

Concurrent Programming with Join Patterns via STMs

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Overview

- 
- Nothing clever.
 - Bait and switch operation.
 - Join patterns in Comega
 - Joins encoded with STMs:
 - Synchronous and asynchronous joins.
 - Choice.
 - Dynamic Joins.

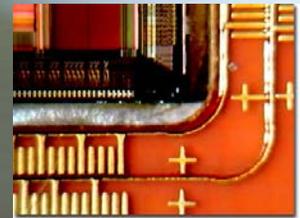


Comega asynchronous methods

```
using System ;
```

```
public class MainProgram
{ public class ArraySummer
  { public async sumArray (int[] intArray)
    { int sum = 0 ;
      foreach (int value in intArray)
        sum += value ;
      Console.WriteLine ("Sum = " + sum) ;
    }
  }
}

static void Main()
{ Summer = new ArraySummer () ;
  Summer.sumArray (new int[] {1, 0, 6, 6, 1, 9, 6, 6}) ;
  Summer.sumArray (new int[] {3, 1, 4, 1, 5, 9, 2, 6}) ;
  Console.WriteLine ("Main method done." ) ;
}
}
```

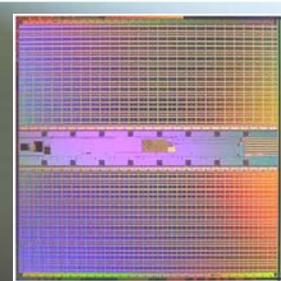


Comega chords

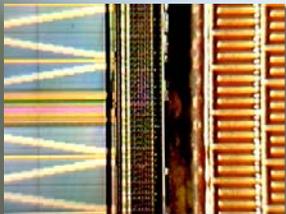
```
using System ;
```

```
public class MainProgram  
{ public class Buffer  
  { public async Put (int value) ;  
    public int Get () & Put(int value)  
    { return value ; }  
  }  
}
```

```
static void Main()  
{ buf = new Buffer () ;  
  buf.Put (42) ;  
  buf.Put (66) ;  
  Console.WriteLine (buf.Get () + " " +  
  buf.Get ()) ;  
}
```



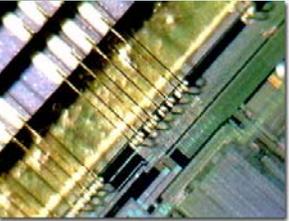
"STM"s in Haskell



```
data STM a
instance Monad STM
-- Monads support "do" notation and sequencing
-- Exceptions
throw :: Exception -> STM a
catch :: STM a -> (Exception->STM a) -> STM a
-- Running STM computations
atomically :: STM a -> IO a
retry :: STM a
orElse :: STM a -> STM a -> STM a
-- Transactional variables
data TVar a
newTVar :: a -> STM (TVar a)
readTVar :: TVar a -> STM a
writeTVar :: TVar a -> a -> STM ()
```



Join2



```
module Main
where

import Control.Concurrent
import Control.Concurrent.STM

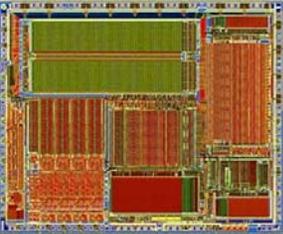
join2 :: TChan a -> TChan b -> IO (a, b)
join2 chanA chanB
    = atomically (do a <- readTChan chanA
                    b <- readTChan chanB
                    return (a, b)
                )

taskA :: TChan Int -> TChan Int -> IO ()
taskA chan1 chan2
    = do (v1, v2) <- join2 chan1 chan2
        putStrLn ("taskA got: " ++ show (v1, v2))

main
    = do chanA <- atomically newTChan
        chanB <- atomically newTChan
        atomically (writeTChan chanA 42)
        atomically (writeTChan chanB 75)
        taskA chanA chanB
```



One-Shot Synchronous Join



```
(&) :: TChan a -> TChan b -> STM (a, b)
```

```
(&) chan1 chan2
```

```
= do a <- readTChan chan1  
     b <- readTChan chan2  
     return (a, b)
```

```
(>>>) :: STM a -> (a -> IO b) -> IO b
```

```
(>>>) joinPattern handler
```

```
= do results <- atomically joinPattern  
     handler results
```

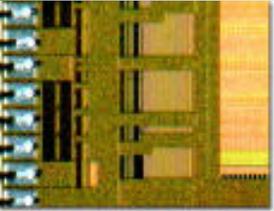
```
example chan1 chan2
```

```
= chan1 & chan2 >>>
```

```
  \ (a, b) -> putStrLn (show (a, b))
```



Puzzle



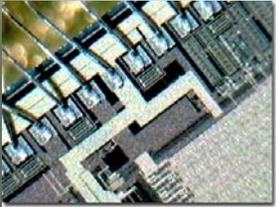
```
main :: IO ()
```

```
main
```

```
= do chan1 <- atomically $ newTChan
    atomically $ writeTChan chan1 42
    atomically $ writeTChan chan1 74
    chan1 & chan1 >>>
    \ (a, b) -> putStrLn (show (a, b))
```



Repeating Asynchronous Join



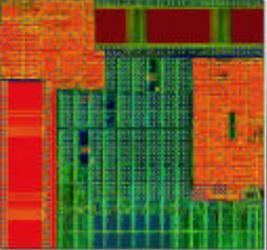
```
(>!>) :: STM a -> (a -> IO ()) -> IO ()
(>!>) joins cont
    = do forkIO (asyncJoinLoop joins cont)
          return () -- discard thread ID
```

```
asyncJoinLoop :: (STM a) -> (a -> IO ()) -> IO ()
asyncJoinLoop joinPattern handler
    = do joinPattern >>> forkIO . handler
          asyncJoinLoop joinPattern handler
```

```
example chan1 chan2
    = chan1 & chan2 >!>
      \ (a, b) -> putStrLn (show ((a, b)))
```



Exploiting Overloading



```
class Joinable t1 t2 where
  (&) :: t1 a -> t2 b -> STM (a, b)

instance Joinable TChan TChan where
  (&) = join2

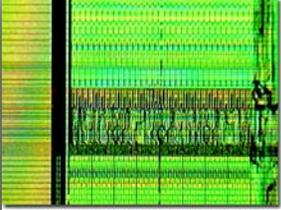
instance Joinable TChan STM where
  (&) = join2b

instance Joinable STM TChan where
  (&) a b = do (x, y) <- join2b b a
                return (y, x)

chan1 & chan2 & chan3 >>>
  \ ((a, b), c) -> putStrLn (show (a, b, c))
```



Biased Synchronous Choice



```
(|+|) :: (STM a, a -> IO c) ->
        (STM b, b -> IO c) ->
        IO c
```

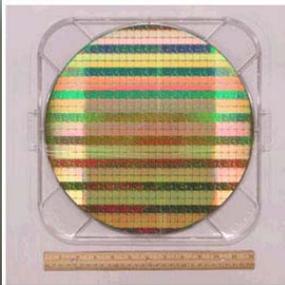
```
(|+|) (joina, action1) (joinb, action2)
= do io <- atomically
      (do a <- joina
          return (action1 a)
        `orElse`
        do b <- joinb
          return (action2 b))
      io
```

```
(chan1 & chan2 & chan3,
 \ ((a,b),c) -> putStrLn (show (a,b,c)))
```

```
|+|
```

```
(chan1 & chan2,
 \ (a,b) -> putStrLn (show (a,b)))
```

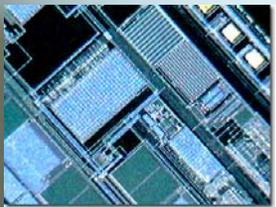
Dynamic Joins



```
example numSensors numSensors chan1 chan2 chan3
= if numSensors = 2 then
    chan1 & chan2 >!> \ (a, b) ->
    putStrLn (show ((a, b)))
else
    chan1 & chan2 & chan3 >!> \ (a, (b, c))
    -> putStrLn (show ((a, b, c)))
```



Conditional Joins



```
(??) :: TChan a -> (a -> Bool) -> STM a
```

```
(??) chan predicate
```

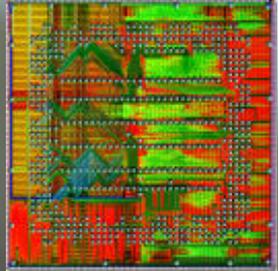
```
= do value <- readTChan chan
   if predicate value then
     return value
   else
     retry
```



```
(chan1 ?? \x -> x > 3) & chan2 >>>
  \ (a, b) -> putStrLn (show (a, b))
```

Summary and Questions

- “Free” joins encoded nicely in terms of STMs.
- Model for understanding join patterns in terms of STMs.
- A good literal implementation (?)
 - Parallel execution?
- Joins as statements instead of declarations.
- Other work: JSR-166 library
- What are joins good for anyway?



Conditional Joins



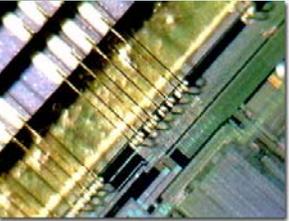
```
(?) :: TChan a -> Bool -> STM a
```

```
(?) chan predicate  
  = if predicate then  
      readTChan chan  
    else  
      retry
```

```
(chan1 ? cond) & chan2 >>>  
\ (a, b) -> putStrLn (show (a, b))
```



Conditional Joins



```
(?) :: TChan a -> STM Bool -> STM a
```

```
(?) chan predicate
```

```
  = do cond <- predicate
```

```
      if cond then
```

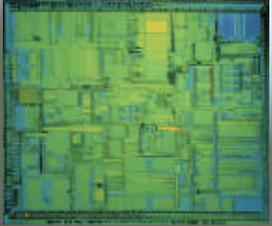
```
        readTChan chan
```

```
      else
```

```
        retry
```



Backup



Backup

