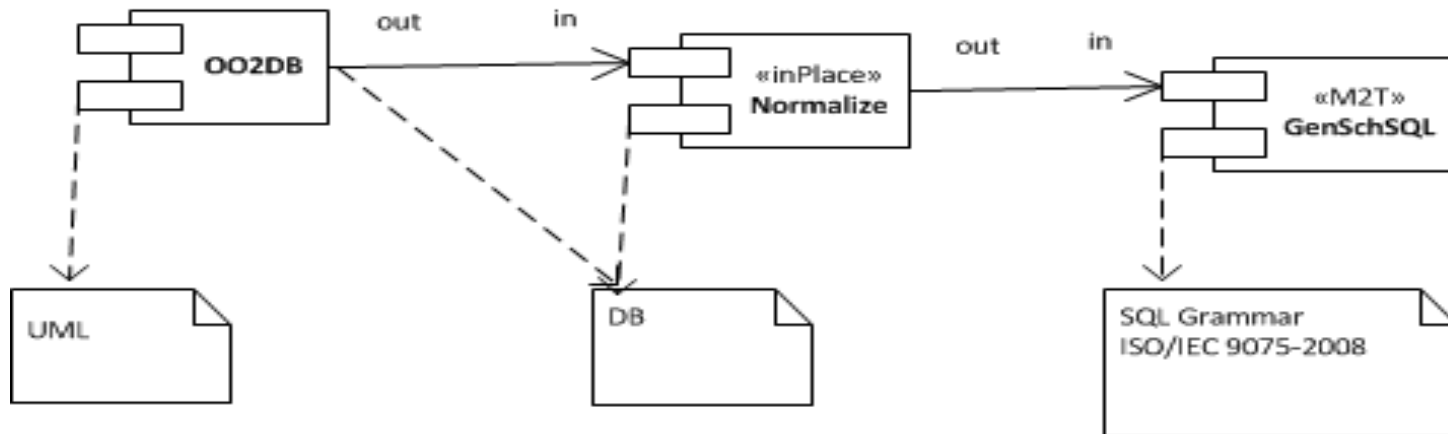
Architecture in *transML*

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- Components and connectors that interact via directional interfaces.
 - Architectural components can be transformations, software (black box), actors (human intervention), or composites
 - BX do not exist in a vacuum!
 - Types (of interfaces, ports, components) given by metamodels, event types, artefacts or architectural components.
- Contracts can be imposed to restrict expected inputs and outputs, and to enable conformance checking.

Architecture Example

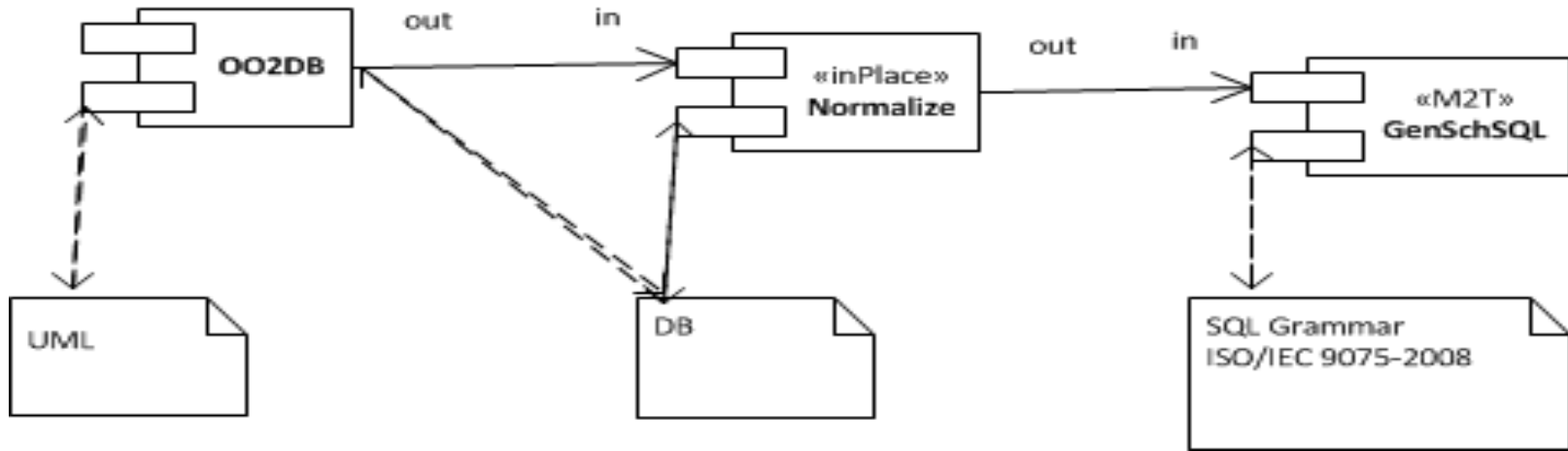
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- Transformation centric view
- Unidirectional: OO->DB->optimise->SQL

Architecture Example

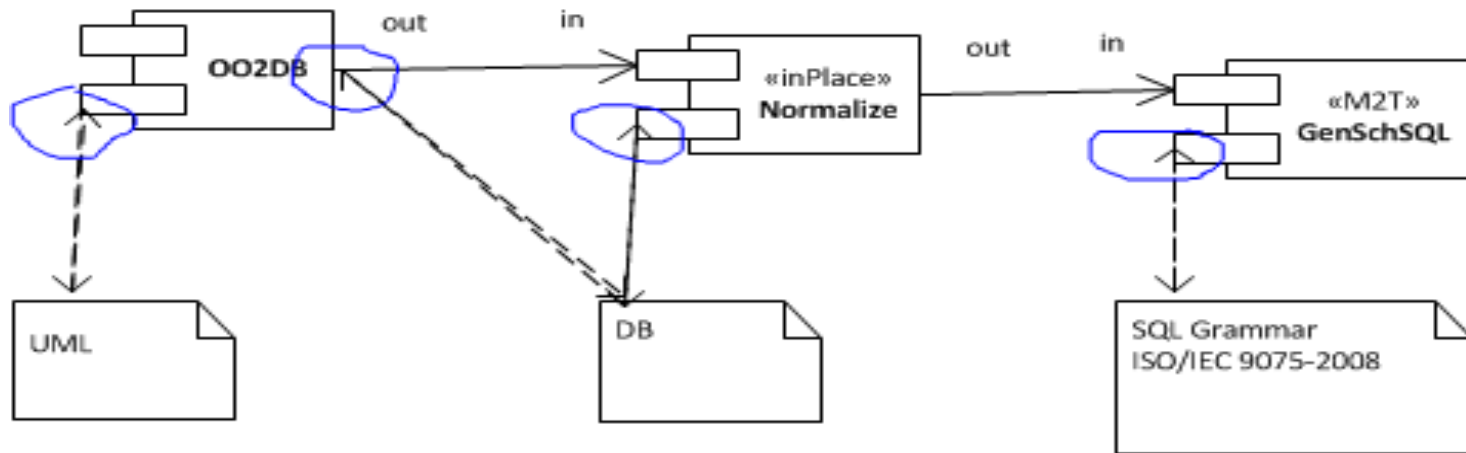
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- Transformation centric view
- Bidirectional components: OO->DB->optimise->SQL

Architecture Example

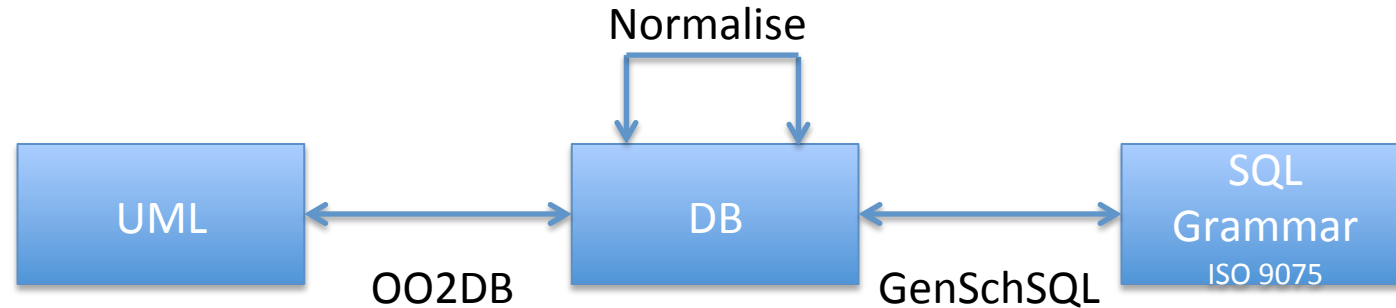
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- Transformation centric view
- Bidirectional components: OO->DB->optimise->SQL

Architecture Example

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- Type centric view (is this a slightly different architecture?)
- BX: OO2DB, Normalise, GenSchSQL could be run individually in either direction.
- Similar to a megamodel, where components are visualised as arrows connecting interfaces.
 - Useful for bridging grammars and models.

Architecture Styles?

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- Are there BX equivalents to typical software architectural styles?
 - Pipe-and-Filter
 - Model-View-Controller
 - Layered
 - Pub-Sub
 - Data-Centric

- The architecture of a transformation indicates the key components and their connectors.
- Engineering of BX continues with design.
 - High-level design: what is transformed into what?
 - Low-level design: how is the transformation carried out?
- Take each in turn

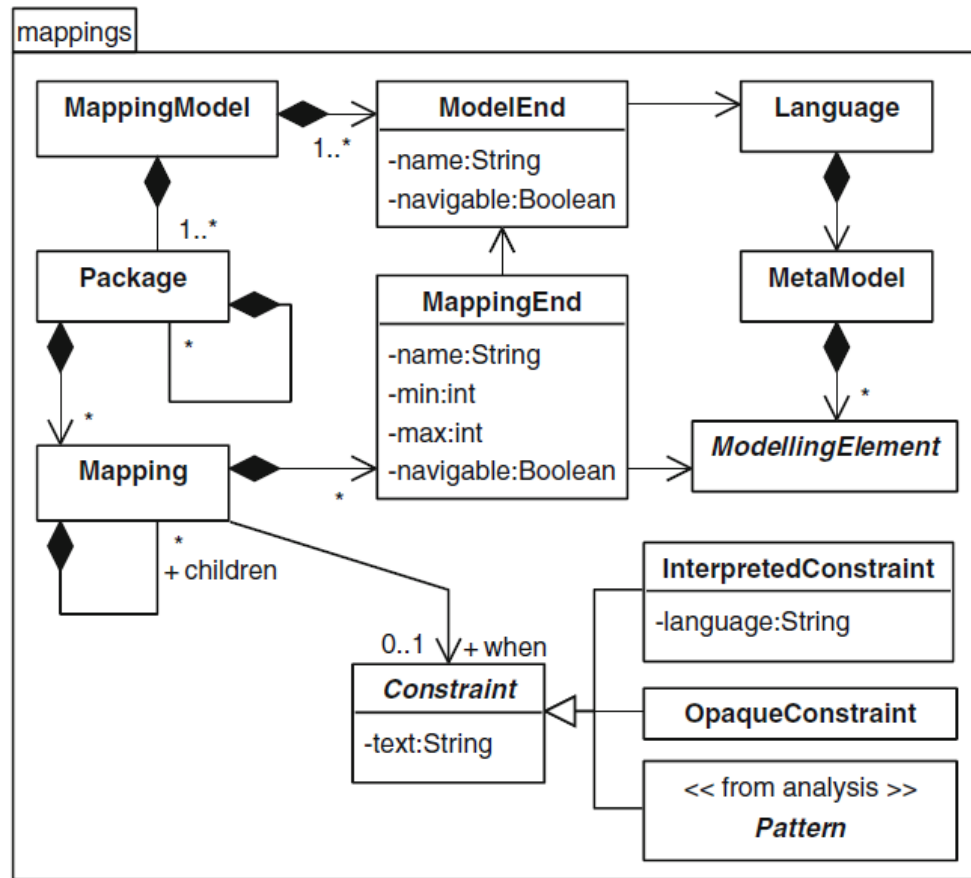
BX High-Level Design

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- Mapping diagram.
- Captures the mappings between arbitrary elements in the transformation.
- *transML* uses a concrete syntax inspired by TGGs.
 - However, mappings are not meant to be used as a tracing mechanism to guide execution of code.
 - Don't address, e.g., execution flow.

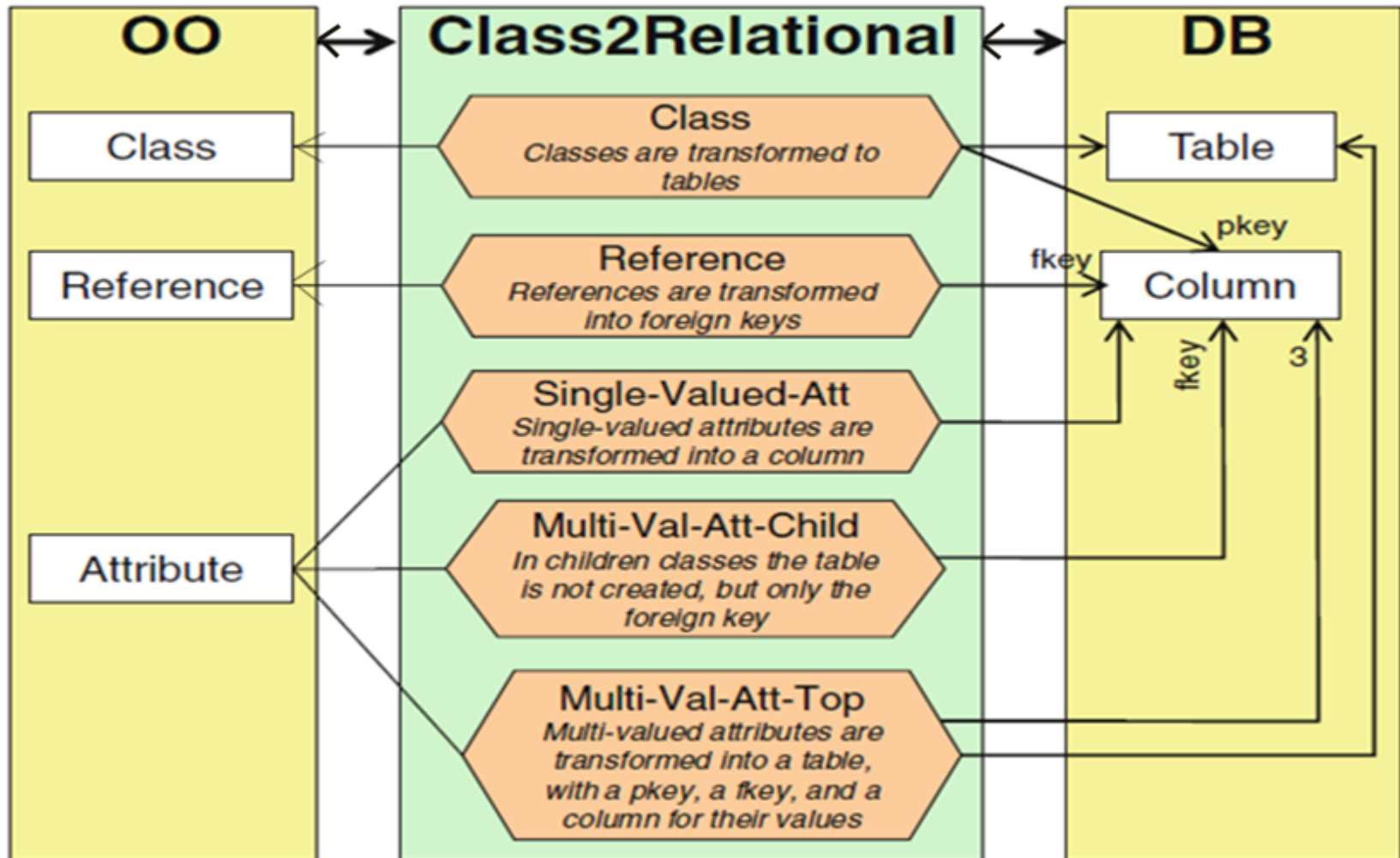
BX Mapping Metamodel

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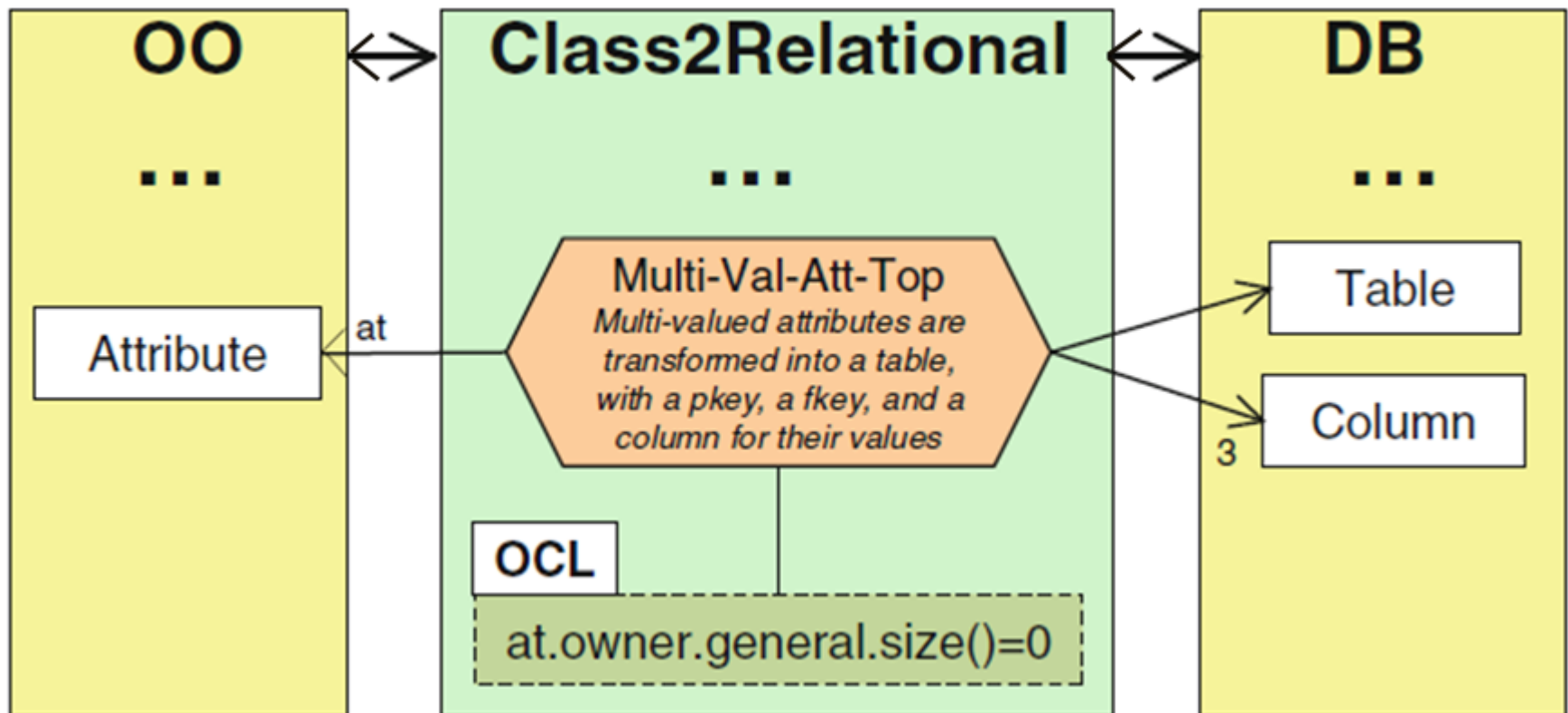
BX Mapping Example

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BX Mapping Example – Adding Constraints

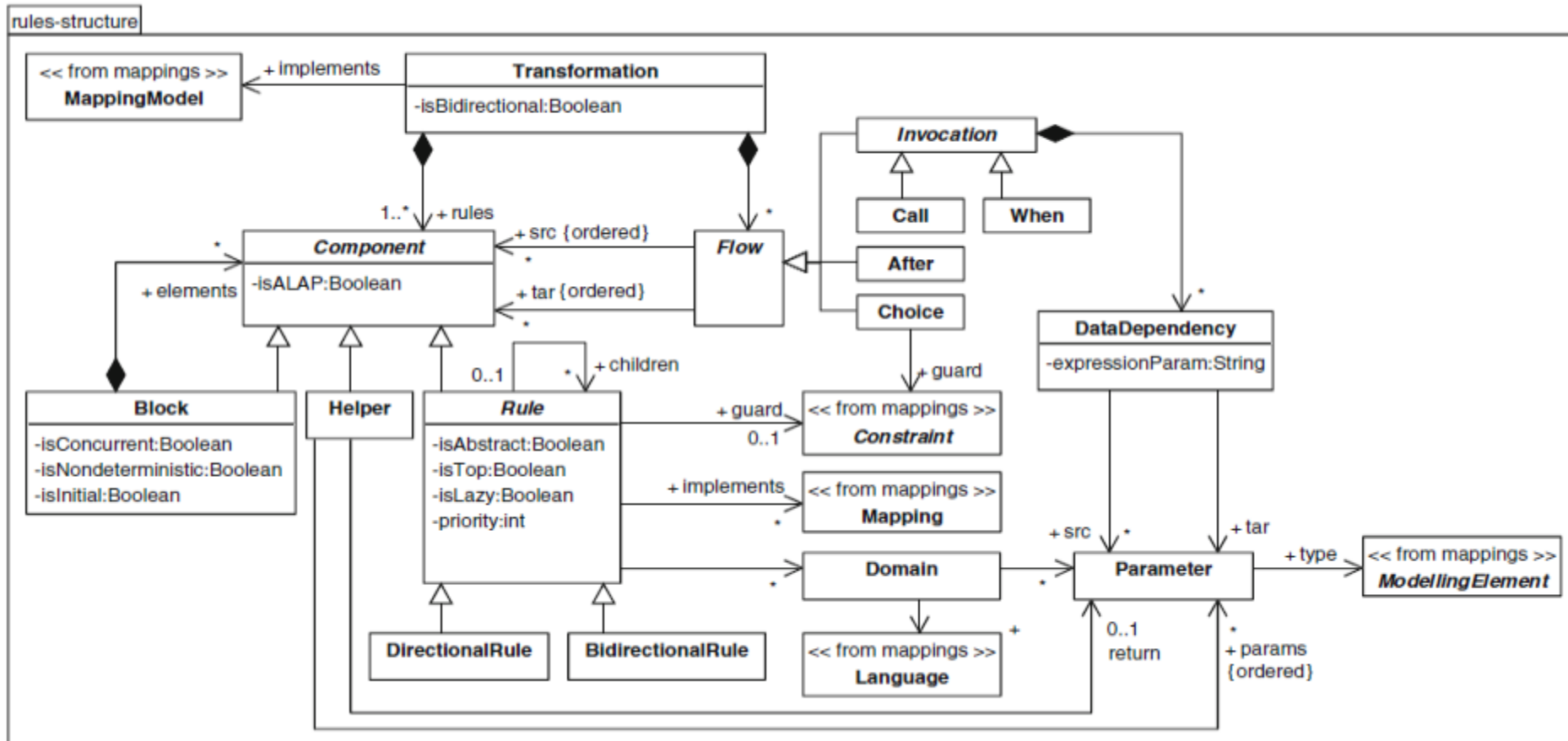
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- Indicates how the BX is to be implemented.
- Could use a BX programming language here.
 - But *transML* provides low-level design languages to try to support platform independence, focus on essentials
 - Essentials: rule structure, control flow, blocks (some not present in programming languages).
- *transML*: rule structure model and rule behaviour model.

Rule Structure Metamodel

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- Describes structure of rules (input, output), execution flow, and data dependencies

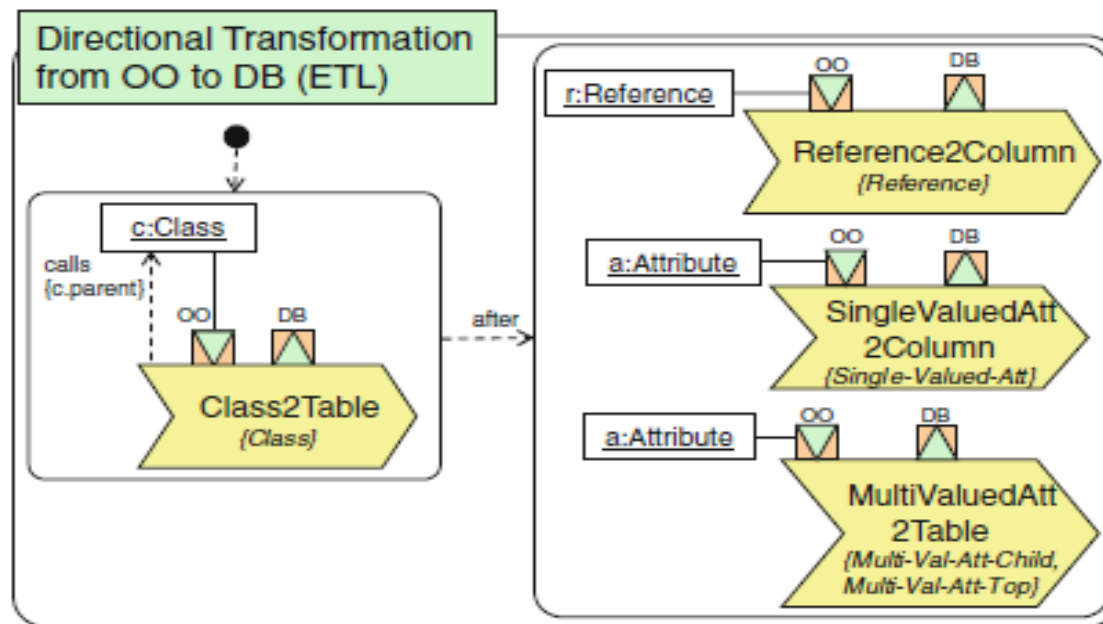
Rule Structure Models

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- These refine mapping diagrams.
- A rule can contribute to the implementation of several mappings.
- Rules may be uni- or bidirectional.
- Execution flow may be explicit (e.g., a subclass of *Flow*) or non-deterministic:
 - A set of rules can be placed inside a non-deterministic block

Example

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Example

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```
transformation Tree2Graph {  
  nondeterministic RuleBlockForward {  
    bidirectional Tree2Node {..};  
    bidirectional TreeEdge2GraphEdge {..} ;  
  }  
  nondeterministic RuleBlockBackward {  
    bidirectional TreeLabelsfromNodeLabels {..};  
    bidirectional TreeEdgesfromGraphEdges{..};  
  }  
}
```

Rule Structure Model

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- With rule structure, the particular implementation language of choice needs to be considered.
- This is because these models capture the rules and their execution flow (which is language semantics-specific).
 - For example, execution flow in ETL: each rule is executed once at each instance of input; for graph transformation it's “as long as possible”.

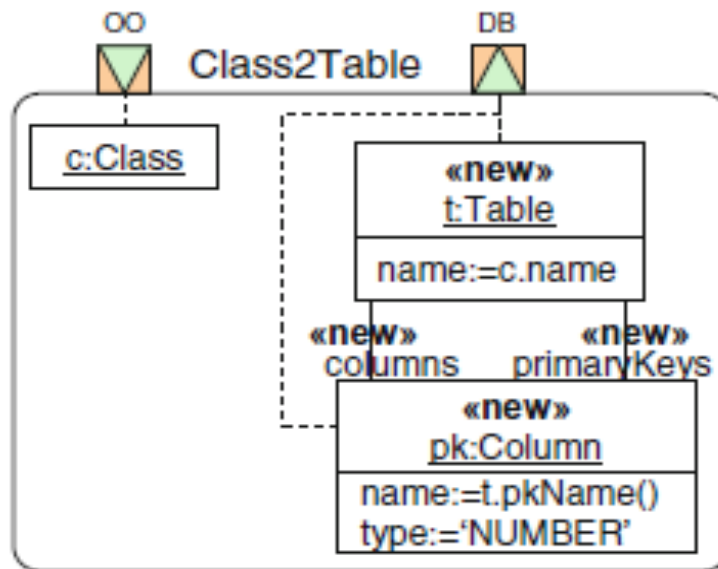
Rule Behaviour Diagram

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- The rule structure models treat rules as black-boxes, ignoring behaviour:
 - Attribute computation, object and link creation.
- Specified using rule behaviour diagrams:
 - Action language
 - Declarative graphical pre/post
 - Object diagrams annotated with operations (similar to Catalysis snapshots)

Example

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transform c: OO!Class
to t:DB!Table, pk: DB!Column

```
t.name:=c.name;  
pk.name:=t.pkName();  
pk.type:='NUMBER';  
t.columns.add(pk);  
t.primaryKeys.add(pk);
```

Design Patterns for BX

- Capture recurring design problems and their solutions (which must be instantiated).
- Many different patterns in the literature, including some for model transformation design.
 - Some of these patterns are applicable to the design of uni- or bidirectional transformations.
 - Some specific for BX.
 - Several examples.

Auxiliary Correspondence Model

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- Weaving tools (such as AMW, EML) can be used to propagate changes from/to models in a BX.
 - They do or can make use of an auxiliary correspondence (weaving) model.
- **Pattern:** defines auxiliary model elements and associations that link source and target elements.
- **Why:** used to record mappings performed by a BX, and to propagate modifications when one model changes.
- **Benefits:** separation of concerns, helps to ensure correctness
- **Disadvantages:** must maintain an additional model.

Unique Instantiation

- **Why:** Avoids creation of unnecessary elements of models and helps to resolve nondeterministic choice in reverse mappings.
 - *E.g.*, in check-before-enforce in QVT-R: new elements are not created if there are elements that satisfy the relations.
- **Benefits:** helps to establish hippocraticness
- **Disadvantages:** must test for existence, adds to cost (but other patterns like indexing can help).

Map Objects Before Links

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- **Why:** Separates the relation between elements in target and source models from the relation between links in the models.
 - That is, first map “nodes”, then map “edges” (largely useful for models with self-associations or circular dependencies)
- **Benefits:** modular specification, e.g., if new association is added to languages, new relation can be added more easily.
- **Disadvantages:** edges modular, features may not be!
 - We’ve seen this type of trade-off before!

Verification of BX

- Many approaches, including correctness by construction, unit testing, etc.
 - *transML* includes a model-based testing approach where tests can be automatically generated from transformation scenarios
- Will talk about one specific and different approach.

BX: is there another way?

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if a framework existed in which it were possible to write the directions of a transformation separately and then check, easily, that they were coherent, we might be able to have the best of both worlds



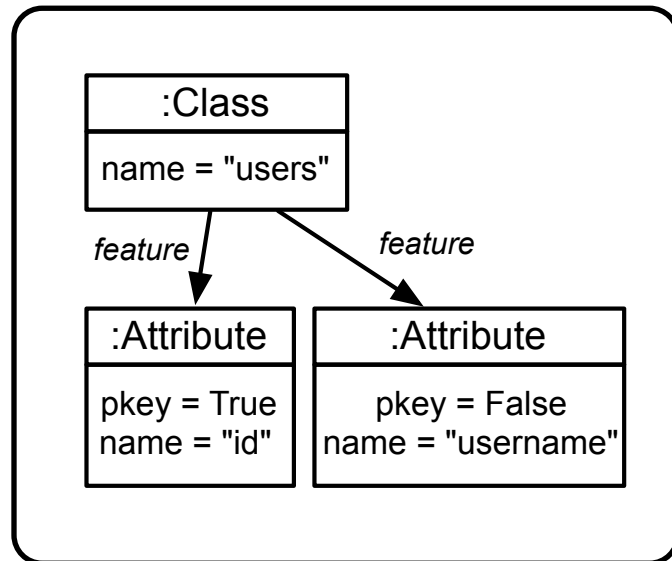
“Faking” BX in Epsilon

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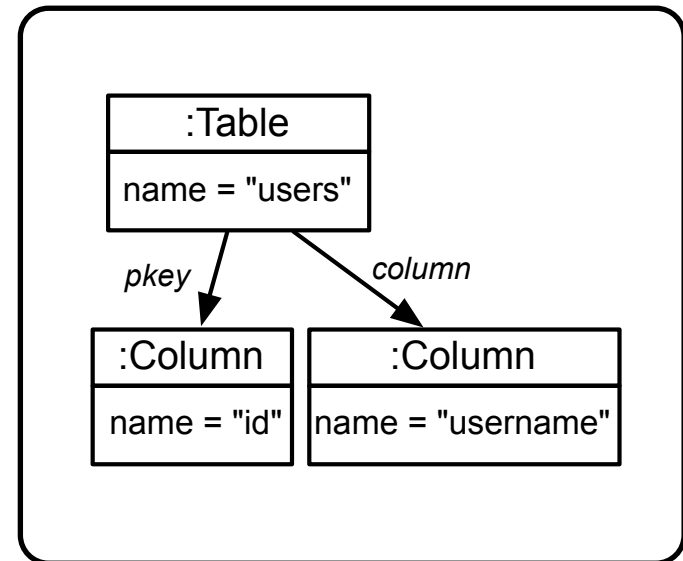
- Epsilon is a platform of interoperable model management languages
- No direct support for BX, but:
 - => languages for unidirectional transformations (ETL, EWL, EOL)
 - => an inter-model consistency language (EVL)
- BX can be faked in Epsilon by:
 - (1) defining pairs of unidirectional transformations
 - (2) defining consistency via inter-model constraints



- two metamodels: **class diagram** and **relational DB**
- consistency defined in terms of a **correspondence between the data** (attributes) in the models



class diagram



relational DB

Example BX “faked” in Epsilon

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- users of the models should be able to create new classes (or tables) whilst maintaining consistency
- first, we specify a pair of unidirectional transformations in Epsilon’s update-in-place language

```
wizard AddClass {  
  do {  
    var c: new Class;  
    c.name = newName;  
    self.Class.all.first().contents.add(  
      c);  
  }}  
}}
```

```
wizard AddTable {  
  do {  
    var table: new Table;  
    table.name = newName;  
    self.Table.all.first().contents.add(  
      table);  
  }}  
}}
```

Example BX “faked” in Epsilon

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- then, we **specify** and **monitor** inter-model constraints that express what it means to be **consistent**

```
context OO!Class {  
  constraint TableExists {  
    check : DB!Table.all.select(t|t.name  
      = self.name).size() > 0  
  }  
}
```

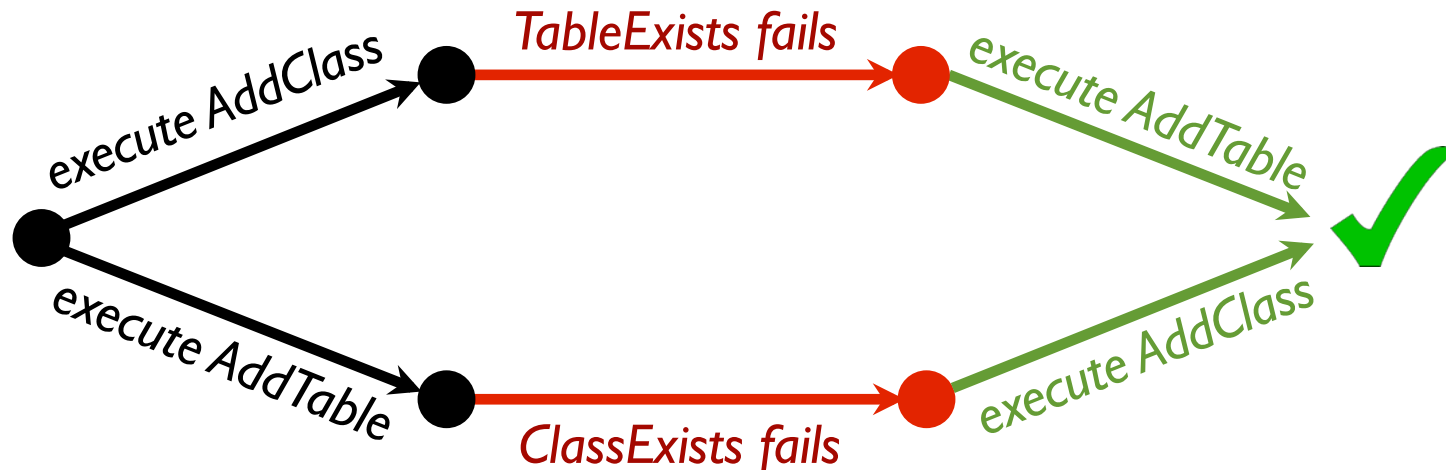
```
context DB!Table {  
  constraint ClassExists {  
    check : OO!Class.all.select(c|c.name  
      = self.name).size() > 0  
  }  
}
```

Example BX “faked” in Epsilon

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}}
```



More needs to be “faked”

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- fake BX lack the consistency guarantees that **true BX have by construction**
- what does this mean?
 - => *compatibility of the directions might not be maintained (e.g., discovered when checking consistency)*
 - => *repair transformations might not actually restore consistency*
- our example is obviously compatible, but we should be able to check this easily and automatically

Our proposal

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Exploit graph transformation verification techniques to check compatibility

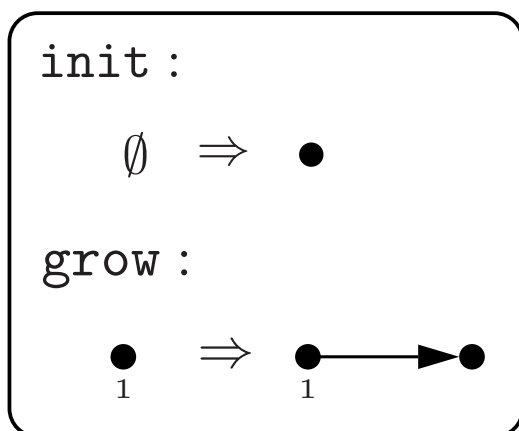
- **graph transformation (GT)** is a computation abstraction
 - => *state is represented as a graph*
 - => *computational steps represented as GT rule applications*

Our proposal

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Exploit graph transformation verification techniques to check compatibility

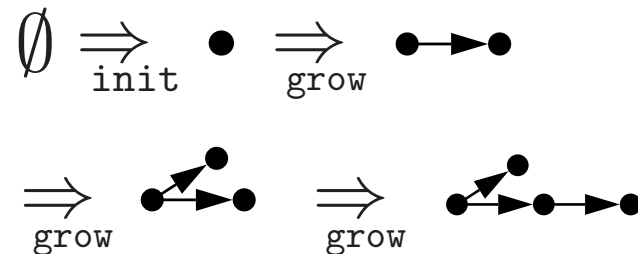
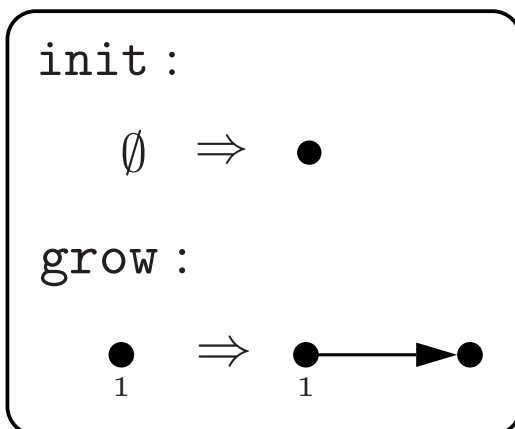
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Our proposal

Exploit graph transformation verification techniques to check compatibility

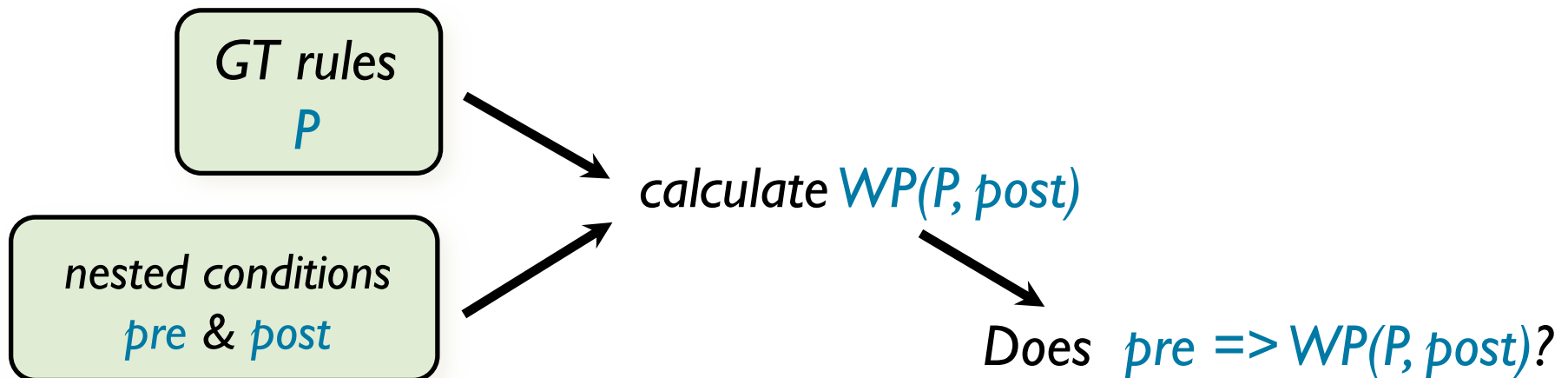
- graph transformation (GT) is a computation abstraction
 - \Rightarrow state is represented as a graph
 - \Rightarrow computational steps represented as GT rule applications



GT Verification

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- functional correctness of GT rules can be verified in a **weakest precondition style**
- **pre-** and **postconditions** are expressed in the graph-based logic of **nested conditions**, equiv. to FO logic
- roughly, to verify $\{\text{pre}\} P \{\text{post}\}$:



Rigorous “faking”

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- translate the unidirectional transformations to **GT rules**
=> denoted P_S and P_T
- translate the inter-model constraints to **nested conditions**
=> denoted evl
- automatically discharge the following specifications using the **weakest precondition calculi**

$\{evl\} P_S; P_T \{evl\}$

$\{evl\} P_T; P_S \{evl\}$

Proving consistency of our CD/DB bx

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P_S

\emptyset

\Rightarrow

:Class
name = newName

P_T

\emptyset

\Rightarrow

:Table
name = newName

evl

$\forall \left(\begin{array}{|c|} \hline \text{:Class} \\ \hline \text{name} = x \\ \hline \end{array} \right)_1, \exists \left(\begin{array}{|c|} \hline \text{:Class} \\ \hline \text{name} = x \\ \hline \end{array} \right)_1 \begin{array}{|c|} \hline \text{:Table} \\ \hline \text{name} = x \\ \hline \end{array} \right)$

$\wedge \forall \left(\begin{array}{|c|} \hline \text{:Table} \\ \hline \text{name} = y \\ \hline \end{array} \right)_2, \exists \left(\begin{array}{|c|} \hline \text{:Table} \\ \hline \text{name} = y \\ \hline \end{array} \right)_2 \begin{array}{|c|} \hline \text{:Class} \\ \hline \text{name} = y \\ \hline \end{array} \right)$

Proving consistency of our CD/DB bx

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P_S

\emptyset

\Rightarrow

:Class
name = newName

P_T

\emptyset

\Rightarrow

:Table
name = newName

evl

$$\begin{aligned} & \forall \left(\begin{array}{|c|} \hline \text{:Class} \\ \hline \text{name = x} \\ \hline \end{array} \right)_1, \exists \left(\begin{array}{|c|} \hline \text{:Class} \\ \hline \text{name = x} \\ \hline \end{array} \right)_1 \begin{array}{|c|} \hline \text{:Table} \\ \hline \text{name = x} \\ \hline \end{array} \right) \\ & \wedge \forall \left(\begin{array}{|c|} \hline \text{:Table} \\ \hline \text{name = y} \\ \hline \end{array} \right)_2, \exists \left(\begin{array}{|c|} \hline \text{:Table} \\ \hline \text{name = y} \\ \hline \end{array} \right)_2 \begin{array}{|c|} \hline \text{:Class} \\ \hline \text{name = y} \\ \hline \end{array} \right) \end{aligned}$$

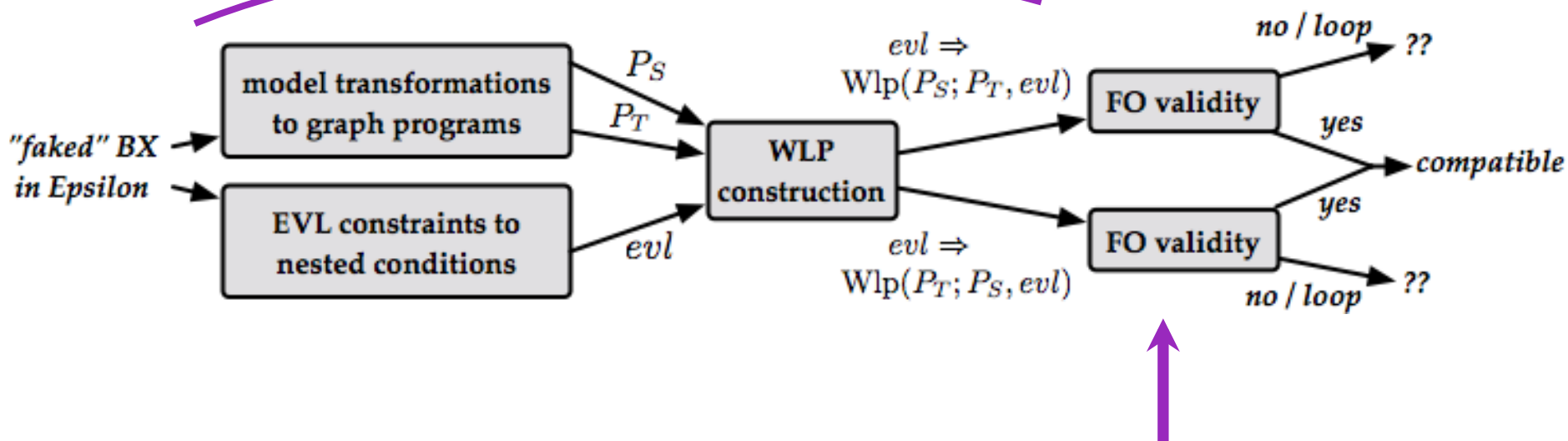


compatible: $WP(P_S;P_T, \text{evl}) \equiv WP(P_T;P_S, \text{evl}) \equiv \text{evl}$

Putting it all together

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we need to do this bit



exploit existing theorem provers here

Our next steps

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- identify a selection of **BX case studies** ✓
- **fake them** in Epsilon, manually translate them into GT rules and nested conditions, and **verify compatibility** ✓
- **implement the translations** for an expressive subset of the Epsilon languages; implement the WP calculation
- challenges and open questions:
 - => *finding counterexamples (e.g. using GROOVE)*
 - => *theoretical / practical limitations (e.g. is FO expressive enough?)*

Wrap-up

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- State of the art in MDE for BX.
- Requirements engineering for BX.
- Architecture and design for BX.
- (A little) Verification of BX.
- What are the future challenges from a SE/MDE perspective?
 - QVT-R: the bugbear.
 - Value proposition of BX versus two unidirectional transformations (Empirical studies! Empirical studies!)
 - When does the requirement for a BX “emerge” in the engineering process? (Work bottom up, top down...)