

# Honour School of Computer Science, Part B

Trinity 2023

# Implementing Hadamard Matrices in SageMath

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Word count: 4998

## Abstract

Hadamard matrices are (-1, +1) square matrices with mutually orthogonal rows. The Hadamard conjecture states that Hadamard matrices of order n exist whenever n is 1, 2, or a multiple of four. However, no construction is known that works for all values of n, and for some orders no Hadamard matrix has yet been found. Given the many practical applications of these matrices, it would be useful to have a way to easily check if a construction for a Hadamard matrix of order n exists, and in case to create it. This project aimed to solve this, by implementing constructions of Hadamard and skew Hadamard matrices to cover all known orders less than or equal to 1000 in SageMath, an open-source mathematical software. This also allowed us to verify the correctness of the results given in the literature. Furthermore, we implemented some additional mathematical objects, such as complementary difference sets and T-sequences, which were not present in SageMath but are needed to construct Hadamard matrices.

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## 1 Introduction

Hadamard matrices were defined for the first time by Sylvester in 1867. Since then, they have been used in many practical applications, such as quantum computing, image analysis, and signal processing.

However, no construction is currently known that works for matrices of every size. Therefore, whenever a Hadamard matrix of a specific order is needed, one must try multiple constructions until the correct one is found (if it is known).

This project aims to alleviate this problem, by providing all the necessary constructions in SageMath, an open-source mathematical software written in Python. Although a few constructions were already present in SageMath (see chapter 2), they provided matrices for infinite series which only covered a few orders. We added many new constructions so that Hadamard and skew Hadamard matrices of all known orders less than or equal to 1000 are now available.

The code can be found on the SageMath GitHub repository<sup>1</sup>. In particular, the functions that I have written have been added to the repository with multiple separate Pull Requests<sup>2-7</sup>. This was done to follow the development guidelines of SageMath.

There were a few particularly important aspects to take into consideration. First of all, given that new constructions are found fairly often, the functions provided should be easily extendable. Furthermore, we must be able to guarantee the correctness of the constructions implemented. Lastly, given that the code is part of open-source software, it should contain clear documentation and must adhere to the coding style adopted by the SageMath community.

<sup>&</sup>lt;sup>1</sup>https://github.com/sagemath/sage

<sup>&</sup>lt;sup>2</sup>https://github.com/sagemath/sage/issues/32267

<sup>&</sup>lt;sup>3</sup>https://github.com/sagemath/sage/issues/34690

<sup>&</sup>lt;sup>4</sup>https://github.com/sagemath/sage/issues/34807

<sup>&</sup>lt;sup>5</sup>https://github.com/sagemath/sage/pull/34985

<sup>&</sup>lt;sup>6</sup>https://github.com/sagemath/sage/pull/35059

<sup>&</sup>lt;sup>7</sup>https://github.com/sagemath/sage/pull/35211

## 1.1 Structure of the Report

This report is divided into the following chapters:

- Chapter 2 contains a definition of Hadamard matrices and a brief description of some methods that were already implemented in SageMath;
- Chapter 3 gives a high-level description of the functions implemented;
- Chapter 4 describes the construction of some sequences with zero nonperiodic autocorrelation;
- Chapter 5 gives some constructions of difference sets;
- Chapter 6 contains a description of the constructions for Hadamard (and skew Hadamard) matrices that have been implemented;
- Chapter 7 contains some final considerations.

## 2 Background

A  $n \times n$  matrix is called a *Hadamard matrix* if its entries are all -1, +1 and the rows are mutually orthogonal. Equivalently, they are (-1, +1) matrices which satisfy the equation:

$$HH^{\top} = H^{\top}H = nI$$

In particular, the latter equality implies that  $|det(H)| = n^{n/2}$ , i.e. the determinant is maximal. Matrices of this type were described for the first time by Sylvester [26], and were studied further by Jacques Hadamard [14].

Additionally, a Hadamard matrix is *skew* if it has the form H = S + I, where I is the identity and S is skew-symmetric:  $S^{\top} = -S$ .

The Hadamard conjecture states that a Hadamard matrix of order n exists if and only if n = 1, 2 or a multiple of four. It is easy to see that for a Hadamard matrix of order n > 2 to exist, n must be a multiple of four. However, the converse has not yet been proven. Currently, Hadamard matrices are known for most orders less than 1000, with the only exceptions being 668, 716, and 892.

A similar conjecture has been proposed for skew Hadamard matrices. Again, skew Hadamard matrices are not known for all orders, and in particular no construction is known for the following values of n < 1000 (see [11]):

356, 404, 428, 476, 596, 612, 668, 708, 712, 716, 764, 772, 804, 808, 820, 836, 856, 892, 900, 916, 932, 940, 952, 980, 996

In the following sections, we will see some constructions of Hadamard matrices that had already been implemented in SageMath.

## 2.1 Paley's Constructions

In 1933, Paley [20] discovered two constructions of Hadamard matrices. They are as follows:

**Theorem 1.** Let q be a prime power, with  $q \equiv 3 \mod 4$ . Then there is a skew

**Theorem 2.** Let m = 2(q+1), where  $q \equiv 1 \mod 4$  is a prime power. Then there is a Hadamard matrix of order m.

## 2.2 Doubling Construction

Sylvester [26] proved that if n is the order of a Hadamard matrix, then there exists a Hadamard matrix of order  $2^t n$  for all values of  $t \ge 0$ .

**Theorem 3.** Let H be a Hadamard matrix of order n. Then the matrix  $H' = \begin{pmatrix} H & H \\ H & -H \end{pmatrix}$  is an Hadamard matrix of order 2n.

Furthermore, Seberry [32] described a similar construction for skew Hadamard matrices:

**Theorem 4.** Suppose  $H_n = S + I_n$  is a skew Hadamard matrix of order n. Then

$$H_{2n} = \begin{pmatrix} S + I_n & S + I_n \\ S - I_n & -S + I_n \end{pmatrix}$$

is a skew Hadamard matrix of order 2n.

These theorems are particularly important, because they imply that when creating new Hadamard matrices of order 4n we only need to worry about the cases when n is odd.

#### 2.3 Regular Symmetric Hadamard Matrices with Constant Diagonal

Regular symmetric Hadamard matrices with constant diagonal (or RSHCD) are symmetric  $n \times n$  Hadamard matrices such that:

- All values on the main diagonal are equal to a value  $\delta \in \{-1, +1\}$ ;
- All rows sums are equal to  $\delta \epsilon \sqrt{n}$ , with  $\epsilon \in \{-1, +1\}$ .

All known RSHCD of order  $n \leq 1000$  had already been implemented in SageMath [3]. However, they only cover the orders:

4, 16, 36, 64, 100, 144, 196, 256, 324, 400, 576, 676, 784, 900

## 3 Program Design

All the functions implemented have a common structure. First of all, given that the code is part of an open-source software, it was of the utmost importance that good documentation was provided. In SageMath, documentation is written using the functions' docstrings. These contain a general description of the implementation, with some references to the relevant papers. Subsequently, one can find a list of the input parameters, together with a short explanation of each one, and a description of the resulting output. Lastly, the documentation provides a few examples of how to use the function.

## 3.1 Testing

In order to look for possible bugs in the code, the docstrings of every function contain some unit tests, which are run by GitHub Continuous Integration tools whenever new code is added to the repository. On average, every function I wrote contains between five and ten tests, depending on its complexity.

Writing these tests is particularly important because, given the large size of the SageMath repository, some new pieces of code may introduce bugs in seemingly unrelated parts of the software.

## 3.2 Common Function Parameters

Since SageMath is a mathematical software, the correctness of the implementation must be guaranteed. Although, as seen in the previous section, many tests have been written for each function, an additional precaution was taken.

In particular, every function that creates a mathematical object runs a check on the object created, to confirm that the result is correct. However, such checks often have quadratic (or worse) complexity, which may add considerable overhead when the input is large. Therefore, the function parameters contain a boolean flag, and the check will be skipped if the parameter is set to false by the user.

Furthermore, it is often not easy to see if a construction can be applied to some input or not (for example, it may depend on whether data for such construction is contained in SageMath). To make the code more user-friendly, in all such cases a

Algorithm 1: Functions structure

def hadamard_matrix(n, existence=False, check=True):									
if existence:									
if Hadamard matrix of order n can be created:									
return True									
return False									
<pre>if Hadamard matrix of order n cannot be created:     raise ValueError()</pre>									
H := create Hadamard matrix of order n									
if check:									
raise exception if H is not a Hadamard matrix									
return H									

boolean parameter called **existence** is present. When this parameter is set to true, the function will not compute the requested object: instead, it returns true if the function can be applied to the given input, and false otherwise.

As an example, Fig. 1 shows the pseudocode of a generic function computing Hadamard matrices.

#### 3.3 Utility Functions

In the previous section, we have seen that most functions need a way to check if the result is the correct mathematical object. To avoid code duplication, I have implemented some utility functions that execute this check. For example, the function are\_complementary\_difference\_sets is used to check if the given sets are complementary difference sets.

Furthermore, these functions contain a boolean parameter verbose. When this is true, the function will print to the console a string explaining why the result is "false". This is particularly useful when we need to check that an object satisfies multiple properties: for example, if we want to check if a matrix is a skew Hadamard matrix and the function is\_skew\_hadamard\_matrix returns false, setting verbose to true will tell us if the matrix is not Hadamard, or if it is Hadamard but not skew.

Lastly, many of the mathematical objects detailed in this project can be obtained from multiple constructions. In these cases, the code contains a utility function (e.g. hadamard\_matrix) that tries to find a result by checking each of the given constructions
in order.

## 4 Sequences with Zero Nonperiodic Autocorrelation

Of particular interest for the construction of Hadamard matrices are complementary sequences.

In general, given a sequence  $A = (a_1, a_2, ..., a_n)$  the nonperiodic autocorrelation function  $N_A(j)$  is defined by [16]:

$$N_A(j) = \sum_{i=1}^{n-j} a_i a_{i+j} \qquad \text{for } 0 \le j \le n$$
$$N_A(j) = 0 \qquad \text{for } j > n$$

According to [23], a family  $X = \{A_1, A_2, ..., A_k\}$  of integer sequences of length n is complementary if it satisfies:

$$\sum_{i=1}^{k} N_{A_i}(j) = 0 \quad j \in \{1, 2, ..., n-1\}$$

#### 4.1 Turyn Sequences

The first sequences that I implemented are Turyn sequences. These are families composed by four (-1, +1) complementary sequences of length l, l, l-1, l-1, with the form (see Definition 7.4 of [23]):

$$X = \{x_1 = 1, x_2, x_3, \dots, x_{l-1}, x_l = -1\}$$
$$U = \{u_1, u_2, \dots, u_{l-1}, u_l = 1\}$$
$$Y = \{y_1, y_2, \dots, y_{l-1}\}$$
$$V = \{v_1, v_2, \dots, v_{l-1}\}$$

These sequences, which were constructed for the first time by Turyn in [30], are known for l = 2, 3, 4, 5, 6, 7, 8, 13, 15.

#### 4.2 Turyn Type Sequences

Some other sequences used for constructing Hadamard matrices are Turyn type sequences. Formally [16],

**Definition.** Four (-1, +1) sequences X, Y, Z, W of lengths n, n, n, n-1 are said to be of Turyn type if

$$N_X(j) + N_Y(j) + 2N_Z(j) + 2N_W(j) = 0$$
 for  $j \ge 1$ 

The sequences of this type that I implemented in SageMath are listed in [1, 16].

#### 4.3 Base Sequences

The Turyn sequences described in section 4.1 can be generalised into the concept of base sequences [16]:

**Definition.** Four (-1,1) sequences A, B, C, D of lengths n + p, n + p, n, n are called base sequences if

$$N_A(j) + N_B(j) + N_C(j) + N_D(j) = 0$$
 for  $j \ge 1$ 

Clearly, Turyn sequences can be seen as base sequences with p = 1. Additionally, base sequences of lengths 2n - 1, 2n - 1, n, n can be constructed from Turyn type sequences of lengths n, n, n, n - 1 [16]:

**Theorem 5.** If X, Y, Z, W are Turyn type sequences of lengths n, n, n, n - 1, then the sequences A = Z; W, B = Z; -W, C = X, D = Y are base sequences of lengths 2n - 1, 2n - 1, n, n.

Here the notation A; B is used to mean sequence A followed by sequence B.

#### 4.4 T-sequences

Lastly, I used the sequences defined so far to implement some constructions of T-sequences. They are defined by [16] as:

**Definition.** Four (-1, 0, 1) sequences A, B, C, D of length n are called T-sequences if

$$N_A(j) + N_B(j) + N_C(j) + N_D(j) = 0$$
 for  $j \ge 1$ 

and in each position exactly one of the entries of A, B, C, D is nonzero.

The first way to generate T-sequences is by using base sequences. From [16]:

**Theorem 6.** Suppose A, B, C, D are base sequences of lengths n + p, n + p, n, n. Then, the following are T-sequences of length 2n + p:

$$T_{1} = \frac{1}{2}(A+B); 0_{n}$$

$$T_{2} = \frac{1}{2}(A-B); 0_{n}$$

$$T_{3} = 0_{n+p}; \frac{1}{2}(C+D)$$

$$T_{4} = 0_{n+p}; \frac{1}{2}(C-D)$$

The notation used is as follows. Suppose  $A = (a_1, a_2, ..., a_k)$ ,  $B = (b_1, b_2, ..., b_k)$  are two sequences, and c is a scalar. Then:

- $c_n$  is a sequence of length n whose elements are all c;
- $A; B = (a_1, ..., a_k, b_1, ..., b_k);$
- $A+B = (a_1+b_1, a_2+b_2, ..., a_k+b_k)$ , and similarly  $A-B = (a_1-b_1, a_2-b_2, ..., a_k-b_k)$ ;
- $cA = (ca_1, ca_2, ..., ca_k).$

In addition, T-sequences of length 4n - 1 can be constructed from Turyn sequences of lengths n, n, n - 1, n - 1. From Theorem 7.7 of [23]:

**Theorem 7.** Suppose A, B, C, D are four Turyn sequences of lengths n, n, n-1, n-1.

Then, the following are T-sequences of length 4n - 1:

$$T_{1} = 1; 0_{4n-2}$$

$$T_{2} = 0; A/C; 0_{2n-1}$$

$$T_{3} = 0_{2n}; B/0_{n-1}$$

$$T_{4} = 0_{2n}; 0_{n}/D$$

The notation used in Theorem 7 is the same as for the previous construction, with the addition that if we have two sequences  $A = (a_1, a_2, ..., a_k)$  and  $B = (b_1, b_2, ..., b_{k-1})$ then  $A/B = (a_1, b_1, a_2, b_2, ..., a_{k-1}, b_{k-1}, a_k)$ .

## 5 Difference Sets

Another concept often used in the construction of Hadamard matrices is that of difference sets.

**Definition.** A  $(v, k, \lambda)$  difference set is a subset D of size k of an additive group G of order v such that every nonidentity element of G can be expressed as a difference  $d_1 - d_2$  of elements of D in exactly  $\lambda$  ways.

We will focus on the construction of some variations of difference sets: relative difference sets, supplementary difference sets, and complementary difference sets.

#### 5.1 *m*-sequences

Given a Galois field G of order  $q = p^m$ , an *m*-sequence is a periodic (infinite) sequence with period  $q^n - 1$ , with elements from G.

These sequences, which will be used in the construction of relative difference sets (section 5.2), can be created as described by Zierler in [33]. In particular, given n + 1 values  $(c_0, c_1, ..., c_n)$ , and the first n values  $a_1, a_2, ..., a_n$  we define the entire sequence as follows:

$$a_k = -c_0^{-1} \sum_{i=1}^n c_i a_{k-i}$$
 for  $k > n$ 

Furthermore, when  $f(x) = c_0 + c_1 x + ... + c_n x^n$  is a primitive polynomial, Zierler proved that there are values  $a_1, ..., a_n$  which construct an *m*-sequence.

In fact, [18] showed that when q = 2, we can use as initial sequence (1, 0, 0, ..., 0). This can be generalised to any value of q. We have therefore a complete algorithm for finding an *m*-sequence (Fig. 2).

This algorithm assumes that there exists a function find\_primitive\_poly for finding a primitive polynomial over a given ring. This was not available in SageMath, so I implemented it by repeatedly creating a random irreducible polynomial until one that is also primitive is found (see Fig. 3). Although no guarantee of the efficiency of this function can be given, it has proven to be fast in practice.

Algorithm 2: Function constructing *m*-sequences

Algorithm 3: Function creating primitive polynomials

```
def find_primitive_poly(T, n):
    primitive = T.irreducible_element(n, algorithm='random')
    while not primitive.is_primitive():
        primitive = T.irreducible_element(n, algorithm='random')
    return primitive
```

#### 5.2 Relative Difference Sets

Elliot and Butson [12] gave the following definition of relative difference sets:

**Definition.** A set R of elements in a group G of order mn is a difference set of G relative to a normal subgroup H of order  $n \neq mn$  if the collection of differences r - s,  $r, s \in R, r \neq s$  contains only elements of G which are not in H, and contains every such element exactly d times.

Such sets are denoted as R(m, n, k, d). Furthermore, we call the set cyclic or abelian if the group G has the corresponding property.

A first construction for relative difference sets which uses m-sequences is described in [12]:

**Theorem 8.** For each m-sequence over a field of  $q = p^m$  elements, there exists a cyclic  $R((q^N-1)/(q-1), q-1, q^{N-1}, q^{N-2})$  where  $q^N-1$  is the period of the m-sequence.  $\Box$ 

Given a *m*-sequence  $a = \{a_i\}_{i=0}^{\infty}$  of period  $q^N - 1$ , the relative difference set over the group of integers modulo  $q^N - 1$  is:

$$R = \{i; 0 \le i < q^N - 1 | a_i = 1\}$$

Using a second construction, we can create relative differences sets with parameters  $R((q^N - 1)/(q - 1), n, q^{N-1}, q^{N-2}d)$ , where q is a prime power and nd = q - 1.

This is possible because of a theorem from [12]:

**Theorem 9.** If R is an R(m, n, k, d) and if  $\sigma$  is a homomorphism of G onto  $\sigma(G)$  with kernel  $K \subset H$ , then  $\sigma(R)$  is an R(m, s, k, td) of  $\sigma(G)$  relative to  $\sigma(H)$ , where n = ts, and t is the order of K.

First, we create a  $R((q^N - 1)/(q - 1), q - 1, q^{N-1}, q^{N-2})$  relative difference set  $S_1$  using the previous construction. Then, we create a homomorphism  $\sigma$  whose kernel has order d. Finally, by applying this homomorphism to  $S_1$  we get the desired relative difference set.

```
Algorithm 4: Function computing R((q^N - 1)/(q - 1), q - 1, q^{N-1}, q^N - 2)defrelative_difference_set_from_homomorphism (q, N, d):G := AdditiveAbelianGroup of order q^N - 1K := subgroup of G of order dsigma = homomorphism with kernel Kdiff_set := relative_difference_set_from_m_sequence (q, N)second_diff_set := [sigma(x) for x in diff_set]return second_diff_set
```

Note that if D is a relative difference set over a group G, then for any value  $t \in G$ the set  $\{t + d \mid d \in D\}$  is also a relative difference set [24] and is called a translate of D.

Lastly, we define an additional property of relative difference sets [24]:

**Definition.** We say that a relative difference set D is fixed by  $t \in G$  if

$$\{td \mid d \in D\} = D$$

#### 5.3 Supplementary Difference Sets

Another variation of difference sets are supplementary difference sets. From Definition 4.3 of [23]:

**Definition.** Let  $S_1, S_2, ..., S_n$  be subsets of G, an additive abelian group of order v. Let  $|S_i| = k_i$ . If the equation g = r - s,  $r, s \in S_i$  has exactly  $\lambda$  solutions for each non-zero element g of g, then  $S_1, S_2, ..., S_n$  will be called  $n - \{v; k_1, k_2, ..., k_n; \lambda\}$  supplementary difference sets (or SDS). If  $k_1 = k_2 = ... = k_n = k$ , we call it a  $n - \{v; k; \lambda\}$  SDS.

Furthermore, if  $S_1 \cap -S_1 = \emptyset$  and  $S_1 \cup -S_1 = G \setminus \{0\}$  we say that  $S_1$  is skew, and the sets are called skew SDS.

#### 5.3.1 SDS from Relative Difference Sets

A construction for an infinite family of  $4 - \{2v; v, v+1, v, v; 2v\}$  SDS is given by Spence in [24]. **Theorem 10.** If q is an odd prime power for which there exists an integer s > 0 such that  $(q - (2^{s+1} + 1))/2^{s+1}$  is an odd prime power, then there exists a  $4 - \{2v; v, v + 1, v, v; 2v\}$  SDS, where v = (q - 1)/2.

The first step of this construction is to use Theorem 8 (with N = 2) to obtain a relative difference set D with parameters R(q + 1, q - 1, q, 1). Then, we compute a translate of D which is fixed by q. In fact, Spence showed that such a set always exists.

Furthermore, he also showed that this set must contain an element congruent to 0 mod q + 1, and therefore we can get a new relative difference set  $D_1$  (fixed by q) where such element is 0 by translating the set by a suitable multiple of q + 1.

Finally, Spence showed how we can use  $D_1$  to construct four polynomials  $\psi_1(x)$ ,  $\psi_2(x)$ ,  $\psi_3(x)$ ,  $\psi_4(x)$  with the form:

$$\psi_k(x) = \sum_{s \in S_k} x^s \quad 1 \le k \le 4$$

The four sets  $S_1, S_2, S_3, S_4$  are SDS with parameters  $4 - \{2v; v, v + 1, v, v; 2v\}$ .

#### 5.3.2 Computation of SDS

Particularly important are also the SDS with parameters  $4 - \{n; k_1, k_2, k_3, k_4; n - \sum_{i=1}^{4} k_i\}$ .

Although no general construction is known for these sets, they have been computed for many values of n [5, 8, 10]. In most cases, they are defined as subsets of the group G of residues modulo n. In particular, papers that use this notation usually provide a subset H of G with |H| = k, a set of values  $C = \{c_i \mid 0 \le i \le (n-1)/(2k)\}$  and four indices sets  $J_1, J_2, J_3, J_4$ .

Then, from the set H we construct (n-1)/k subsets of G:

$$\alpha_{2i} = \{c_i h \mid h \in H\}$$
$$\alpha_{2i+1} = \{-x \mid x \in \alpha_{2i}\}$$

Algorithm 5: Basic algorithm for computing SDS

```
def construction_sds(n, H, indices, subsets_gen):
    Z = Zmod(n)
    subsets = []
    for el in subsets_gen:
         even_sub = \{x * el \text{ for } x \text{ in } H\}
         odd\_sub = \{-x \text{ for } x \text{ in } even\_sub}\}
         subsets.append(even_sub)
         subsets.append(odd_sub)
    def generate_set(index_set, subs):
         S = set()
         for idx in index_set:
             S = S.union(subs[idx])
         return S
    S1 = generate\_set(indices[0], subsets)
    S2 = generate\_set(indices[1], subsets)
    S3 = generate\_set(indices[2], subsets)
    S4 = generate\_set(indices[3], subsets)
    return [S1, S2, S3, S4]
```

and the SDS  $S_1, S_2, S_3, S_4$  are:

$$S_i = \bigcup_{j \in J_i} \alpha_j \quad 1 \le i \le 4$$

I have generalised this algorithm (summarised in Fig. 5), so that it is possible to add 0 to some subsets, and it allows to specify some  $\alpha_i$  directly as a set.

Lastly, I have implemented some additional constructions. In particular, [6] defines some skew SDS over a group of polynomials, and [11] gives some skew SDS where  $S_1$ is the Paley-Todd difference set.

Overall, skew SDS of this type are now available in SageMath for n equal to:

37, 39, 43, 49, 65, 67, 73, 81, 93, 97, 103, 109, 113, 121, 127, 129, 133, 145, 151, 157, 163, 169, 181, 213, 217, 219, 239, 241, 247, 267, 331, 631

Additional non-skew SDS are also available for n = 191, 251.

## 5.4 Complementary Difference Sets

Finally, we define complementary difference sets [29]:

**Definition.** Two subsets A and B of an additive abelian group G of order 2m + 1 will be called complementary difference sets in G if

- A contains m elements;
- $\alpha \in A$  implies  $-\alpha \notin A$ ;
- for each  $\delta \in G$ ,  $\delta \neq 0$  the equations

$$\delta = \alpha_1 - \alpha_2$$
$$\delta = \beta_1 - \beta_2$$

have altogether m-1 distinct solution vectors.

Using the notation from the previous section, A, B are complementary difference sets if they are skew SDS with parameters  $2-\{2m+1; m, m; m-1\}$ . I have implemented three different constructions.

The first construction creates complementary difference sets over a group of order q, when q is a prime power congruent to 3 mod 4. Given a Galois field G of order q, Szekeres [27] showed that the two sets A = B which contain the nonzero squares in G are complementary difference sets over the additive group of G.

A second function allows to create complementary difference sets over a group of order  $q = p^t$ , where p is a prime congruent to 5 mod 8, and  $t \equiv 1, 2, 3 \mod 4$ . In [29], Szekeres gave a construction for the case  $t \equiv 1 \mod 2$ , which uses a Galois field G of order q.

Let  $\rho$  be a generator of the multiplicative group of G, and  $C_0$  be the set of non-zero fourth powers of G. Then, define the sets  $C_1, C_2, C_3$  as  $C_i = \rho^i C_0$ . The complementary difference sets over the additive group of G are:

$$A = C_0 \cup C_1$$
$$B = C_0 \cup C_3$$

In 1971, Szekeres published a new paper [27], which covers the case  $t \equiv 2 \mod 4$ . Let G be the Galois field of order q. Then, if  $\rho$  is a multiplicative generator of G, let  $C_0$  be the set of nonzero eighth powers of G. Define  $C_i = \rho^i C_0$  for  $1 \le i \le 7$ ; the complementary difference sets are:

$$A = C_0 \cup C_1 \cup C_2 \cup C_3$$
$$B = C_0 \cup C_1 \cup C_6 \cup C_7$$

The last function creates complementary difference sets over a group of order n = 2m + 1, when 4m + 3 is a prime power [29]. Let  $\rho$  be a primitive element of the Galois field of order 4m + 3. Then, define Q to be the set of squares in the Galois field. The following sets are complementary difference sets in the group of integers modulo n:

$$A = \{a \mid 0 \le a \le n \land \rho^{2a} - 1 \in Q\}$$
$$B = \{b \mid 0 \le b \le n \land -\rho^{2b} - 1 \in Q\}$$

## 6 Hadamard Matrices

#### 6.1 Williamson Construction

At the start of my project, the first order for which no Hadamard matrix was present in SageMath was 116. The construction for this order is due to Williamson [15]: he proved that the matrix H given by

$$H = \begin{pmatrix} A & B & C & D \\ B & A & D & -C \\ C & -D & A & B \\ D & C & -B & A \end{pmatrix}$$

is a Hadamard matrix of order 4n, if A, B, C, D are  $n \times n$  symmetric circulant matrices (i.e. matrices where every row contains the same entries as the previous row, but rotated to the right by one element) that commute with each other. Furthermore, they must satisfy the condition:

$$A^2 + B^2 + C^2 + D^2 = 4nI$$

Such matrices are called Williamson matrices.

#### 6.2 Goethals-Seidel Array

Goethals and Seidel [13] discovered that given four (-1, +1) matrices A, B, C, D of order n such that

$$AA^\top + BB^\top + CC^\top + DD^\top = 4nI$$

then a Hadamard matrix of order 4n can be constructed by plugging them into the Goethals-Seidel array:

$$GS(A, B, C, D) = \begin{pmatrix} A & BR & CR & DR \\ -BR & A & D^{\top}R & -C^{\top}R \\ -CR & -D^{\top}R & A & B^{\top}R \\ -DR & C^{\top}R & -B^{\top}R & A \end{pmatrix}$$

Here, R is the  $n \times n$  permutation matrix with all ones on the anti-diagonal.

Furthermore, if A = S + I with S a skew-symmetric matrix, the Goethals-Seidel array will give a skew Hadamard matrix.

#### 6.2.1 Hadamard Matrices from Supplementary Difference Sets

The Goethals-Seidel array has been used extensively to construct Hadamard matrices (both skew and non-skew) of order 4v from SDS over groups of size v. As explained in [7], a sufficient condition for constructing such matrices is that the SDS  $S_1, S_2, S_3, S_4$ with parameters  $4 - \{v; k_1, k_2, k_3, k_4; \lambda\}$ , satisfy

$$k_1 + k_2 + k_3 + k_4 = v + \lambda$$

Additionally, if  $S_1$  is skew the resulting Hadamard matrix will be skew.

Given these SDS (described in section 5.3.2), we can create  $v \times v$  matrices  $A_1$ ,  $A_2$ ,  $A_3$ ,  $A_4$ , which have entries:

$$(A_n)_{i,j} = \begin{cases} -1 & \text{if } i - j \in S_n \\ 1 & \text{otherwise} \end{cases}$$

These matrices can be plugged into the Goethals-Seidel array to get the desired Hadamard matrix.

#### Skew Hadamard Matrix of Order 292

I used this construction to obtain a skew Hadamard matrix of order 292. According to multiple papers, this matrix was known since 1978. However, the only paper which we were able to find describing a construction for it was a paper by Djoković [9], which incorrectly cites the construction for a non-skew Hadamard matrix.

We contacted the author of [9], who acknowledged that the paper did not contain the correct reference, and helped us by constructing himself the skew SDS that can be used to obtain the skew Hadamard matrix.

#### 6.3 Construction from T-sequences

Cooper and Wallis [4] described a construction of Hadamard matrices that uses "Tmatrices".

**Definition** ([23]). Four circulant (0, 1, -1) matrices  $X_i$ , i = 1, 2, 3, 4, of order n which are non-zero for each of the  $n^2$  entries for exactly one i, and which satisfy

$$\sum_{i=1}^{4} X_i X_i^{\top} = nI$$

will be called T-matrices of order n.

Given such matrices, and Williamson matrices A, B, C, D of order w, Cooper and Wallis showed that it is possible to construct a Hadamard matrix of order 4nw. Let

$$\begin{split} e_1 &= GS(X_1, X_2, X_3, X_4) \\ e_2 &= GS(X_2, -X_1, X_4, -X_3) \\ e_3 &= GS(X_3, -X_4, -X_1, X_2) \\ e_4 &= GS(X_4, X_3, -X_2, -X_1) \end{split}$$

Then, the Hadamard matrix is given by  $(a \times b \text{ represent the tensor product between} a \text{ and } b)$ :

$$H = e_1 \times A + e_2 \times B + e_3 \times C + e_4 \times D$$

Although some T-matrices have been computed directly (e.g. in [21]), a more convenient way to obtain them is from T-sequences. In fact, if we use T-sequences of length n as the first rows of four circulant matrices  $X_1, X_2, X_3, X_4$ , we obtain four T-matrices.

Hence, we can look for a Hadamard matrix of order 4n by checking if there is a decomposition of n into two factors w, t such that we have Williamson matrices of order w and T-matrices of order t (see Fig. 6).

Algorithm 6: Cooper-Wallis construction

#### 6.4 Skew Hadamard Matrices from Good Matrices

A different type of matrices, called Good matrices, can be used to construct skew Hadamard matrices. They are defined in [17] as:

**Definition.** Four (1, -1) matrices A, B, C, D of order n (odd) with the properties:

- $MN^{\top} = NM^{\top}$  for  $M, N \in \{A, B, C, D\}$ ;
- $(A I)^{\top} = -(A I), B^{\top} = B, C^{\top} = C, D^{\top} = D;$
- $AA^{\top} + BB^{\top} + CC^{\top} + DD^{\top} = 4nI.$

will be called good matrices.

Good matrices of order n = 1, 3, ..., 31 are listed in [28]. These matrices can be used to obtain a skew Hadamard matrix of order 4n:

$$H = \begin{pmatrix} A & B & C & D \\ -B & A & D & -C \\ -C & -D & A & B \\ -D & C & -B & A \end{pmatrix}$$

#### 6.5 Miyamoto Construction

In [19], Miyamoto provided a construction for an infinite series of Hadamard matrices:

**Theorem 11.** Let q be a prime power and  $q \equiv 1 \mod 4$ . If there is a Hadamard matrix of order q - 1, then there is a Hadamard matrix of order 4q.

This construction uses conference matrices, which are matrices where the diagonal contains all zeros, all other entries are (-1, 1) and the matrix satisfies  $CC^{\top} = (n-1)I$ .

Paley's second construction of Hadamard matrices provides a method to obtain conference matrices of order q + 1 (q an odd prime power) in the form:

$$C = \begin{pmatrix} 0 & e_q \\ e_q^\top & D \end{pmatrix}$$

where  $e_k$  is the row vector containing all ones.

Then, by permuting rows and columns of the matrix, we can rewrite it as:

$$C = \begin{pmatrix} 0 & 1 & e_m & e_m \\ 1 & 0 & e_m & -e_m \\ e_m^\top & e_m^\top & -C_1 & -C_2 \\ e_m^\top & -e_m^\top & C_2^\top & C_4 \end{pmatrix}$$

Now, the Hadamard matrix K of order q-1 is split into four sub matrices  $K_1$ ,  $K_2$ ,  $K_3$ ,  $K_4$ :

$$K = \begin{pmatrix} K_1 & K_2 \\ -K_3 & K_4 \end{pmatrix}$$

To simplify notation, define the following:

$$U_{11} = U_{33} = C_1$$
  

$$U_{12} = U_{34} = C_2$$
  

$$U_{21} = U_{43} = -C_2^\top$$
  

$$U_{22} = U_{44} = C_4$$
  

$$U_{13} = U_{14} = U_{23} = U_{24} = U_{31} = U_{32} = U_{41} = U_{42} = 0$$
  

$$V_{13} = -V_{31}^\top = K_1$$
  

$$V_{14} = -V_{41}^\top = K_2$$
  

$$V_{23} = -V_{32}^\top = K_3$$
  

$$V_{24} = V_{32}^\top = K_4$$
  

$$V_{11} = V_{22} = V_{33} = V_{44} = I$$
  

$$V_{12} = V_{21} = V_{34} = V_{43} = 0$$

and then, for  $1 \leq i, j \leq 4$  let:

$$T_{ij} = \begin{pmatrix} U_{ij} + V_{ij} & U_{ij} - V_{ij} \\ U_{ij} - V_{ij} & U_{ij} + V_{ij} \end{pmatrix}$$

Finally, the Hadamard matrix of order 4q is given by:

$$H = \begin{pmatrix} 1 & -e & 1 & e & 1 & e & 1 & e \\ -e^{\top} & T_{11} & e^{\top} & T_{12} & e^{\top} & T_{13} & e^{\top} & T_{14} \\ -1 & -e & 1 & -e & 1 & e & -1 & -e \\ -e^{\top} & -T_{21} & -e^{\top} & T_{22} & e^{\top} & T_{23} & -e^{\top} & -T_{24} \\ -1 & -e & -1 & -e & 1 & -e & 1 & e \\ -e^{\top} & -T_{31} & -e^{\top} & -T_{32} & -e^{\top} & T_{33} & e^{\top} & T_{34} \\ -1 & -e & 1 & e & -1 & -e & 1 & -e \\ -e^{\top} & -T_{41} & e^{\top} & T_{42} & -e^{\top} & -T_{43} & -e^{\top} & T_{44} \end{pmatrix}$$

#### 6.6 Spence Construction from Supplementary Difference Sets

Spence [24] proposed a construction that uses SDS with parameters  $4 - \{2v; v, v, v, v + 1; 2v\}$ :

**Theorem 12.** If there exist  $4 - \{2v; v, v, v, v + 1; 2v\}$  supplementary difference sets in the cyclic group of order 2v then there exists a Hadamard matrix of order 4(2v+1).  $\Box$ 

The SDS  $S_1, S_2, S_3, S_4$  are used to create four matrices  $A_1, A_2, A_3, A_4$ :

$$(A_l)_{i,j} = \begin{cases} +1 & \text{if } i-j \in S_l \\ -1 & \text{if } i-j \notin S_l \end{cases}$$

Furthermore, let P be the permutation matrix with ones on the anti-diagonal. The Hadamard matrix is given by:

$$H = \begin{pmatrix} +1 & -1 & +1 & +1 & e & e & e & e \\ +1 & +1 & -1 & +1 & -e & e & -e & e \\ -1 & +1 & +1 & +1 & -e & e & e & -e \\ -1 & -1 & -1 & +1 & -e & -e & e & e \\ -e^{\top} & e^{\top} & e^{\top} & -e^{\top} & A_1 & A_2P & A_3P & A_4P \\ -e^{\top} & -e^{\top} & e^{\top} & e^{\top} & -A_2P & A_1 & -A_4^{\top}P & A_3^{\top}P \\ -e^{\top} & -e^{\top} & -e^{\top} & -e^{\top} & -A_3P & A_4^{\top}P & A_1 & -A_2^{\top}P \\ e^{\top} & -e^{\top} & e^{\top} & -e^{\top} & -A_4P & -A_3^{\top}P & A_2^{\top}P & A_1 \end{pmatrix}$$

#### 6.7 Construction from Complementary Difference Sets

In [2], Blatt and Szekeres showed that given complementary difference sets of size m, a skew Hadamard matrix of order 4(m + 1) exists.

Suppose that A, B are two complementary difference sets over a group G. Then, the Hadamard matrix will be in the form H = I + S, where S is defined as follows. Let  $\gamma_1, \gamma_2, ..., \gamma_{2m+1}$  be the elements of G. We have, for  $1 \le i, j \le 2m+1$ :

$$-S_{2m+1+i,2m+1+j} = S_{ij} = \begin{cases} +1 & \text{if } \gamma_j - \gamma_i \in A \\ -1 & \text{otherwise} \end{cases}$$
$$-S_{2m+1+j,i} = S_{i,2m+1+j} = \begin{cases} +1 & \text{if } \gamma_j - \gamma_i \in B \\ -1 & \text{otherwise} \end{cases}$$

Furthermore,

$$-S_{4m+3,i} = S_{i,4m+3} = \begin{cases} +1 & \text{for } 1 \le i \le 2m+1\\ -1 & \text{for } 2m+2 \le i \le 4m+2 \end{cases}$$
$$S_{4m+4,i} = -S_{i,4m+4} = +1 \text{ for } 1 \le i \le 4m+3$$
$$S_{ii} = 0 \text{ for } 1 \le i \le 4m+4 \end{cases}$$

It is easy to see from the definition of S that it is skew-symmetric. Hence, the resulting Hadamard matrix will be skew.

#### 6.8 Spence Construction of Skew Hadamard Matrices

Another construction of skew Hadamard matrices using complementary difference sets was given by Spence [25].

**Theorem 13.** If there exists a cyclic projective plane of order q and two complementary difference sets in a cyclic group of order  $1 + q + q^2$ , then there exists a skew-Hadamard matrix of the Goethals-Seidel type of order  $4(1 + q + q^2)$ .

He noted that cyclic projective planes of order q always exist if q is a prime power. Therefore, using the known constructions of complementary difference sets it is easy to see that a skew Hadamard matrix of order  $4(1 + q + q^2)$  can be constructed whenever q is a prime power such that either  $1 + q + q^2$  is a prime congruent to 3, 5, 7 mod 8 or  $2q^2 + 2q + 3$  is a prime power.

The cyclic projective plane is used by Spence to create a  $(1 + q^2 + q^4, 1 + q^2, 1)$ difference set. Since a construction for such sets Was already present in SageMath, I used it directly. Then, let D be a translate of this set fixed by q. We define a subset  $D_1$ :

$$D_1 = \{ d \in D \mid d \equiv 0 \mod 1 - q + q^2 \}$$

The elements in  $D \setminus D_1$  can be partitioned into pairs  $(d_i, d'_i)$  such that  $d_i \equiv d'_i \mod 1 + q + q^2$  and  $d_i \not\equiv d_j \mod 1 + q + q^2$  whenever  $i \neq j$ . Given these pairs, we define a new set:

$$D_2 = \{ d_i \mod 1 + q + q^2 \mid 1 \le i \le \frac{1}{2}(1 + q^2) \}$$

Then, we obtain the matrices R and S of order  $1 + q + q^2$ :

$$R_{ij} = \begin{cases} +1 & \text{if } j - i \equiv d \mod 1 + q + q^2 \text{ for some } d \in D_1 \cup D_2 \\ -1 & \text{otherwise} \end{cases}$$
$$S_{ij} = \begin{cases} +1 & \text{if } j - i \equiv d \mod 1 + q + q^2 \text{ for some } d \in D_2 \\ -1 & \text{otherwise} \end{cases}$$

Now, let A, B be the complementary difference sets of order  $1 + q + q^2$ . We define two additional matrices of order  $1 + q + q^2$ :

$$P_{ij} = \begin{cases} +1 & \text{if } j - i \in A \\ -1 & \text{otherwise} \end{cases}$$
$$Q_{ij} = \begin{cases} +1 & \text{if } j - i \in B \\ -1 & \text{otherwise} \end{cases}$$

Finally, plugging the matrices P, Q, R, S into the Goethals-Seidel array will give a skew Hadamard matrix of order  $4(1 + q + q^2)$ .

#### 6.9 Skew Hadamard Matrices from Amicable Orthogonal Designs

The last construction of skew Hadamard matrices that I implemented uses the following theorem [22]:

**Theorem 14.** Suppose there is an orthogonal design of type (1, m, mn - m - 1) in order mn. Suppose n is the order of amicable designs of types ((1, n - 1); (n)). Then there is a skew Hadamard matrix of order mn(n - 1).

Orthogonal designs are defined as follows:

**Definition** (Seberry [22]). An orthogonal design of order n and type  $(u_1, u_2, ..., u_k) \in \mathbb{Z}_{>0}^k$  on the commuting variables  $x_1, x_2, ..., x_k$  is an  $n \times n$  matrix A with entries from  $\{0, x_1, x_2, ..., x_k\}$  such that

$$AA^{\top} = \sum_{i=1}^{k} (u_i x_i^2) I_n$$

Furthermore, two orthogonal designs M of type  $(m_1, ..., m_p)$  and N of type  $(n_1, ..., n_q)$ , both of order n, are called amicable of type  $((m_1, ..., m_p); (n_1, ..., n_q))$  if  $MN^{\top} = NM^{\top}$ .

Now, suppose M, N are amicable orthogonal designs of type ((1, n - 1); (n)). They can be rewritten in the form:

$$M = xI + y \begin{pmatrix} 0 & e \\ -e^{\top} & P \end{pmatrix} \qquad N = z \begin{pmatrix} 1 & e \\ -e^{\top} & D \end{pmatrix}$$
(1)

where e is the  $1 \times n - 1$  vector of all ones.

Then, let J be the  $(n-1) \times (n-1)$  matrix of all ones, and K be the orthogonal design of order mn and type (1, m, mn - m - 1). Replacing the variables of K with P, J, D respectively we get a skew Hadamard matrix of order mn(n-1).

I used this construction to obtain a skew Hadamard matrix of order 756, by setting m = 1 and n = 28. However, to do so it has been necessary to find the orthogonal designs M, N, K used in the construction.

An orthogonal design of type (1, 1, 26) (K) is listed in Appendix G of [23]. However, for the amicable orthogonal designs M, N of type ((1, 27); (28)) I used a more general approach, which creates orthogonal designs of type ((1, n - 1); (n)) from amicable Hadamard matrices of order n.

#### 6.9.1 Construction of Amicable Hadamard Matrices

Amicable Hadamard matrices are defined as:

**Definition** (Seberry[23], Chapter 5.10). Two  $n \times n$  Hadamard matrices W and M are called amicable Hadamard matrices of order n if:

- W is a skew Hadamard matrix;
- M is symmetric;
- $WM^{\top} = MW^{\top}$ .

Seberry [23] proved that two such matrices M, W of order n are equivalent to two amicable orthogonal designs of type ((1, n - 1); (n)). If we write W = I + S, the two orthogonal designs will be:

$$A = xI + yS$$
  $B = zM$ 

Furthermore, if M and W are normalised, the resulting orthogonal designs will be in the form described in Eq. 1.

Hence, we have now transformed the problem into finding two amicable Hadamard matrices of order 28. A construction of such matrices is described by Seberry in [31]: this works for any order n = q + 1, where q is a prime power.

Let G be a Galois field of order q, and order its elements such that  $a_0 = 0$  and  $a_{q-i} = -a_i$  for  $1 \le i \le q - 1$ . Then, define  $\chi(x)$  as follows:

$$\chi(x) = \begin{cases} 0 & \text{if } x = 0\\ 1 & \text{if } x \text{ is a square}\\ -1 & \text{otherwise} \end{cases}$$

We can create two  $q \times q$  matrices S, R, where S is defined by  $S_{ij} = \chi(a_j - a_i)$ , and the entries of R are:

$$R_{ij} = \begin{cases} 1 & \text{if } i = j = 0 \lor (j = q - i \land 1 \le i \le q - 1) \\ 0 & \text{otherwise} \end{cases}$$

Now, let P = S + I and D = R + RS. The two amicable Hadamard matrices are given by:

$$W = \begin{pmatrix} 1 & e \\ -e^{\top} & P \end{pmatrix} \qquad M = \begin{pmatrix} 1 & e \\ e^{\top} & D \end{pmatrix}$$

## 7 Conclusion

The aim of this project was to implement Hadamard and skew Hadamard matrices of order up to 1000 in SageMath. I achieved this by implementing nine new methods for obtaining these matrices (as well as some additional constructions, as seen in chapters 4 and 5). Therefore, from version 10.0 of SageMath it will be possible to construct skew and non-skew Hadamard matrices of every order less than or equal to 1000, for which a construction is known.

In total, I have added more than 5000 lines of code to the SageMath repository (of which around 1000 contain the documentation). This code is easily extendable: as explained in section 3.3, a generic function hadamard\_matrix which accesses all implemented constructions is available. Therefore, if a new construction is added to SageMath, it is enough to add it also to this function, and then all users that were using Hadamard matrices will be able to use the new orders without having to modify their code.

Furthermore, extensive tests have been written for all the methods added to Sage-Math, and users can use the check parameter if they want to be sure that the function is working correctly. These design decisions make sure that the requirements detailed in Chapter 1 have been met.

#### 7.1 Challenges

While working on this project, one of the main difficulties has been that many of the papers that I read use different notations, often conflicting with each other. For example, the name "complementary difference sets" has sometimes been used to refer to supplementary difference sets.

Furthermore, it has been hard to determine how to create some Hadamard matrices, because many papers listed the known orders without citing the relevant constructions. In particular, this happened with the skew Hadamard matrix of order 292, for which we could not find any published construction.

Lastly, while implementing some functions I realised that they were generalisations of constructions that I had already added to SageMath. Therefore, if I had to work on this project again I would try to choose the constructions more carefully, to avoid redundancy.

## 7.2 Future Work

Given the nature of the project, it would be easy to extend it by adding more constructions for Hadamard matrices. On the other hand, it may also be useful to search for constructions that cover new orders of Hadamard matrices.

Lastly, since the Hadamard conjecture is still open, it would be interesting to try to prove (or disprove) it.

## A Table Of Constructions

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Table 2 details for every odd value of n < 250 which method can be used to construct the Hadamard matrix of order 4n (whenever n is even, the Hadamard matrix can be constructed using the doubling construction). Similarly, Table 3 lists the constructions of skew Hadamard matrices. Note that some entries of the two tables are empty: this indicates that no construction for the corresponding order is known. Table 1 contains an explanation of the abbreviations used in the two lists.

Table 1: Algorithms used in tables 2-3

PaleyI	Paley's first construction						
PaleyII	Paley's second construction						
Will	Williamson construction						
$\operatorname{GS}$	Goethals-Seidel array						
SDS	Construction from (possibly skew) SDS						
CW(t)	Construction of Hadamard matrix of order $4n$ from T-sequences of length $t$ (and Williamson matrices of order $n/t$ )						
Good	construction from good matrices						
Miy	Miyamoto Construction						
CDS	Construction from complementary difference sets						
Spence(q)	Spence construction of skew Hadamard matrix of order $4(1+q+q^2)$						
AOD(m, n)	construction of a skew Hadamard matrix of order $mn(n-1)$ from a micable orthogonal designs						

Table 2: Hadamard matrices of order $4n$ , up to 1000										
1	PaleyI	3	PaleyI	5	PaleyI	7	PaleyI	9	PaleyII	
11	PaleyI	13	PaleyII	15	PaleyI	17	PaleyI	19	PaleyII	
21	PaleyI	23	Will	25	PaleyII	27	PaleyI	29	Will	
31	PaleyII	33	PaleyI	35	PaleyI	37	PaleyII	39	Will	
41	PaleyI	43	Will	45	PaleyI	47	CW(47)	49	PaleyII	
51	PaleyII	53	PaleyI	55	PaleyII	57	PaleyI	59	CW(59)	
61	PaleyI	63	PaleyI	65	CW(5)	67	CW(67)	69	PaleyII	
71	PaleyI	73	Miy	75	PaleyII	77	PaleyI	79	PaleyII	
81	CW(3)	83	PaleyI	85	PaleyII	87	PaleyI	89	CW(89)	
91	PaleyII	93	CW(3)	95	PaleyI	97	PaleyII	99	PaleyII	
101	Miy	103	SDS	105	PaleyI	107	CW(107)	109	Miy	
111	PaleyI	113	Miy	115	PaleyII	117	PaleyI	119	CW(7)	
121	PaleyII	123	PaleyI	125	PaleyI	127	SDS	129	PaleyII	
131	PaleyI	133	CW(7)	135	PaleyII	137	PaleyI	139	PaleyII	
141	PaleyI	143	PaleyI	145	PaleyII	147	PaleyI	149	Miy	
151	SDS	153	CW(3)	155	PaleyI	157	PaleyII	159	PaleyII	
161	PaleyI	163	SDS	165	PaleyI	167		169	PaleyII	
171	PaleyI	173	PaleyI	175	PaleyII	177	PaleyII	179		
181	PaleyII	183	CW(3)	185	PaleyI	187	PaleyII	189	CW(3)	
191	SDS	193	Miy	195	PaleyII	197	PaleyI	199	PaleyII	
201	PaleyII	203	PaleyI	205	PaleyII	207	PaleyI	209	CW(11)	
211	PaleyII	213	CW(71)	215	PaleyI	217	PaleyII	219	SDS	
221	PaleyI	223		225	PaleyII	227	PaleyI	229	PaleyII	
231	PaleyII	233	Miy	235	CW(47)	237	PaleyI	239	SDS	
241	Miy	243	PaleyI	245	CW(5)	247	CW(13)	249	CW(83)	

Table 3: Skew Hadamard matrices of order $4n$ , up to 1000									
1	Good	3	Good	5	Good	7	Good	9	Good
11	Good	13	Good	15	Good	17	Good	19	Good
21	Good	23	Good	25	Good	27	Good	29	Good
31	Good	33	PaleyI	35	PaleyI	37	SDS	39	SDS
41	PaleyI	43	SDS	45	PaleyI	47	GS	49	SDS
51	CDS	53	PaleyI	55	CDS	57	PaleyI	59	GS
61	PaleyI	63	PaleyI	65	SDS	67	SDS	69	GS
71	PaleyI	73	SDS	75	CDS	77	PaleyI	79	CDS
81	SDS	83	PaleyI	85	CDS	87	PaleyI	89	
91	CDS	93	SDS	95	PaleyI	97	SDS	99	CDS
101		103	SDS	105	PaleyI	107		109	SDS
111	PaleyI	113	SDS	115	CDS	117	PaleyI	119	
121	SDS	123	PaleyI	125	PaleyI	127	SDS	129	SDS
131	PaleyI	133	SDS	135	CDS	137	PaleyI	139	CDS
141	PaleyI	143	PaleyI	145	SDS	147	PaleyI	149	
151	SDS	153		155	PaleyI	157	SDS	159	CDS
161	PaleyI	163	SDS	165	PaleyI	167		169	SDS
171	PaleyI	173	PaleyI	175	CDS	177		179	
181	SDS	183	$\operatorname{Spence}(13)$	185	PaleyI	187	CDS	189	AOD(1, 28)
191		193		195	CDS	197	PaleyI	199	CDS
201		203	PaleyI	205		207	PaleyI	209	
211	CDS	213	SDS	215	PaleyI	217	SDS	219	SDS
221	PaleyI	223		225		227	PaleyI	229	
231	CDS	233		235		237	PaleyI	239	SDS
241	SDS	243	PaleyI	245		247	SDS	249	

Table 3: Skew Hadamard matrices of order 4n, up to 1000

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