

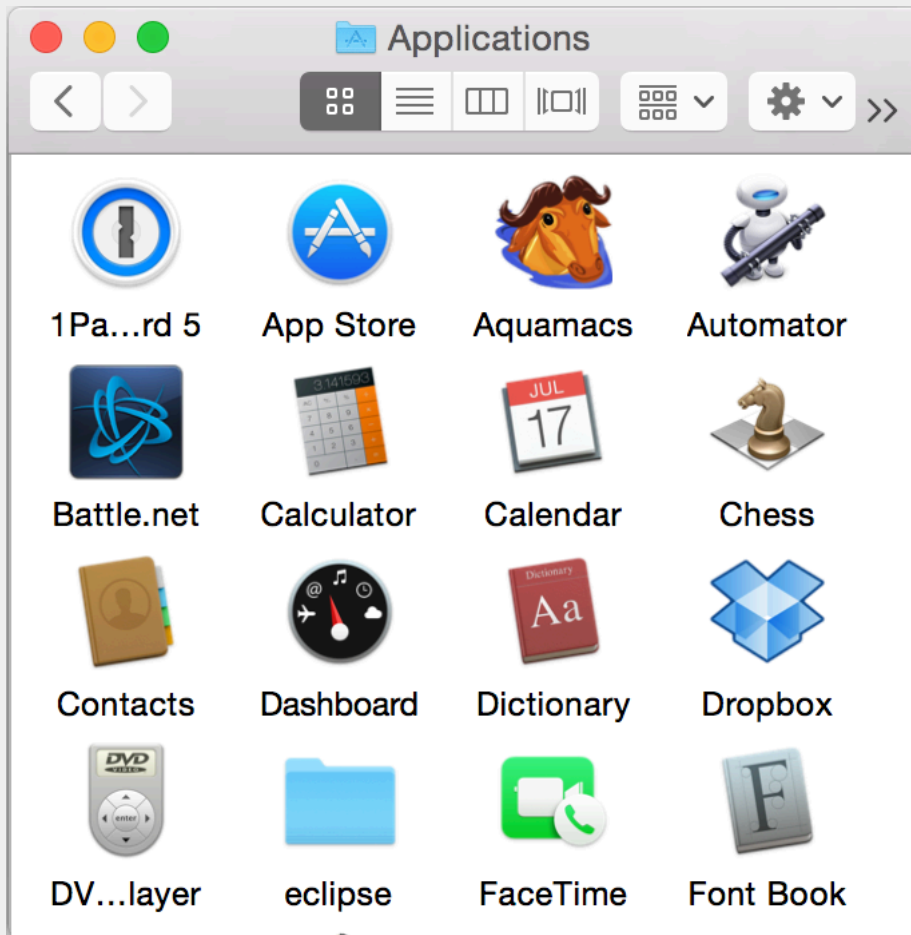
# Curry-Howard for GUIs: classical linear linear temporal logic (work in progress!)

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WG 2.8 2015



# How do we *think* about GUIs?



- an array of buttons
- each button *waits* for a click
- each button has a different effect (e.g. starts a different app)
- logically, each button is an *independent* process

# A Callback-driven GUI API

```
button.onClick : (ClickData -> IO ()) -> IO ()  
  
-- add the callback to the appropriate handler  
button.onClick callback =  
    handlers[click] := callback :: (!handlers[click])
```

- pass to the button a function to be invoked on a click event
- callback stored in a per-widget collection
- button.onClick has a continuation type  
⇒ classical logic?

# Temporal Behavior

- GUI widgets *wait* for events
- handling of an event yields a natural notion of clock “tick”
  - process all of the callbacks for one event
- some resources are available only “now”
  - e.g. the data associated with the current event
- some resources are available “always” (at any point in the future)
  - e.g. a callback associated with a widget
- some resources are available only “eventually”
  - e.g. the data from some future event

# From Callbacks to Eventually

```
button.onClick    : (ClickData -> IO ()) -> IO ()  
                  :  $\Box$ (ClickData -> IO ()) -> IO ()  
                  : ( $\Box$  $\neg$ ClickData) -> IO ()  
                  :  $\neg$  $\Box$  $\neg$ ClickData  
                  :  $\Diamond$ ClickData
```

- callback creation ~ *eventually modality* of temporal logic
  - also called the “possibility” modality
- classical logic (should) yield a CPS-based implementation
- Question: Can we make anything out of this observation?

# Type Structure

- Ordinary Types       $A$       useable "now"
- Always Types       $\Box A$       useable at *any* (future) time
- Eventually Types       $\Diamond A$       useable at *some* (future) time

- See [Pfenning & Davies] for modal logic

# Always Modality

- The type  $\Box A$  is "always A" or "necessarily A".
- Box is a comonad.

$$\boxed{\Delta; \Gamma \vdash A}$$

$$\frac{\Delta; . \vdash A}{\Delta; \Gamma \vdash \Box A}$$

$$\frac{\Delta; \Gamma \vdash \Box A \quad \Delta, A; \Gamma \vdash B}{\Delta; \Gamma \vdash B}$$

$$\frac{A \in \Delta}{\Delta; \Gamma \vdash A}$$

# Always Modality

- The type  $\Box A$  is “always  $A$ ” or “necessarily  $A$ ”.
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$$\boxed{\Delta; \Gamma \vdash A}$$

$$\frac{\Delta; \cdot \vdash e : A}{\Delta; \Gamma \vdash \text{box } e : \Box A} \quad \frac{\Delta; \Gamma \vdash e_1 : \Box A \quad \Delta, a:A; \Gamma \vdash e_2 : B}{\Delta; \Gamma \vdash \text{let box } a = e_1 \text{ in } e_2 : B}$$

$$\frac{a:A \in \Delta}{\Delta; \Gamma \vdash a : A}$$



# Eventually Modality

- The type  $\diamond A$  is “eventually  $A$ ” or “possibly  $A$ ”.
- Diamond is a monad.

$$\frac{\Delta; \Gamma \vdash A}{\Delta; \Gamma \vdash \diamond A}$$

$$\frac{\Delta; \Gamma \vdash \diamond A \quad \Delta; A \vdash \diamond B}{\Delta; \Gamma \vdash \diamond B}$$

# Eventually Modality

- The type  $\diamond A$  is “eventually  $A$ ” or “possibly  $A$ ”.
- Diamond is a monad.

$$\frac{\Delta; \Gamma \vdash e : A}{\Delta; \Gamma \vdash \text{future } e : \diamond A}$$

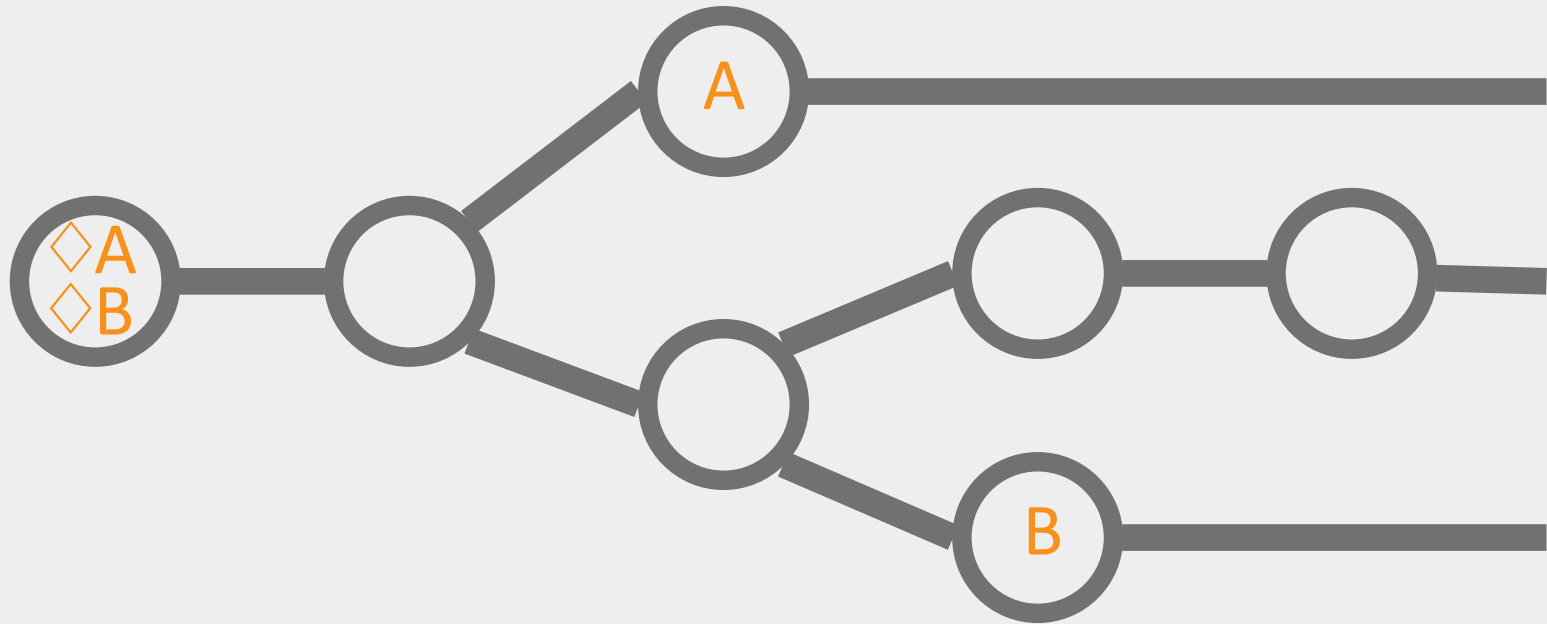
$$\frac{\Delta; \Gamma \vdash e_1 : \diamond A \quad \Delta; x:A \vdash e_2 : \diamond B}{\Delta; \Gamma \vdash \text{wait } x = e_1 \text{ in } e_2 : \diamond B}$$

# Linear Temporal Logic

- The type  $\diamond A$  means “eventually A”.
  - Would like to think of this as an “A event”
  - Built-in primitives could provide other sources of  $\diamond A$
- But... not enough structure to order them
  - In a GUI, we often think of the *sequence* of events

total order: for any A, B.  $A \leq B$  or  $B \leq A$

# Branching vs Linear Time



# Linear Temporal Logic

- Encode the ordering as this rule:

$$\frac{\Delta; \Gamma_1 \vdash \diamond B \quad \Delta; A, \diamond B \vdash \diamond C \quad \Delta; \Gamma_2 \vdash \diamond A \quad \Delta; \diamond A, B \vdash \diamond C}{\Delta; \Gamma_1, \Gamma_2 \vdash \diamond C}$$

- Call this operation “select”:
  - Wait for whichever event fires first, choose a continuation based on the outcome
  - The second operation will still eventually happen

# Linear Temporal Logic

- Encode the ordering as this rule:

$$\frac{\begin{array}{l} \Delta; \Gamma \vdash e_1 : \diamond B \qquad \Delta; a:A, b:\diamond B \vdash c_1 : \diamond C \\ \Delta; \Gamma \vdash e_2 : \diamond A \qquad \Delta; a:\diamond A, b:B \vdash c_2 : \diamond C \end{array}}{\Delta; \Gamma \vdash \text{select } e_1 \mid e_2 \text{ as} \\ \begin{array}{l} | a, b \rightarrow c_1 \\ | a, b \rightarrow c_2 \end{array} : \diamond C}$$

- Call this operation "select":
  - Wait for whichever event fires first, choose a continuation based on the outcome
  - The second operation will still eventually happen

# Linear Time, Logically

- lets us say that any two events can be ordered:

$$\diamond A \rightarrow \diamond B \rightarrow \diamond(A \times \diamond B) + \diamond(\diamond A \times B)$$

- also permits synchronization on “eventually always” propositions:

$$\text{sync: } \diamond \square A \rightarrow \diamond \square B \rightarrow \diamond \square (A \times B)$$

# Classical *Linear* Linear Temporal Logic

- Ordinary Types       $A$       useable “now”
- Always Types       $\square A$       useable at *any* (future) time
- Eventually Types       $\diamond A$       useable at *some* (future) time
  
- Classical Linear Logic  $\Rightarrow$  Concurrent Programming
  - See e.g. [Wadler] [Pfenning]
  - $\pi$ -calculus notation
  
- Benefits: similar to Rust’s affine types
  - separation of resources
  - race prevention



# Safety

```
button.onClick : (ClickData -> Safe) -> Safe
```

- here `IO ()` is the answer type.
- this is too permissive; we don't want *all* terms of type `IO ()`
- ... only those commands that preserve the event loop invariants
  - Idea: for GUIs replace `IO ()` with `Safe`, a refinement that permits only "good" computations
  - show that safety is preserved when composing richer types

# What is Safety?

A widget contains:

- ▶ Some first-order data (color, height, text, etc.)
- ▶ A collection of event handlers
- ▶ So a heap can be formalized as:

Data heap	$h$	$::=$	$\cdot \mid h, h \mid l : d$
Queue	$q$	$\in$	$\text{Loc} \rightarrow \mathcal{M}^{\text{fin}}(\text{Val})$
Store	$\sigma$	$\in$	$\text{Data} \times \text{Queue}$

- ▶ Key problem: event handlers are *higher-order state*

# Safety, Semantically

$$\text{Ok} = \left\{ (\sigma, t, \sigma') \mid \begin{array}{l} \forall \phi \# h. \exists \pi \in \text{Perm}. \\ \langle \sigma \cdot \phi; t \rangle \Downarrow \langle \pi(\sigma') \cdot \phi; () \rangle \end{array} \right\}$$

$$\text{Safe}_n = \left\{ \begin{array}{l} \overbrace{(h, q)}^\sigma \\ \forall l \in \text{Loc}, e \in \text{Event}. \\ \text{Safe}_n^*((h, [q|l : \emptyset]), e, q(l)) \end{array} \right\}$$

$$\text{Safe} = \bigcap_n \text{Safe}_n$$

$$\text{Safe}_0^*(\sigma, e, ks) = \top$$

$$\text{Safe}_{n+1}^*(\sigma, e, \epsilon) = \top$$

$$\text{Safe}_{n+1}^*(\sigma, e, k \cdot ks) = \begin{array}{l} \exists \sigma' \in \text{Safe}_n. \\ \text{Ok}(\sigma, k e, \sigma') \wedge \\ \text{Safe}_n^*(\sigma', e, ks) \end{array}$$

- Safe = heaps maintaining safety on callbacks

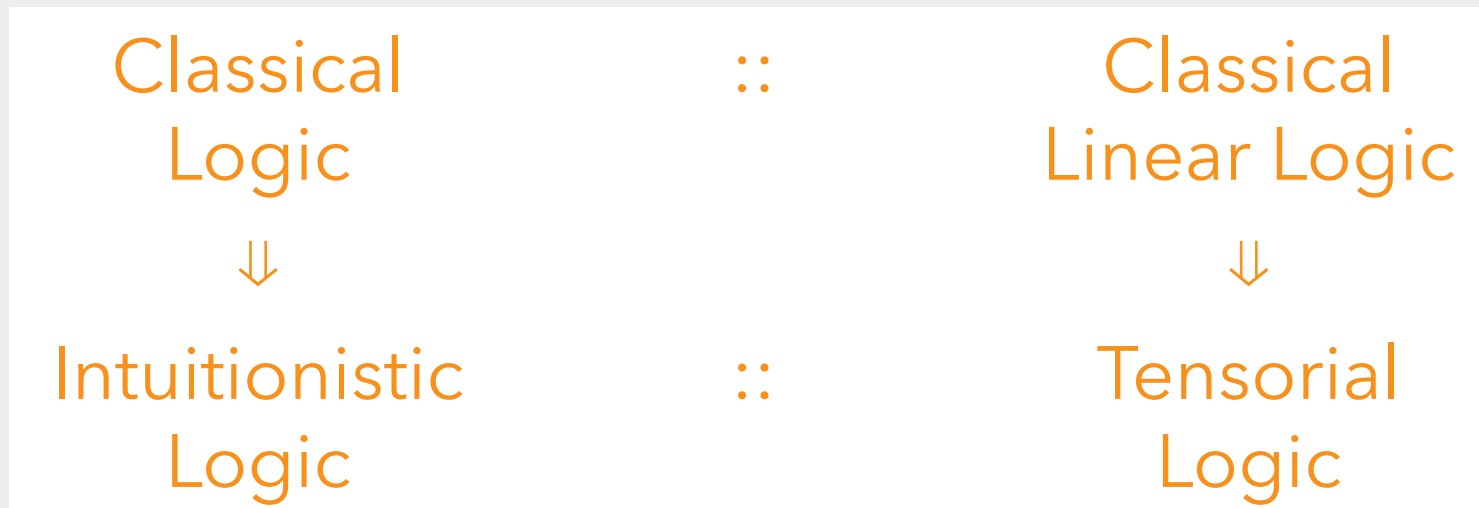
# Separation Algebra of Safe Heaps

$$\begin{aligned} h \# h' &\triangleq \text{dom}(h) \cap \text{dom}(h') = \emptyset \\ (h, q) \# (h', q') &\triangleq h \# h' \end{aligned}$$

$$\begin{aligned} h \cdot h &= \begin{cases} h, h' & \text{if } h \# h \\ \perp & \text{otherwise} \end{cases} \\ q \cdot q' &= \lambda l. q(l) \cup q'(l) \end{aligned}$$

$$\begin{aligned} \epsilon &= (\cdot, []) \\ (h, q) \cdot (h', q') &= \begin{cases} (h \cdot h', q \cdot q') & \text{if } h \# h \\ \perp & \text{otherwise} \end{cases} \end{aligned}$$

# Compilation Strategy



- Translation is double-negation (i.e. CPS translation)
- Mellies' *tensorial logic*

# Realizability Semantics of Continuations

Type =  $\{\langle \sigma; v \rangle \mid \sigma \in \text{Safe}\}$

1

$A * B$

0

$A_1 + A_2$

$\neg A$

$\Box A$

# Double Negation (CPS)

$$\begin{aligned} \llbracket 0 \rrbracket &= 0 \\ \llbracket A \oplus B \rrbracket &= \llbracket A \rrbracket + \llbracket B \rrbracket \end{aligned}$$

$$\begin{aligned} \llbracket ! \rrbracket &= 1 \\ \llbracket A \otimes B \rrbracket &= \llbracket A \rrbracket * \llbracket B \rrbracket \end{aligned}$$

$$\begin{aligned} \llbracket \top \rrbracket &= \neg 0 \\ \llbracket A \& B \rrbracket &= \neg(\neg \llbracket A \rrbracket + \neg \llbracket B \rrbracket) \end{aligned}$$

$$\begin{aligned} \llbracket \perp \rrbracket &= \neg 1 \\ \llbracket A \wp B \rrbracket &= \neg(\neg \llbracket A \rrbracket * \neg \llbracket B \rrbracket) \end{aligned}$$

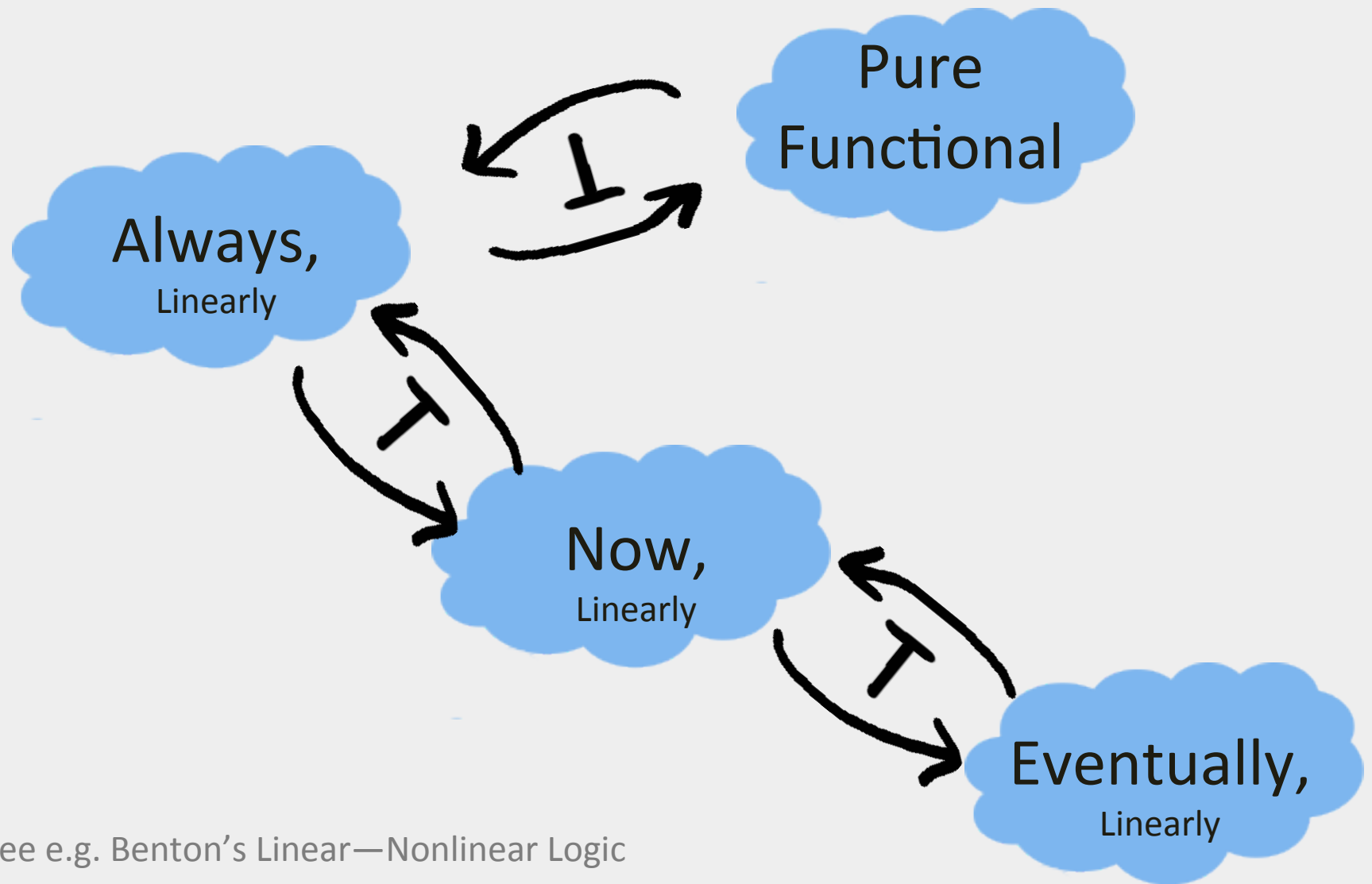
$$\begin{aligned} \llbracket \Box A \rrbracket &= \Box \llbracket A \rrbracket \\ \llbracket \Diamond A \rrbracket &= \neg \Box \neg \llbracket A \rrbracket \end{aligned}$$

# Status

- Still nailing down the semantics
  - Interaction between linearity & temporal logic
  - Proofs that the safety invariants compose
- Playing around with syntax
  - Sequent formulations of the type system
  - Pi-calculus? Mu calculus?
- No implementation (yet!)
- Jennifer: thinking about “composition of logical features”
  - Combining semantics

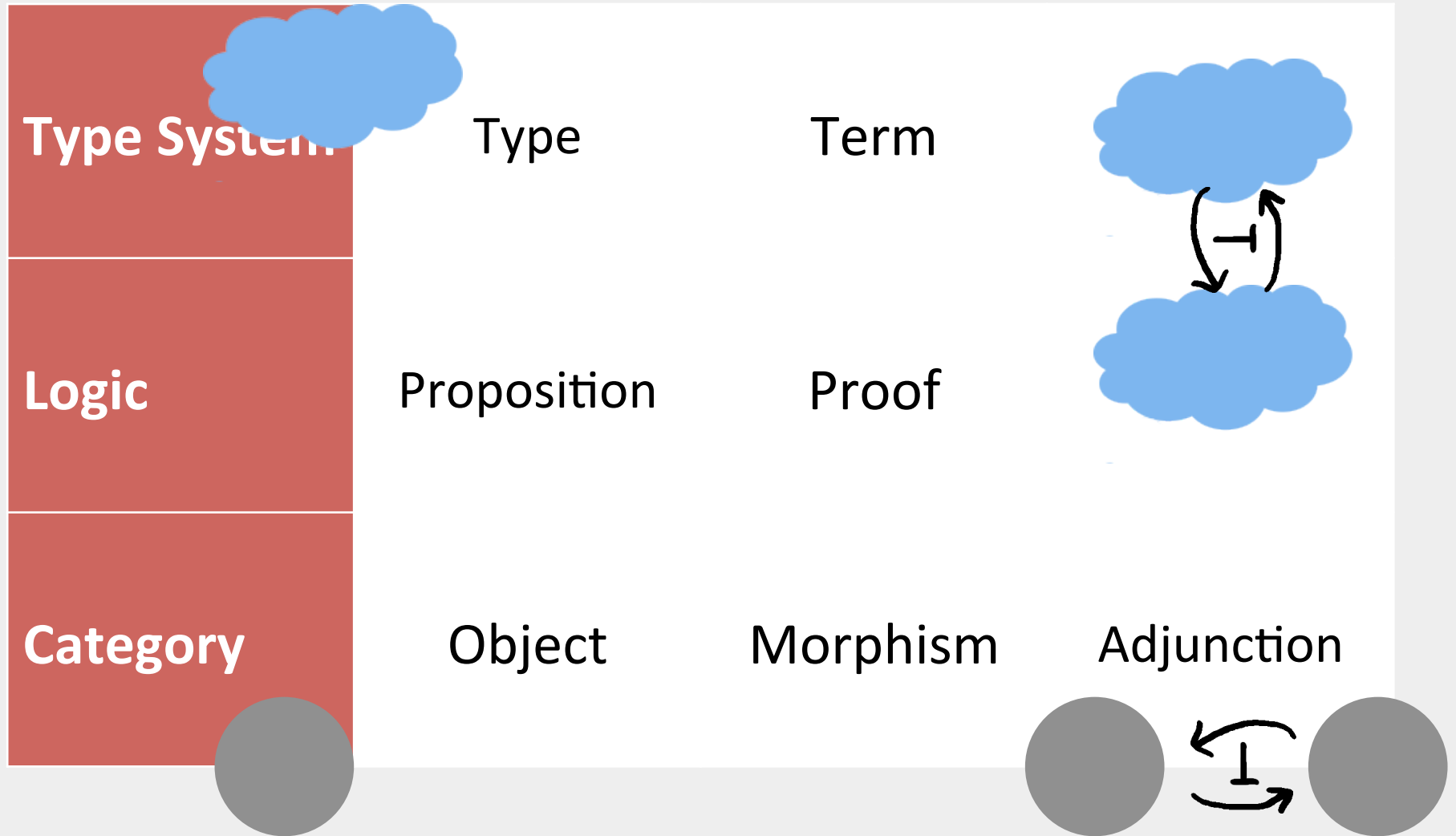


# Features as Computational “Worlds”



See e.g. Benton's Linear—Nonlinear Logic

"Adjoint functors arise everywhere..."



# Questions

- Connection to Functional Reactive Programming?
- Behavior/Signal vs. Event
  - $\square A \sim T \rightarrow A$  where T is the domain of Time
  - $\diamond A \sim T \times A$
- Connection to Concurrent ML?
  - first-class synchronization primitives?

# Interactive Programs

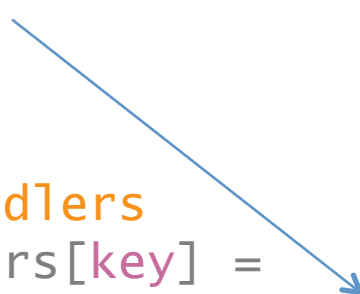
- event loop *waits* for events
- programs register *callbacks* with the event handler
- event loop invokes the callbacks for each event
- GUI Programs are(?):
  - higher-order
  - concurrent
  - imperative
  - CPS

```
-- event loop
while (true) {
  let event = get_event();
  for (f in handlers[event]) {
    f(event.data);
  }
}

-- handlers
handlers[key] =
  [fun d -> ...; fun d -> ...;]

handlers[click] =
  [fun d -> ...; fun d -> ...;]

handlers[mouseMove] =
  [fun d -> ...;]
```



# Linear Type Structure

- Linear Types  $A$  useable exactly once "now"
- Always Types  $\square A$  useable once at any (future) time
- Eventually Types  $\diamond A$  useable once at some (future) time
- Persistent Types  $!A$  unrestricted uses at any time

- box is a comonad
- diamond is a monad
- sequent calculus:

$$\frac{\vdash \diamond \Delta, A}{\vdash \diamond \Delta, \square A} \qquad \frac{\vdash \Delta, A}{\vdash \Delta, \diamond A}$$

# Safety

```
button.onClick : (ClickData -> IO ()) -> IO ()
                : (ClickData -> Safe) -> Safe
                : □(ClickData -> Safe) -> Safe
                : □¬ClickData -> Safe
                : ¬□¬ClickData
                : ◇ClickData
```

- callback creation ~ eventually modality of temporal logic
- linearity lets us characterize independence
- classical logic (should) yield a CPS-based implementation

# Facts about CPS Translation

$$\llbracket 1 \rrbracket = (1 \rightarrow a) \rightarrow a$$

$$\llbracket A \times B \rrbracket = (A \rightarrow B \rightarrow a) \rightarrow a$$

$$\llbracket A \rightarrow B \rrbracket = A \rightarrow (B \rightarrow a) \rightarrow a$$

- CPS is a double negation translation of the types:

$$\neg A = A \rightarrow a$$

- the “answer type” is  $a$
- CPS translation is *parametric* in the answer type [Friedman 76]